Gradual Verification

(with Implicit Dynamic Frames)

```
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Prof. Jonathan Aldrich, CMU, Pittsburgh, USA
Prof. Éric Tanter, University of Chile, Santiago, Chile
Prof. Gregor Snelting, KIT, Karlsruhe, Germany
```

```
int getFour(int i)
    requires ?; // haven't figured that one out, yet
    ensures result = 4;
{
    i = i + 1;
    return i;
}
```

Motivation

- Program verification (against some specification)
- Two flavors: dynamic & static

```
// spec: callable only if (this.balance >= amount)
void withdrawCoins(int amount)
{
    // business logic
    this.balance -= amount;
}
```

Dynamic Verification

- runtime checks
- testing techniques
- guarantee compliance at runtime

```
// spec: callable only if (this.balance >= amount)
void withdrawCoins(int amount)
{
    // business logic
    this.balance -= amount;
}
```

Dynamic Verification

- runtime checks
- testing techniques
- guarantee compliance at runtime

```
void withdrawCoins(int amount)
{
   assert this.balance >= amount;
   // business logic
   this.balance -= amount;
}
```

Dynamic Verification – Drawbacks

runtime checks

runtime overhead

testing techniques

additional efforts

guarantee compliance at runtime pot. late detection

```
void withdrawCoins(int amount)
   assert this.balance >= amount;
   // business logic
   this.balance -= amount;
```

Static Verification

- declarative
- formal logic
- guarantee compliance in advance

```
void withdrawCoins(int amount)
   requires this.balance >= amount;
{
   // business logic
   this.balance -= amount;
}
```

Static Verification — Drawbacks

- declarative
- formal logic
- guarantee compliance in advance annotation overhead

limited expressiveness decidability

```
void withdrawCoins(int amount)
   requires this.balance >= amount;
   // business logic
   this.balance -= amount;
```

Static Verification — Drawbacks

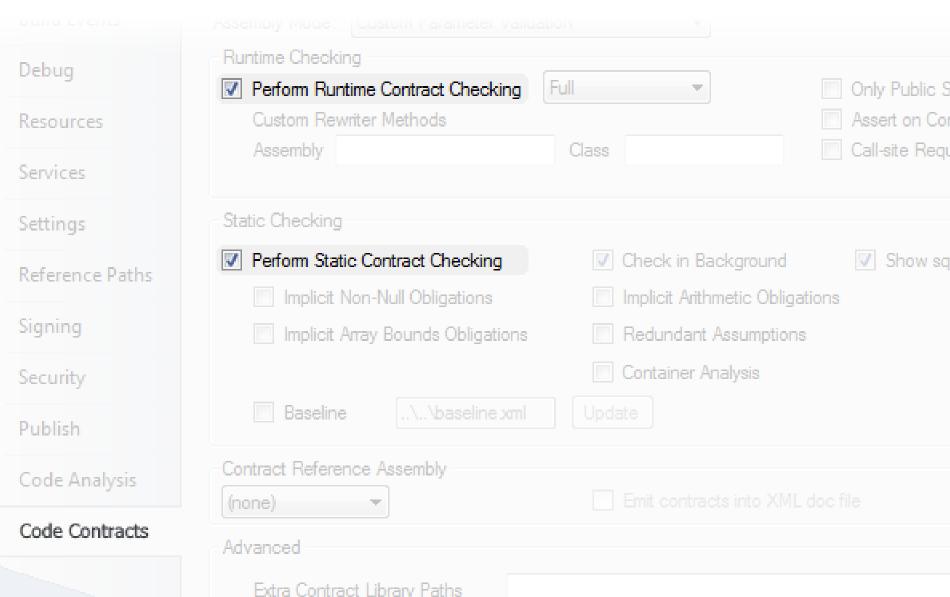
- declarative
- formal logic
- 0.5

limited expressiveness decidability

guarantee compliance in advance annotation overhead

```
void withdrawCoins(int amount)
   requires this.balance >= amount;
   ensures this.balance == old(this.balance) - amount;
{
   // business logic
   this.balance -= amount;
}
```

- "relaxed" static verification (warnings on failure)
- turn contracts into runtime assertions ("patch")



"Static Checking Where Possible, Dynamic Checking When Needed"

"Static Checking Where Possible, Dynamic Checking When Needed"

```
void withdrawCoins(int amount)
    requires this.balance >= amount;
{
    ...
}
...
acc.balance = 100;
acc.withdrawCoins(50); // can prove acc.balance >= 50
acc.withdrawCoins(30); // can't prove acc.balance >= 30
acc.withdrawCoins(30); // can't prove acc.balance >= 30
```

"Static Checking Where Possible, Dynamic Checking When Needed"

```
void withdrawCoins(int amount)
    requires this.balance >= amount;
{
    ...
}
...
acc.balance = 100;
acc.withdrawCoins(50); // statically guaranteed
acc.withdrawCoins(30); // dynamically guaranteed
acc.withdrawCoins(30); // dynamically guaranteed
```

```
"Static Typing Where Possible,

Dynamic Typing When Needed" (Erik Meijer)
```

```
void withdrawCoins(int amount)
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"Static Typing Where Possible,

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= Gradual Typing

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"Static Typing Where Possible,

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= Gradual Typing
```

draw on recent advances in gradual typing

Ronald Garcia, Alison M. Clark, Éric Tanter. **Abstracting Gradual Typing.**43rd ACM SIGPLAN-SIGACT
POPL '16

adapt methodology to verification setting

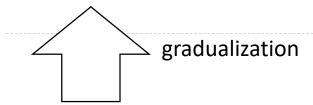
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Gradual System

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define gradual (type) system in terms of a pre-existing static one = "gradualization"

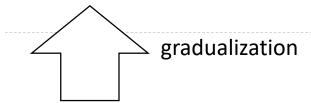
Gradual System



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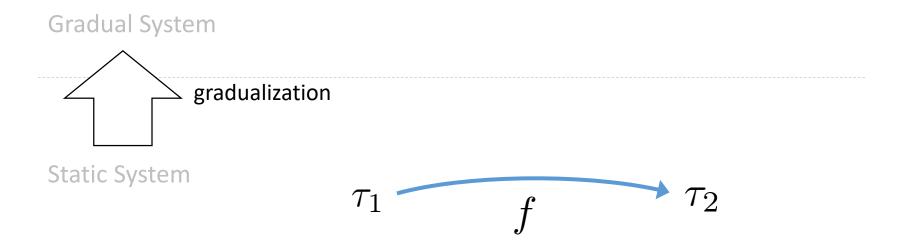
- define gradual (type) system in terms of a pre-existing static one = "gradualization"
- parts of a semantics affected by gradualization are expressible as
 predicates/functions operating on types

Gradual System



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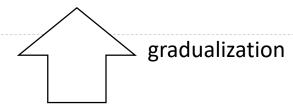
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- define gradual (type) system in terms of a pre-existing static one = "gradualization"
- parts of a semantics affected by gradualization are expressible as
 predicates/functions operating on types





$$f$$
 \mathcal{T}_2
$$f(au) = au \cap \mathbf{int}$$
 typeof(if then <\tau> else 42)

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Gradual System

$$\widetilde{\tau} ::= \tau \mid ?$$

$$T_1$$

$$f$$

$$T_2$$

$$f(\tau) = \tau \sqcap \text{int}$$

$$\text{typeof(if then <τ> else 42)}$$

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Gradual System

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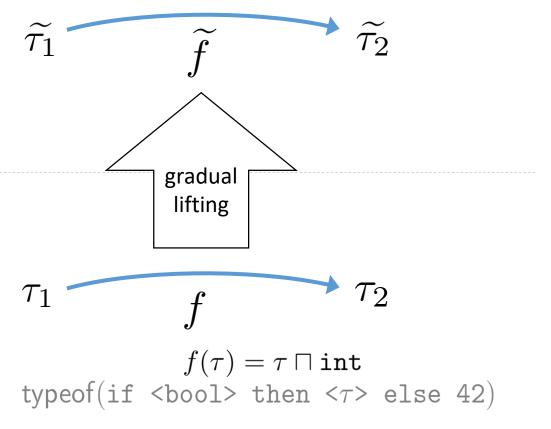
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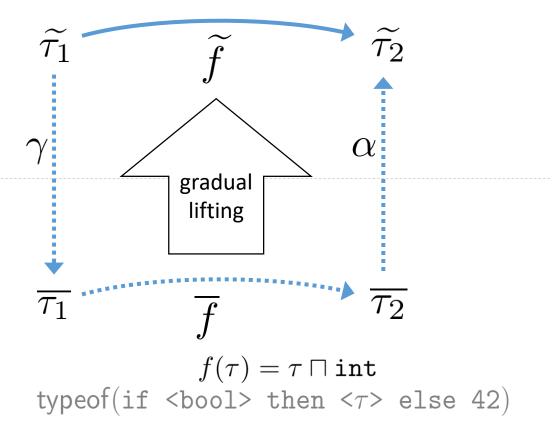


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Gradual System

$$\gamma(\tau) = \{ \tau \}$$

$$\gamma(?) = \text{Types}$$

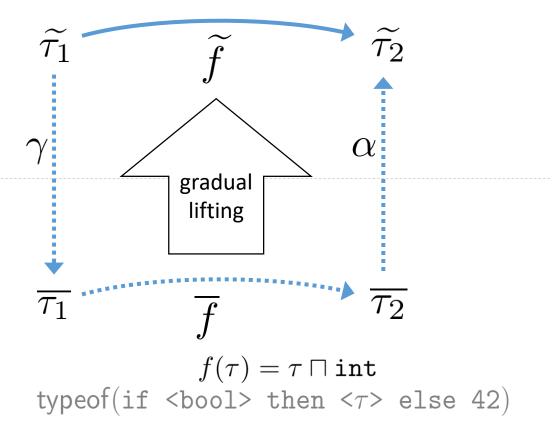


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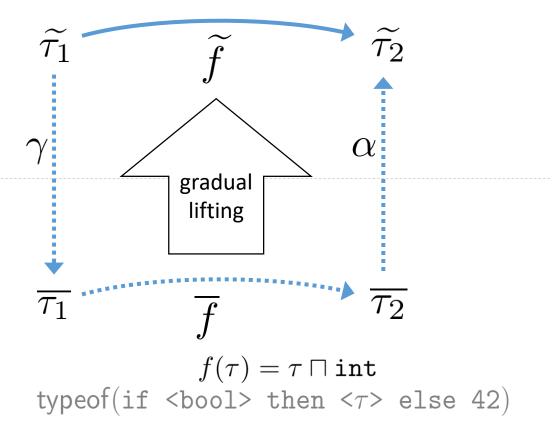


