



Important instruction to examiners:

- 1) The answers should be examined by key words and not as word to word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more importance (Not applicable for subject English and Communication Skills).
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by the candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given stepwise for numerical problems. In some cases the assumed constant values may be vary and there may be some difference in the candidates answer and model answer.
- 6) In case of some questions credit may be given by judgment on part of examiner of relevant answer based on candidates understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.



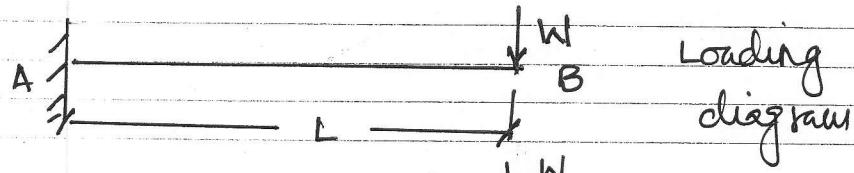
SUMMER- 13 EXAMINATION

Subject Code- 120 1S Model Answer: Engineering Mechanics

Q 1	Attempt any TEN	20 Marks
(a)	Newton force :- 1 N force is that force which when acts on a body of mass 1 kg produces an acceleration of 1 m/sec^2 in it.	1 M
	<u>OR</u> A force which produces an acceleration of 1 m/sec^2 in a body of mass 1 kg is called as unit Newton force or one Newton force.	
	$1\text{ N} = 1\text{ kg} \times 1\text{ m/sec}^2$	1 M.
	$1\text{ N} = 1\text{ kg} \cdot \text{m/sec}^2$	
(b)	condition of equilibrium wrt. moment for Non-concurrent system. → The Algebraic sum of Moment of all forces about any point is equal to zero.	2 M
	$\therefore \sum M = 0$ $\therefore \sum \text{clockwise moment} - \sum \text{Anticlockwise moment} = 0$ $\therefore \sum \text{clockwise moment} = \sum \text{Anticlockwise moment}$	
(c)	If three concurrent non-collinear forces are in equilibrium, then each force is equilibrant of remaining two forces.	2 M

Q 1.

(d)

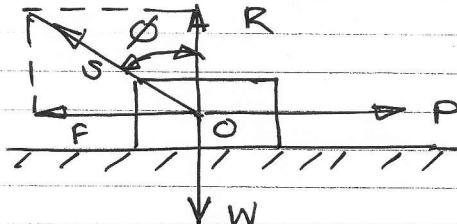


1M



$$M_A = WL$$

(e)



1M.

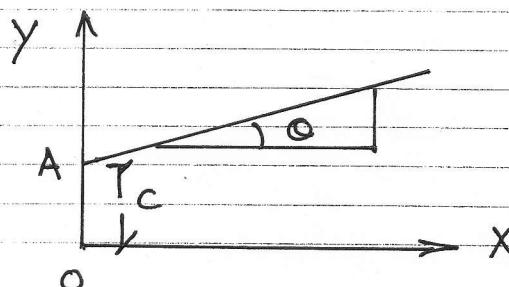
Angle of friction :- It is the angle made by Resultant reaction with the normal reaction, when body is in limiting equilibrium.

(f)

(i) If geometrical shape is symmetrical about x and y axis, then centroid lies at the intersection of s Axis of symmetry.

(ii) If geometrical shape is symmetrical about any one axis, then the centroid lies on that axis

(g)



1M

Law of Machine :- The relation between

the load lifted (W) and the effort applied (P) is known as the law of Machine.

$$\therefore P = mW + C$$

1M

where

$P = \text{effort}$

$w = \text{load}$

$m = \text{slope}$

$\therefore c = \text{effort required at zero load.}$

(h) Ideal Machine :- when efficiency of machine is 100% then it is 2M. called as ideal Machine

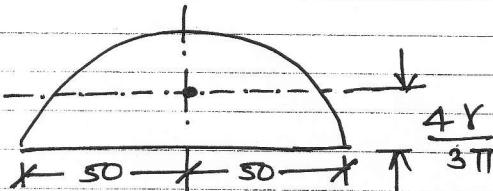
or

It is a machine in which friction is zero

or

It is a machine in which output is equal to input.

(i)



1 M

$$\therefore \bar{y} = \frac{4Y}{3\pi} = \frac{4 \times 50}{3\pi} = 21.22 \text{ mm}$$

1 M.

(j) Dynamic or Kinetic friction :-

It is the friction experienced by a body in motion

Two Types of Dynamic friction

(i) Rolling friction.

(ii) sliding friction.

1 M

(k) Graphical conditions of equilibrium for non-concurrent forces

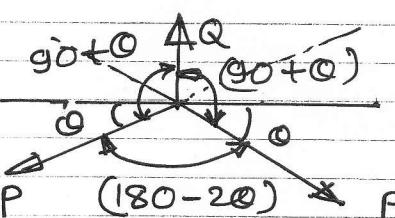
(i) force diagram or vector diagram

must be a closed figure

1 M

(ii) funicular Polygon must be a closed figure.

1 M

Q1
(l)

1 M

use lami's theorem

$$\frac{P}{\sin(90 + \theta)} = \frac{P}{\sin(90 + \theta)} = \frac{Q}{\sin(180 - 2\theta)}$$

$$\frac{P}{\cos\theta} = \frac{Q}{\sin 2\theta}$$

$$\therefore Q = \frac{\sin 2\theta}{\cos\theta} \cdot P \quad (\text{Acting away from the point}) \quad 1 M$$

$$Q = \frac{2\sin\theta\cos\theta}{\cos^2\theta} \times P$$

$$Q = 2P\sin\theta$$

(m) velocity Ratio for differential axle and wheel

$$\therefore V.R. = \frac{2D}{d_1 - d_2} \quad 1 M$$

∴ where D = diameter of wheel

∴ d_1 = diameter of bigger axle $1 M$ ∴ d_2 = diameter of smaller axle

(n)

$$\mu = 0.30$$

we have to find angle of Repose

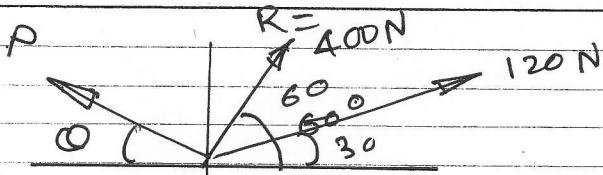
$$\text{As } \mu = \tan\alpha$$

$$0.3 = \tan\alpha$$

$$\therefore \alpha = \tan^{-1}(0.3)$$

$$\therefore \boxed{\alpha = 16.699^\circ} \quad 1 M$$

Q 2
(a)



∴ Resolving forces and resultant.

$$\therefore \Sigma F_x = -P\cos\theta + 120\cos 30$$

$$\therefore 400\cos 60 = -P\cos\theta + 120\cos 30$$

$$\therefore P\cos\theta = 103.92 - 200$$

$$\therefore P\cos\theta = -96.08 \quad \text{--- } \textcircled{1} \quad 1M$$

$$\therefore \Sigma F_y = P\sin\theta + 120\sin 30$$

Resolve R vertically

$$\therefore 400\sin 60 = P\sin\theta + 120\sin 30$$

$$\therefore P\sin\theta = 286.41 \quad \text{--- } \textcircled{2} \quad 1M$$

divide eqn $\textcircled{2}$ by eqn $\textcircled{1}$

$$\frac{P\sin\theta}{P\cos\theta} = \frac{286.41}{-96.08}$$

$$\tan\theta = -2.98$$

$$\theta = -71.455^\circ \quad \text{--- } \text{where -ve sign indicates Anticlockwise} \quad 1M$$

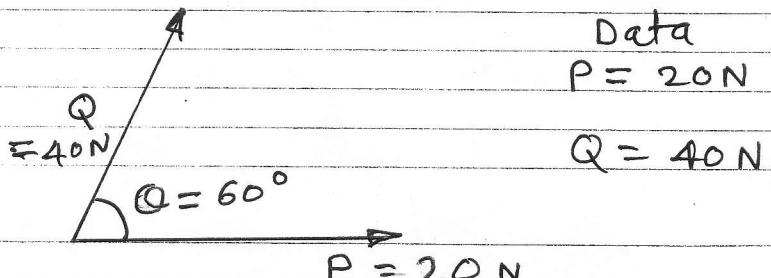
put value of θ in eqn angle with X axis

$$P\sin 71.455 = 286.41$$

$$P = 302.096 N$$

1M.

