Framing Rules

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1 Definitions

Note: in this document "formula" refers to "precise formula," however gradual formulas will eventually be supported.

A **permission** is to either access a field, written access(e.f), or to assume a predicate holds of its arguments, written $assume(\alpha_C(\overline{e}))$.

A formula ϕ requires a permission π if ϕ contains an access or assumption that π premits. The set of all permissions that ϕ requires (the set of permissions required to frame ϕ) is called the requirements of ϕ .

A formula ϕ grants permission π if it contains an adjuct that yields π .

A set of permissions Π frames a formula ϕ if and only if ϕ requires only permissions contained in Π , written

$$\Pi \vDash_I \phi$$
.

The **footprint** of a formula ϕ is the smallest permission mask that frames ϕ , written

$$|\phi|$$
.

A formula ϕ is **self-framing** if and only if for any set of permissions ϕ , $\Pi \vDash_I \phi$, written

$$\vdash_{\mathsf{frm}I} \phi$$
.

In other words, ϕ is self-framing if and only if it grants all the permissions that it requires.

2 Framing without Aliasing

For this section framing desicions do not consider aliasing, for the sake of an introduction.

2.1 Deciding Framing without Aliasing

The following algorithm decides $\Pi \vDash_{I} \phi$ for a given set of permissions Π and formula ϕ .

```
\Pi \vDash_I \phi \iff \mathsf{match} \ \phi \ \mathsf{with} \ | \ v, x
                                                                                                              \top
                                                                                                     \mapsto \quad \Pi \vDash_I e_1, e_2
                                                e_1 \oplus e_2
                                                e_1 \odot e_2
                                                                                                     \mapsto \Pi \vDash_I e_1, e_2
                                                e.f
                                                                                                    \mapsto \Pi \vDash_I e \land acc(e.f) \in \Pi
                                                acc(e.f)
                                                                                                     \mapsto \Pi \models_I e
                                                                                                     \mapsto \Pi \cup \mathsf{granted}(\phi_1 \circledast \phi_2) \vDash_I \phi_1, \phi_2
                                                \phi_1 \circledast \phi_2
                                                                                                     \mapsto \Pi \models_I \overline{e}
                                                \alpha_C(\overline{e})
                                                if e then \phi_1 else \phi_2
                                                                                                   \mapsto \Pi \vDash_I e, \phi_1, \phi_2
                                                unfolding \alpha_C(\overline{e}) in \phi \mapsto \operatorname{assume}(\alpha_C(\overline{e})) \in \Pi \wedge \Pi \models_I \alpha_C(\overline{e}) \wedge \Pi \models_I \phi
```

The following algorithm collects the set of permissions granted by a given formula ϕ .

2.2 Notes

- The conditional expression e in a formula of the form (if e then ϕ_1 else ϕ_2) is considered indeterminant for the purposes of statically deciding framing.
- The body formula ϕ in a formula of the form (unfolding $acc_C(\overline{e})$) in ϕ) does not have to make use of the $assume(acc_C(\overline{e}))$ required by the structure.

2.3 Deciding Self-Framing without Aliasing

The following algorithm decides $\vdash_{\mathsf{frm}I} \phi$ for a given formula ϕ .

$$\vdash_{\mathsf{frm} I} \phi \iff \varnothing \vDash_I \phi$$

3 Aliasing

Let I be the set of identifiers. A pair of identifiers $x, y \in I$ are **unique** if they are not the same identifier. The proposition that x, y are unique is written unique(x, y) (note that this is importantly different notation from x = y). The proposition that two identifiers refer to the same memory in the heap is written x = y. A set of identifiers $\{x_{\alpha}\}$ is **aliasing** if and and only if each x_{α} refers to the same memory in the heap i.e.

$$x_{\alpha_1} = \cdots = x_{\alpha_k}$$
 where $\{\alpha\} = \{\alpha_1, \dots, \alpha_k\}$.

The proposition that $\{x_{\alpha}\}$ is aliasing is written aliasing $\{x_{\alpha}\}$.

An aliasing context is a set A of aliasing propositions. As a set of propositions, the consistency of A can be considered. Explicitly, A is consistent if and only if

$$\nexists x,y \in I : \mathsf{unique}(x,y) \land A \vdash \mathsf{aliasing}\{x,y\} \land \sim \mathsf{aliasing}\{x,y\}$$

The proposition that A is consistent is written consistent(A).

