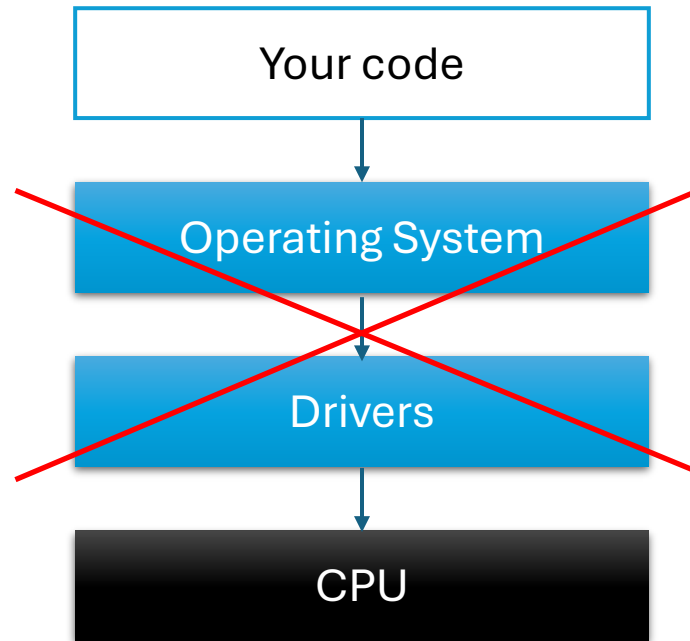


# Introduction to Bare Metal Coding

with Olve Maudal



A 90 minute mini-course at GET Academy, May 2025

- Round of introduction (10 min)
- Reflection and discussion (10 min) - ultra-low-power "smart collar" for sheep
- Demo (15 min) - development board, bare metal coding
- Exercise (15 min) - "Hello, world!" on JSLinux
- Presentation (10 min) - Embedded, C, Assembler, C++, Examples, tiobe
- Demo (15 min) - microcontroller, blinky, bare metal C, pure SDK example, Arduino C, microPython
- Ad-hoc discussions / Summary / Wrap up (15 min)

# Round of introduction

- Your name, and where are you right now?
- Favorite development environment, operating system and programming language?
- Any experience with C, assembler, microchips and bare metal programming?



## Exercise: ultra-low-power "smart collar" for sheep

A fast-spreading virus threatens Australia's sheep. If infected animals are identified within months, treatment works; if not, entire flocks could be lost.

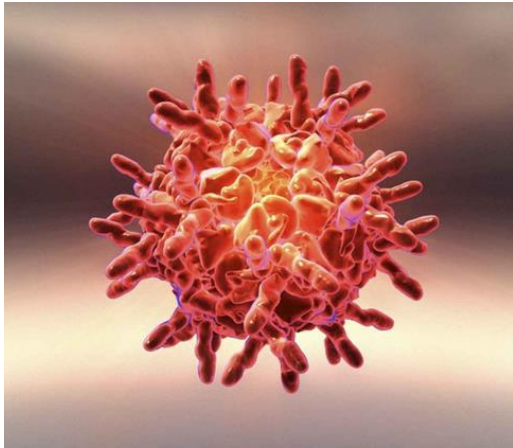
The federal government has asked your brilliant start-up company to deliver 100 working collars in 4 weeks and a concept plan within 7 days.

Each collar must:

- Uniquely identify its wearer (128-bit UUID)
- Log the last 10 000 sheep encountered within approx 5 m proximity
- Upload the log automatically when a reading station is within 100 m
- Run for at least 12 months on a battery and survive rain, dust and head-butts

If trials succeed, production will scale to 1 million units per week at a bill-of-materials (BOM) under €5.

Focus on the smart collar - let's have a brainstorming session...