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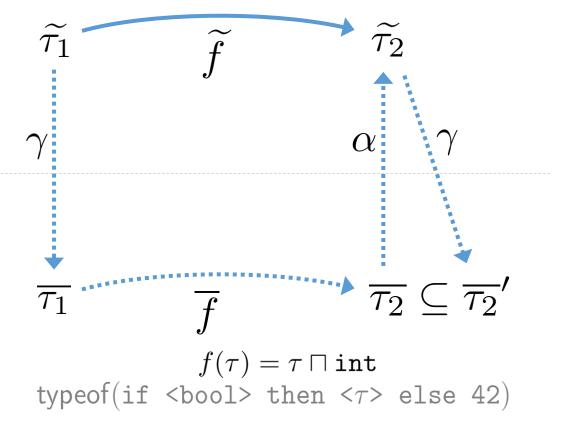
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$$\gamma(?) = \text{Types}$$

Static System



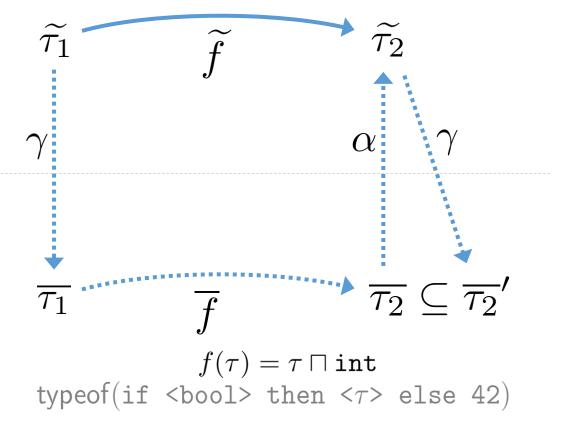
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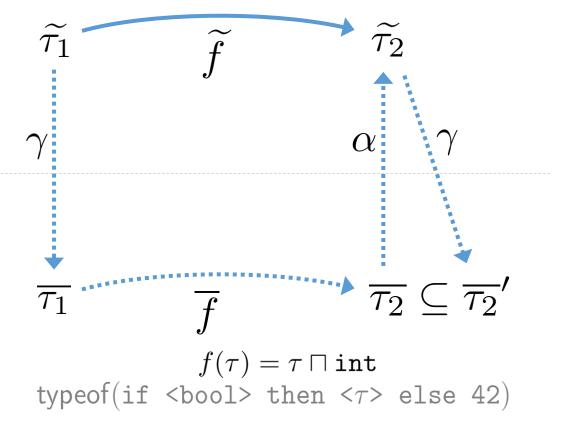
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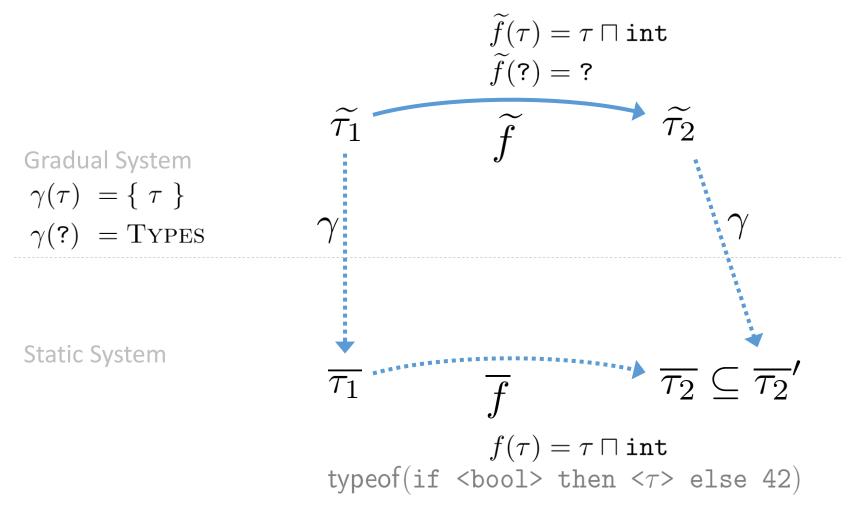
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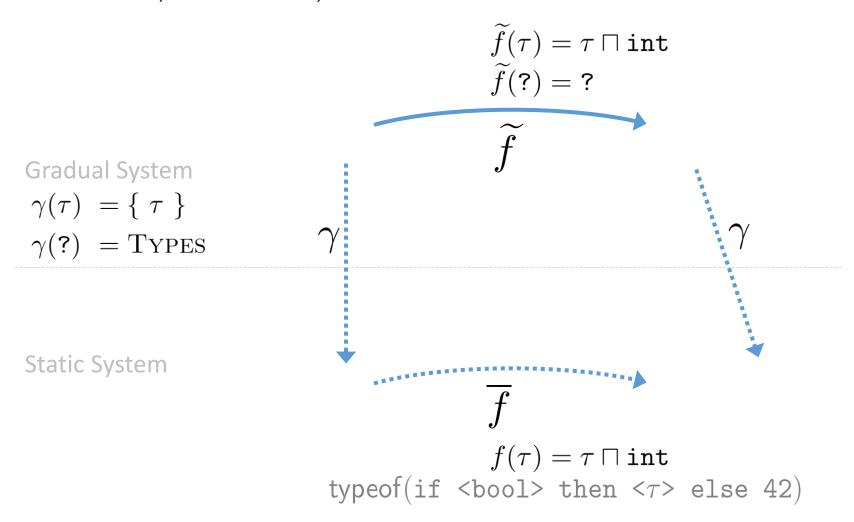
Static System



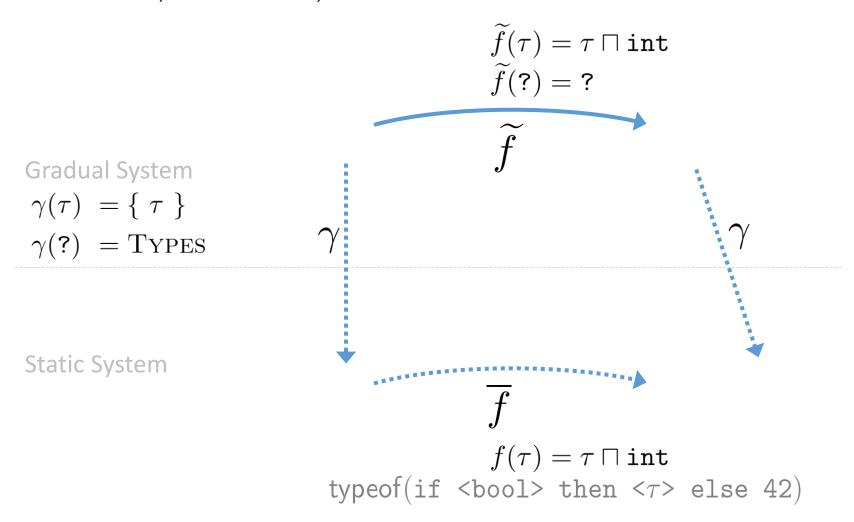
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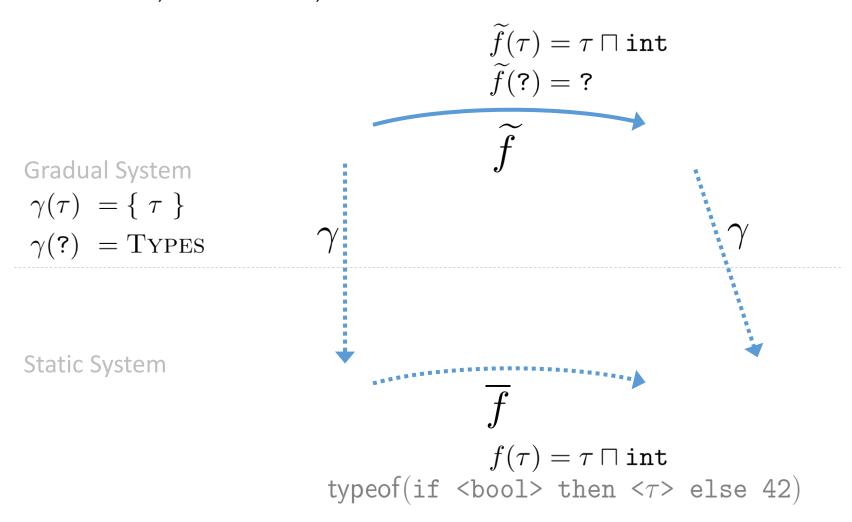
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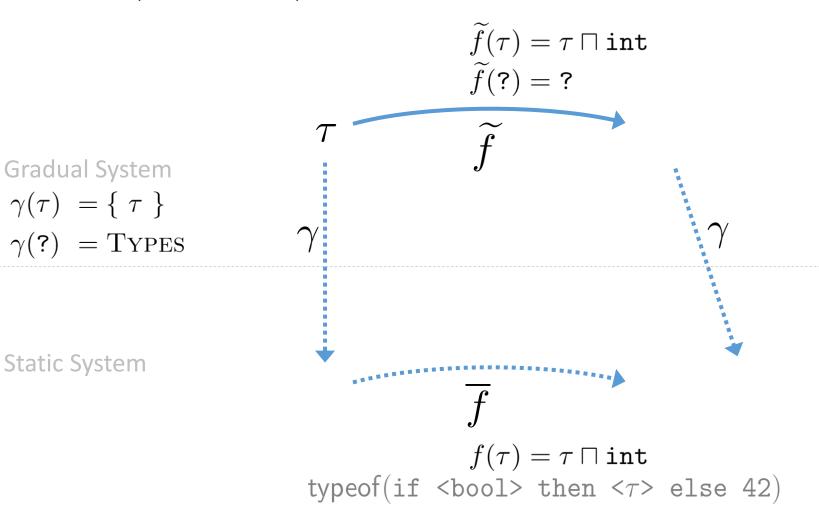


