

THE PSEUDO-INVERSE OF A MATRIX

OMAR HIJAB

INTRODUCTION

The pseudo-inverse of a matrix is widely used in applied settings, most recently in Data Science. However, the pseudo-inverse is apparently not widely appreciated or presented in the typical undergraduate mathematics curriculum.

This note hopes to remedy this lapse. As the content has been well-understood for the better part of a century, the novelty, if any, is the presentation.

Every (square or non-square) matrix has a pseudo-inverse. The pseudo-inverse, often called the Moore-Penrose inverse [1], [3], [4], is a natural extension of the inverse of a matrix.

The pseudo-inverse of A is sometimes denoted A^+ [5]. However, because the inverse of A is denoted A^{-1} , we find the notation A^- more appropriate.

Let I be the identity matrix. The inverse of A , if it exists, is the unique matrix X satisfying

$$(1) \quad AX = I \quad \text{and} \quad XA = I.$$

If A has d rows and N columns, the *shape* of A is (d, N) . When (1) happens, both X and I have the same shape as A .

The residuals are

$$(2) \quad \|AX - I\|^2 \quad \text{and} \quad \|XA - I\|^2.$$

These are scalar functions of X . For the residuals to be well-defined, the shape of X must equal the shape of A^t . If A is non-square, the identity matrices I in the residuals are not the same shape.

If A is invertible, the unique minimizer of the residuals is $X = A^{-1}$. Given this, one approach to the pseudo-inverse is to seek a matrix X minimizing the residuals.

Let P_c be the projection onto the column space of A , and P_r the projection onto the row space of A . If A is not full-rank, then one of AX or XA can never equal I . Because of this, another approach to the pseudo-inverse is to modify (1) by seeking X satisfying

$$(3) \quad AX = P_c \quad \text{and} \quad XA = P_r.$$

This second approach suggests modifying the residuals to

$$(4) \quad \|AX - P_c\|^2 \quad \text{and} \quad \|XA - P_r\|^2,$$

yielding a third approach. In fact, using $P_c A = A$ and $A P_r = A$, it is easy to check that the residuals (4) differ from the residuals (2) by constants.

A solution X_0 of $f(X) = 0$ is *least norm* if $\|X_0\| \leq \|X\|$ for all solutions X of $f(X) = 0$. A minimizer X_0 of $f(X)$ is *least norm* if $\|X_0\| \leq \|X\|$ for all minimizers X of $f(X)$.

The *pseudo-inverse* A^- of A is the matrix X in the following Theorem. In particular, the shape of A^- equals the shape of A^t .

Theorem. *There is a unique least norm solution of $AX = P_c$, a unique least norm solution of $XA = P_r$, a unique least norm minimizer of $\|AX - I\|^2$, a unique least norm minimizer of $\|XA - I\|^2$, a unique solution of the Penrose axioms*

- A.** $AXA = A$,
- B.** $XAX = X$,
- C.** AX is symmetric,
- D.** XA is symmetric,

and the five matrices are equal.

Immediate consequences are $(A^-)^t = (A^t)^-$, and $P^- = P$ if P is a projection. A matrix U is orthogonal if

$$UU^t = I = U^tU,$$

equivalently if $U^{-1} = U^t$. A matrix U is *pseudo-orthogonal* if $U^- = U^t$.

Corollary. *A matrix U is pseudo-orthogonal iff UU^t is a projection iff U^tU is a projection.*

Examples are matrices with orthonormal or zero columns and matrices with orthonormal or zero rows. In particular, a zero matrix is pseudo-orthogonal.

Corollary. $P_c = AA^-$ and $P_r = A^-A$.

Recall a linear system $Ax = b$ is solvable iff b is in the column space of A . By the corollary, this happens iff $AA^-b = b$, exhibiting a solution $x = A^-b$ of $Ax = b$.

Let u, v, w be vectors. The dot product is denoted $v \cdot w$, and the tensor product of u, v is the matrix $u \otimes v$ satisfying $(u \otimes v)w = (v \cdot w)u$.

Let Q be a symmetric matrix of rank r and with eigenvalue decomposition

$$Q = \lambda_1 v_1 \otimes v_1 + \lambda_2 v_2 \otimes v_2 + \cdots + \lambda_r v_r \otimes v_r.$$

Here v_1, v_2, \dots, v_r are orthonormal vectors and $\lambda_1, \lambda_2, \dots, \lambda_r$ are nonzero.

Corollary. *The pseudo-inverse of Q is*

$$Q^- = \frac{1}{\lambda_1} v_1 \otimes v_1 + \frac{1}{\lambda_2} v_2 \otimes v_2 + \cdots + \frac{1}{\lambda_r} v_r \otimes v_r.$$

Let A be a matrix of rank r and with singular value decomposition

$$A = \sigma_1 u_1 \otimes v_1 + \sigma_2 u_2 \otimes v_2 + \cdots + \sigma_r u_r \otimes v_r.$$

Here u_1, u_2, \dots, u_r and v_1, v_2, \dots, v_r are orthonormal vectors, and $\sigma_1, \sigma_2, \dots, \sigma_r$ are positive.