BLE      μA      NXP      RP2040      Flash      Bluetooth

Nordic      nRF52      TI      ST      MSP

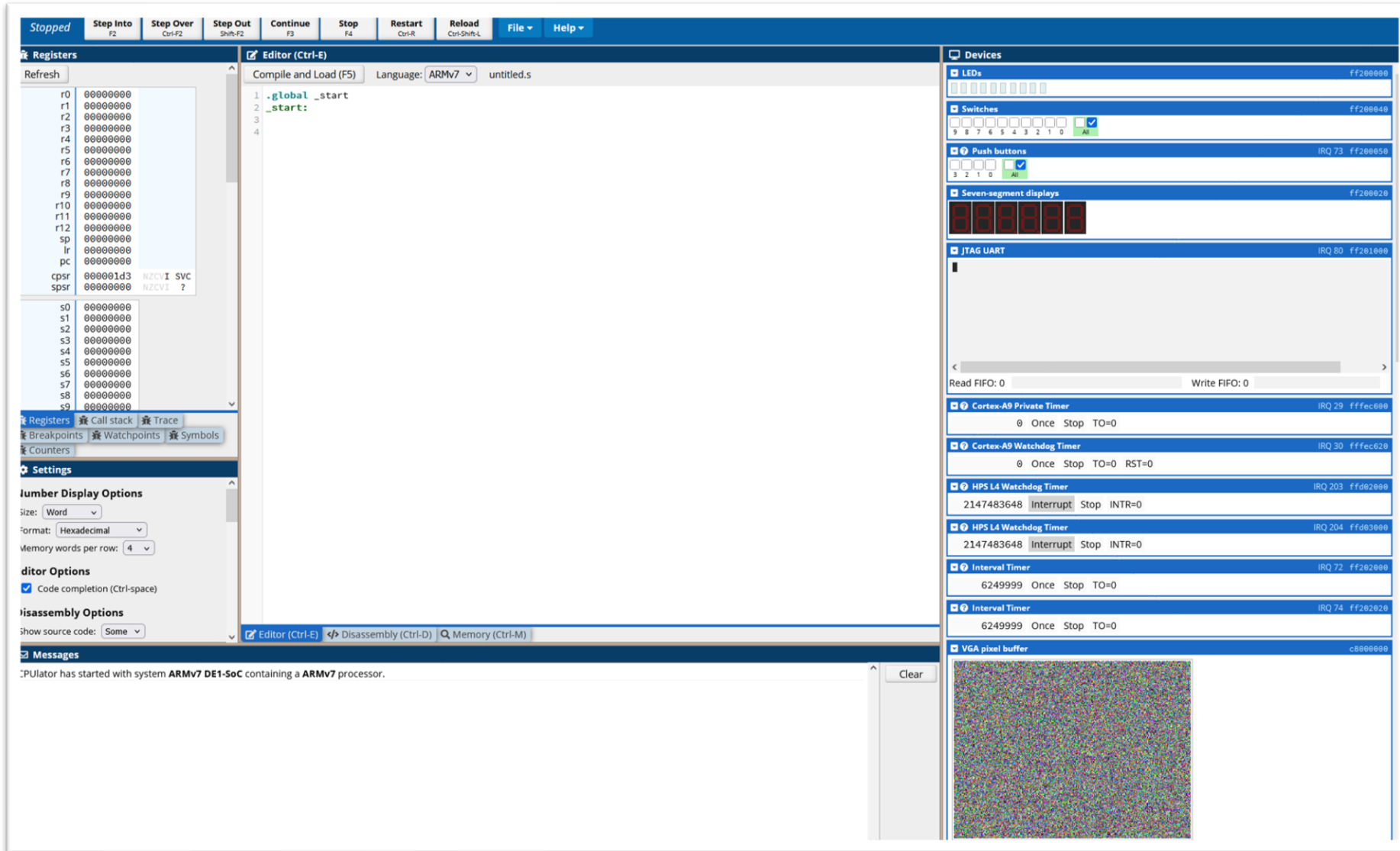
PIC18      Silicon Labs      Microchip      PIC16      GFSK

Zigbee      Realtek      Espressif      LoRa      VLPS      AVR

PIC18      Renesas      Ambiq      ESP      ATmega

FSK      Cortex-M0      EM2

# CPUlator DE1SOC



<https://cpulator.01xz.net/?sys=arm-de1soc>

```

.global _start

_start:
    ldr r0, =0xff200020
    ldr r1, =1

forever:
    str r1, [r0]
    add r1, #1
    bl delay
    b forever

delay:
    mov r2, #10000

waitloop:
    sub r2, #1
    cmp r2, #0
    bne waitloop
    bx lr

