Gradually Verified Language with Recursive Predicates

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1 Weakest Predonditions

1.1 Concrete Weakest Liberal Precondition Rules

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\mathsf{WLP}:\ \mathsf{STATEMENT} \times \mathsf{SATFORMULA} \to \mathsf{SATFORMULA}
\mathsf{WLP}(s,\phi) := \mathsf{match}\ s \ \mathsf{with}
  skip
                                                                        \mathsf{WLP}(s_1, \ \mathsf{WLP}(s_2, \phi))
  s_1; s_2
  T x
                                                                  \mapsto footprint(e) \land [e/x]\phi
 x := e
                                                                  \mapsto \quad [\mathsf{newInstance}(C)/x] \phi
 x := \text{new } C
  x.f := y
                                                                  \mapsto footprint(x.f) \land [y/x.f]\phi
                                                                  \mapsto footprint(\overline{e}) \land (z != null) \land
  y := z.m_C(\overline{e})
                                                                           [z/{\tt this}, \overline{e/x}] {\sf pre}(m_C) \wedge
                                                                           \phi - [z/\text{this}, \overline{e/\text{old}(x)}] \text{post}(m_C)
  if (e) \{s_{
m th}\} else \{s_{
m el}\}
                                                                  \mapsto footprint(e) \land
                                                                           if (e) then (e \wedge \mathsf{WLP}(s_{\mathrm{th}}, \phi)) else (\sim e \wedge \mathsf{WLP}(s_{\mathrm{el}}, \phi))
 while (e) invariant \phi_{\mathrm{inv}} \{s_{\mathrm{bod}}\}
                                                                 \mapsto footprint(e) \land \phi_{\mathrm{inv}} \land
                                                                           \mathsf{WLP}(s_{\mathrm{bod}},\ (\sim e\ \land\ \phi)\ \lor
                                                                                                WLP(while (e) invariant \phi_{inv} \{s_{bod}\}, \phi))
  assert \phi_{\rm ass}
                                                                  \mapsto footprint(\phi_{ass}) \land \phi_{ass} \land \phi
 hold \phi_{\text{hol}} \{s_{\text{bod}}\}
                                                                          unimplemented
 release \phi_{\mathrm{rel}}
                                                                          unimplemented
  unfold \alpha_C(\overline{e})
                                                                  \mapsto footprint(\overline{e}) \land [\mathsf{unfolded}(\alpha_C(\overline{e}))/\alpha_C(\overline{e})]\phi \land
                                                                           [\phi'/\text{unfolding }\alpha_C(\overline{e}) \text{ in } \phi']
  fold \alpha_C(\overline{e})
                                                                  \mapsto footprint(\overline{e}) \land [\alpha_C(\overline{e})/\text{unfolded}(\alpha_C(\overline{e}))]\phi
```

Some utility functions are defined as follows. Note that the implementations of these functions can be made much more efficient than the naive definition here in mathematical notation. For example, calculating the footprint of expressions and formulas can avoid redundancy by not generating permissions that are already satisfied. This can be implemented as implicit in \land operations.

 $\mathsf{newInstance}(C) := \mathsf{an}$ object that is a new instance of class C where all fields are assigned to their default values

$$\mathsf{unfolded}(\alpha_C(\overline{e})) := [\overline{e/x}]\mathsf{body}(\alpha_C)$$

$$\left(\bigwedge\phi_{i}\right)-\left(\bigwedge\psi_{j}\right):=\bigwedge\left\{ \phi_{i}:\nexists\psi\subset\left\{ \psi_{j}\right\} ,\psi\implies\phi_{i}\right\}$$

 $pre(m_C) := the pre-condition of the static contract for <math>m_C$ $post(m_C) := the post-condition of the static contract for <math>m_C$

 $\mathsf{body}(\alpha_C) := \mathsf{the} \ \mathsf{body} \ \mathsf{of} \ \mathsf{predicate} \ \alpha_C$