

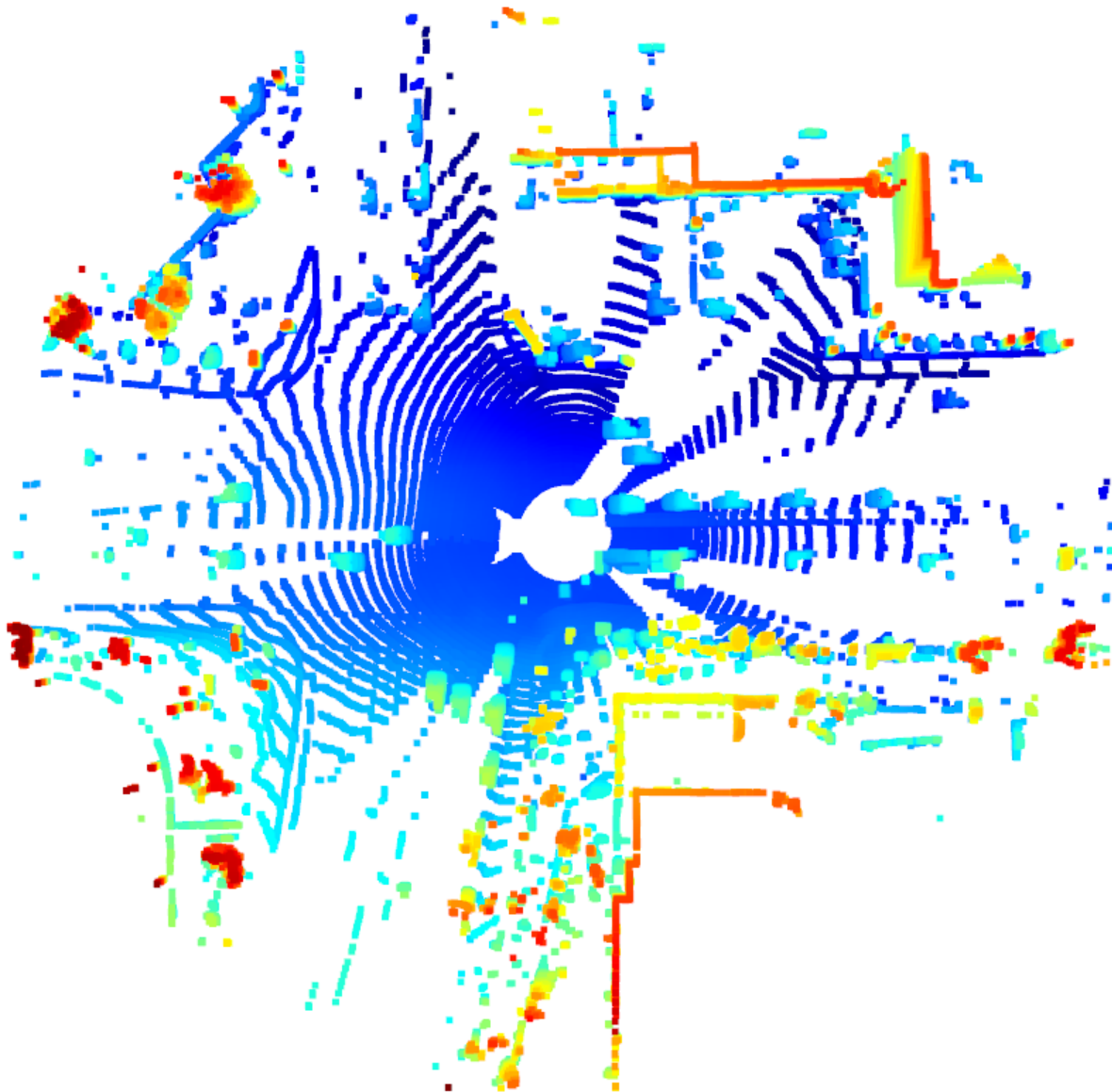
Sensor-Fusion Mid-Term Project Writeup