```

```

.global _start

.equ SWITCHES_BASE, 0xff200040
.equ DISPLAY_BASE, 0xff200020

_start:
    ldr r0, =SWITCHES_BASE
    ldr r1, =DISPLAY_BASE

forever:
    ldr r2, [r0]
    str r2, [r1]
    b forever

```

```

#include <stdint.h>
#include <stdio.h>

uint32_t * SWITCHES_BASE = (uint32_t*)0xff200040;
uint32_t * DISPLAY_BASE = (uint32_t*)0xff200020;

int main(void)
{
    uint32_t status = 0;
    uint32_t prev_status = 0;
    while (1) {
        status = *SWITCHES_BASE;
        *DISPLAY_BASE = status;
        if (status != prev_status) {
            printf("%08lx\n", status);
            prev_status = status;
        }
    }
}

```

# Hello, world!

```
Welcome to JS/Linux (i586)

Use 'vlogin username' to connect to your account.
You can create a new account at https://vfsync.org/signup .
Use 'export_file filename' to export a file to your computer.
Imported files are written to the home directory.

localhost:~# cat hello.c
#include <stdio.h>
int main(void)
{
    printf("hello world\n");
    return 0;
}

localhost:~# gcc -o hello hello.c
localhost:~# ./hello
hello world
localhost:~#
```

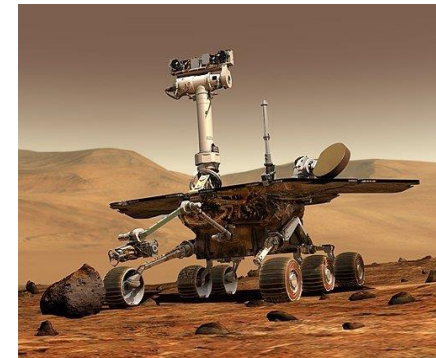
```
#include <stdio.h>

int main(void)
{
    for (int n = 0; n < 20; n++) {
        int d = 2;
        while (d < n && n % d != 0)
            ++d;
        if (d == n)
            printf("%d\n", n);
    }
}
```

- 0) Visit <https://bellard.org/jslinux/> and start x86 console emulator
- 1) Compile [hello.c](#) and run the program
- 2) Use the [nano](#) editor ("[nano hello.c](#)") to change the output string, recompile and run
- 3) Extra: type in the program on the right and try to figure out what it does

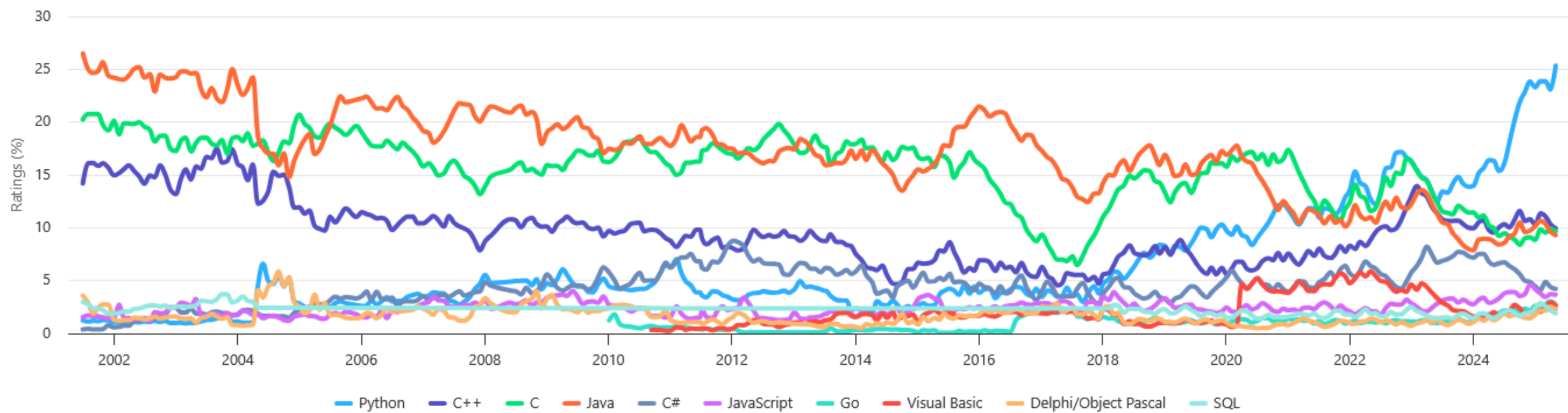


# Why C



## TIOBE Programming Community Index

Source: [www.tiobe.com](http://www.tiobe.com)