(b)



* Magnitude of Resultant (R)

$$R = \sqrt{P^2 + Q^2 + 2PQ\cos\theta} \quad 1M$$

Q 2
(b)
cont.

$$R = \sqrt{(20)^2 + (40)^2 + 2 \times 20 \times 40 \times \cos 60}$$

$$R = \sqrt{2800}$$

$$R = 52.915 \text{ N}$$

1M

* Direction of Resultant w.r.t to P force
 $\therefore P = 20 \text{ N}$

$$\tan \alpha = \frac{Q \sin \theta}{P + Q \cos \theta}$$

$$= \frac{40 \sin 60}{20 + 40 \cos 60}$$

$$= \frac{34.641}{40}$$

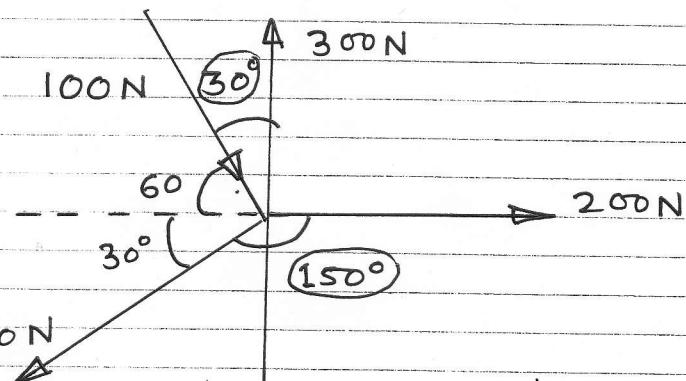
$$= 0.866$$

$$\alpha = 40.893^\circ \text{ w.r.t to } 20 \text{ N force} \quad 1 \text{ M}$$

OR

$$\alpha = 19.107^\circ \text{ w.r.t to } 40 \text{ N force.}$$

(c)



Resolution and composition of forces

$$\sum F_x = 200 + 100 \cos 60 - 80 \cos 30$$

$$= 180.718 \text{ N}$$

1M

$$\sum F_y = 300 - 100 \sin 60 - 80 \sin 30$$

$$= 173.397 \text{ N}$$

1M

Q 2
(c)

* Magnitude of Resultant

cont.

$$\therefore R = \sqrt{(\varepsilon_{fx})^2 + (\varepsilon_{fy})^2}$$

$$\therefore R = \sqrt{(180.718)^2 + (173.397)^2}$$

$$\therefore R = 250.450 \text{ N}$$

1 M

* Direction of Resultant

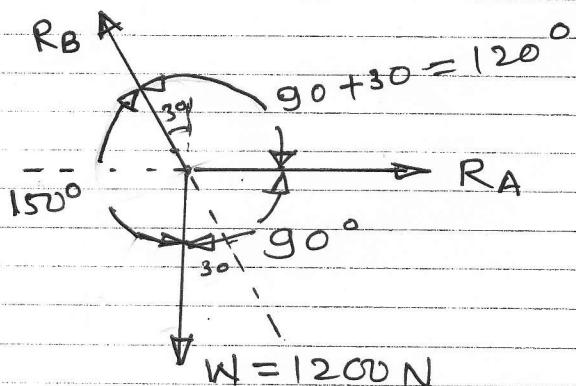
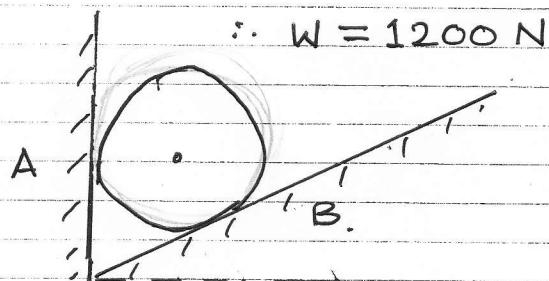
$$\therefore \tan \theta = \frac{\varepsilon_{fy}}{\varepsilon_{fx}}$$

$$= \frac{173.397}{180.718}$$

$$= 0.959$$

$$\therefore \theta = 43.815^\circ$$

1 M

Q2
(d)

1 M

free body diagram

let R_A and R_B be the reactions at points A and B respectively.

Applying Lami's theorem to forces R_A , R_B & 1200 N .

Q 2
(d)
cont.

$$\frac{R_A}{\sin 150} = \frac{R_B}{\sin 90} = \frac{1200}{\sin 120}$$

1M

considering first and third term.

$$\therefore \frac{R_A}{\sin 150} = \frac{1200}{\sin 120}$$

$$\therefore R_A = \frac{1200 \times \sin 150}{\sin 120}$$

$$\therefore R_A = 692.820 \text{ N}$$

1M

considering second and third term

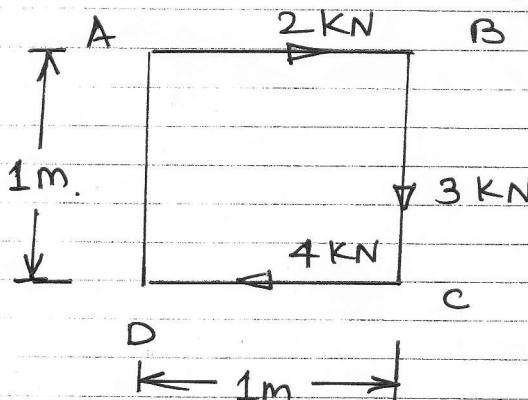
$$\therefore \frac{R_B}{\sin 90} = \frac{1200}{\sin 120}$$

$$\therefore R_B = \frac{1200 \times \sin 90}{\sin 120}$$

$$\therefore R_B = 1385.64 \text{ N}$$

1M

(e)



* composition of forces

$$\Sigma F_x = 2 - 4$$

$$= -2 \text{ kN} = 2 \text{ kN} (\leftrightarrow)$$

 $\frac{1}{2} \text{ M}$

$$\Sigma F_y = -3 \text{ kN}$$

$$= 3 \text{ kN. } (\downarrow)$$

 $\frac{1}{2} \text{ M}$

* Magnitude of Resultant

$$R = \sqrt{(\Sigma F_x)^2 + (\Sigma F_y)^2}$$

Q 2
(e)
cont.

$$\therefore R = \sqrt{(-2)^2 + (-3)^2}$$

$$\therefore R = 3.605 \text{ N}$$

1M

* direction of resultant (θ)

$$\therefore \tan \theta = \frac{\Sigma f_y}{\Sigma f_x}$$

$$= \frac{-3}{-2}$$

$$\therefore \theta = \tan^{-1}(1.5)$$

$$\therefore \theta = 56.309$$

1M

* location of Resultant w.r.t.