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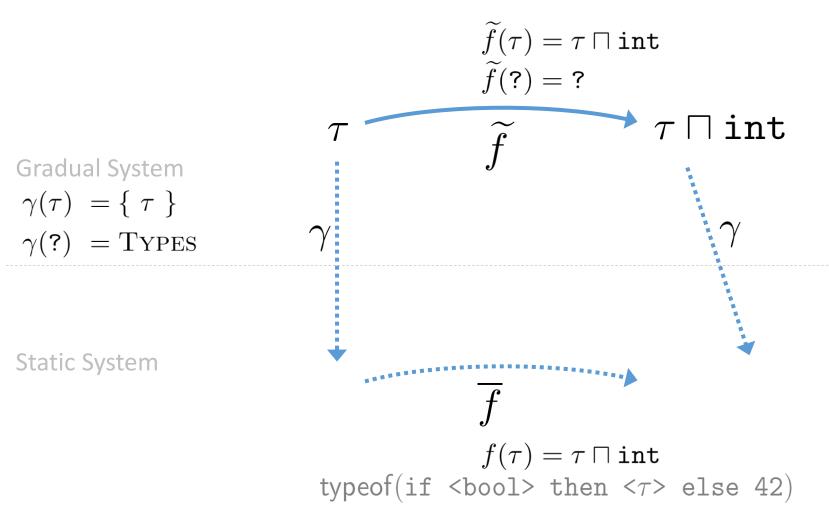


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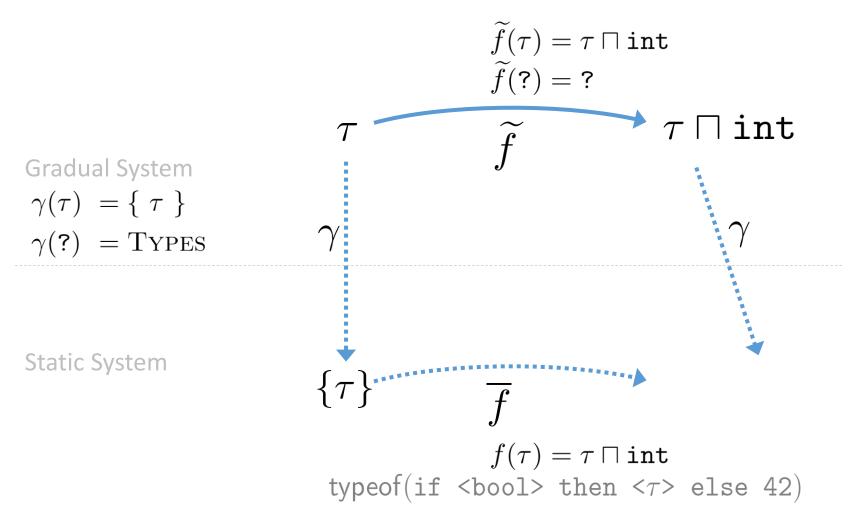




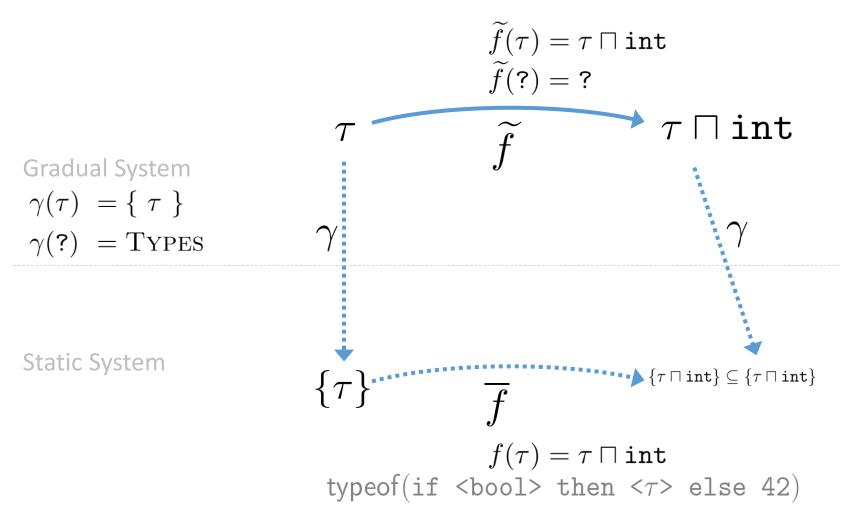
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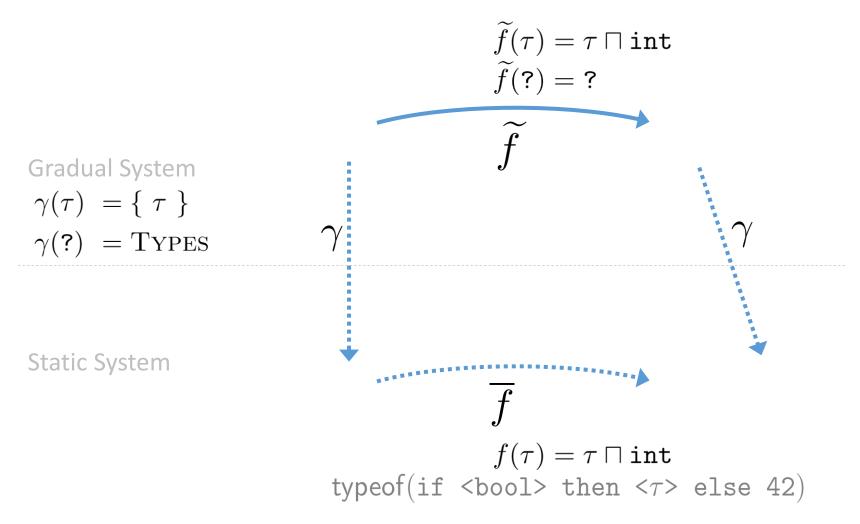
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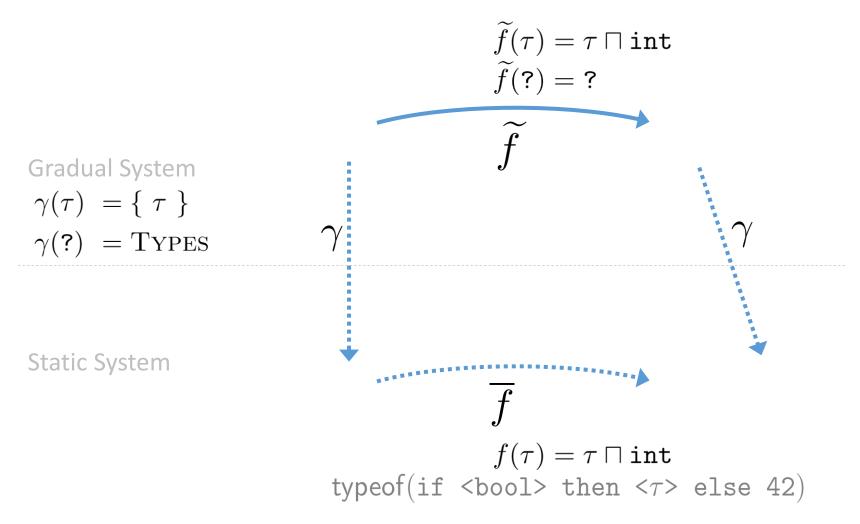
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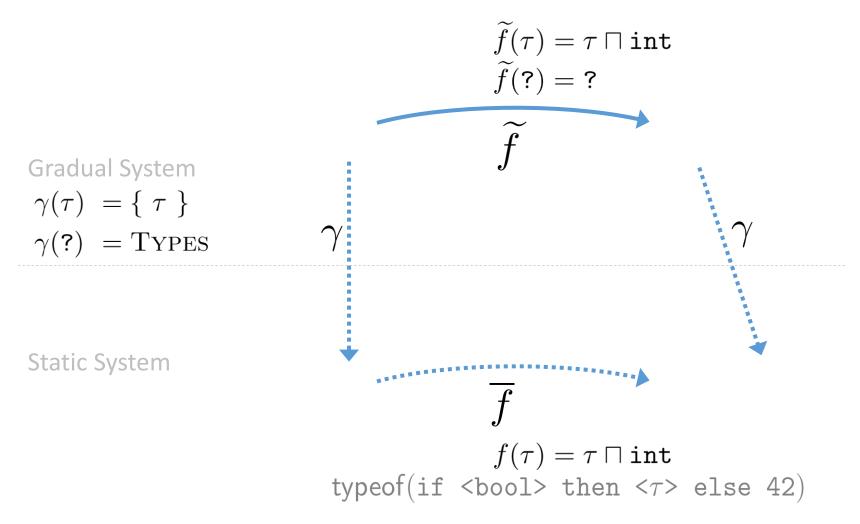
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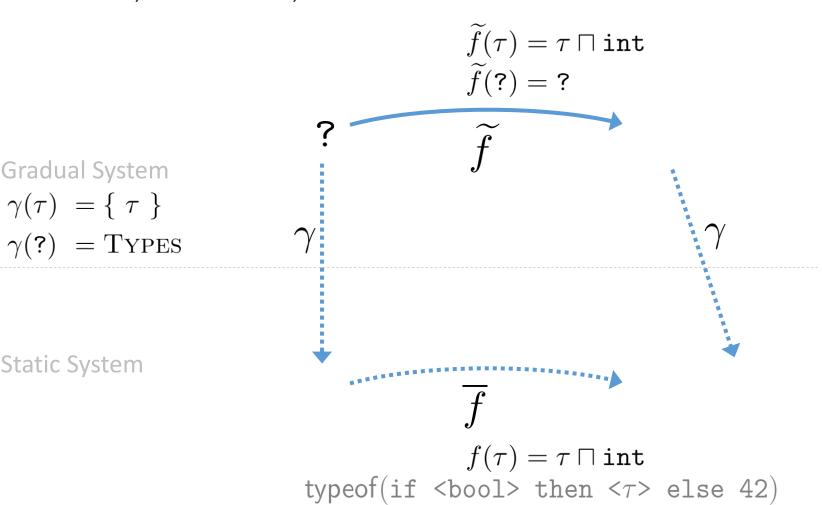
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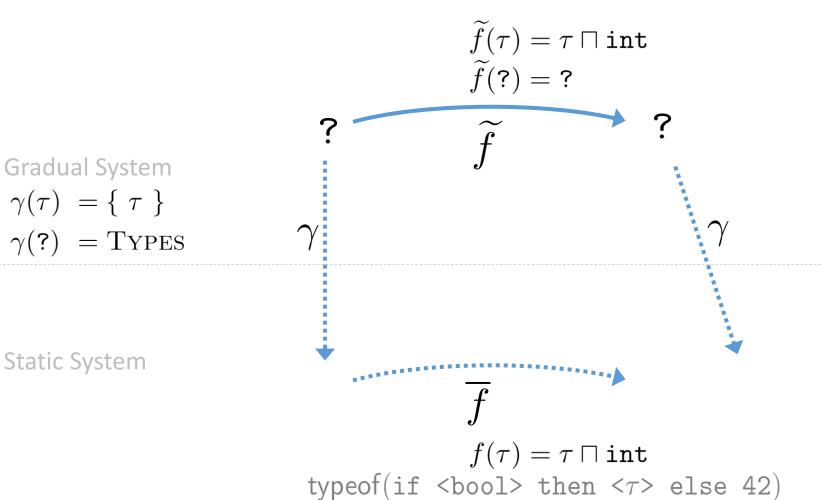
Johannes Bader