<https://www.tiobe.com/tiobe-index/>

```

#include <stdio.h>
#include <assert.h>
#include <stdbool.h>

static bool is_divisible(int numerator, int denominator) {
    return numerator % denominator == 0;
}

static bool isprime(int number)
{
    if (number < 2)
        return false;
    int denominator = 2;
    while (denominator < number) {
        if (is_divisible(number, denominator))
            return false;
        denominator += 1;
    }
    return true;
}

static int count_primes_in_range(int begin, int end)
{
    int count = 0;
    for (int n = begin; n < end; n++)
        if (isprime(n))
            count++;
    return count;
}

int main(void)
{
    assert(1 + 2 == 3);
    assert(isprime(3) == true);
    assert(isprime(4) == false);
    assert(isprime(5) == true);
    assert(isprime(2) == true);
    assert(isprime(1) == false);
    assert(count_primes_in_range(0,10) == 4);
    assert(count_primes_in_range(0,20) == 8);
    fprintf(stderr, "All tests passed\n");
    return 0;
}

```

```

$ cc -std=c17 -Wall -Wextra -pedantic count_primes.c && ./a.out
All tests passed
$

```

## primelib.h

```
#ifndef PRIMELIB_H_INCLUDED
#define PRIMELIB_H_INCLUDED

#include <stdbool.h>

bool isprime(int number);
int count_primes(int begin, int end);

#endif
```

## primelib.c

```
#include "primelib.h"

static bool superslow_isprime(int number)
{
    if (number < 2)
        return false;
    int denominator = 2;
    while (denominator < number) {
        if (number % denominator == 0)
            return false;
        ++denominator;
    }
    return true;
}

bool isprime(int number)
{
    return superslow_isprime(number);
}

int count_primes(int begin, int end)
{
    int count = 0;
    for (int n = begin; n < end; ++n)
        if (isprime(n))
            ++count;
    return count;
}
```

## primelib\_tests.c

```
#include "primelib.h"

#include <assert.h>
#include <stdio.h>

int main(void)
{
    assert(isprime(0) == false);
    assert(isprime(1) == false);
    assert(isprime(2) == true);
    assert(isprime(3) == true);
    assert(isprime(4) == false);
    assert(isprime(5) == true);
    assert(count_primes(0,10) == 4);
    assert(count_primes(2,10) == 4);
    assert(count_primes(10,20) == 4);
    assert(count_primes(11,19) == 3);
    assert(count_primes(1,20) == 8);
    assert(count_primes(1000,2000) == 135);

    fprintf(stderr, "All tests passed\n");
    return 0;
}
```