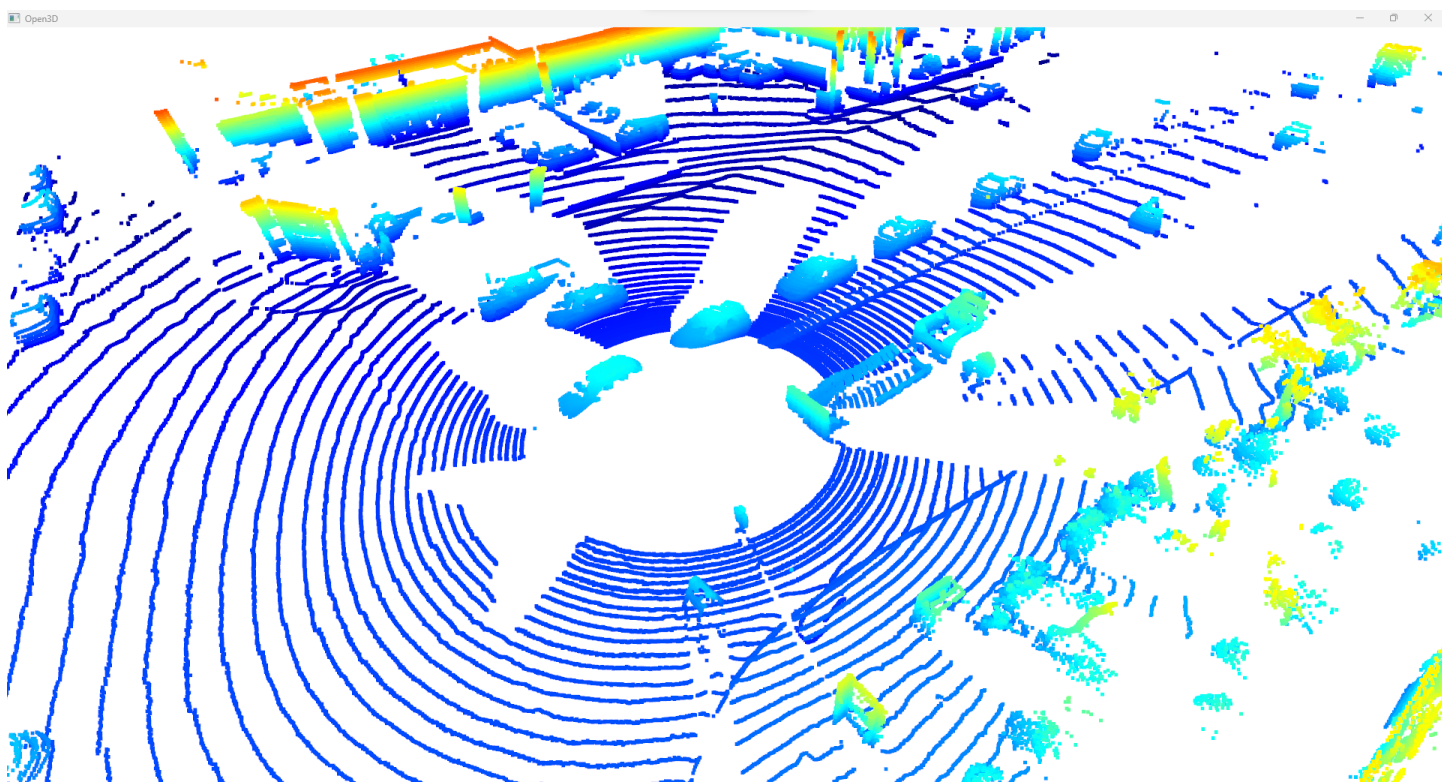
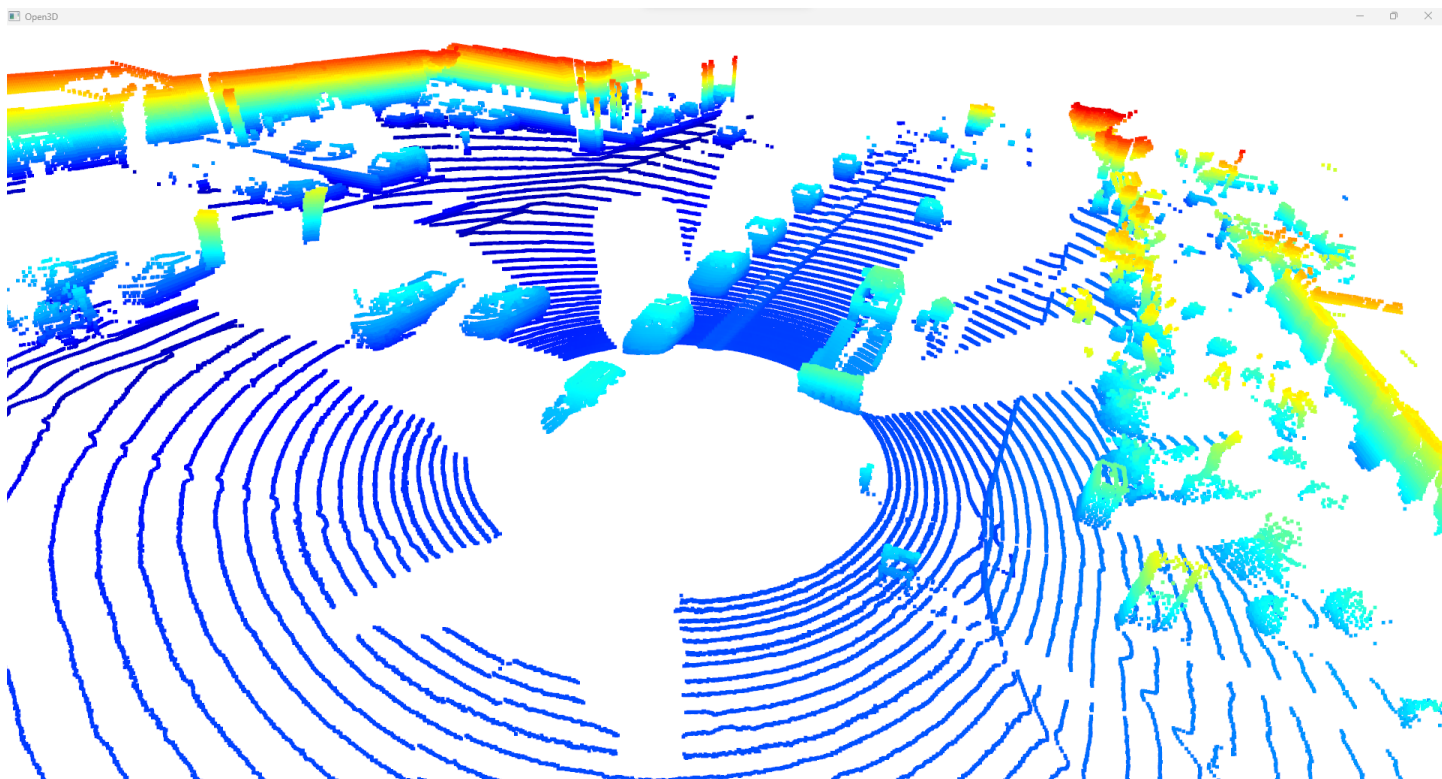
In the following pictures we can see many vehicles with many visibility degrees.