Static System

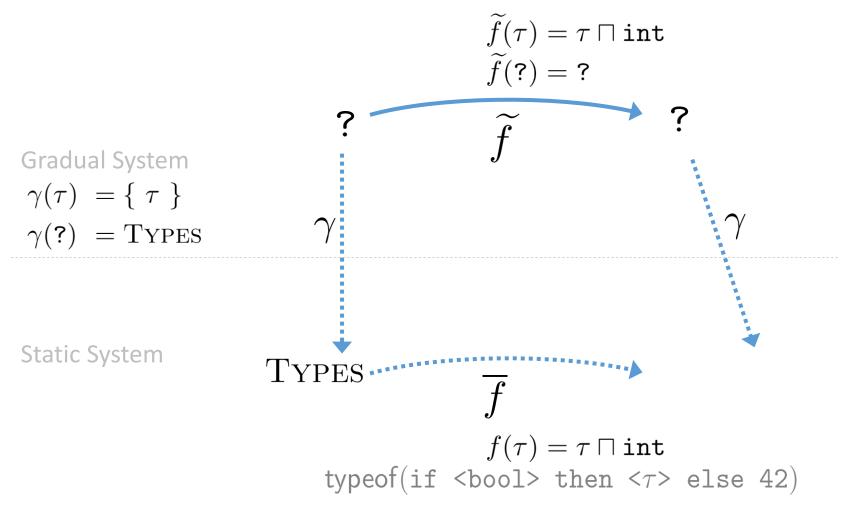
Gradual Verification

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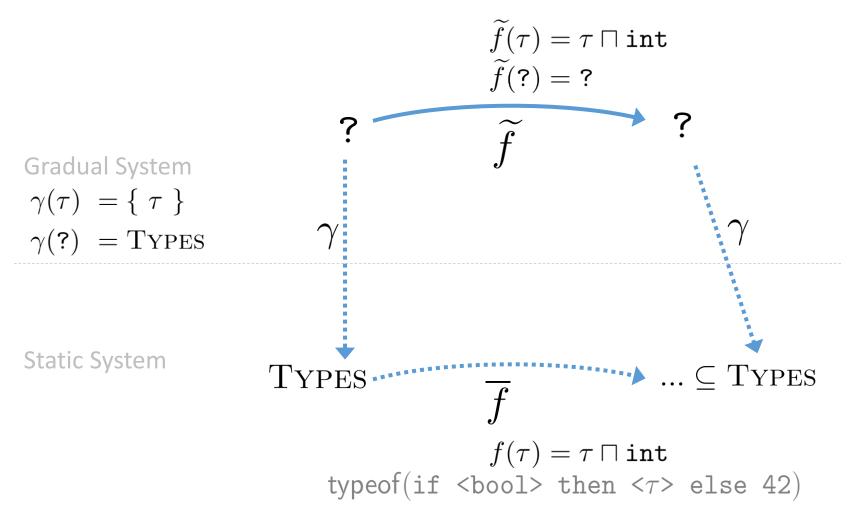
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How does this relate to Verification?

```
int getFour(int i)
    requires ?; // haven't figured that one out, yet
    ensures result = 4;
{
    i = i + 1;
    return i;
}
```