## primedemo.c

```
#include "primelib.h"

#include <stdio.h>

int main(void)
{
    int lower_bound = 4000;
    int upper_bound = 5000;

    printf("Number of primes in range [%d, %d) is ", lower_bound, upper_bound);
    fflush(stdout);

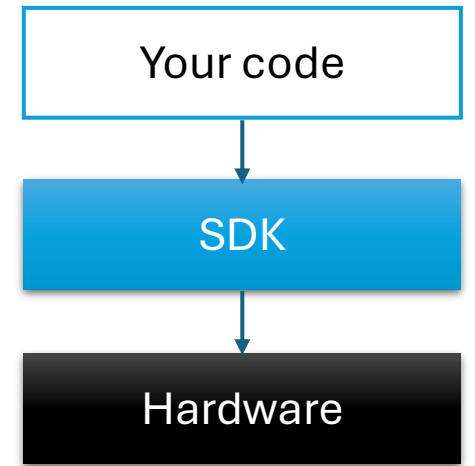
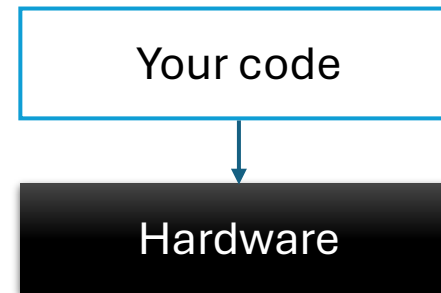
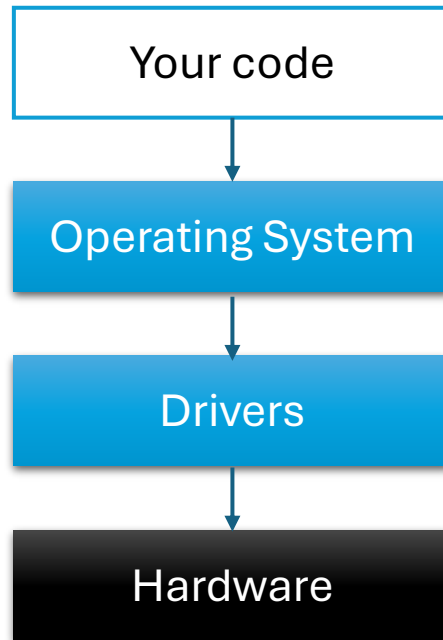
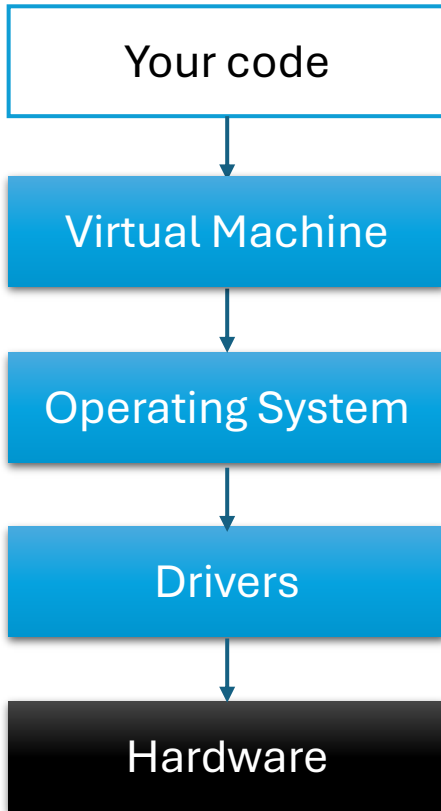
    int number_of_primes = count_primes_in_range(lower_bound, upper_bound);

    printf("%d\n", number_of_primes);

    return 0;
}
```

```
$ cc -c primelib.c
$ cc -o primelib_tests primelib_tests.c primelib.o
$ ./primelib_tests
All tests passed
$ cc -o primedemo primedemo.c primelib.o
$ ./primedemo
Number of primes in range [4000, 5000) is 119
$ echo $?
0
$
```





wokwi.com/projects/new/pi-pico-sdk

WOKWI

SAVE

SHARE

Docs

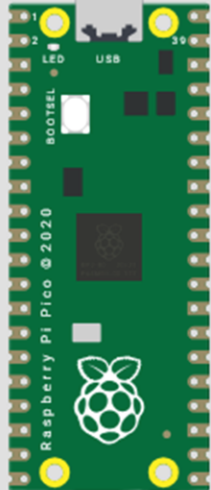
SIGN UP

main.c

diagram.json

```
1  #include "pico/stdlib.h"
2
3  #define LED_DELAY_MS 1000
4
5  int pico_led_init(void) {
6      gpio_init(PICO_DEFAULT_LED_PIN);
7      gpio_set_dir(PICO_DEFAULT_LED_PIN, GPIO_OUT);
8      return PICO_OK;
9  }
10
11 void pico_set_led(bool led_on) {
12     gpio_put(PICO_DEFAULT_LED_PIN, led_on);
13 }
14
15 int main() {
16     int rc = pico_led_init();
17     hard_assert(rc == PICO_OK);
18     while (true) {
19         pico_set_led(true);
20         sleep_ms(LED_DELAY_MS);
21         pico_set_led(false);
22         sleep_ms(LED_DELAY_MS);
23     }
24 }
```