Taking moment of all forces about 'A'

$$\Sigma M_{FA} = 3 \times 1 + 4 \times 1$$

$$= 7 \text{ KN-m} \quad \text{---} \quad \textcircled{1}$$

let 'x' be the distance of 'R'
from Point 'A'

\therefore Moment of R about A

$$M_{RA} = R \times x \quad \text{---} \quad \textcircled{2}$$

equating eqn $\textcircled{1}$ and $\textcircled{2}$

$$R \times x = 7$$

$$3.605x = 7$$

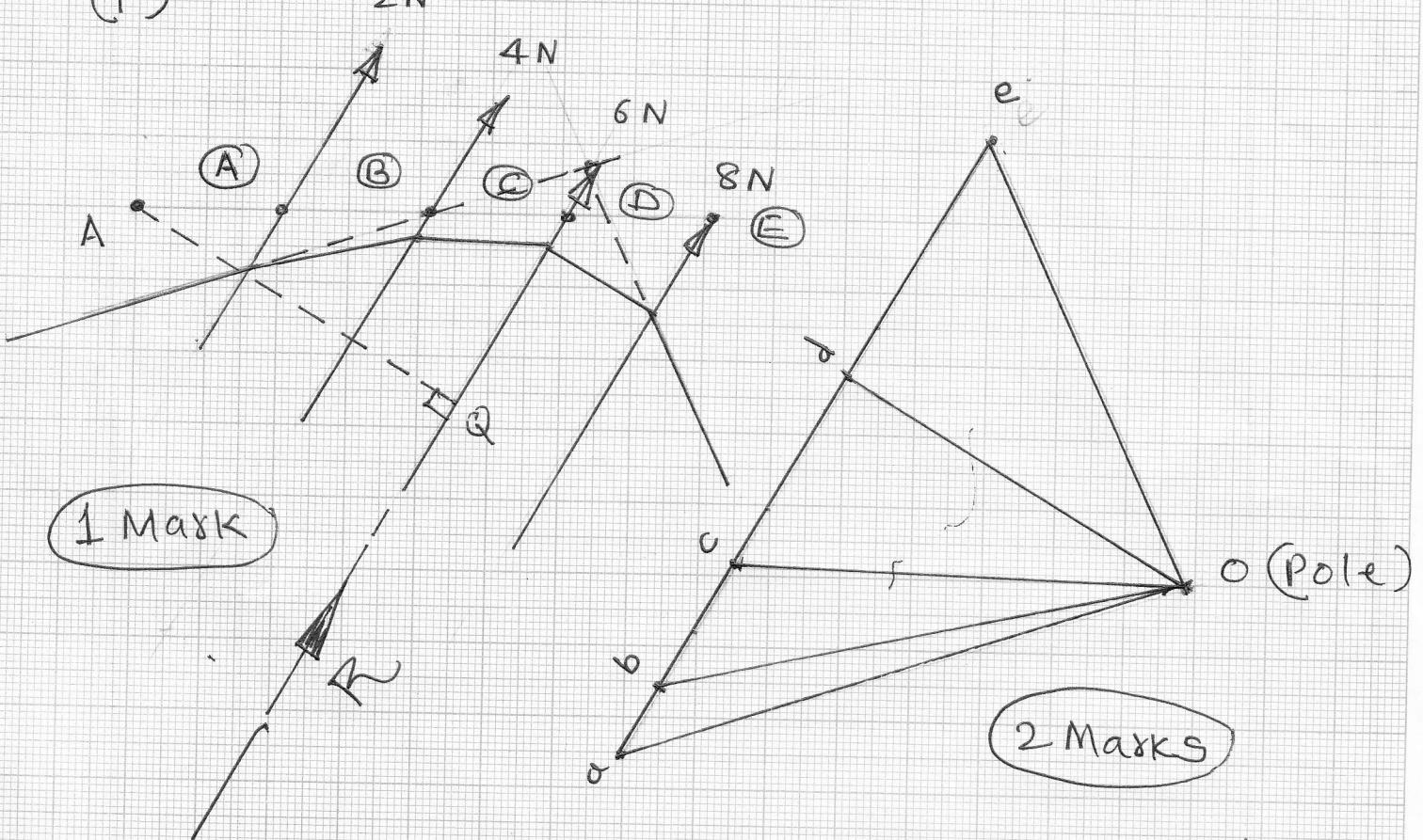
$$\therefore x = 1.942 \text{ m}$$

1M

Q 2
(F)

Space diagram

scale 1cm = 0.5m



Vector diagram

scale
1cm = 2N /

calculations

① Magnitude of Resultant (R)

$$R = l(ae) \times 2 \text{ N}$$

$$R = 10 \times 2$$

$$R = 20 \text{ N} (\uparrow \text{at } 60^\circ \text{ to horizontal})$$

1/2 M

② Distance of Resultant (x)

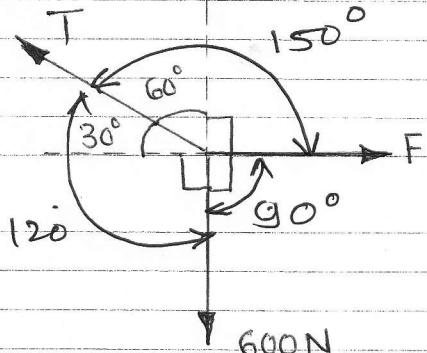
$$\begin{aligned} \text{Horizontal distance} &= 6\text{cm} \times 0.5\text{m} \\ &\text{from 'A'} &= 3\text{m}. \end{aligned}$$

1/2 M

$$\begin{aligned} \text{Perpendicular distance from A} \\ \therefore x &= l(AQ) = 5.3 \times 0.5 = 2.65\text{m} \end{aligned}$$

Q-3

a)



applying Lamis
Theorem

$$\frac{F_1}{\sin \theta_1} = \frac{F_2}{\sin \theta_2} = \frac{F_3}{\sin \theta_3}$$

01

01

$$\frac{600}{\sin 150^\circ} = \frac{T}{\sin 90^\circ} = \frac{F}{\sin 120^\circ}$$

$$\text{i) } \frac{600}{\sin 150^\circ} = \frac{T}{\sin 90^\circ}$$

$$T = \frac{600 \times \sin 90^\circ}{\sin 150^\circ}$$

$$\therefore T = \frac{600}{0.5} = 1200 \text{ N}$$

$$\boxed{T = 1200 \text{ N}}$$

01

$$\text{ii) } \frac{600}{\sin 150^\circ} = \frac{F}{\sin 120^\circ}$$

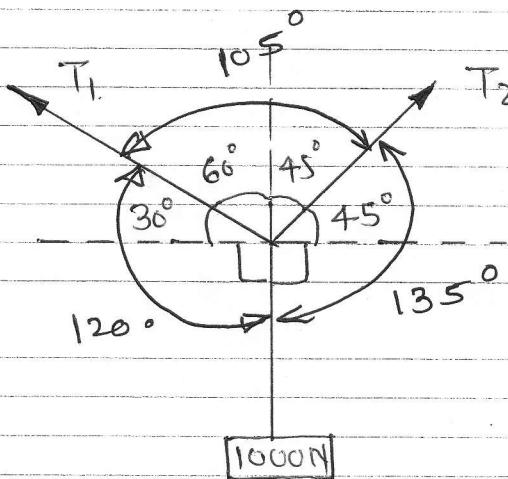
$$F = \frac{600 \times \sin 120^\circ}{\sin 150^\circ}$$

$$F = \frac{519.615}{0.5}$$

$$\boxed{F = 1039.23 \text{ N}}$$

01

b)



