

# ENGSCI 213: MATHEMATICAL MODELLING 2SE

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# CURRENT TOPIC

## 2. *Discrete probability models* [3 lectures]

Discrete random variables and discrete probability distributions. Probability mass functions and cumulative distribution functions. Binomial and Poisson distributions.

# LECTURE 5

- Expectation and variance as reduced summaries of probability distributions/random variables
- The cumulative distribution as an alternative representation of the (whole) probability distribution

## RECAP: BERNOULLI TRIALS AND THE BINOMIAL DISTRIBUTION

A *Bernoulli random variable*  $Y$  is a random variable which only takes 2 values, 0 and 1 say.

The probability (mass) function is

$$P(Y = y) = f_Y(y) = \begin{cases} p, & \text{if } y = 1 \\ 1 - p, & \text{if } y = 0 \end{cases}$$

# RECAP: BERNOULLI TRIALS AND THE BINOMIAL DISTRIBUTION

A random experiment is called a *set of Bernoulli trials* if it consists of several trials such that

- Each trial has only *2 possible outcomes* (e.g. 1 or 0, often called "Success" or "Failure")
- The *probability of "Success"*  $p$  is the *same* for all trials
- The trials are *independent* i.e. "Success in trial  $i$ " doesn't affect the chances of "Success" in any other trial.

# RECAP: BERNOULLI TRIALS AND THE BINOMIAL DISTRIBUTION

A *Binomial* random variable  $X$  *summarises* the results of a *set of Bernoulli trials* as just a count of the number of success.

$X \sim \text{Bin}(n, p)$  if  $X$  is the number of successes out of  $n$  independent Bernoulli trials

## RECAP: BERNOULLI TRIALS AND THE BINOMIAL DISTRIBUTION

The probability (mass) function for a *Binomial* random variable is given by

$$P(X = x) = f_X(x) = \binom{n}{x} p^x (1 - p)^{n-x}$$

# SUMMARISING A PROBABILITY DISTRIBUTION/RANDOM VARIABLE

The *'full' information* about a probability distribution for a random variable  $X$  is contained in a tabulation or plot of the probability function  $P(X = x)$  for *each value  $x$* .

We could give a list of *'interesting features'* of the distribution - e.g. what values of  $X$  are 'most likely', how 'variable'  $X$ 's values are etc.



# SUMMARISING A PROBABILITY DISTRIBUTION/RANDOM VARIABLE

A full list of features would be enough to 'fully specify' the distribution. *In many cases, however, we want to only give 'reduced' summary of the full information* contained in the distribution e.g...

# SUMMARISING A PROBABILITY DISTRIBUTION/RANDOM VARIABLE

- a measure of the '*centre*' of the distribution (for example the 'mean' or 'mode' - called '*location*' measures)
- a measure of the '*spread*' of a distribution (e.g. the 'standard deviation' or 'variance' - called '*scale*' measures')

We will look at how to define some of these as *types of averages* ('moments')

# EXPECTATION

*The **expectation** or '**mean**' of a discrete random variable  $X$  is written  $E(X)$  and defined by*

$$E(X) := \sum_{x \in S_X} xP(X = x)$$

$E(X)$  is also often denoted by  $\mu_X$  and called the 'mean'. *It is not random* and not a function of a particular sample - it is a *property of the whole/'true'/'population' distribution*. It represents what value of  $X$  you expect to get 'on average'.

# EXPECTATION OF A CONDITIONAL RANDOM VARIABLE (CONDITIONAL EXPECTATION)

We can define a *conditional random variable* symbolised as  $X|Y = y$  and called 'X given Y' (i.e. 'Y' is taken as 'fixed' at a given value  $y$ ) which has a probability distribution

$$P((X|Y = y) = x) = P(X = x | Y = y)$$

This is just a name for a *new distribution over  $X$  values*, which takes into account 'background' information given by  $Y = y$ , i.e.  $P(X = x | y = y) \neq P(X = x)$  in general.

# EXPECTATION OF A CONDITIONAL RANDOM VARIABLE (CONDITIONAL EXPECTATION)

The *conditional expectation* of  $X|Y = y$  is then simply determined by substituting into our definition

$$E((X|Y = y)) := \sum_{x \in S_X} xP(X = x | y = y)$$

(Again - note that  $P(X = x | y = y)$  is just a name for a new distribution over  $X$  values)

# VARIANCE AND STANDARD DEVIATION

A measure of the '*variability*' of  $X$  values can be also defined as a type of expectation

The *variance* of a discrete random variable  $X$  is defined by

$$\begin{aligned} \text{Var}(X) &:= E[(x - E[x])^2] \\ &= \sum_{x \in S_X} (x - E(X))^2 P(X = x) \end{aligned}$$

(think: 'mean square difference'; note: we can also define 'higher' moments/averages)

# VARIANCE AND STANDARD DEVIATION

*The **standard deviation** is given by*

$$SD(X) = \sqrt{Var(X)}$$

# PROPERTIES OF MEAN

For constants  $a, b, c$

$$E(aX + bY + c) = aE(X) + bE(Y) + c$$

*(linearity)*

*If  $X$  and  $Y$  are **independent** random variables then  $E(XY) = E(X)E(Y)$  (not true in general!)*



# PROPERTIES OF VARIANCE

$$\begin{aligned} \text{Var}(X) &= E(X^2) - E(X)^2 \\ \text{Var}(aX + b) &= a^2 \text{Var}(X) \end{aligned}$$

*If  $X$  and  $Y$  are **independent** random variables then*

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) \text{ (not true in general!)}$$

# EXAMPLES

Some example calculations.

# CUMULATIVE DISTRIBUTION FUNCTION

Rather than giving a reduced summary, we can also represent our probability (mass) distribution in a *different but equivalent (no loss of info)* manner as a sort of '*running total*'

This is called the *cumulative distribution function* and is defined as...

# CUMULATIVE DISTRIBUTION FUNCTION

The *cumulative distribution* is the '*sum of probability up to  $x$* '.

It is often denoted by a capital  $F$  (c.f. the mass function)

$F_X(x)$  and given by

$$\begin{aligned} F_X(x) &:= P(X \leq x) \\ &= \sum_{x' \in S_X | x' \leq x} P(X = x') \end{aligned}$$

# **R EXAMPLES**

See lecture supplement for plots etc!