Simulation



```
#include "pico/stdlib.h"

#define LED_DELAY_MS 1000

int pico_led_init(void) {
    gpio_init(PICO_DEFAULT_LED_PIN);
    gpio_set_dir(PICO_DEFAULT_LED_PIN, GPIO_OUT);
    return PICO_OK;
}

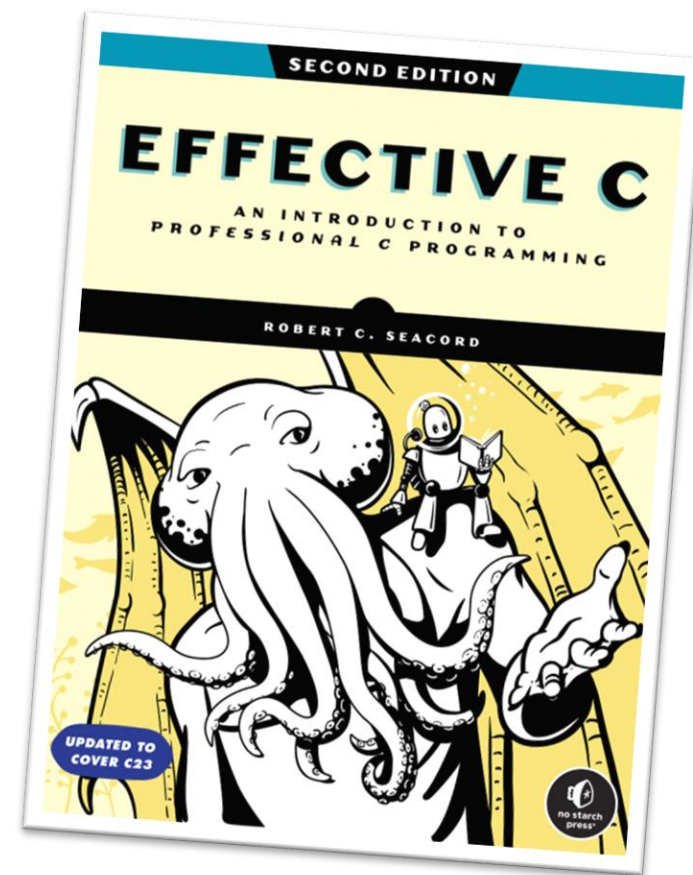
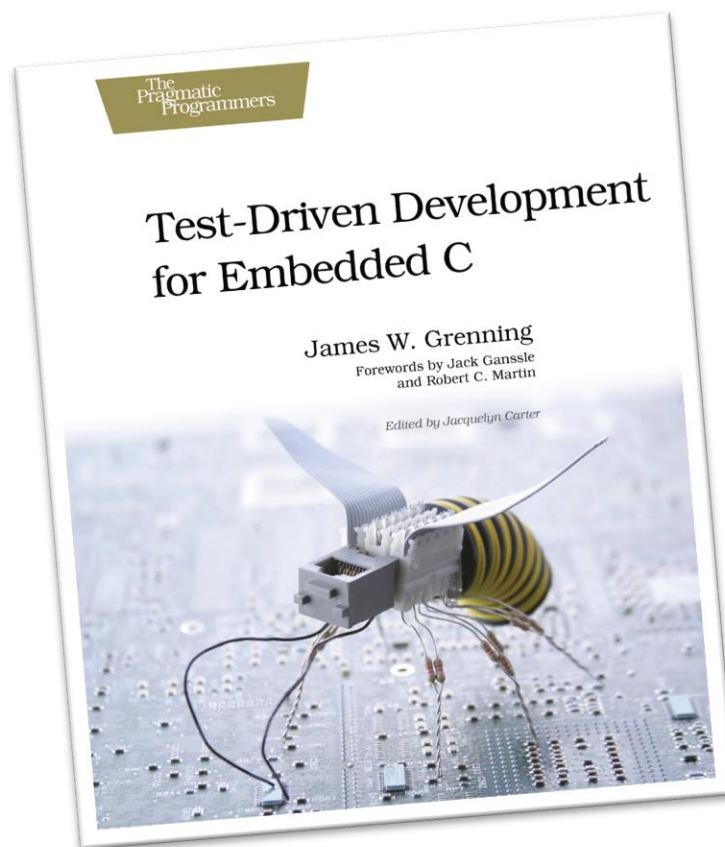
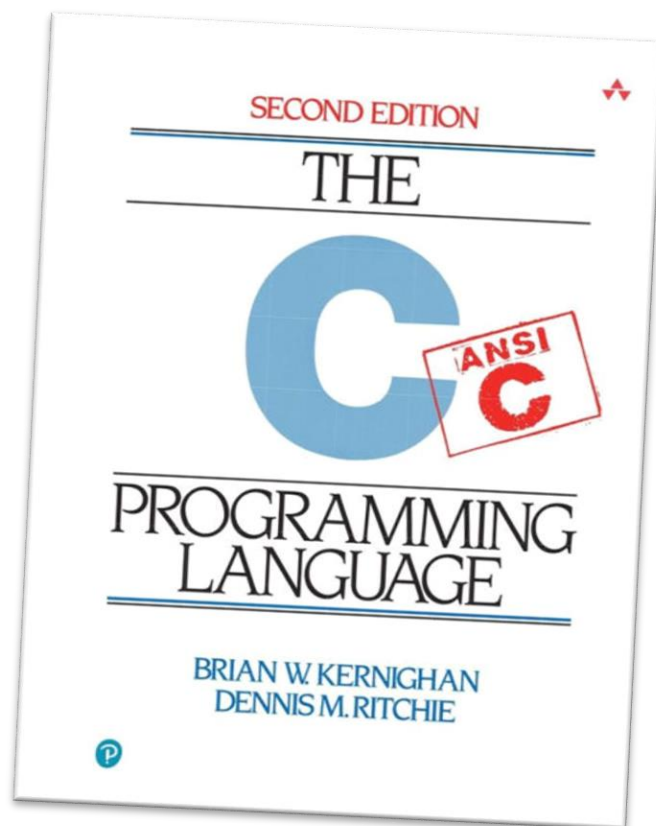
void pico_set_led(bool led_on) {
    gpio_put(PICO_DEFAULT_LED_PIN, led_on);
}

int main() {
    int rc = pico_led_init();
    hard_assert(rc == PICO_OK);
    while (true) {
        pico_set_led(true);
        sleep_ms(LED_DELAY_MS);
        pico_set_led(false);
        sleep_ms(LED_DELAY_MS);
    }
}
```