Types restrict, which **values** are valid for a certain variable

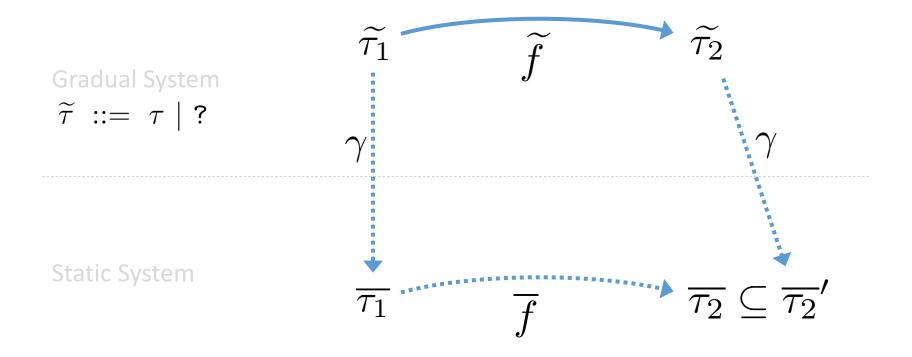
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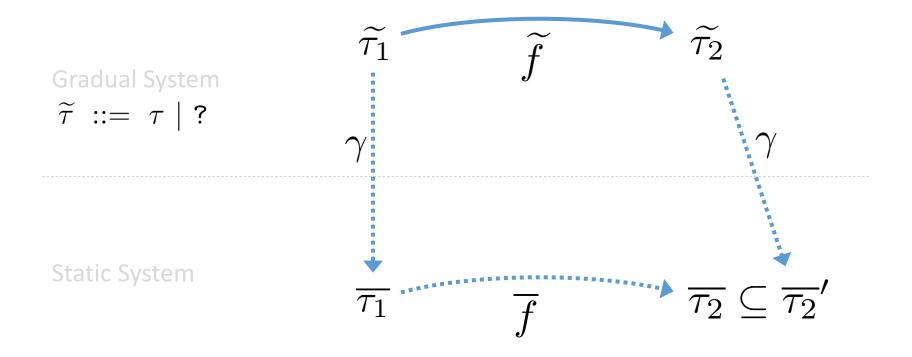
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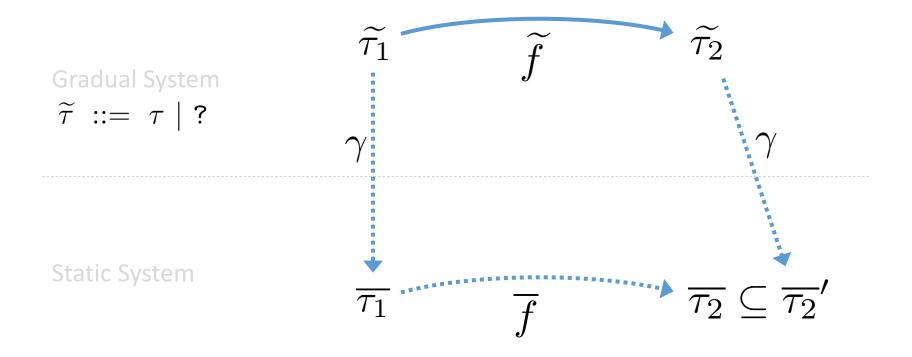
i = i + 1;
    return i;
}
```

Types restrict, which values are valid for a certain variable

Formulas restrict, which program states are valid for a certain point during execution







Abstracting Gradual Typing Ronald Garcia, Alison M. Clark, and Éric Tanter Verification

Gradual System $\widetilde{\phi}_1$ \widetilde{f} ϕ_2 γ γ Static System $\overline{\phi}_1$ \overline{f} $\overline{\phi}_2 \subseteq \overline{\phi}_2'$

Abstracting Gradual Typing Ronald Garcia, Alison M. Clark, and Éric Tanter Verification

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Abstracting Gradual Typing Ronald Garcia, Alison M. Clark, and Éric Tanter Verification

Gradual System $\widetilde{\phi}_1$ \widetilde{f} ϕ_2 γ γ Static System $\overline{\phi}_1$ \overline{f} $\overline{\phi}_2 \subseteq \overline{\phi}_2'$

Gradualization – Overview

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

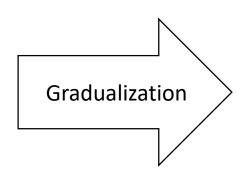
Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness



Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\tilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Syntax

$$s \in Stmt$$

 $\phi \in FORMULA$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static
$$\vdash \{\phi\} \ s \ \{\phi\}$$

Dynamic
$$\pi \longrightarrow \pi$$

Formula
$$\pi \models \phi$$

$$s$$
 ::= skip | x := e | assert ϕ | s_1 ; s_2

$$\phi$$
 ::= true | (e_1 = e_2) | $\phi_1 \wedge \phi_2$

Syntax

$$s \in Stmt$$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static
$$\vdash \{\phi\} \ s \ \{\phi\}$$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$s$$
 ::= skip | x := e | assert ϕ | s_1 ; s_2 ϕ ::= true | $(e_1$ = $e_2)$ | ϕ_1 \wedge ϕ_2

=
$$(VAR \rightarrow N_0) \times STMT$$

 $\langle [x \mapsto 6, y \mapsto 3], x := y; assert (x = 3) \rangle$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static
$$\vdash \{\phi\} \ s \ \{\phi\}$$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

$$\overline{ \; \vdash \{\phi\} \; \mathtt{skip} \; \{\phi\} } \; \mathrm{HS}$$
KIP

$$\vdash \{\phi[e/x]\}\ x := e\ \{\phi\}$$
 HASSIGN

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Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\langle [\mathtt{x} \mapsto 6, \mathtt{y} \mapsto 3], \mathtt{x} := \mathtt{y}; \; \mathtt{assert} \; (\mathtt{x} = 3) \rangle$$

$$\longrightarrow^*$$

$$\langle [\mathtt{x} \mapsto 3, \mathtt{y} \mapsto 3], \mathtt{skip} \rangle$$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

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Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

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$$\longrightarrow^*$$

$$\langle [\mathtt{x} \mapsto 3, \mathtt{y} \mapsto 3], \mathtt{skip} \rangle$$

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$$\mathtt{x} := \mathtt{y}; \; \mathtt{assert} \; (\mathtt{x} = 3)$$

$$\langle [\mathtt{x} \mapsto 3, \mathtt{y} \mapsto 3], \mathtt{skip} \rangle$$

Syntax

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 $\phi \in \text{Formula}$

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Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\langle [x \mapsto 3], s \rangle \vDash (x = 3)$$

 $\langle [x \mapsto 4, y \mapsto 4], s \rangle \vDash (y = x)$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

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Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

$$\langle [x \mapsto 3], s \rangle \vDash (x = 3)$$

 $\langle [x \mapsto 4, y \mapsto 4], s \rangle \vDash (y = x)$

Natural definition of implication

$$\phi_1 \Rightarrow \phi_2 \stackrel{\mathsf{def}}{\Longleftrightarrow} \forall \pi. \ \pi \vDash \phi_1 \implies \pi \vDash \phi_2$$

Syntax

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 $\phi \in \text{Formula}$

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Natural definition of implication

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$$(x = 3) \land (y = 2) \Rightarrow (y = 2)$$

Syntax

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 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

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 $\langle [x \mapsto 4, y \mapsto 4], s \rangle \vDash (y = x)$

Natural definition of implication

$$\phi_1 \Rightarrow \phi_2 \stackrel{\mathsf{def}}{\Longleftrightarrow} \forall \pi. \ \pi \vDash \phi_1 \implies \pi \vDash \phi_2$$

$$(x = 3) \land (y = 2) \Rightarrow (y = 2)$$

$$(a = b) \land (b = c) \Rightarrow (a = c)$$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

Semantical validity of Hoare triples

$$\vDash \{\phi\} \ s \ \{\phi'\}$$

$$\stackrel{\mathsf{def}}{\iff}$$

$$\forall \pi, \pi' \colon \pi \xrightarrow{s} \pi' \land \pi \vDash \phi \implies \pi' \vDash \phi'$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

Gradualization – Overview

Syntax

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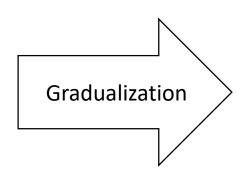
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Dynamic $\pi \longrightarrow \pi$

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Soundness



Syntax

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 $\widetilde{\phi} \in \widetilde{F}ORMULA$

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Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradualization – Approach

Syntax

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 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{\mathbf{F}}\mathbf{ORMULA}$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradualization – Approach

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 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

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Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

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 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradualization – Approach

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Soundness

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

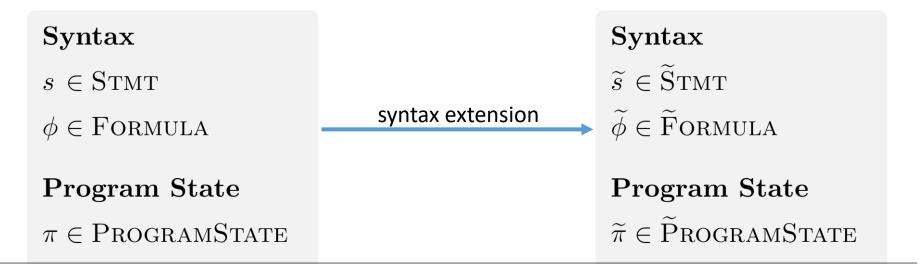
 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$



Rules Implementation

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

 $\operatorname{\mathbf{Syntax}}_{\sim}$

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}_{\mathbf{ROGRAMSTATE}}$

Rules

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

? ∉ Formula

Implementation

syntax extension

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Rules

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

? ∉ Formula

$$\widetilde{\phi} ::= \phi \mid ?$$

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Rules

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

? ∉ Formula

Implementation

$$\widetilde{\phi} ::= \phi \mid ?$$

$$\widetilde{\phi} ::= \phi \mid \phi \wedge ?$$

where $? \stackrel{\mathsf{def}}{=} \mathsf{true} \land ?$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}\mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ORMULA

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Rules

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

? ∉ Formula

$$(x = 3) \land (y = ...)$$

 $(x = 3) \land ?$

$$\widetilde{\phi} ::= \phi \mid ?$$

$$\widetilde{\phi} ::= \phi \mid \phi \wedge ?$$

where
$$? \stackrel{\mathsf{def}}{=} \mathsf{true} \land ?$$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Rules

Formula $\subset \widetilde{F}$ ormula

 $? \in \widetilde{F}ORMULA$

 $? \notin Formula$

$$\widetilde{\phi} ::= \phi \mid ?$$

$$\gamma(\phi) = \{ \phi \}$$

$$\gamma(?) = SATFORMULA$$

$$= \{ \phi \mid \exists \pi. \ \pi \vDash \phi \}$$

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{S}TMT$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

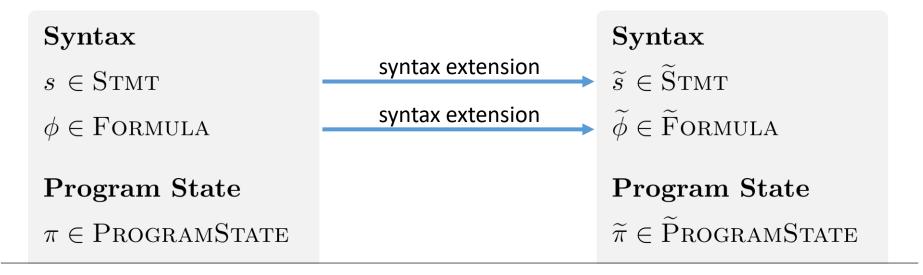
 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Semantics

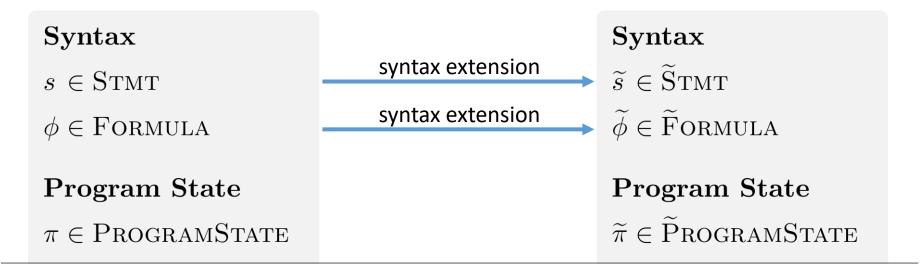
Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$



Rules



Rules

 $\operatorname{STMT} \subseteq \widetilde{\operatorname{S}}\operatorname{TMT}$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathbf{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ormula

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Rules

 $STMT \subseteq \widetilde{S}TMT$

Implementation

s ::= x := e | assert ϕ | s_1 ; s_2

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathbf{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ORMULA

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Rules

 $STMT \subseteq \widetilde{S}TMT$

$$\widetilde{s}$$
 ::= x := e | assert $\widetilde{\phi}$ | $\widetilde{s_1}$; $\widetilde{s_2}$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

syntax extension
syntax extension

Syntax

 $\widetilde{s} \in \widetilde{S}TMT$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}_{\mathbf{ROGRAMSTATE}}$

Rules

 $STMT \subseteq \widetilde{S}TMT$

Implementation

$$\widetilde{s}$$
 ::= x := e | assert $\widetilde{\phi}$ | $\widetilde{s_1}$; $\widetilde{s_2}$ $\gamma:\widetilde{\mathrm{S}}_{\mathrm{TMT}} o \mathcal{P}^{\mathrm{STMT}}$ $\gamma(\mathrm{assert}\ \widetilde{\phi}) = \{ \ \mathrm{assert}\ \phi \mid \phi \in \gamma(\widetilde{\phi}) \ \}$

...

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}$ TMT