01

Apply Lamis Theorem

$$\text{i) } \frac{1000}{\sin 105^\circ} = \frac{T_1}{\sin 135^\circ} = \frac{T_2}{\sin 120^\circ}$$

$$T_1 = \frac{1000 \times \sin 135^\circ}{\sin 105^\circ}$$

$$T_1 = 732.05 \text{ N}$$

01

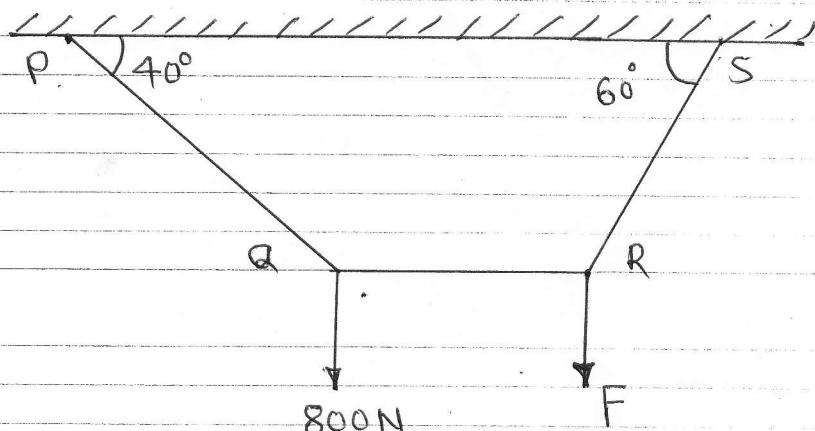
$$\text{ii) } \frac{1000}{\sin 105^\circ} = \frac{T_2}{\sin 120^\circ}$$

$$T_2 = \frac{1000 \times \sin 120^\circ}{\sin 105^\circ}$$

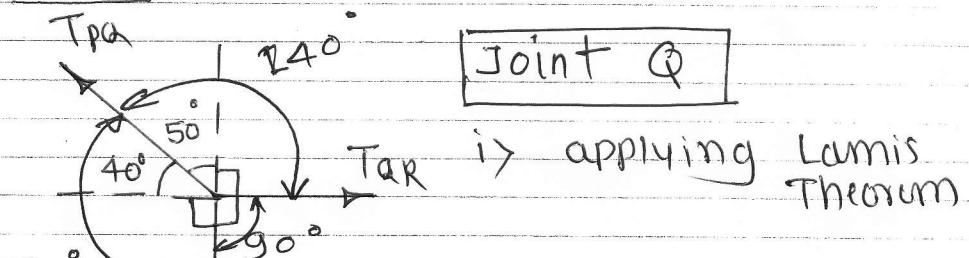
$$T_2 = 896.58 \text{ N}$$

01

Q)



Step-I



$$\frac{800}{\sin 140^\circ} = \frac{T_{PQ}}{\sin 90^\circ} = \frac{T_{QR}}{\sin 130^\circ}$$

FBD at Q

$$\therefore \frac{800}{\sin 140^\circ} = \frac{T_{PQ}}{\sin 90^\circ}$$

$$T_{PQ} = \frac{800 \times \sin 90^\circ}{\sin 140^\circ}$$

$$T_{PQ} = 1244.58 \text{ N} \quad \text{Tension}$$

01

$$\therefore \frac{800}{\sin 140^\circ} = \frac{T_{QR}}{\sin 130^\circ}$$

$$\therefore T_{QR} = \frac{800 \times \sin 130^\circ}{\sin 140^\circ}$$

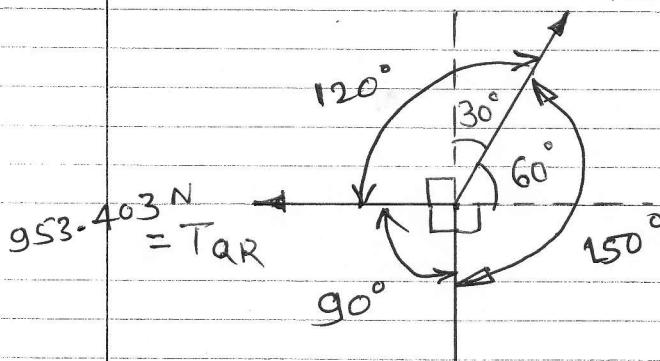
$$\therefore T_{QR} = 953.403 \text{ N} \quad \text{Tension}$$

01

Step-II >

[Joint R]

TRS



$$\frac{F}{\sin 120^\circ} = \frac{TRS}{\sin 90^\circ} = \frac{g53 \cdot 403}{\sin 150^\circ}$$

$$\frac{F}{\sin 120^\circ} = \frac{g53 \cdot 403}{\sin 150^\circ}$$

$$F = \frac{g53 \cdot 403}{\sin 150^\circ} \times \sin 120^\circ$$

$$F = 1651.34 \text{ N}$$

01

$$\frac{TRS}{\sin 90^\circ} = \frac{g53 \cdot 403}{\sin 150^\circ}$$

$$TRS = \frac{g53 \cdot 403}{\sin 150^\circ} \times \sin 90^\circ$$

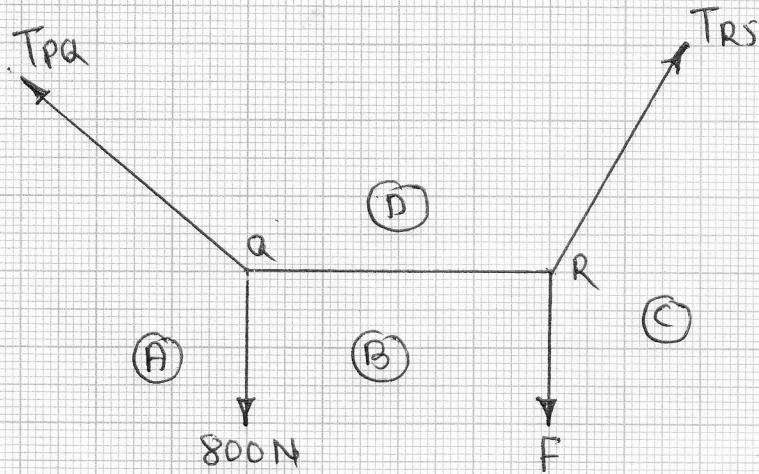
$$TRS = 1906.806 \text{ N} \quad \text{Tensile}$$

01

Q-3 (d)

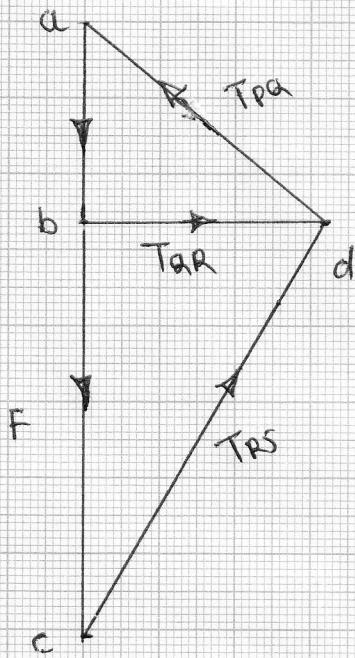
Scale

1cm = 300N



01
marks

From The graph



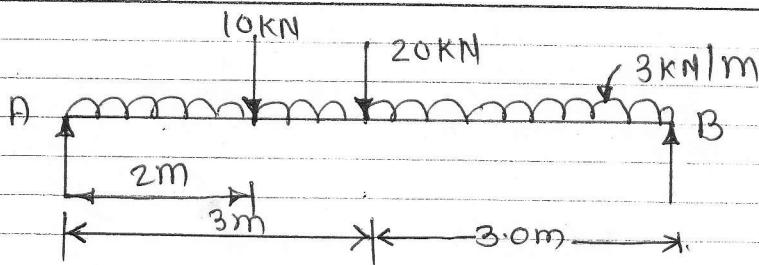
VECTOR DIAGRAM

(01-Marks)

