

Gradually Verified Language with Recursive Predicates

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1 Weakest Predonditions

1.1 Concrete Weakest Liberal Precondition (WLP) Rules

$\text{WLP} : \text{STATEMENT} \times \text{SATFORMULA} \rightarrow \text{SATFORMULA}$

$\text{WLP}(s, \phi) := \text{match } s \text{ with}$

skip	$\mapsto \phi$
$s_1; s_2$	$\mapsto \text{WLP}(s_1, \text{WLP}(s_2, \phi))$
$T \ x$	$\mapsto \phi$
$x := e$	$\mapsto \text{footprint}(e) \wedge [e/x]\phi$
$x := \text{new } C$	$\mapsto [\text{new}(C)/x]\phi$
$x.f := y$	$\mapsto \text{footprint}(x.f) \wedge [y/x.f]\phi$
$y := z.m_C(\bar{e})$	$\mapsto \text{footprint}(\bar{e}) \wedge z \neq \text{null} \wedge$ $[z/\text{this}, \bar{e}/x]\text{pre}(m_C) * \text{handleMethod}(m_C, \phi)$
if $(e) \{s_{\text{the}}\} \text{ else } \{s_{\text{els}}\}$	$\mapsto \text{if } (e) \text{ then } \text{WLP}(s_{\text{the}}, \phi)$ $\text{else } \text{WLP}(s_{\text{els}}, \phi)$
while $(e) \text{ invariant } \phi_{\text{inv}} \{s_{\text{bod}}\}$	$\mapsto \text{footprint}(e) \wedge \phi_{\text{inv}} \wedge$ $\text{if } e \text{ then } \text{WLP}(s_{\text{bod}}, \phi_{\text{inv}}) \text{ else } \text{WLP}(\text{true}, \phi)$
assert ϕ_{ass}	$\mapsto \text{footprint}(\phi_{\text{ass}}) \wedge \phi_{\text{ass}} \wedge \phi$
hold $\phi_{\text{hol}} \{s_{\text{bod}}\}$	$\mapsto (\text{unimplemented})$
release ϕ_{rel}	$\mapsto (\text{unimplemented})$
unfold $\alpha_C(\bar{e})$	$\mapsto \text{footprint}(\bar{e}) \wedge$ $[\text{unfolded}(\alpha_C(\bar{e}))/\alpha_C(\bar{e}),$ $\phi'/\text{unfolding } \alpha_C(\bar{e}) \text{ in } \phi']\phi$
fold $\alpha_C(\bar{e})$	$\mapsto \text{footprint}(\bar{e}) \wedge [\alpha_C(\bar{e})/\text{unfolded}(\alpha_C(\bar{e}))]\phi$

1.1.1 Utility Functions

The implementations of the functions in this section can be made much more efficient than the naive definition here in mathematical notation. For example, calculating the **footprint** of expressions and formulas can avoid redundancy by not generating permission-subformulas that are already satisfied. This can be implemented as implicit in \wedge by a wrapper \wedge_{wrap} operation in some way similar to this:

$$\phi \wedge_{\text{wrap}} \phi' := \begin{cases} \phi & \text{if } \phi \Rightarrow \phi' \\ \phi \wedge \phi' & \text{otherwise} \end{cases}$$

Some utility functions are defined as follows:

$\text{new}(C)$	$:=$	an object that is a new instance of class C where all fields are assigned to their default values
$\text{unfolded}(\alpha_C(\bar{e}))$	$:=$	$\overline{[e/x]\text{body}(\alpha_C)}$
$\text{pre}(z.m_C(\bar{e}))$	$:=$	$[z/\text{this}, \overline{e/x}]\text{pre}(m_C)$
$\text{pre}(m_C)$	$:=$	the static pre-condition of m_C
$\text{post}(z.m_C(\bar{e}))$	$:=$	$[z/\text{this}, \overline{e/\text{old}(x)}]\text{post}(m_C)$
$\text{post}(m_C)$	$:=$	the static post-condition of m_C
$\text{body}(\alpha_C)$	$:=$	the body of α_C

$$\begin{aligned}
\text{footprint}(e) &:= \text{match } e \text{ with} \\
&\quad \left| \begin{array}{ll} e.f & \mapsto \text{footprint}(e') \wedge e' \neq \text{null} \wedge \text{acc}(e'.f) \\ e_1 \oplus e_2 & \mapsto \text{footprint}(e_1) \wedge \text{footprint}(e_2) \\ e_1 \odot e_2 & \mapsto \text{footprint}(e_1) \wedge \text{footprint}(e_2) \\ e & \mapsto \text{true} \end{array} \right. \\
\text{footprint}(\bar{e}) &:= \bigwedge \text{footprint}(e) \\
\text{footprint}(\phi) &:= \bigwedge \{ \text{footprint}(e) : e \text{ appears in } \phi \} \wedge \\
&\quad \bigwedge \{ \alpha_C(\bar{e}) : \text{unfolding } \alpha_C(\bar{e}) \text{ in } \phi' \text{ appears in } \phi \}
\end{aligned}$$

$$\text{handleMethod}(z.m_C(\bar{e}), \phi) \quad := \quad (\text{footprint}(\text{pre}(z.m_C(\bar{e}))) \wedge \text{footprint}(\text{post}(z.m_C(\bar{e})))) * \phi$$