- HackadayU: Raspberry Pi Pico and RP2040 ([YouTube](#))
- RP2040 - Introduction to Assembly Language ([YouTube](#))
- <https://github.com/raspberrypi/pico-bootrom-rp2040>
- <https://github.com/raspberrypi/pico-sdk>
- <https://datasheets.raspberrypi.com/rp2040/rp2040-datasheet.pdf>
- <https://datasheets.raspberrypi.com/pico/getting-started-with-pico.pdf>
- <https://cpulator.01xz.net/?sys=arm-de1soc>
- [https://fpgacademy.org/Downloads/DE1-SoC\\_Computer\\_ARM.pdf](https://fpgacademy.org/Downloads/DE1-SoC_Computer_ARM.pdf)
- <https://developer.arm.com/documentation/dui0662/latest/>
- Assembly Language Programming with ARM <https://www.youtube.com/watch?v=gfmRrPjnEw4>
- <https://godbolt.org/>
- Reintroduction to C <https://www.youtube.com/watch?v=Kq7Wlexp6JU>

?



<https://olvemaudal.com/talks/>

!

# About bootstraps and booting a computer



The phrase “pull yourself up by your bootstraps” originated shortly before the turn of the 20th century. It’s attributed to a late-1800s physics schoolbook that contained the example question “Why can not a man lift himself by pulling up on his bootstraps?”

...

This idiom is also the source of “booting” a computer, as well the mathematical Bootstrap Method.