An alias context is **overlapping** if and only if there exist at least two unique sets of identifiers such that they have a non-empty intersection and both are asserted aliasing in A i.e.

$$\exists I_1, I_2 \subset I : (I_1 \neq I_2) \land (I_1 \cap I_2 \neq \emptyset) \land (\mathsf{aliasing}(I_1) \in A) \land (\mathsf{aliasing}(I_2) \in A)$$

An overlapping alias context is inefficient for deciding the propositions that it entails. Fortunately the framing-deciding algorithm I present ensures that its tracked alias context never becomes becomes overlapping.

A alias context A is **full** if and only if

$$\forall I_{\alpha} \subset I : A \vdash P(I_{\alpha}) \implies \exists P(I_{\alpha'}) \in A : I_{\alpha} \subset I_{\alpha'}$$

where P is an aliasing predicate (either aliasing or \sim aliasing). In other words, a full alias context is the most efficient representation of its total propositional strength. Note that, of course, a full alias context that contains aliasing $\{x\}$ need not contain $\sim\sim$ aliasing $\{x\}$,... although it does indeed entail these propositions. This is useful for efficient computation, as demonstrated in the following.

Given A an alias context and $x \in I$ an identifier, define:

```
aliases-of(x) := the largest set such that x \in \text{aliases-of}(x) \land A \vdash \text{aliasing}(\text{aliases-of}(x)) not-aliases-of(x) := the largest set such that \forall x' \in \text{not-aliases-of}(x) : A \vdash \sim \text{aliasing}\{x, y'\}
```

If A is non-overlapping and full, the computation of aliases-of(x) is simply the extraction from A the proposition that asserts aliasing of a set of identifiers that contains x and the computation of not-aliases-of(x) is the collection of all identifiers other than x mentioned in propositions of A that assert the negation of aliasing with x. For example,

$$A := \{ \text{aliasing } \{x, y\}, \text{aliasing } \{z\}, \sim \text{aliasing } \{x, z\}, \sim \text{aliasing } \{y, z\} \}$$

id	aliases-of (id)	$not ext{-aliases-of}(\mathit{id})$
x	$\{x,y\}$	{z}
y	$\{x,y\}$	$\{z\}$
z	$ $ $\{z\}$	$\{x,y\}$

4 Framing with Aliasing

For this section framing desicions do consider aliasing.

4.1 New Permissions

4.2 Deciding Framing with Aliasing

Given Π a permission set and ϕ a formula, the proposition that Π frames ϕ is written

$$\Pi \vDash_I \phi$$

The following algorithm decides $\Pi \vDash_I \phi$.

```
\Pi \vDash_I \phi \quad \Longleftrightarrow \quad \mathsf{match} \ \phi \ \mathsf{with}
                                                                                           Т
                         v
                                                                                           Т
                         \boldsymbol{x}
                                                                                 \mapsto \Pi \vdash \sim (\sim \text{ aliased } \{x,y\})
                         x = y
                         x \odot y
                                                                                 \mapsto \Pi \vdash \sim (\sim (\sim \text{ aliased } \{x,y\}))
                                                                                 \mapsto (\Pi \sqcup \mathsf{granted}_{\Pi}(e_1) \vDash_I e_1)
                         e_1 \oplus e_2
                                                                                           \land (\Pi \sqcup \mathsf{granted}_{\Pi}(e_2) \vDash_I e_2)
                         e_1 \& \& e_2
                                                                                 \mapsto (\Pi \sqcup \mathsf{granted}_{\Pi}(e_1) \vDash_I e_1) \land (\Pi \sqcup \mathsf{granted}_{\Pi}(e_2) \vDash_I e_2)
                                                                                 \mapsto \quad (\Pi \sqcup \mathsf{granted}_{\Pi}(e_1) \vDash_I e_1) \ \lor \ (\Pi \sqcup \mathsf{granted}_{\Pi}(e_2) \vDash_I e_2)
                         e_2 \parallel e_2
                         e_2 \odot e_2
                                                                                 \mapsto (\Pi \sqcup \mathsf{granted}_{\Pi}(e_1) \vDash_I e_1) \land (\Pi \sqcup \mathsf{granted}_{\Pi}(e_2) \vDash_I e_2)
                         acc(e.f)
                                                                                 \mapsto (\Pi \vdash \mathsf{reserved}(e.f))
                                                                                 \mapsto \quad \Pi \sqcup \mathsf{granted}_{\Pi}(\phi_1 \circledast \phi_2) \vDash_I \phi_1, \phi_2
                         \phi_1 \circledast \phi_2
                                                                                 \mapsto \Pi \sqcup \models_I \overline{e}
                         \alpha_C(\overline{e})
                                                                                 \mapsto (\Pi \vDash_I e) \land (\Pi \sqcup \mathsf{granted}_{\Pi}(e) \vDash_I \phi_1)
                         if e then \phi_1 else \phi_2
                                                                                           \land (\Pi \sqcup \{ \sim \pi \mid \pi \in \mathsf{granted}_{\Pi}(e) \} \vDash_I \phi_2)
                         \texttt{unfolding} \ \alpha_C(\overline{e}) \ \texttt{in} \ \phi' \ \mapsto \ (\Pi \vDash_I \alpha_C(\overline{e})) \ \land \ (\Pi \sqcup \{\texttt{assumed}(\alpha_C(\overline{e}))\} \vDash_I \phi')
```

```
granted_{\Pi}(\phi) := match \phi with
                                                                                        \mapsto
                                                                                                  Ø
                                                                                        \mapsto
                                                                                                  Ø
                              \boldsymbol{x}
                                                                                                \{ aliased(aliases_{\Pi}(x) \cup aliases_{\Pi}(y)) \}
                              x = y
                                                                                                    \sqcup \{ \sim \operatorname{aliased} \{x', \tilde{y}\} \mid x' \in \operatorname{aliases}_{\Pi}(x), \tilde{y} \in \operatorname{non-aliases}_{\Pi}(y) \}
                                                                                                    \ \sqcup \ \{ \sim \mathsf{aliased} \ \{ \tilde{x}, y' \} \mid \tilde{x} \in \mathsf{non-aliases}_\Pi(x), y' \in \mathsf{aliases}_\Pi(y) \}
                              x \oplus y
                                                                                        \mapsto \{ \sim \operatorname{aliased}(\{x'\} \cup \operatorname{aliases}_{\Pi}(y)) \mid x' \in \operatorname{aliases}_{\Pi}(x) \}
                                                                                                    \sqcup \ \{ \sim \operatorname{aliased}(\{y'\} \cup \operatorname{aliases}_{\Pi}(x)) \mid y' \in \operatorname{aliases}_{\Pi}(x) \}
                              e_1 \oplus e_2
                              e_2 \odot e_2
                              acc(e.f)
                                                                                                  \{ \operatorname{reserved}(x'.f) \mid x' \in \operatorname{aliases}_{\Pi}(x) \}
                                                                                        \mapsto
                              \phi_1 * \phi_2
                                                                                                  \operatorname{granted}_{\Pi}(\phi_1) \sqcup^* \operatorname{granted}_{\Pi}(\phi_2)
                              \phi_1 \wedge \phi_2
                                                                                                  \operatorname{granted}_{\Pi}(\phi_1) \sqcup^{\wedge} \operatorname{granted}_{\Pi}(\phi_2)
                              \alpha_C(\overline{e})
                              if e then \phi_1 else \phi_2
                                                                                        \mapsto (granted<sub>\Pi</sub>(e) \sqcup granted<sub>\Pi</sub>(\phi_1))
                                                                                                   \sqcap (\{ \sim \pi \mid \pi \in \mathsf{granted}_{\Pi}(e) \} \sqcup \mathsf{granted}_{\Pi}(\phi_2))
                              \texttt{unfolding} \ \alpha_C(\overline{e}) \ \texttt{in} \ \phi' \ \mapsto \ \{\texttt{assumed}(\alpha_C(\overline{e}))\} \ \sqcup \ \texttt{granted}_\Pi(\phi')
```

4.3 Notes

4.4 Deciding Self-Framing with Aliasing

The following algorithm decides $\vdash_{\mathsf{frm}I} \phi$ for a given formula ϕ .