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

Syntax

 $\widetilde{s} \in \widetilde{S}TMT$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

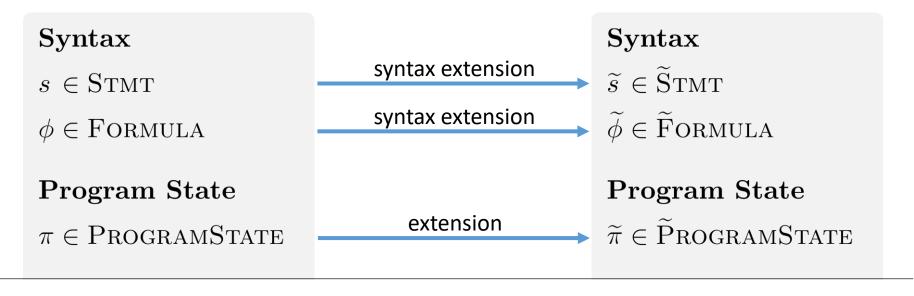
 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$



Rules

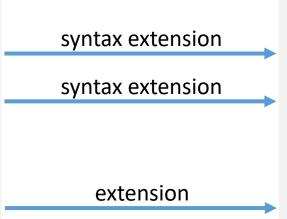
Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in PROGRAMSTATE$



Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathsf{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ORMULA

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}$ ROGRAMSTATE

Rules

PROGRAMSTATE

 \subseteq

PROGRAMSTATE

Implementation

PROGRAMSTATE = $(VAR \rightarrow N_0) \times STMT$

 $\widetilde{P}_{ROGRAM}STATE = (VAR \rightarrow \mathbb{N}_0) \times \widetilde{S}_{TMT}$

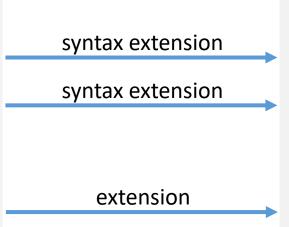
Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$



Syntax

 $\widetilde{s} \in \widetilde{S}TMT$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}\mathrm{ORMULA}$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ State

Rules

PROGRAMSTATE

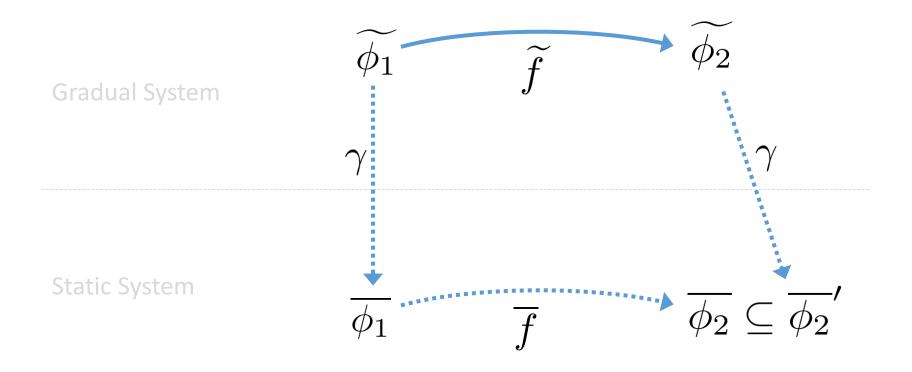
 \subseteq

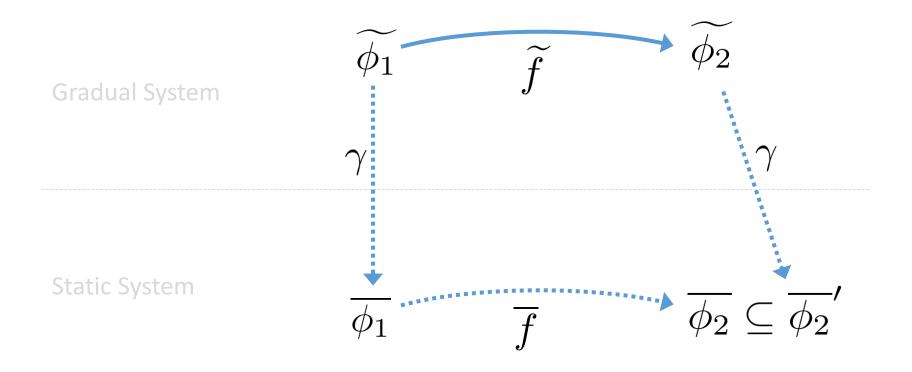
PROGRAMSTATE

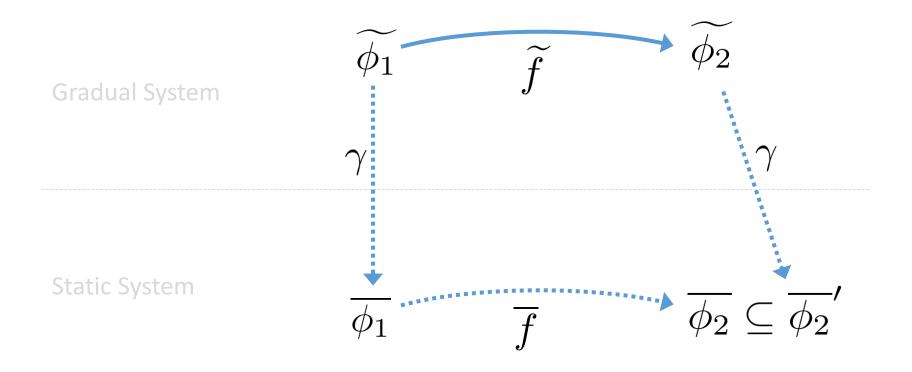
PROGRAMSTATE =
$$(VAR \rightarrow N_0) \times STMT$$

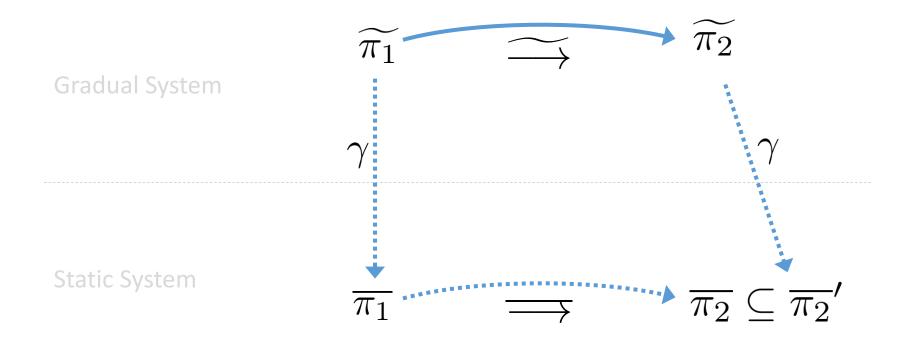
$$\widetilde{P}_{ROGRAMSTATE} = (V_{AR} \rightharpoonup \mathbb{N}_0) \times \widetilde{S}_{TMT}$$

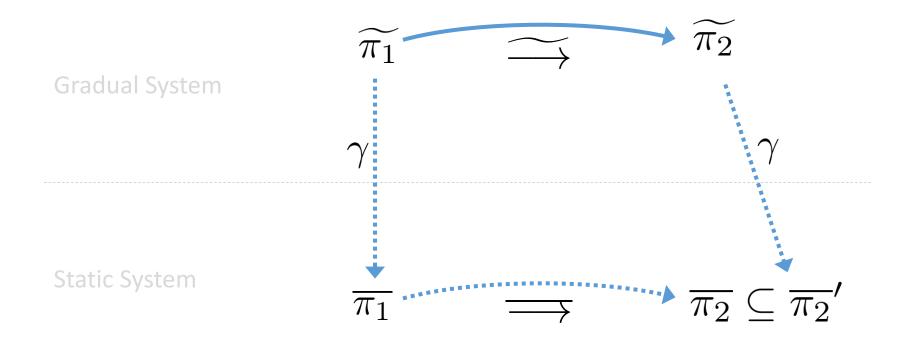
$$\gamma(\langle \sigma, \widetilde{s} \rangle) = \{\sigma\} \times \gamma(\widetilde{s})$$

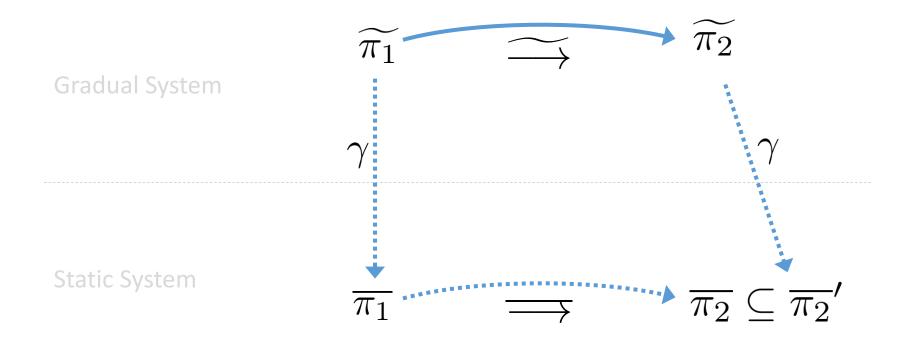


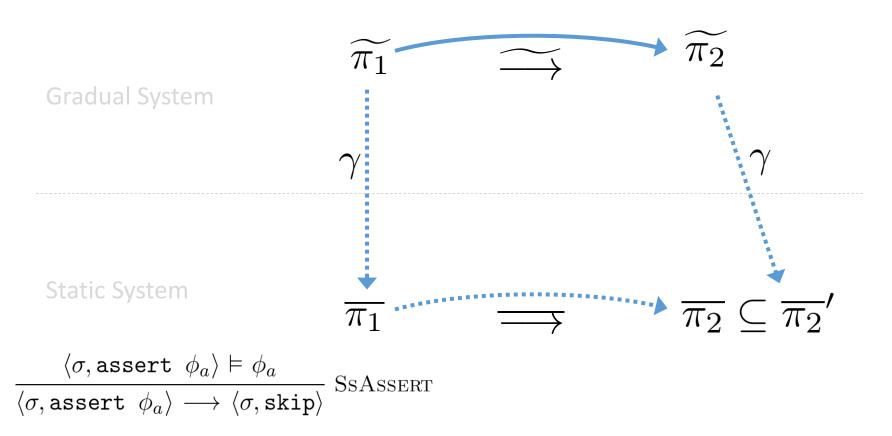












Johannes Bader Gradual Verification 34

Johannes Bader Gradual Verification 34

Gradual Verification - Approach

Syntax

 $s \in STMT$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

Syntax

 $\widetilde{s} \in \widetilde{S}TMT$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradual Verification - Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

function lifting

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ormula

Program State

 $\widetilde{\pi} \in \widetilde{\mathbf{P}}\mathbf{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Gradual Verification - Approach

Syntax

 $s \in STMT$

 $\phi \in FORMULA$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

 $\vdash \{\phi\} \ s \ \{\phi\}$ Static

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

predicate lifting

function lifting

predicate lifting

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathsf{TMT}}$

 $\widetilde{\phi} \in \widetilde{\mathrm{F}}$ ormula

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

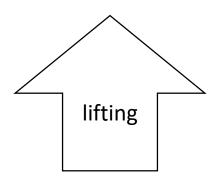
Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

$$\widetilde{P} \subseteq \widetilde{\operatorname{F}}$$
ORMULA × $\widetilde{\operatorname{S}}$ TMT × $\widetilde{\operatorname{F}}$ ORMULA



 $P \subseteq \text{Formula} \times \text{Stmt} \times \text{Formula}$

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

$$\frac{\phi \Rightarrow \phi_a}{\vdash \{\phi\} \text{ assert } \phi_a \{\phi\}} \text{ HASSERT}$$

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

$$\frac{\phi \Rightarrow \phi_a}{\vdash \{\phi\} \text{ assert } \phi_a \{\phi\}} \text{ HASSERT} \qquad P(\phi_1, \phi_a, \phi_2) = \phi_1 = \phi_2 \land \phi_1 \Rightarrow \phi_a$$

Johannes Bader Gradual Verification 40

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

$$\frac{\phi \Rightarrow \phi_a}{\vdash \{\phi\} \text{ assert } \phi_a \ \{\phi\}} \text{ HASSERT } P(\phi_1, \phi_a, \phi_2) = \phi_1 = \phi_2 \land \phi_1 \Rightarrow \phi_a$$

$$\vdash \{(x = 3) \land (y = 4)\} \text{ assert } (x = 3) \{(x = 3) \land (y = 4)\}$$

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

$$\frac{\phi \Rightarrow \phi_a}{\vdash \{\phi\} \text{ assert } \phi_a \ \{\phi\}} \text{ HASSERT } P(\phi_1, \phi_a, \phi_2) = \phi_1 = \phi_2 \land \phi_1 \Rightarrow \phi_a$$

$$\vdash \{(x = 3) \land (y = 4)\} \text{ assert } (x = 3) \{(x = 3) \land (y = 4)\}$$

$$\stackrel{\sim}{\vdash} \{(x = 3) \land (y = 4)\} \text{ assert } (x = 3) \{(x = 3) \land (y = 4)\}$$

Predicate Lifting in a Nutshell

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

Johannes Bader Gradual Verification 40

Predicate Lifting in a Nutshell

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

Predicate Lifting in a Nutshell

all gradually lifted predicates satisfy

$$\frac{\phi_1 \in \gamma(\widetilde{\phi_1}) \qquad \phi_2 \in \gamma(\widetilde{\phi_2}) \qquad \phi_3 \in \gamma(\widetilde{\phi_3}) \qquad P(\phi_1, \phi_2, \phi_3)}{\widetilde{P}(\widetilde{\phi_1}, \widetilde{\phi_2}, \widetilde{\phi_3})}$$

Gradual Verification - Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

predicate lifting

function lifting

predicate lifting

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}} \mathbf{TMT}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Soundness

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff \qquad \qquad \iff \qquad \qquad \iff \qquad \qquad \forall \pi, \pi'. \ \pi \stackrel{s}{\longrightarrow} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi'}\}$$

$$\stackrel{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vdash} \ \widetilde{\phi} \implies \widetilde{\pi'} \ \widetilde{\vdash} \ \widetilde{\phi'}$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\widetilde{\vDash}}{\vDash} \{ \widetilde{\phi} \} \ \widetilde{s} \ \{ \widetilde{\phi'} \}$$

$$\overset{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\vdash \{(x = 2)\} \ y := 4 \ \{(x = 2) \land (y = 4)\}$$

$$\vdash \{(x = 2)\} \ y := 4 \ \{(x = 2) \land (y = 4)\}$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\widetilde{\vDash} \left\{ \widetilde{\phi} \right\} \, \widetilde{s} \, \left\{ \widetilde{\phi'} \right\}$$

$$\overset{\text{def}}{\iff}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}, \, \widetilde{\pi} \, \overset{\widetilde{s}}{\longrightarrow} \, \widetilde{\pi'} \wedge \widetilde{\pi} \, \widetilde{\vDash} \, \widetilde{\phi} \, \Longrightarrow \, \widetilde{\pi'} \, \widetilde{\vDash} \, \widetilde{\phi'}$$

$$\widetilde{\vdash} \{(x = 2)\} \ y := 4 \{(x = 2) \land (y = 4)\}$$

 $\widetilde{\vdash} \{(x = 2)\} \ y := 4 \{(x = 2) \land (y = 4)\}$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\widetilde{\vDash}}{\vDash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \ \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\widetilde{\vdash}$$
 {?} y := 4 {(x = 2) \land (y = 4)}
 $\widetilde{\vdash}$ {?} y := 4 {(x = 2) \land (y = 4)}

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\widetilde{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi'}\} \\ \overset{\text{def}}{\iff}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\widetilde{\vdash} \ \{?\} \ y := 4 \ \{(x = 2) \land (y = 4)\}$$

 $\neg \widetilde{\vdash} \ \{?\} \ y := 4 \ \{(x = 2) \land (y = 4)\}$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{\delta} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{\delta} \ \{\widetilde{\phi}'\}$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\widetilde{\vdash}$$
 {?} y := 4 {(x = 2) \land (y = 4)}
 $\neg \widetilde{\vdash}$ {?} y := 4 {(x = 2) \land (y = 4)}

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{\delta} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{\delta} \ \{\widetilde{\phi}'\}$$

if it were true, we would have a gradual system without runtime checks

$$\overset{\widetilde{\vDash}}{\vDash} \{ \widetilde{\phi} \} \ \widetilde{s} \ \{ \widetilde{\phi'} \}$$

$$\overset{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \overset{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\widetilde{\vdash}$$
 {?} y := 4 {(x = 2) \land (y = 4)}
 $\neg \widetilde{\vdash}$ {?} y := 4 {(x = 2) \land (y = 4)}

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness
$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\widetilde{\vDash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\mathsf{def}}{\Longleftrightarrow}$$

$$\forall \widetilde{\pi}, \widetilde{\pi}', \widetilde{\pi} \xrightarrow{\widetilde{s}} \widetilde{\pi}' \land \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \implies \widetilde{\pi}' \ \widetilde{\vDash} \ \widetilde{\phi}'$$

$$\widetilde{\vdash} \ \{?\} \ y := 4 \ \{ (x = 2) \ \land \ (y = 4) \}$$

$$\widetilde{\vdash} \ \{?\} \ y := 4; \ assert \ (x = 2) \ \{ (x = 2) \ \land \ (y = 4) \}$$

$$\vdash \{\phi\} \ s \ \{\phi'\}$$

$$\vDash \{\phi\} \ s \ \{\phi'\}$$
Soundness

$$\models \{\phi\} \ s \ \{\phi'\}$$

$$\iff$$

$$\forall \pi, \pi'. \ \pi \xrightarrow{s} \pi' \land \pi \models \phi \implies \pi' \models \phi'$$

$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi'}\}$$
 Soundness
$$\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s}; \ \text{assert} \ \widetilde{\phi'} \ \{\widetilde{\phi'}\}$$

$$\overset{\widetilde{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overset{\mathsf{def}}{\iff}$$

$$\forall \widetilde{\pi}, \widetilde{\pi'}. \ \widetilde{\pi} \stackrel{\widetilde{s}}{\longrightarrow} \widetilde{\pi'} \wedge \widetilde{\pi} \ \widetilde{\vDash} \ \widetilde{\phi} \ \Longrightarrow \ \widetilde{\pi'} \ \widetilde{\vDash} \ \widetilde{\phi'}$$

$$\widetilde{\vdash}$$
 {?} y := 4 {(x = 2) \land (y = 4)} $\widetilde{\vdash}$ {?} y := 4; assert (x = 2) {(x = 2) \land (y = 4)}

Johannes Bader Gradual Verification 43

Gradual Verification - Approach

Syntax

 $s \in STMT$

 $\phi \in FORMULA$

