

### Tutorial 3 : Bifurcation theory -

Selected solutions + Extra comments (see end)

2D, 1 co-0.

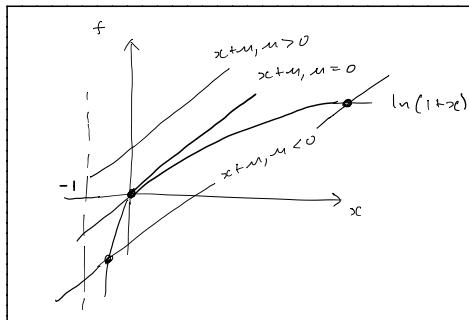
a) - c) : see lecture notes.

d). See later in this doc →

3. a).  $\dot{x} = \underbrace{m + x}_{} - \underbrace{\ln(1+x)}_{= f(x; m)} = f(x; m)$

FP:  $f(x; m) = 0$

graphically or using computer: (Harder case)



Note!

$$\frac{d}{dx} (\ln(1+x)) = \frac{1}{1+x}$$

at  $x=0$

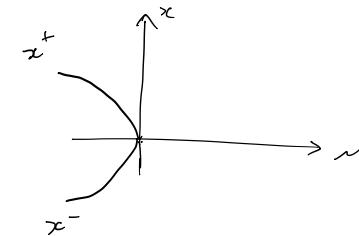
$$\frac{d}{dx} (\ln(1+x)) = 1$$

for  $x > 0$ ,  $< 1$ .

Expect : no sol<sup>n</sup> for  $m > 0$   
 1 sol<sup>n</sup> for  $m = 0$   
 2 sol<sup>n</sup> for  $m < 0$

saddle-node

Diagram without stability



Stability

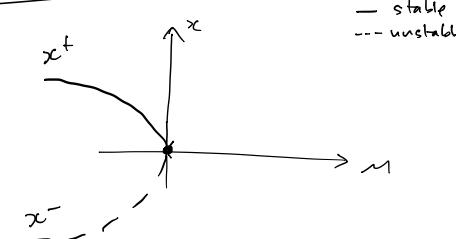
$$f(x; m) = m + x - \ln(1+x)$$

$$Df(x; m) = 1 - \frac{1}{1+x}$$

$$> 0 \left\{ \begin{array}{l} \text{if } 1 > \frac{1}{1+x} \\ \text{ie } 1+x > 1 \\ \text{ie } x > 0 \end{array} \right\} \text{unstable}$$

$$< 0 \left\{ \begin{array}{l} \text{if } 1 < \frac{1}{1+x} \\ \text{ie } x < 0 \end{array} \right\} \text{stable}$$

Diagram with stability



— stable  
--- unstable

$$3e). \quad \dot{x} = x + \frac{mx}{1+x^2}$$

(another harder-ish case)

I.FP.  $f(x; m) = 0$

$$x + \frac{mx}{1+x^2} = 0$$

$$\Leftrightarrow \frac{x(1+x^2+mx)}{1+x^2} = 0$$

$$\Leftrightarrow x(1+x^2+mx) = 0 \quad \& \quad 1+x^2 \neq 0$$

$$\Rightarrow \frac{x=0}{\text{always exists}} \quad \text{or} \quad \frac{1+x^2+mx=0}{x = \pm \sqrt{-m-1}}$$

Introduce  $\lambda = -m$  for convenience.

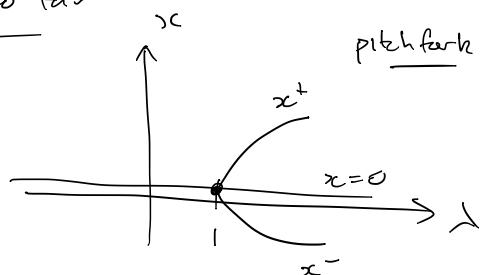
$$\Rightarrow x = \pm \sqrt{\lambda - 1}$$

$\lambda < 1 \Rightarrow$  no real soln ( $+x=0$ )

$\lambda = 1 \Rightarrow$  one real soln ( $+x=0$ )

$\lambda > 1 \Rightarrow$  two real soln ( $+x=0$ )

