

# Quadratic Interpolation

August, 4<sup>th</sup> 2017

Oltan Doci

# History

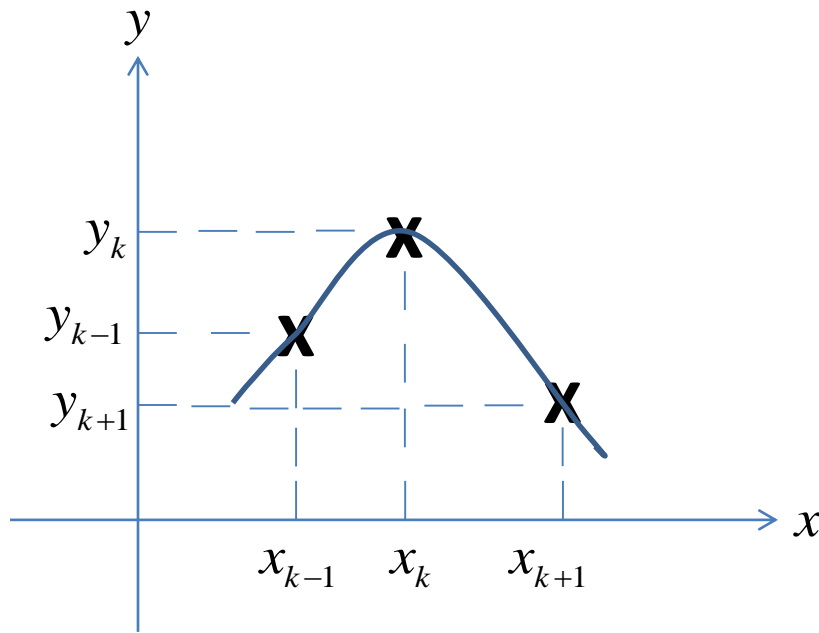
Date	Draft	Author	Comment
August 4 <sup>th</sup> , 2017	0	O.D.	Creation

# Quadratic interpolation

- The idea is to find interpolated point based on a parabolic function defined by the polynomial equation:

$$y = ax^2 + bx + c$$

- In this case we need 3 points of the parabola:



- The next point, interpolated, is given directly by the polynomial equation after finding the unknown variables: a, b and c

# Quadratic interpolation

- The system of linear equations would be:

$$\begin{cases} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ y_k = ax_k^2 + bx_k + c \\ y_{k+1} = ax_{k+1}^2 + bx_{k+1} + c \end{cases}$$

- There are many solutions types for this system (Cramer, Gauss, ...).
- Here we will show the straight solution procedure based on eliminations/substitutions.
- At the end we will detail a practical example based on a FFT peak

# Quadratic interpolation

- By eliminating  $c$  (retrieve the 1<sup>st</sup> line), one gets:

$$\begin{cases} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ y_k - y_{k-1} = a(x_k^2 - x_{k-1}^2) + b(x_k - x_{k-1}) \\ y_{k+1} - y_k = a(x_{k+1}^2 - x_k^2) + b(x_{k+1} - x_k) \end{cases}$$

- Isolate  $b$  (by dividing lines 2 and 3):

$$\begin{cases} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ \frac{y_k - y_{k-1}}{x_k - x_{k-1}} = a \frac{x_k^2 - x_{k-1}^2}{x_k - x_{k-1}} + b \\ \frac{y_{k+1} - y_k}{x_{k+1} - x_k} = a \frac{x_{k+1}^2 - x_k^2}{x_{k+1} - x_k} + b \end{cases}$$

- As  $x$  points are distinct, here we don't have 0 division

# Quadratic interpolation

- By eliminating  $b$  (retrieve the 2<sup>nd</sup> line), one gets:

$$\left\{ \begin{array}{l} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ \frac{y_k - y_{k-1}}{x_k - x_{k-1}} = a \frac{x_k^2 - x_{k-1}^2}{x_k - x_{k-1}} + b \\ \frac{y_{k+1} - y_k}{x_{k+1} - x_k} - \frac{y_k - y_{k-1}}{x_k - x_{k-1}} = a \left( \frac{x_{k+1}^2 - x_k^2}{x_{k+1} - x_k} - \frac{x_k^2 - x_{k-1}^2}{x_k - x_{k-1}} \right) \end{array} \right.$$

- Here  $a$  is given by the 3<sup>rd</sup> line and then we can find easily  $b$  using 2<sup>nd</sup> line so finally  $c$  is deduced in the 1<sup>st</sup> line.

# Quadratic interpolation

## FFT example

- On this example we suppose that we have a FFT result in the frequency domain where we are in presence of a peak (sinusoidal wave in time of a Doppler signal for ex)
- The goal is to find the maximum of the peak. Instead of taking the maximum between 3 points of the peak, we use quadratic interpolation for a better accuracy of this maximum.
- As x step here is 1 because x are digital indexes (at sampling frequency), we can write the previous linear system:

$$\begin{cases} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ y_k - y_{k-1} = a(x_k^2 - x_{k-1}^2) + b \\ y_{k+1} + y_{k-1} = a(x_{k+1}^2 + x_{k-1}^2) \end{cases}$$

# Quadratic interpolation

## FFT example

- Or, because of 1 step on x points, one gets:

$$\begin{aligned}x_k^2 - x_{k-1}^2 &= (x_k + x_{k-1})(x_k - x_{k-1}) \\ &= x_k + x_{k-1}\end{aligned}$$

- So the 2<sup>nd</sup> line in the system is simplified by:

$$\begin{cases} y_{k-1} = ax_{k-1}^2 + bx_{k-1} + c \\ y_k - y_{k-1} = a(x_k + x_{k-1}) + b \\ y_{k+1} + y_{k-1} = a(x_{k+1}^2 + x_{k-1}^2) \end{cases}$$



# Quadratic interpolation

## FFT example

- So the solution is:

$$\begin{cases} a = \frac{y_{k+1} + y_{k-1}}{x_{k+1}^2 + x_{k-1}^2} \\ b = y_k - y_{k-1} - a(x_k + x_{k-1}) \\ c = y_{k-1} - ax_{k-1}^2 - bx_{k-1} \end{cases}$$

- Or the derivative function on the maximum is 0, so one gets:

$$\left. \frac{dy}{dx} \right|_{x=x_{\max}} = 2ax_{\max} + b = 0$$

$$\Rightarrow \begin{cases} x_{\max} = -\frac{b}{2a}, \text{ for } a \neq 0 \\ y_{\max} = ax_{\max}^2 + bx_{\max} + c \end{cases}$$