Program State

 $\pi \in PROGRAMSTATE$

Semantics

 $\vdash \{\phi\} \ s \ \{\phi\}$ Static

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

predicate lifting

function lifting

predicate lifting

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathsf{TMT}}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAM}$ STATE

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Soundness

Gradual Verification - Approach

Syntax

 $s \in Stmt$

 $\phi \in \text{Formula}$

Program State

 $\pi \in \mathsf{PROGRAMSTATE}$

Semantics

Static $\vdash \{\phi\} \ s \ \{\phi\}$

Dynamic $\pi \longrightarrow \pi$

Formula $\pi \models \phi$

Soundness

syntax extension

syntax extension

extension

predicate lifting

function lifting

predicate lifting

runtime check injection

Syntax

 $\widetilde{s} \in \widetilde{\mathbf{S}}_{\mathsf{TMT}}$

 $\widetilde{\phi} \in \widetilde{F}ORMULA$

Program State

 $\widetilde{\pi} \in \widetilde{P}_{ROGRAMSTATE}$

Semantics

Static $\widetilde{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}\}$

Dynamic $\widetilde{\pi} \longrightarrow \widetilde{\pi}$

Formula $\widetilde{\pi} \stackrel{\sim}{\models} \widetilde{\phi}$

Soundness

$$\widetilde{\vdash}$$
 {?} y := 2; x := 3 {(x = 3) \land (y = 2)}

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\} }{\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}} \ \widetilde{\mathrm{HSeQ}}$$

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\}} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\phi_1} = (y = 2)$$

$$\widetilde{\phi_2} = (y = 2)$$

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\} }{\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}} \ \widetilde{\mathrm{HSeQ}}$$

a)
$$\widetilde{\phi_1}=(y=2)$$
 $\widetilde{\phi_2}=(y=2)$

b)
$$\widetilde{\phi_1} = ?$$
 $\widetilde{\phi_2} = ?$

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\} }{\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}} \ \widetilde{\mathrm{HSeQ}}$$

a)
$$\widetilde{\phi_1} = (y = 2)$$
 $\widetilde{\phi_2} = (y = 2)$

"good" (information carried over)

b)
$$\widetilde{\phi_1} = ?$$
 $\widetilde{\phi_2} = ?$

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\}} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

a)
$$\widetilde{\phi_1}=(y=2)$$
 $\widetilde{\phi_2}=(y=2)$

"good" (information carried over)

b)
$$\widetilde{\phi_1} = ?$$
 $\widetilde{\phi_2} = ?$

"too weak" (could prove invalid triples) idea: try to be as precise as possible

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\}} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

a)
$$\widetilde{\phi_1}=(y=2)$$
 $\widetilde{\phi_2}=(y=2)$

"good" (information carried over)

b)
$$\widetilde{\phi_1} = ?$$
 $\widetilde{\phi_2} = ?$

"too weak" (could prove invalid triples) idea: try to be as precise as possible

c)
$$\widetilde{\phi_1}=(y=2) \wedge (x=4)$$
 $\widetilde{\phi_2}=(y=2)$

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\}} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

a)
$$\widetilde{\phi_1}=(y=2)$$
 $\widetilde{\phi_2}=(y=2)$

"good" (information carried over)

b)
$$\widetilde{\phi_1}=?$$
 $\widetilde{\phi_2}=?$

"too weak" (could prove invalid triples) idea: try to be as precise as possible

c)
$$\phi_1 = (y = 2) \land (x = 4)$$

 $\widetilde{\phi_2} = (y = 2)$

"too strict" (Hoare triple invalid) idea: try to produce valid Hoare triple

$$\frac{\widetilde{\phi_1} \widetilde{\Rightarrow} \widetilde{\phi_2}}{\widetilde{\vdash} \{?\} \ y := 2 \ \{\widetilde{\phi_1}\}} \qquad \widetilde{\vdash} \ \{\widetilde{\phi_2}\} \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

$$\widetilde{\vdash} \ \{?\} \ y := 2; \ x := 3 \ \{(x = 3) \ \land \ (y = 2)\}$$

a)
$$\widetilde{\phi_1}=(y=2)$$
 $\widetilde{\phi_2}=(y=2)$

"good" (information carried over)

b)
$$\widetilde{\phi_1}=?$$
 $\widetilde{\phi_2}=?$

"too weak" (could prove invalid triples) idea: try to be as precise as possible

c)
$$\phi_1 = (y = 2) \land (x = 4)$$

 $\widetilde{\phi_2} = (y = 2)$

"too strict" (Hoare triple invalid)

idea: try to produce valid Hoare triple
if we could decide that we would not be here

don't even present the gradual verifier with choices in the first place

don't even present the gradual verifier with choices in the first place

treat static Hoare logic as (multivalued) function

$$\vdash \{\cdot\} \cdot \{\cdot\} \subseteq FORMULA \times STMT \times FORMULA$$

$$\vdash \{\cdot\} \cdot \{\cdot\} : FORMULA \times STMT \rightarrow \mathcal{P}^{FORMULA}$$

don't even present the gradual verifier with choices in the first place

treat static Hoare logic as (multivalued) function

$$\vdash \{\cdot\} \cdot \{\cdot\} \subseteq FORMULA \times STMT \times FORMULA$$

$$\vdash \{\cdot\} \cdot \{\cdot\} : FORMULA \times STMT \to \mathcal{P}^{FORMULA}$$

...and then lift that function

$$\vec{\vdash} \{\cdot\} \cdot \{\cdot\} : \widetilde{F}ORMULA \times \widetilde{S}TMT \to \widetilde{F}ORMULA$$

don't even present the gradual verifier with choices in the first place

treat static Hoare logic as (multivalued) function

$$\vdash \{\cdot\} \cdot \{\cdot\} \subseteq FORMULA \times STMT \times FORMULA$$

$$\vdash \{\cdot\} \cdot \{\cdot\} : FORMULA \times STMT \to \mathcal{P}^{FORMULA}$$

...and then lift that function

$$\vec{\vdash} \{\cdot\} \cdot \{\cdot\} : \widetilde{F}ORMULA \times \widetilde{S}TMT \to \widetilde{F}ORMULA$$

- Properties
 - can derive gradual lifting (that's still what the verifier needs)
 - deterministic verifier
 - stronger, assertion-free notion of soundness

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

$$\frac{\overset{\widetilde{\phi_{q1}}}{\vec{\rightarrow}} \overset{\widetilde{\phi_{q2}}}{\vec{\rightarrow}} \overset{\widetilde{\phi_{q2}}}{\vec{\vdash}} {\{\widetilde{\phi_{p}}\}} \overset{\widetilde{s_{1}}}{\vec{s_{1}}} {\{\widetilde{\phi_{q1}}\}} \overset{\widetilde{\vdash}}{\vec{\vdash}} {\{\widetilde{\phi_{q2}}\}} \overset{\widetilde{s_{2}}}{\vec{s_{2}}} {\{\widetilde{\phi_{r}}\}} \overset{\vec{\text{H}}\text{SEQ}}{\vec{\rightarrow}} \overset{\vec{\rightarrow}}{\vec{\rightarrow}} {\{\widetilde{\phi_{p}}\}} \overset{\vec{\rightarrow}}{\vec{s_{1}}} {\{\widetilde{\phi_{p}}\}} \overset{\vec{\rightarrow}}{\vec{s_{1}}} {\{\widetilde{\phi_{p}}\}} \overset{\vec{\rightarrow}}{\vec{s_{2}}} {\{\widetilde{\phi_{r}}\}}$$

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

$$\frac{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1} \ \{\widetilde{\phi_q}\} \qquad \vec{\vdash} \{\widetilde{\phi_q}\} \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}}{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1}; \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}} \ \vec{\mathrm{HSeQ}}$$

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

$$\frac{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1} \ \{\widetilde{\phi_q}\} \qquad \vec{\vdash} \{\widetilde{\phi_q}\} \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}}{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1}; \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}} \ \vec{\mathrm{HSeQ}}$$

$$\vec{\vdash} \{\text{true}\} \ y := 2 \{ (y = 2) \}$$

$$\vec{\vdash} \{ (y = 2) \} \ x := 3 \{ (x = 3) \land (y = 2) \}$$

$$\vec{\vdash} \{\text{true}\} \ y := 2; \ x := 3 \{ (x = 3) \land (y = 2) \}$$

$$\vec{\vdash} \{\text{true}\} \ y := 2; \ x := 3 \{ (x = 3) \land (y = 2) \}$$

$$\frac{\phi_{q1} \Rightarrow \phi_{q2}}{\vdash \{\phi_p\} \ s_1 \ \{\phi_{q1}\} \ \vdash \{\phi_{q2}\} \ s_2 \ \{\phi_r\}} + \{\phi_p\} \ s_1; \ s_2 \ \{\phi_r\}$$
 HSEQ

$$\frac{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1} \ \{\widetilde{\phi_q}\} \qquad \vec{\vdash} \{\widetilde{\phi_q}\} \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}}{\vec{\vdash} \{\widetilde{\phi_p}\} \ \widetilde{s_1}; \ \widetilde{s_2} \ \{\widetilde{\phi_r}\}} \ \vec{\mathrm{HSeQ}}$$

$$\neg \vec{\vdash} \{ \text{true} \} \ y := 4; \ x := 3 \{ (x = 3) \land (y = 2) \}$$

Obtaining a Gradual Lifting

$$\vdash \{\cdot\} \cdot \{\cdot\} \subseteq \text{Formula} \times \text{Stmt} \times \text{Formula}$$

$$\downarrow \textbf{1. obtain deterministic lifting}$$

$$\vdash \{\cdot\} \cdot \{\cdot\} : \widetilde{\text{Formula}} \times \widetilde{\text{Stmt}} \to \widetilde{\text{Formula}}$$

$$\downarrow \textbf{2. derive gradual lifting}$$

$$\vdash \{\cdot\} \cdot \{\cdot\} : \widetilde{\text{Formula}} \times \widetilde{\text{Stmt}} \times \widetilde{\text{Formula}}$$

$$\vdash \{\widetilde{\phi_1}\} \ \widetilde{s} \ \{\widetilde{\phi_2}\} \quad \stackrel{\text{def}}{\Longleftrightarrow} \quad \exists \widetilde{\phi_2'}. \ \vdash \{\widetilde{\phi_1}\} \ \widetilde{s} \ \{\widetilde{\phi_2'}\} \wedge \widetilde{\phi_2'} \cong \widetilde{\phi_2}$$

Lemma: $\widetilde{\vdash} \{\cdot\} \cdot \{\cdot\}$ is a gradual lifting of $\vdash \{\cdot\} \cdot \{\cdot\}$

Soundness

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\widetilde{\vdash} \ \{\widetilde{\phi}\} \ \widetilde{s}; \ \text{assert} \ \widetilde{\phi}' \ \{\widetilde{\phi}'\}$$

Soundness

$$\stackrel{\vec{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\} \\ \stackrel{\widetilde{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

Soundness

$$\overrightarrow{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overrightarrow{\in} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

Soundness

$$\stackrel{\vec{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\} \\ \stackrel{\widetilde{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