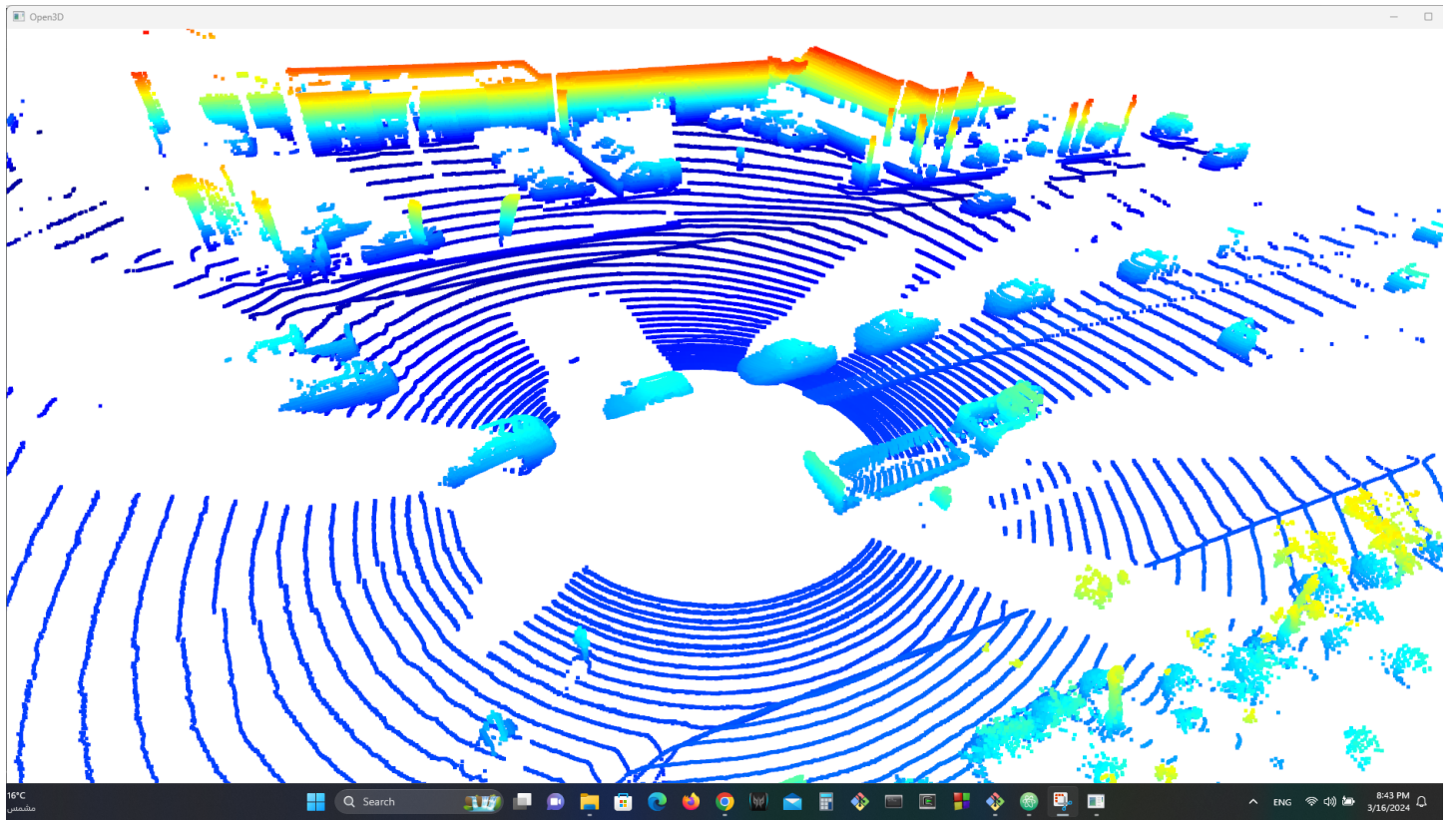
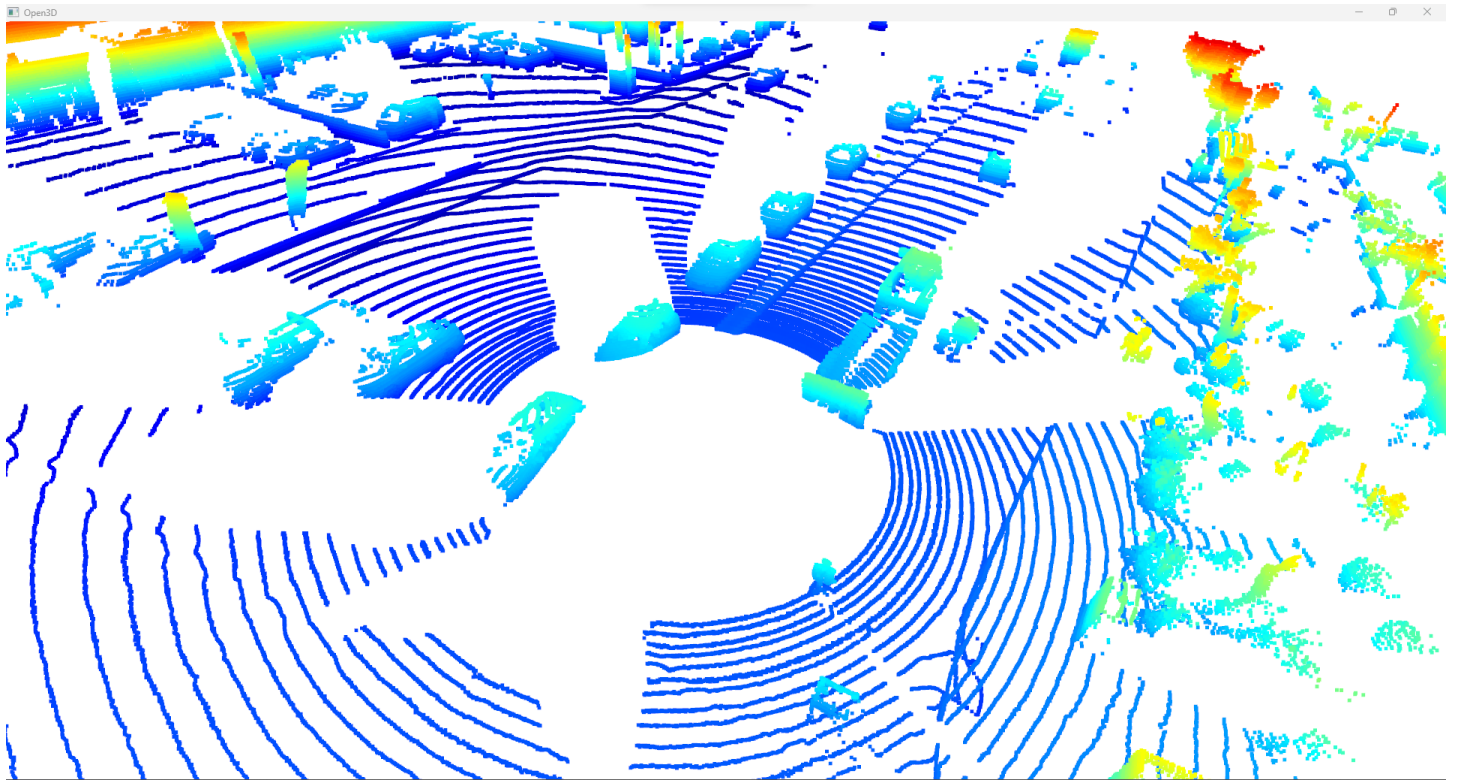
The most stable features we can identify in the point-cloud are:

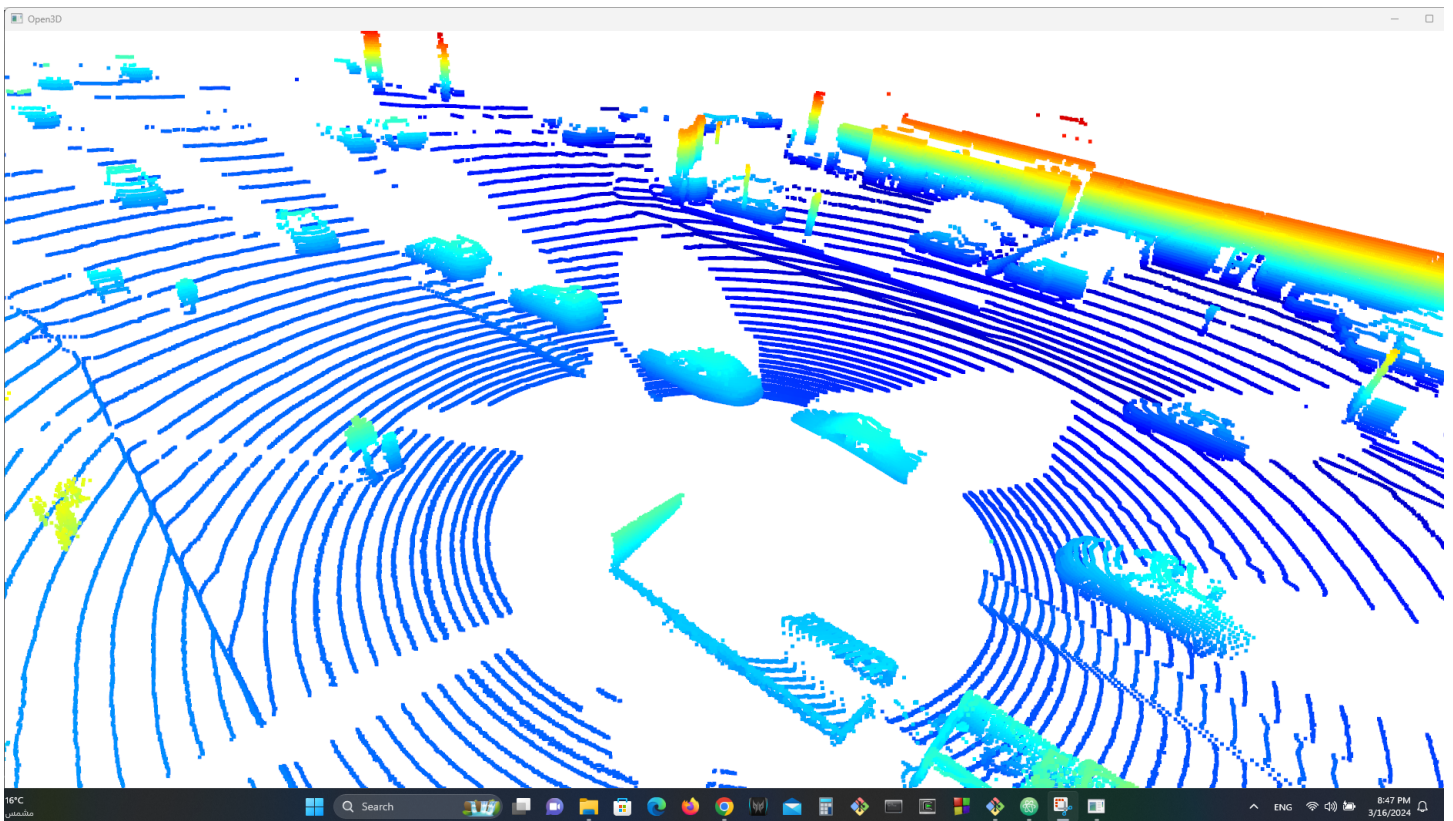
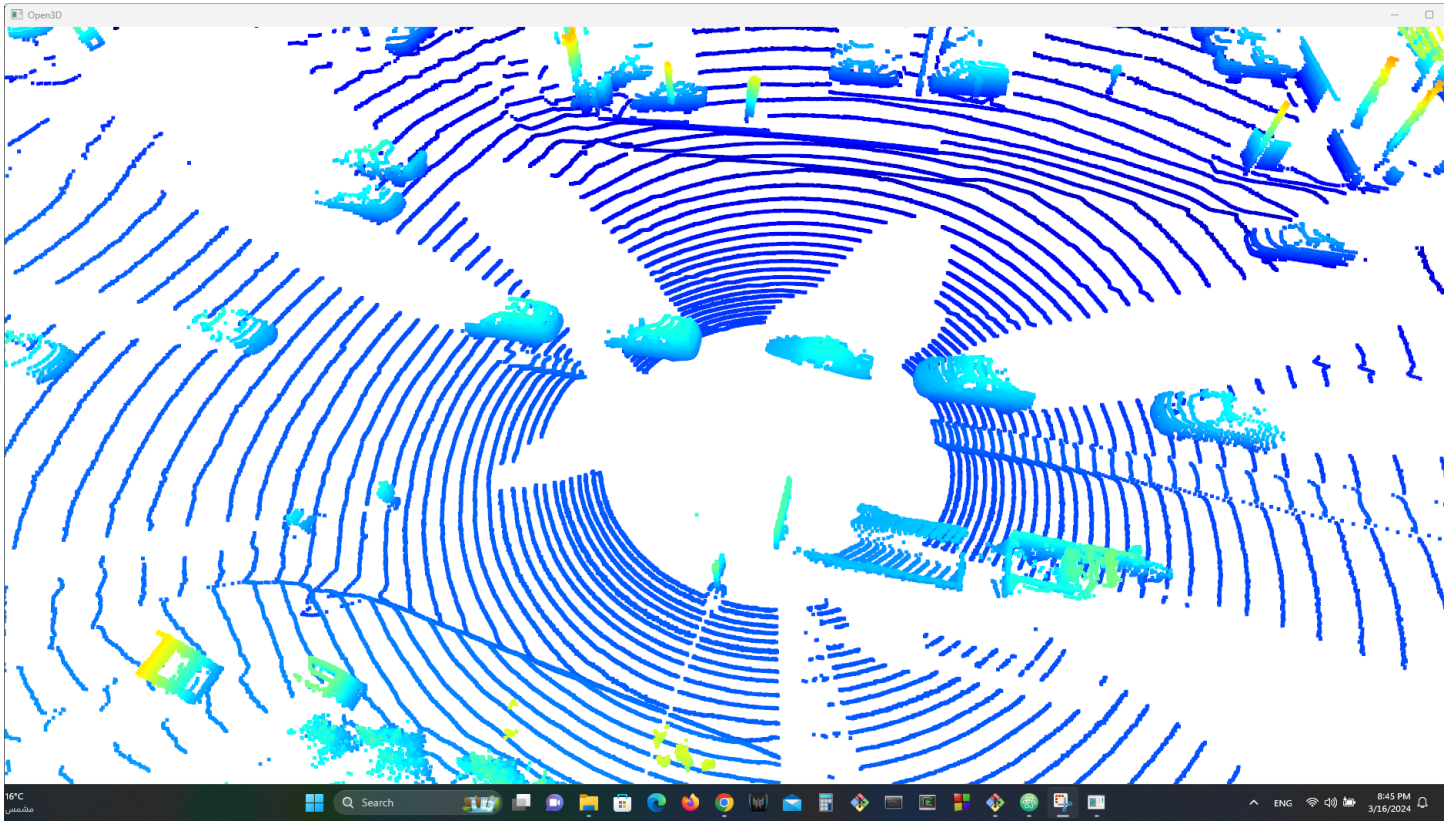
- the Vehicle Front & Rear Bumpers
- Front & back Glass wind-shields
- Side mirrors
- Vehicle wheels
- Side windows frames
- Vehicle cargo box (weather it's being trailed by the vehicle or attached to it)

Some features may appear or disappear depending on the angle of view.









Here also I'd like to share my results on the performance evaluation for the object detection:

