

some title

January 3, 2018

Regression

Correlation

The most crucial part in defining correlation geometrically is defining the dot product as it enables to compute the length of a vector:

$$|\vec{a}| = \sqrt{\langle \vec{a}, \vec{a} \rangle}$$

and the angle between any two vectors:

$$\cos(\vec{a}, \vec{b}) = \frac{\langle \vec{a}, \vec{b} \rangle}{|\vec{a}| |\vec{b}|}$$

Now we define scalar product of two random vectors as covariation between them:

$$\langle X, Y \rangle = \text{Cov}(X, Y)$$

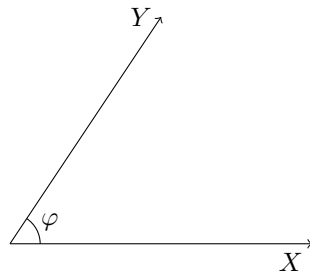
The main characteristics of a random vector are its length and direction. So, we introduce the length

$$\sqrt{\text{Cov } X, X} = \sqrt{\text{Var}(X)} = \sigma_X$$

and the angle between two random vectors

$$\cos(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}} = \text{Corr}(X, Y)$$

Note that from the definition of the angle it follows that correlation is limited within an interval $[-1, 1]$.



The most widespread definition of correlation is

$$\text{Corr}(X, Y) = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X) \text{Var}(Y)}}$$

Figure 1: Random vector X of length σ_X and random vector Y of length σ_Y , $\cos \varphi$ is the angle between X and Y .

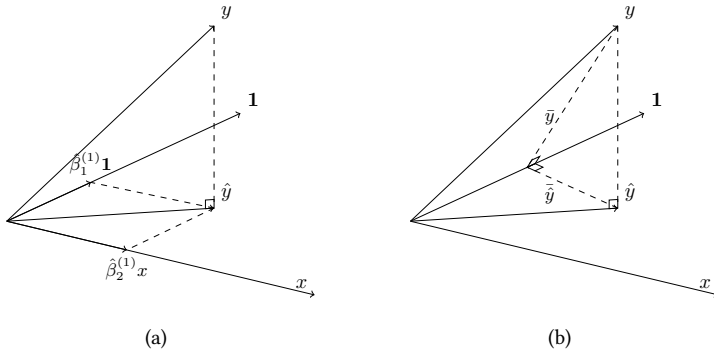
Another important geometrical tool is projection. Recall that for any two vectors the scalar product $\langle \vec{a}, \vec{b} \rangle$ can be interpreted as the length of projected \vec{b} multiplied by the length of \vec{a} . The projection itself is $\cos(\vec{a}, \vec{b})\vec{b}$. Same holds for random vectors. The projection of a random vector Y onto $\{cX | c \in \mathbb{R}\}$ is $\text{Corr}(X, Y) \cdot Y$.

Regression line and point of averages

Theorem 1. *The point of averages lies on the estimated regression line.*

Proof. For the geometrical proof it suffices to show that \hat{y} is a linear combination of the regressors, which is true by construction, and that $\frac{1}{n} \sum_{i=1}^n \hat{y}_i = \frac{1}{n} \sum_{i=1}^n y$. In order for the pictures to be more clear the proof will be presented for the case of two regressors.

The first step is regressing y on $\text{Lin}(\mathbf{1}, x)$. As shown in Figure 2(a), we obtain \hat{y} as a linear combination of $\mathbf{1}$ and x . The next step is to regress both y and \hat{y} on $\mathbf{1}$ which results in \bar{y} and $\bar{\hat{y}}$ correspondingly. By the theorem of three perpendiculars, $\bar{y} = \bar{\hat{y}}$ which is shown in Figure 2(b).



If the regression contains the intercept, the following equation holds:

$$\begin{aligned}\hat{y} &= X\hat{\beta} = X(X^T X)^{-1} X^T y \\ &= X(X^T X)^{-1} X^T X\beta + X(X^T X)^{-1} X^T \varepsilon\end{aligned}$$

Premultiplying both sides by X^T , we obtain:

$$\begin{aligned}X^T \hat{y} &= X^T X(X^T X)^{-1} X^T X\beta \\ &\quad + X^T X(X^T X)^{-1} X^T \varepsilon \\ &= X^T X\beta + X^T \varepsilon\end{aligned}$$

This is a system of equations. The first row of X^T is $\mathbf{1}$ vector, so we can write out the first equation:

Figure 2: (a): Regression of y on $\text{Lin}(\mathbf{1}, x)$;

(b): Regression of y and \hat{y} on $\mathbf{1}$.

From the first equation in the system

$$X^T \hat{y} = X^T y$$

we obtain

$$\sum_{i=1}^n \hat{y}_i = \sum_{i=1}^n y$$

And this finishes the proof:

$$\frac{1}{n} \sum_{i=1}^n y = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k x_{ij} \beta_j$$

□

Frisch–Waugh–Lovell theorem

Theorem 2. *Consider regression*

$$y = X_1 \beta_1 + X_2 \beta_2 + u \quad (1)$$

where $X_{n \times k} = [X_1 X_2]$, i.e. X_1 consists of first k_1 columns of X and X_2 consists of remaining k_2 columns of X , β_1 and β_2 are comfortable, i.e. $k_1 \times 1$ and $k_2 \times 1$ vectors. Consider another regression

$$M_1 y = M_1 X_2 \beta_2 + M_1 u \quad (2)$$

where $M_1 = I - P_1$ projects onto the orthogonal complement of the column space of X_1 and $P_1 = X_1(X_1^T X_1)^{-1} X_1^T$ is the projection onto the column space of X_1 . Then the estimate of β_2 from regression 1 will be the same as the estimate from regression 2.

Proof. Geometrical proof will be presented for the following model:

$$y_i = \beta_1 x_i + \beta_2 z_i + u_i \quad (3)$$

We start with regression ‘all-at-once’ and will distinct its coefficients with index (1). The only step in obtaining $\beta_1^{(1)}$ is regressing y on $\text{Lin}(x, z)$

From regression 2 we get the following estimator:

$$\begin{aligned}\hat{\beta}_2 &= ((M_1 X_2)^T M_1 X_2)^{-1} (M_1 X_2)^T M_1 y \\ &= (X_2^T M_1^T M_1 X_2)^{-1} X_2^T M_1^T M_1 y \\ &= (X_2^T M_1 X_2)^{-1} X_2^T M_1 y\end{aligned}$$

As for regression 1, let us note that due to $y = \hat{y} + \hat{u}$ y can be decomposed as follows:

$$y = P y + M y = X_1 \hat{\beta}_1 + X_2 \hat{\beta}_2 + M y$$

Premultiplying both sides by $X_2^T M_1$, we obtain:

$$\begin{aligned}X_2^T M_1 y &= X_2^T M_1 X_1 \hat{\beta}_1 + X_2^T M_1 X_2 \hat{\beta}_2 + X_2^T M_1 M y \\ &= X_2^T M_1 X_2 \hat{\beta}_2 + X_2^T M_1 M y \\ &= X_2^T M_1 X_2 \hat{\beta}_2\end{aligned}$$

On the last step we used the fact that

$$\begin{aligned}(X_2^T M_1 M y)^T &= y^T M^T M_1^T X_2 \\ &= y^T M M_1 X_2 = y^T M X_2 = 0^T\end{aligned}$$

Assuming $X_2^T M_1 X_2$ is invertible, we get the same estimator

$$\hat{\beta}_2 = (X_2^T M_1 X_2)^{-1} X_2^T M_1 y$$

and then expanding \hat{y} as a linear combination of basis vectors x and z , which is shown in Figure 3(a). Figure 3(b) depicts $Lin(x, z)$.

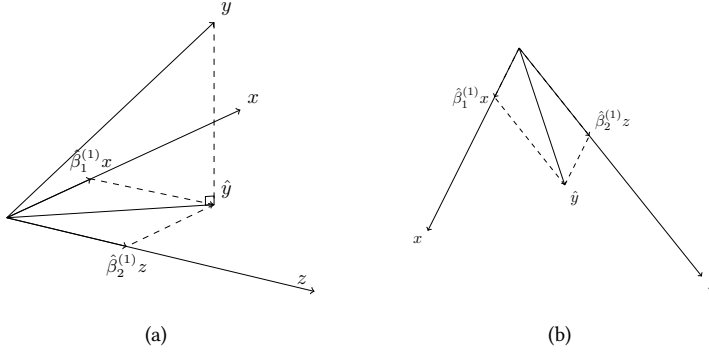


Figure 3: (a): Regression of y on $Lin(x, z)$; (b): $Lin(x, z)$.

As for the model 2, where several regressions are performed consecutively, we start with regressing y on z , resulting in \tilde{y} , which we will refer to as “cleansed” y .

$$\begin{aligned} y &= \alpha z + \varepsilon \\ \hat{\alpha} &= \frac{y^T z}{z^T z} \\ \tilde{y} = \hat{\varepsilon} &= y - \frac{y^T z}{z^T z} z \end{aligned} \quad (4)$$

Following that, x is regressed on z , resulting in \tilde{x} – “cleansed” x .

$$\begin{aligned} x &= \gamma z + \nu \\ \hat{\gamma} &= \frac{x^T z}{z^T z} \\ \tilde{x} = \hat{\nu} &= x - \frac{x^T z}{z^T z} z \end{aligned} \quad (5)$$

Geometric results of these two steps are presented in 4(a).

Finally, ‘cleansed’ y must be regressed on ‘cleansed’ x . However, it cannot be performed immediately as \tilde{y} and \tilde{x} are skew lines. So at first, we fix this problem by translation and after that obtain $\hat{\beta}_1^{(2)} \tilde{x}$ (see Figure 4(b)).

Now, let us picture all the results in one figure and mark some main points.

In Figure 5(b) segments AF and $BH = DG$ stand for $\hat{\beta}_1^{(1)} x$ and $\hat{\beta}_1^{(2)} \tilde{x}$ respectively, while segments AC and BC represent x and \tilde{x} . Having two congruent angles, triangles ABC and FHC are similar. Then, it follows:

$$\frac{AF}{AC} = \frac{BH}{BC} \Leftrightarrow \frac{\hat{\beta}_1^{(1)} x}{x} = \frac{\hat{\beta}_1^{(2)} \tilde{x}}{\tilde{x}} \Leftrightarrow \hat{\beta}_1^{(1)} = \hat{\beta}_1^{(2)}$$

□

(b)

Figure 4: (a): Regression of y on z and of x on z ; (b): Translation of \tilde{x} .