A

$T_{PA} = ab \times \text{scale factor}$	01
$= 4.15 \times 300 = \underline{\underline{1244.53N}}$	2
$T_{AR} = bd \times \text{scale factor}$	01
$= 3.176 \times 300 = \underline{\underline{953N}}$	2
$T_{RS} = cd \times \text{scale factor}$	01
$= 6.35 \times 300 = \underline{\underline{1906 N}}$	2
$F = bc \times \text{scale factor}$	01
$= 5.5 \times 300 = \underline{\underline{1650.64 N}}$	2

e)



01

$$\sum F_y = 0$$

$$RA + RB = 10 + 20 + (3 \times 6)$$

$$RA + RB = 48 \quad \textcircled{1}$$

$$\sum M_A = 0$$

$$-RB \times 6 + (20 \times 3) + (10 \times 2) + (3 \times 6) \times \frac{6}{2} = 0$$

$$-RB \times 6 + 60 + 20 + 54 = 0$$

$$-RB \times 6 + 134 = 0$$

$$RB = 22.33 \text{ kN}$$

1½

put RB value in eqn ①

$$RA + RB = 48$$

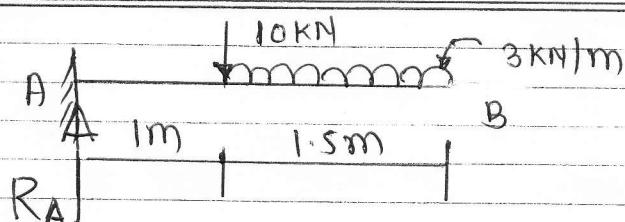
$$RA + 22.33 = 48$$

$$RA = 48 - 22.33$$

$$RA = 25.67 \text{ kN}$$

1½

f)



0

$$\sum F_y = 0$$

$$0 = RA - 10 - 3 \times 1.5$$

$$RA = 3 \times 1.5 + 10$$

$$RA = 14.5 \text{ kN}$$

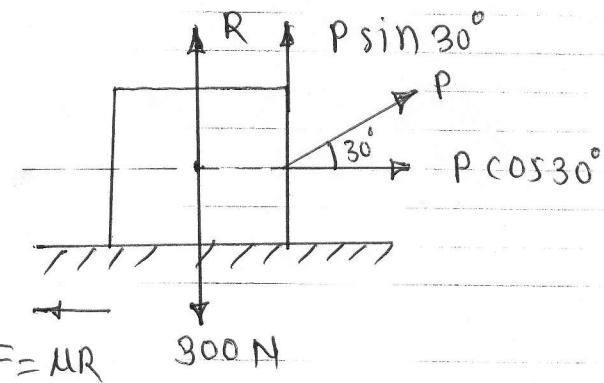
02

$$RA = 14.5 \text{ kN}$$

17/33

Q-4

a)



$$\sum F_x = 0$$

$$P \cos 30^\circ - \mu R = 0$$

$$\mu R = P \cos 30^\circ$$

$$R = \frac{P \cos 30^\circ}{\mu}$$

$$R = P \times 3.464$$

$$R = 3.464P$$

02

$$\sum F_y = 0$$

$$R - 300 + P \sin 30^\circ = 0$$

$$R - 300 + 0.5P = 0$$

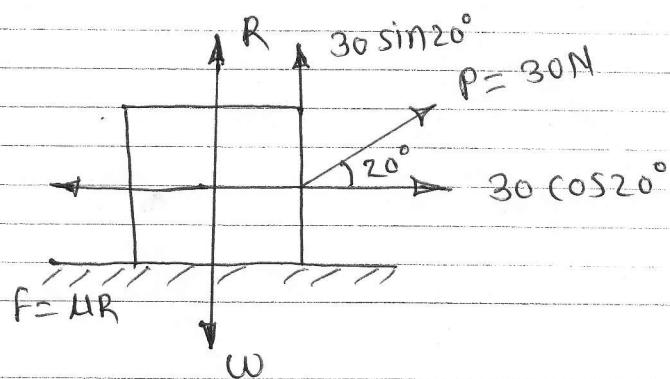
$$3.464P - 300 + 0.5P = 0$$

$$3.964P = 300$$

$$P = 75.68 \text{ N}$$

02

b



01

$$\sum F_y = 0$$

$$R - w + 30 \sin 20^\circ = 0$$

$$R - w + 10.26 = 0$$

$$R = w - 10.26$$

①

01

$$\sum F_x = 0$$

$$30 \cos 20^\circ - \mu R = 0$$

$$30 \cos 20^\circ = \mu R$$

$$R = \frac{30 \cos 20^\circ}{\mu}$$

$$R = \frac{30 \cdot \cos 20^\circ}{0.20} = \frac{28.19}{0.20}$$

$$R = 140.95 \text{ N}$$

01

Put value of R in eqⁿ ①

$$R = w - 10.26$$

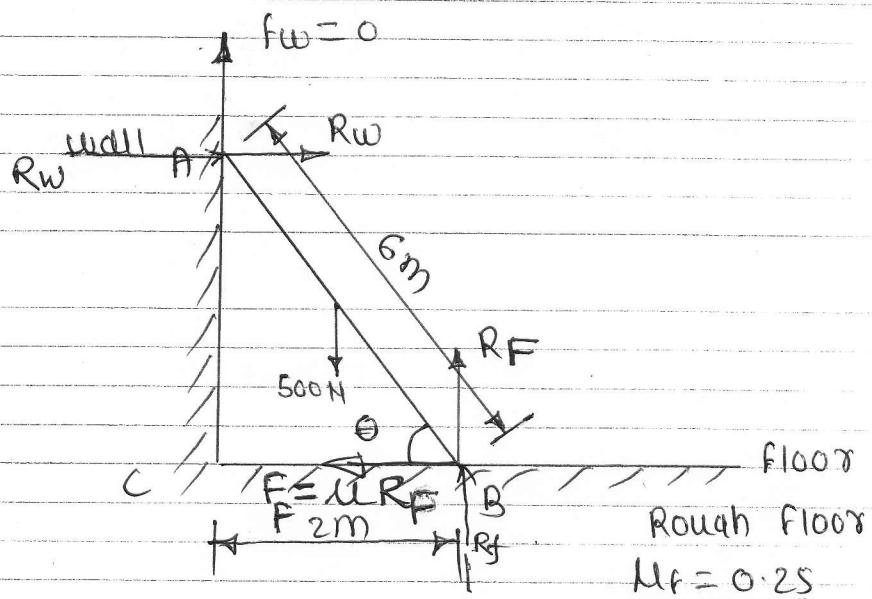
$$140.95 = w - 10.26$$

$$w = 140.95 + 10.26$$

$$w = 151.21 \text{ N}$$

01

C)