```
y := 2
 x := 3
 assert (y = 2) \land (a = 5);
```

Soundness

$$\stackrel{\overrightarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\} \\ \stackrel{\overleftarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

```
y := 2

x := 3

assert (y = 2) \land (a = 5);

\vec{\vdash} \{true\} \ y := 2; \ x := 3 \{(x = 3) \land (y = 2)\}
```

Soundness

$$\stackrel{\overrightarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\} \\ \stackrel{\overleftarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

```
y := 2

x := 3

assert (y = 2) \land (a = 5);

\vec{\vdash} \{true\} y := 2; x := 3 \{(x = 3) \land (y = 2)\}
```

Soundness

$$\overrightarrow{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$

$$\overrightarrow{\in} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

Soundness

$$\stackrel{\overrightarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\} \\ \stackrel{\overleftarrow{\vdash}}{\vdash} \{\widetilde{\phi}\} \ \widetilde{s} \ \{\widetilde{\phi}'\}$$
 Soundness

- very helpful for optimizations
- in the thesis:
 - criteria for gradual system to satisfy $\vec{\mathrm{S}}\mathrm{OUNDNESS}$
 - criteria for a system with zero runtime overhead when all annotations are static

Implicit Dynamic Frames

```
\{(p1.age = 19) \land (p2.age = 19)\}
p1.age++
\{(p1.age = 20) \land (p2.age = 19)\}
```

Implicit Dynamic Frames

```
\{(p1.age = 19) \land (p2.age = 19)\}

p1.age++

\{(p1.age = 20) \land (p2.age = 19)\}

\{acc(p1.age) * acc(p2.age) * (p1.age = 19) * (p2.age = 19)\}

p1.age++

\{acc(p1.age) * acc(p2.age) * (p1.age = 20) * (p2.age = 19)\}
```

Implicit Dynamic Frames

```
\{(p1.age = 19) \land (p2.age = 19)\}
p1.age++
\{(p1.age = 20) \land (p2.age = 19)\}
\{acc(p1.age) * acc(p2.age) * (p1.age = 19) * (p2.age = 19)\}
p1.age++
\{acc(p1.age) * acc(p2.age) * (p1.age = 20) * (p2.age = 19)\}
{?*(p1.age = 19)*(p2.age = 19)}
p1.age++
{?*(p1.age = 20)*(p2.age = 19)}
```

Timeline

Design & Implementation

github.com/olydis/GradVer

May June July August September

Documentation

github.com/olydis/GradVerThesis

Timeline

Design & Implementation

github.com/olydis/GradVer

16к Соq

May June July August September

6.5кгос **LaTeX**

Documentation

github.com/olydis/GradVerThesis

Timeline

Design & Implementation
github.com/olydis/GradVer

olydis.github.io/GradVer/impl/HTML5

16к Соq

4.5кLOC TypeScript

May June July August September

6.5к Loc **LaTeX**

Documentation

github.com/olydis/GradVerThesis