Diagram so far



### Stability

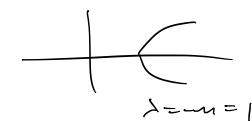
$$f = x + \frac{mx}{1+x^2}$$

$$Df = 1 + \frac{(1+x^2)m - mx \cdot 2x}{(1+x^2)^2} \quad (\text{quotient rule})$$

$$= 1 + \frac{m + x^2(m-2m)}{(1+x^2)^2}$$

$$= 1 + \frac{m(1-x^2)}{(1+x^2)^2}$$

Convenient points



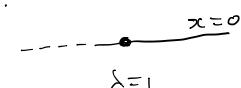
$$x = 0$$

$$Df = 1 + m = 1 - \lambda$$

$$> 0 \text{ if } \lambda < 1$$

$$< 0 \text{ if } \lambda > 1$$

So:



Next consider  $x^+$  &  $x^-$ .

$$Df(x, \lambda) = 1 - \lambda \frac{(1-x^2)}{(1+x^2)^2}$$

$x^+$  &  $x^-$  have same stability

( $x^2$  only in  $Df$ ).

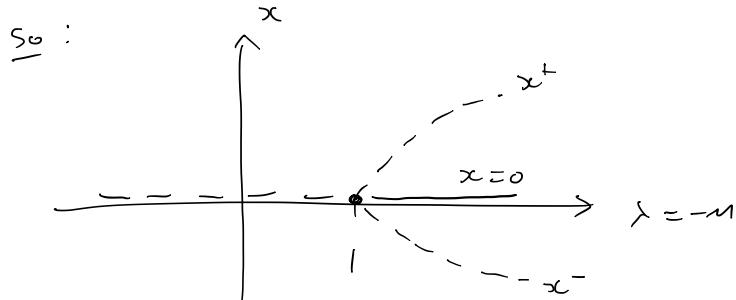
convenient:

$$x^+ = \sqrt{\lambda-1}$$

$$\text{set } x^+ = 1 \Rightarrow \lambda = 2$$

$$Df = 1 - \cancel{x}$$

$$= 1 > 0 \text{ unstable.}$$



pitchfork at  $\lambda = 1$   
ie  $\mu = -1$ .

Two-dim, 1-co-dim.

$$1. \quad \dot{x} = -y + \mu x + xy^2$$

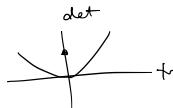
$$\dot{y} = x + \mu y - x^2$$

$$\text{FP: } (0,0) \Rightarrow \dot{x} = \dot{y} = 0 \checkmark$$

$$Df(0,0) = \begin{pmatrix} \mu & -1 \\ 1 & \mu \end{pmatrix} = A.$$

$$\text{tr} = 2\mu$$

$$\det = \mu^2 + 1$$



expect pure imag./Hopf  
for  $\text{tr} = 0 \Rightarrow \mu = 0$ .

charac. equation.

$$\lambda^2 - 2\mu\lambda + \mu^2 + 1 = 0$$

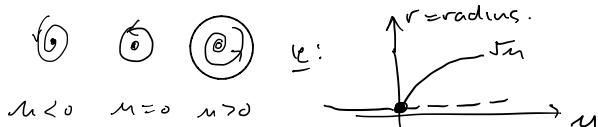
$$= (\lambda - \mu)^2 + 1 = 0$$

$$\lambda = \mu \pm i$$

$\left. \begin{array}{l} \mu < 0 \Rightarrow \text{stable spiral} \\ \mu = 0 \Rightarrow \text{pure im.} \\ \mu > 0 \Rightarrow \text{unstable spiral} \end{array} \right\}$

Crossing speed  $\left. \frac{d(\Re(\lambda))}{d\mu} \right|_{\mu=0} = 1 \neq 0$   
 $\Rightarrow$  non-degenerate.

Assume supercritical (should use computer to check):



## 2d. More complicated example

$$\dot{x} = \mu x + x^3 - x^5$$

$$\text{EP. } x(\mu + x^2 - x^4) = 0$$

$$x=0 \text{ or}$$

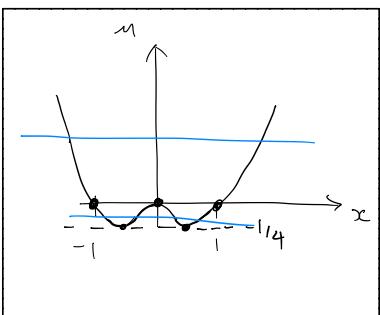
$$\mu + x^2 - x^4 = 0.$$

Answer to

think about  $\mu$  vs  $x$ :