Q)

$$\sum F_x = 0$$

$$R_W - F_f = 0$$

$$R_W - 0.25 R_F = 0$$

$$R_W = 0.25 R_F$$

Q)

$$\sum F_y = 0$$

$$F_{Wx} + R_F - 500 = 0 \quad \therefore \text{As } F_{Wx} = 0$$

$$R_F = 500\text{ N}$$

Q)

frictional force

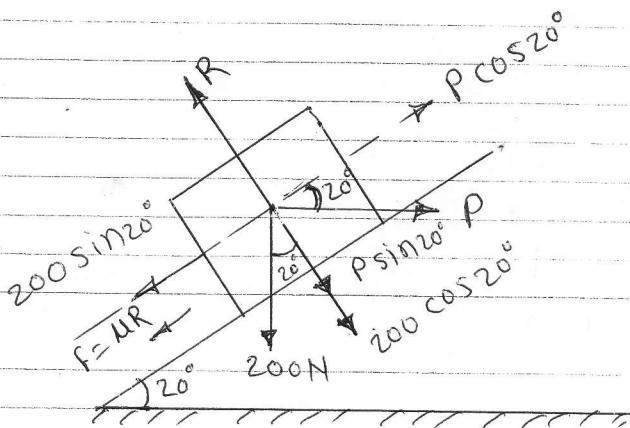
$$F_f = 0.25 \times R_F$$

$$= 0.25 \times 500$$

$$F_f = 125\text{ N}$$

Q)

d



01

$$\sum F_x = 0$$

$$P \cos 20^\circ - 200 \sin 20^\circ - \mu R = 0$$

$$P \cos 20^\circ - 68.40 - 0.2R = 0$$

$$P \cos 20^\circ - 0.2R = 68.40 \quad \text{--- (1)}$$

01

$$\sum F_y = 0$$

$$R - P \sin 20^\circ - 200 \cos 20^\circ = 0$$

$$R - P \sin 20^\circ - 187.94 = 0$$

$$R - P \sin 20^\circ = 187.94 \quad \text{--- (2)}$$

$$R = 187.94 + 0.34P$$

01

Put value of R in eqn (1)

$$P \cos 20^\circ - 0.2(187.94 + 0.34P) = 68.40$$

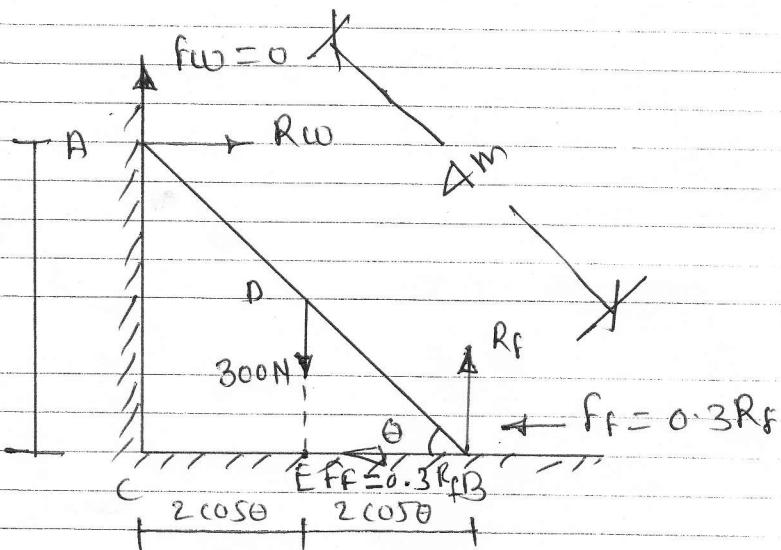
$$0.94P - 37.588 - 0.068P = 68.40$$

$$0.88P = 68.40 + 37.588$$

$$P = 120.44 \text{ N}$$

01

e)

i) in $\triangle ABC$

$$\sin \theta = \frac{AC}{AB} = \frac{AC}{4}$$

$$\therefore AC = 4 \sin \theta$$

in $\triangle DBE$

$$\cos \theta = \frac{BE}{BD} = \frac{BE}{2}$$

$$BE = 2 \cos \theta$$

01

ii) $\sum M = 0$

$$R_W - 0.3 R_F = 0$$

$$R_W = 0.3 R_F \quad \text{--- (1)}$$

$$\sum F_y = 0$$

$$R_F - 300 = 0$$

$$R_F = 300 \text{ N}$$

01

$$R_W = 0.3 R_F$$

$$R_W = 0.3 \times 300$$

$$R_W = 90 \text{ N}$$

01

Taking moment at point B

$$MB = 0$$

$$R_w \times 4 \sin \theta - 300 \times 2 \cos \theta = 0$$

$$R_w \times 4 \sin \theta = 600 \cos \theta$$

but $R_w = 90\text{N}$ put in above eqn

$$90 \times 4 \sin \theta = 600 \cos \theta$$

$$360 \sin \theta = 600 \cos \theta$$

$$\frac{\sin \theta}{\cos \theta} = \frac{600}{360}$$

$$\tan \theta = 1.6667$$

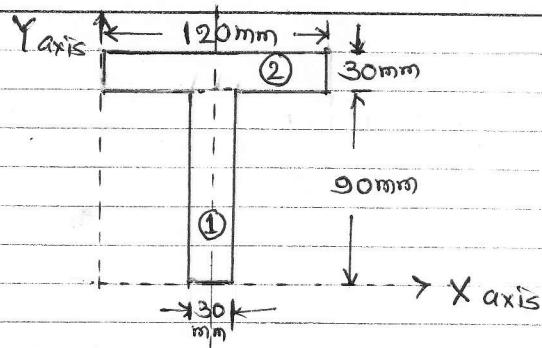
$$\therefore \theta = 59.036^\circ$$

Q)

F) Laws of static friction

- i) The direction of frictional force is opposite to that of motion.
- ii) Frictional force acts at the common surface of contact.
- iii) The limiting value of frictional force is proportional to normal reaction.
- iv) Limiting friction is independent of area of contact.
- v) friction is dependent on material and roughness at surface of contact.

1 for
any
four

Q 5
a)

$$\text{Area } A_1 = 90 \times 30 = 2700 \text{ mm}^2$$

$$A_2 = 120 \times 30 = 3600 \text{ mm}^2$$

$$\text{Total Area } (A) = 6300 \text{ mm}^2$$

$$(A_1 + A_2)$$

Due to axis of symmetry (Yaxis) Vertical axis.

$$\bar{x} = \frac{120}{2} = 60 \text{ mm.}$$

To find \bar{y}

y_1 = Dist. of centroid of Area A₁ from x axis

$$= \frac{90}{2} = 45 \text{ mm.}$$

y_2 = Dist. of centroid of Area A₂ from x axis.

$$= 90 + \frac{30}{2} = 105 \text{ mm.}$$

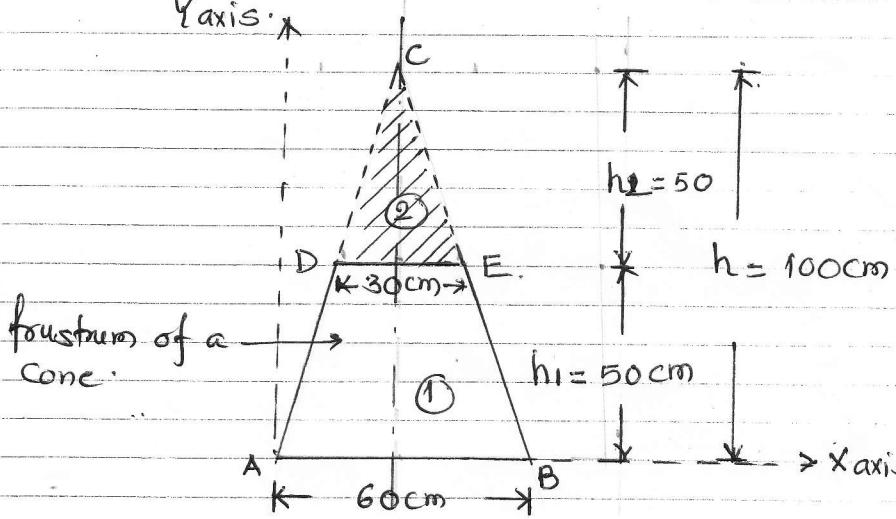
$$\therefore \bar{y} = \frac{A_1 y_1 + A_2 y_2}{A}$$

$$= \frac{(2700 \times 45) + (3600 \times 105)}{6300}$$

$$= 79.29 \text{ mm.}$$

$$\therefore \text{Centroid} = (60, 79.29).$$

5 b).