$$\text{ie } \mu = \underline{x^4 - x^2} = x^2(x^2 - 1)$$

Shape

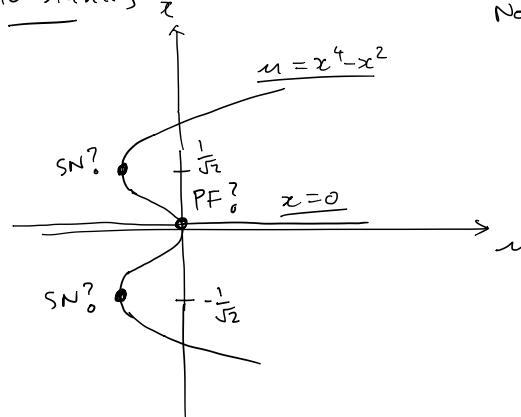


$$\text{minima: } \frac{d\mu}{dx} = 4x^3 - 2x = 0 \Rightarrow 2x(2x^2 - 1) = 0$$

$$\text{ie } x=0 \Rightarrow \mu=0$$

$$x = \pm \frac{1}{\sqrt{2}} \Rightarrow \mu = -\frac{1}{4}$$

w/o stability



Note: symmetric  
in  $x \rightarrow -x$ .

→ deformed pitchfork at origin

↳ expected since small higher power modification  
of  $\underline{\mu x + x^3 - (x^5)}$   
expect higher  
powers to drop  
out.

→ other bifurcations appear to  
be Saddle-nodes.

Stability

$$Df = \mu + 3x^2 - 5x^4$$

$$Df(x=0) = \mu$$

If  $\mu > 0 \Rightarrow Df > 0$  unstable  
 $\mu < 0 \Rightarrow Df < 0$  stable.

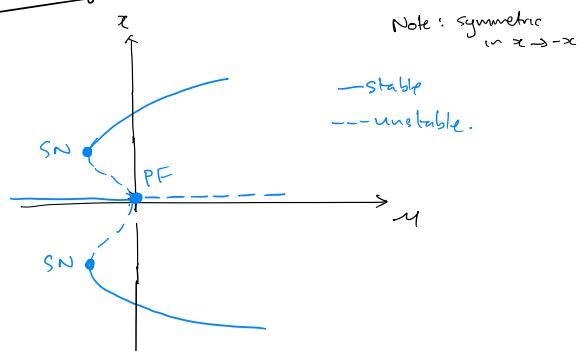
$$Df(\mu = x^4 - x^2) = x^4 - x^2 + 3x^2 - 5x^4$$

$$= 2x^2 - 4x^4$$

$$= 2x^2(1 - 2x^2)$$

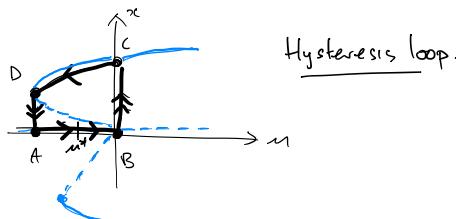
$\left. \begin{cases} > 0 & \text{if } x^2 < \frac{1}{2} \\ < 0 & \text{if } x^2 > \frac{1}{2} \end{cases} \right\}$  unstable  
stable

### Final diagram



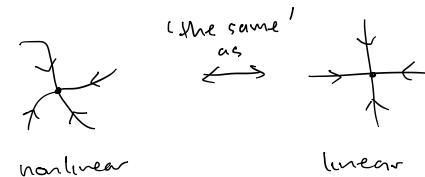
Notes:

- The pitchfork is subcritical: new solns are unstable.
- The diagram below illustrates hysteresis & jumps can occur here.
  - consider increasing  $u$  from  $u^*$  up to  $B$ ,  $u^* \in (A, B)$
  - the system will follow stable branches.
  - on  $A \rightarrow B$ ,  $x=0$  is stable.
  - when  $u > 0$  the system jumps to  $x^+$  or  $x^-$  (say  $x^+$ ).
  - when  $u$  is decreased back from its  $B$  value,  $x$  stays at  $x^+$ , rather than  $x=0$ , until  $D$ .
  - Thus we have a source of irreversibility/hysteresis: to return to  $(x, u) = (0, u^*)$ ,  $u^* \in (A, B)$ , we have to first decrease  $u$  all the way back past  $A$  (&  $u^*$ ) & then back up to  $u^*$ .
  - if once we go past  $B$ , we can't just decrease  $u$  back to  $u^*$  & get  $x=0$ .