5 b)

Continued....

Considering two cones (ABC) and (CDE)
as shown in fig.

$$\frac{AB}{DE} = \frac{h}{h_1}$$

$$\therefore \frac{60}{30} = \frac{h_1 + 50}{h_1}$$

$$\therefore 60h_1 = 30(h_1 + 50)$$

$$2h_1 = h_1 + 50$$

$$\therefore h_1 = 50 \text{ cm.}$$

1

Due to axis of symmetry (vertical axis).

$$\bar{x} = \frac{60}{2} = 30 \text{ cm.}$$

~~Volume of cone~~: \bar{y}_1 = for cone (ABC).

$$V_1 = \frac{1}{3} \pi r_1^2 h$$

$$= \frac{1}{3} \pi (30)^2 \times 100$$

$$= 94247.78 \text{ cm}^3$$

\bar{y}_2 = for cone (CDE)

$$V_2 = \frac{1}{3} \pi r_2^2 \times h_2$$

$$= \frac{1}{3} \pi (15)^2 \times 50$$

$$= 11780.97 \text{ cm}^3$$

Net volume = Volume of fourturn of a cone.

$$V = V_1 - V_2 = 94247.78 - 11780.97$$

$$= 82466.81 \text{ cm}^3$$

To find \bar{y}

$$y_1 = \frac{100}{4} = 25 \text{ cm.}$$

$$y_2 = 50 + \frac{50}{4} = 62.5 \text{ cm.}$$

$$\therefore \bar{y} = \frac{V_1 y_1 - V_2 y_2}{V_1 - V_2} = 94247.78$$

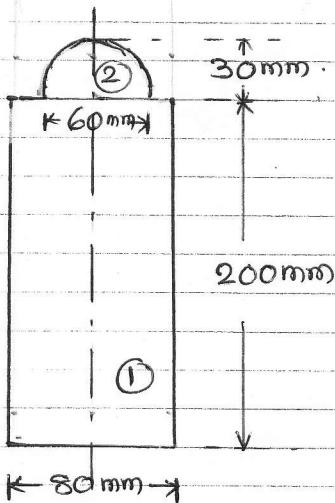
$$= \frac{(94247.78 \times 25) - (11780.97 \times 62.5)}{82466.81}$$

$$\bar{y} = 19.64 \text{ cm.}$$

\therefore Centroid = (30 cm, 19.64 cm).

1

5 c).



$$V_1 = \text{Vol. of cylinder} = \pi r^2 h.$$

$$= \pi (40)^2 \times 200 = 1005309.65 \text{ mm}^3$$

$$V_2 = \text{Vol. of hemisphere}.$$

$$= \frac{2}{3} \pi r^3 = \frac{2}{3} \pi (30)^3$$

$$= 56548.67 \text{ mm}^3$$

$$\therefore \text{Total volume } V = V_1 + V_2.$$

$$V = 1005309.65 + 56548.67.$$

$$= 1061858.32 \text{ mm}^3$$

$$\text{Due to axis of symmetry } \bar{x} = \frac{80}{2} = 40 \text{ mm.}$$

To find \bar{y}

$$y_1 = \frac{200}{2} = 100 \text{ mm}$$

$$y_2 = 200 + \frac{3}{8}(30) = 211.25 \text{ mm}$$

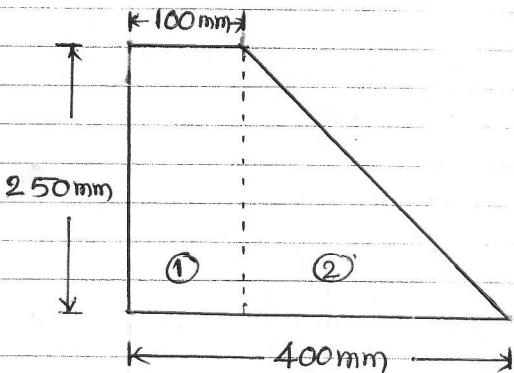
$$\therefore \bar{y} = \frac{V_1 y_1 + V_2 y_2}{V}$$

$$= \frac{(1005309.65 \times 100) + (56548.67 \times 211.25)}{1061858.32}$$

$$= 105.924 \text{ mm.}$$

$$\therefore \text{Centroid} = (40, 105.924),$$

5d)



$$\text{Area } A_1 = 100 \times 250 = 25000 \text{ mm}^2$$

$$A_2 = \frac{1}{2} \times 300 \times 250 = 37500 \text{ mm}^2$$

$$\text{Total Area (A)} = 62500 \text{ mm}^2$$

To find \bar{x} :

$$x_1 = \frac{100}{2} = 50 \text{ mm}$$

$$x_2 = 100 + \left(\frac{1}{3} \times 300\right) = 200 \text{ mm}$$

$$\therefore \bar{x} = \frac{A_1 x_1 + A_2 x_2}{A}$$

$$= \frac{(25000 \times 50) + (37500 \times 200)}{62500}$$

$$= 140 \text{ mm.}$$

$$\text{To find } \bar{y} = y_1 = \frac{250}{2} = 125 \text{ mm}$$

$$y_2 = \frac{1}{3} \times 250 = 83.33 \text{ mm.}$$

$$\bar{y} = \frac{A_1 y_1 + A_2 y_2}{A}$$

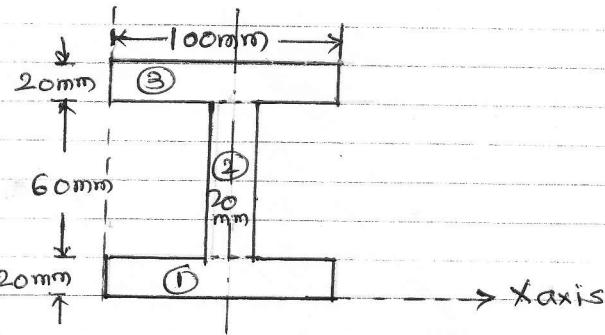
$$= \frac{(25000 \times 125) + (37500 \times 83.33)}{62500}$$

$$= 100 \text{ mm.}$$

$$\text{Centroid} = (140, 100 \text{ mm})$$

↑ Y-axis

5 e).



1.

$$\text{Area } A_1 = 100 \times 20 = 2000 \text{ mm}^2$$

$$A_2 = 60 \times 20 = 1200 \text{ mm}^2$$

$$A_3 = 100 \times 20 = 2000 \text{ mm}^2$$

$$\text{Total Area} = 5200 \text{ mm}^2$$

1

Due to axis of symmetry $\bar{x} = \frac{100}{2} = 50 \text{ mm}$.
OR

To find \bar{x} $x_1 = 50, x_2 = 50, x_3 = 50 \text{ mm}$.

$$\begin{aligned} \therefore \bar{x} &= \frac{A_1x_1 + A_2x_2 + A_3x_3}{A} \\ &= \frac{(2000 \times 50) + (1200 \times 50) + (2000 \times 50)}{5200} \\ &= 50 \text{ mm}. \end{aligned}$$

1.

To find \bar{y}

$$y_1 = \frac{20}{2} = 10 \text{ mm},$$

$$y_2 = 20 + \frac{60}{2} = 50 \text{ mm}$$

$$y_3 = 20 + 60 + \frac{20}{2} = 90 \text{ mm}.$$

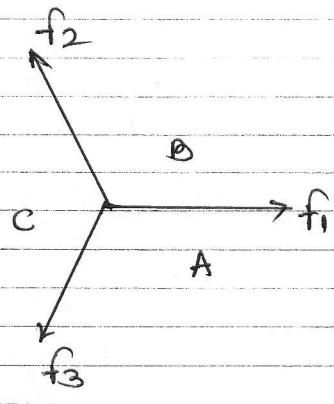
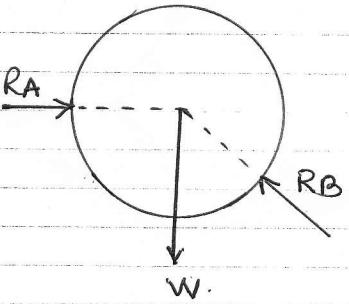
$$\therefore \bar{y} = \frac{A_1y_1 + A_2y_2 + A_3y_3}{A}$$

$$= \frac{(2000 \times 10) + (1200 \times 50) + (2000 \times 90)}{5200}$$

$$= 50 \text{ mm}.$$

1.

Centroid $(50 \text{ mm}, 50 \text{ mm})$.

5 f)	<p>i) scalar quantity</p> <p>a) It is a physical quantity having only magnitude but no direction.</p> <p>b) Examples: Mass, area, volume, density, time, speed, work etc.</p>	<p>Vector quantity</p> <p>a) It is a physical quantity having both magnitude and direction.</p> <p>b) Examples: Momentum, moment, velocity, force, etc.</p>	$\frac{1}{2}$ $\frac{1}{2}$
ii) Force	<p>a) It is an external agency which changes or tends to change the state of rest or uniform motion of a body.</p> <p>b) S.I unit of force is Newton.</p>	<p>Couple</p> <p>a) Two equal, unlike, parallel, non-collinear forces form a couple and it produces only rotary motion without linear motion.</p> <p>S.I unit of couple is N.m.</p>	$\frac{1}{2}$ $\frac{1}{2}$
iii) Space Diagram	<p>a) It shows exact location and direction of the forces with the help of Bow's notation.</p>	<p>Free Body Diagram</p> <p>a) If a body is separated from its surroundings, if it is called as free body and if all active & reactive forces acting on the body are shown, then it is called as free body diagram.</p>	$\frac{1}{2}$
	<p>b).</p> 	<p>b).</p> 	$\frac{1}{2}$

5 f). iv).	Resultant.	Equilibrium.
a)	It is a single force which can produce the same effect on the body as it is produced by all the forces acting together.	a) It is a single force which brings the system of forces or body in equilibrium when acts on the body with other forces.
b)	It creates the motion in the body.	b) It keeps the body at rest.

Q 6.

a).

Data: Effort wheel radius (R) = 15 cm.Load drum radius (r) = 20 cm.No. of teeth on worm wheel (T) = 50.Worm screw is single-threaded $n = 1$.

$$\text{Velocity Ratio} = \frac{R}{nr}$$

$$= \frac{15 \times 50}{1 \times 30}$$

$$= 25$$

2

To find: Load (w) when (P) = 30 N and efficiency (η) = 40%.

$$\% \eta = \frac{M \cdot A}{V \cdot R} \times 100$$

$$40 = \frac{M \cdot A}{25} \times 100$$

$$\therefore M \cdot A = 10.$$

$$M \cdot A = \frac{W}{P}$$

$$10 = \frac{W}{30}$$

$$W = 300 \text{ N.}$$

1

1

6b

Data:

$$\text{Load } (W) = 20\text{KN} = 20000\text{N.}$$

$$\text{Effort } (P) = 200 \text{ N.}$$

$$\text{Length of handle } (l) = 250 \text{ mm}$$

$$\text{Pitch of screw } (p) = 5 \text{ mm.}$$

$$V.R. = \frac{2\pi l}{p}$$

$$= \frac{2\pi \times 250}{5} = 314.16$$

$$M.A. = \frac{W}{P} =$$

$$= \frac{20,000}{200} = 100.$$

$$\% \text{ efficiency } (\eta) = \frac{M.A}{V.R.} \times 100.$$

$$= \frac{100}{314.16} \times 100 = 31.83$$

2

6c

Data: Load $(W_1) = 3.0\text{KN} = 3000\text{N.}$

$$\text{Effort } (P_1) = 60 \text{ N.}$$

$$\text{Load } (W_2) = 5.0\text{KN} = 5000\text{N.}$$

$$\text{Effort } (P_2) = 90 \text{ N.}$$

Law of machine - $P = mW + C.$

$$60 = m(3000) + C \dots (i)$$

$$90 = m(5000) + C \dots (ii)$$

Subtracting (i) from (ii)

$$30 = 2000m$$

$$\therefore m = \frac{30}{2000} = 0.015$$

 \therefore from (i) or (ii)

$$60 = 0.015(3000) + C$$

$$C = 15$$

1

1

6c

Continued - - - .

$$\therefore \text{Law of machine} - P = 0.015W + 15$$

1.

$$\text{Maximum Mechanical Advantage} = \frac{1}{m}$$

$$= \frac{1}{0.015} = 66.67$$

1.

6d).

$$\text{i) Maximum efficiency} = \frac{\text{Max. M. A.}}{V.R.} = \frac{1/m}{V.R.}$$

2.

$$\therefore \text{Maximum } \eta = \frac{1}{m \times V.R.}$$

Where m = slope of the line.

$V.R.$ = Velocity ratio.

ii) Irreversible machine:

A machine which is not capable of doing work in the reverse direction after the effort is removed, is called the irreversible.

or non-reversible machine.

The condition for the machine to be non-reversible is that its efficiency must be less than 50%.

2

6e)

Data: Dia of effort wheel (D) = 15 cm.

Dia. of Load. drum (d) = 10 cm.

No. of teeth on spur (T_s) = 60

No. of teeth on pinion (T_p) = 20.

Effort (P) = 60 N.

Load (W) = 1000 N.

6 e) Continued...

$$\text{Velocity Ratio (V.R)} = \frac{D}{d} \times \frac{T_{S_1}}{T_{P_1}} \times \frac{T_{S_2}}{T_{P_2}}$$

$$= \frac{15}{10} \times \frac{60}{20} \times \frac{60}{20} = 13.5$$

1.

$$\text{Mechanical Advantage (M.A)} = \frac{\text{Load}}{\text{Effort}} = \frac{W}{P}$$

$$= \frac{1000}{60} = 16.67.$$

1.

$$\% \text{ efficiency} = \frac{\text{M.A}}{\text{V.R}} \times 100$$

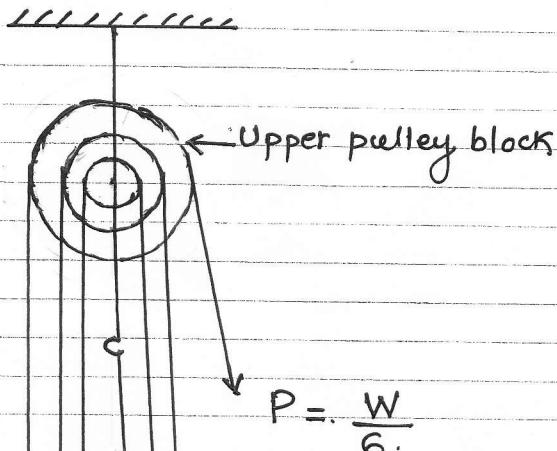
$$= \frac{16.67}{13.50} \times 100.$$

2.

$$\% \eta = 123.48$$

6 f.

Three Sheave
pulley blocks



3

Lower pulley block.

$$\text{M.A} = \frac{W}{P}$$

$$= \frac{W}{W/6} = 6$$

Assuming NO friction $\text{M.A} = \text{V.R}$.
 $\therefore \text{V.R} = 6$

1

33/33

Note for Examiner: In the above answers if students are writing some additional points or information which may be correct but not included in the model answer sheet. Examiners are requested to go through each answer carefully.