### Comments on bifurcation theory & 'qualitative' analysis

Recall in analysing dynamics we were interested in connecting



the idea is that the dynamics are qualitatively the same near hyperbolic fixed points

→ they are 'the same' in the key/interesting respects

- ↳ ~~fixed points~~
- ↳ ~~stability~~

→ we don't care about the rest of the exact 'quantitative' details!

Formally, 'the same' usually means:

can continuously transform one to other & back. called a 'Homeomorphism'

informally: equivalent up to 'stretching'-etc.

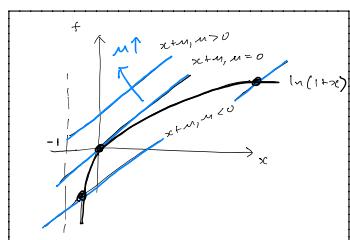
Similarly in bifurcation theory, ie near non-hyperbolic fixed points, we focused on the key 'qualitative' properties:

- number of fixed points
- stability

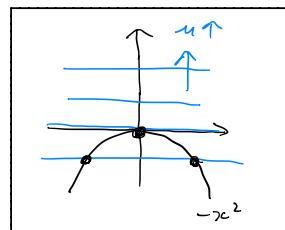
& how these change as a parameter varies

Two bifurcations are 'qualitatively the same' if they 'change' in the 'same way'.

Eg we saw more complicated cases give rise to the same types of bifurcation as in simple examples:



(the same)  
as  
↔



$$\text{FP: } x+m - \ln(1+x) = 0$$

i.e.  
 $y = x+m$   
 intersects  
 $y = \ln(1+x)$

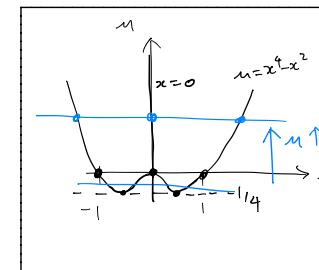
$$\text{FP: } m + x^2 = 0$$

i.e.  
 $y = m$   
 intersects  
 $y = -x^2$

The 'key property' is 'looking like': 

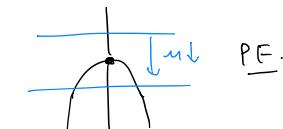
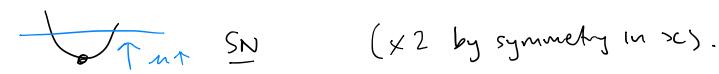
Similarly,  $\text{FP: } x(m+x^2-x^4)=0$

$\Rightarrow$



$$\begin{aligned} x &= 0 \\ \text{or} \\ m &= x^4 - x^2 \\ &= x^2(1-x^2) \end{aligned}$$

Has local regions that 'look like'!

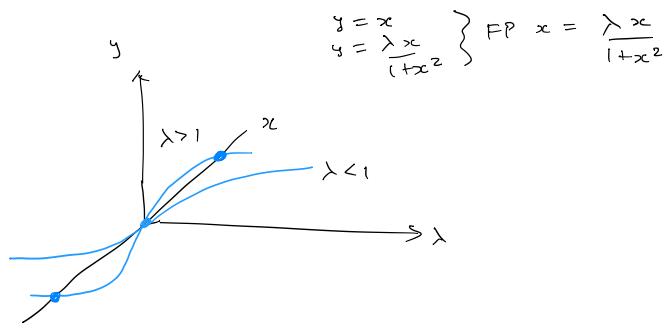


Exercise: sketch similar diagrams for

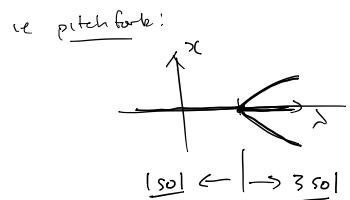
$$\boxed{f = x - \frac{\lambda x}{1+x^2}}$$

Hint: split into two functions of  $x$   
 one depending on  $\lambda$ , one  
 independent of  $\lambda$ , &  
 consider  $\lambda$  variations.

Partial solution



"Like"  
 $x - \lambda x^3 = 0$ :  
 $\lambda$  varies  
 $1 \leftrightarrow 3$  fixed points.



[ Could also deduce from ]  
Taylor series

Upshot: geometrically, the 'same' things  
are happening in the more complicated  
systems as happen in the 'simple'  
systems.