Corollary. *The pseudo-inverse of A is*

$$A^- = \frac{1}{\sigma_1} v_1 \otimes u_1 + \frac{1}{\sigma_2} v_2 \otimes u_2 + \cdots + \frac{1}{\sigma_r} v_r \otimes u_r.$$

AN EXAMPLE

Let

$$A = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 6 & 7 & 8 & 9 & 10 \\ 11 & 12 & 13 & 14 & 15 \end{pmatrix}.$$

Using the Penrose axioms, one verifies

$$A^- = \frac{1}{150} \begin{pmatrix} -37 & -10 & 17 \\ -20 & -5 & 10 \\ -3 & 0 & 3 \\ 14 & 5 & -4 \\ 31 & 10 & -11 \end{pmatrix}.$$

If the rows of A are u, v, w , then $w = 2v - u$, so the rank of A is $r = 2$. Let a, b, c, d, e be the columns of A . We show

$$f = (-100, -3, 94), \quad g = (2, 1, 0)$$

span the column space of A .

To this end, recall $x = (t_1, t_2, t_3, t_4, t_5)$ solves $Ax = f$ iff

$$f = t_1a + t_2b + t_3c + t_4d + t_5e.$$

Using $x = A^-f$ and $x = A^-g$ to solve $Ax = f$ and $Ax = g$ and writing out the components of x , we obtain

$$\begin{aligned} 50f &= 1776a + 985b + 194c - 597d - 1388e, \\ 50g &= -28a - 15b - 2c + 11d + 24e. \end{aligned}$$

Similarly, let B be the matrix with columns f and g ,

$$B = (f, g) = \begin{pmatrix} -100 & 2 \\ -3 & 1 \\ 94 & 0 \end{pmatrix},$$

and solve $Bx = a, Bx = b, Bx = c, Bx = d, Bx = e$ using

$$B^- = \frac{1}{564} \begin{pmatrix} -1 & 2 & 5 \\ 185 & 194 & 203 \end{pmatrix}.$$

Writing out the components of x , we obtain

$$\begin{aligned} 94a &= 11f + 597g, & 47b &= 6f + 347g, & 94c &= 13f + 791g, \\ 47d &= 7f + 444g, & 94e &= 15f + 985g. \end{aligned}$$

This shows f, g span the column space of A .

Let

$$Q = AA^t = \begin{pmatrix} 55 & 130 & 205 \\ 130 & 330 & 530 \\ 205 & 530 & 855 \end{pmatrix}.$$

Since the column spaces of A and Q agree, Q has two nonzero eigenvalues λ .

To find λ , we restrict Q to its column space by inserting $u = sf + tg$ into $Qu = \lambda u$, leading to

$$(5) \quad Q(sf + tg) = \lambda(sf + tg).$$

Taking the dot product with f then with g leads to the 2×2 homogeneous linear system $(M - \lambda N) \begin{pmatrix} s \\ t \end{pmatrix} = 0$, where

$$M = \begin{pmatrix} f \cdot Qf & f \cdot Qg \\ g \cdot Qf & g \cdot Qg \end{pmatrix} = \begin{pmatrix} 4032830 & 62590 \\ 62590 & 1070 \end{pmatrix},$$

and

$$N = \begin{pmatrix} f \cdot f & f \cdot g \\ g \cdot f & g \cdot g \end{pmatrix} = \begin{pmatrix} 18845 & -203 \\ -203 & 5 \end{pmatrix}.$$

Setting the determinant of $M - \lambda N$ to zero yields

$$\lambda^2 - 1240\lambda + 7500 = 0,$$

which is solved by

$$\lambda_{\pm} = 620 \pm 10\delta, \quad \delta = \sqrt{3769}.$$

To solve for (s, t) , let

$$S = B^{-1}QB = \begin{pmatrix} 620 & 10 \\ 10\delta^2 & 620 \end{pmatrix}.$$

Let $b = QB \begin{pmatrix} s \\ t \end{pmatrix}$ and $x = \lambda \begin{pmatrix} s \\ t \end{pmatrix}$. Then (5) may be written $Bx = b$, which is solved by $x = B^{-1}b = S \begin{pmatrix} s \\ t \end{pmatrix}$. It follows (5) is implied by

$$S \begin{pmatrix} s \\ t \end{pmatrix} = \lambda \begin{pmatrix} s \\ t \end{pmatrix},$$

which is solved by

$$(s, t) = (1, \pm\delta).$$

Thus the corresponding eigenvectors of Q are $f \pm \delta g$. Let u_{\pm} be the unit vectors proportional to $f \pm \delta g$.

Since u_{\pm} correspond to distinct eigenvalues, they are orthogonal. Hence u_{\pm} form an orthonormal basis for the column space of A . From this, the eigenvalue decomposition of AA^t is

$$AA^t = \lambda_+ u_+ \otimes u_+ + \lambda_- u_- \otimes u_-.$$

Let $p = (-72, 11, 94, 177, 260)$, $q = (4, 3, 2, 1, 0)$. Then, as before, one checks p , q span the row space of A . Repeating the analysis with

$$Q = A^t A = \begin{pmatrix} 158 & 176 & 194 & 212 & 230 \\ 176 & 197 & 218 & 239 & 260 \\ 194 & 218 & 242 & 266 & 290 \\ 212 & 239 & 266 & 293 & 320 \\ 230 & 260 & 290 & 320 & 350 \end{pmatrix}, \quad B = (p, q) = \begin{pmatrix} -72 & 4 \\ 11 & 3 \\ 94 & 2 \\ 177 & 1 \\ 260 & 0 \end{pmatrix},$$

and $S = B^{-1}QB$, leads to the same S , the same nonzero eigenvalues, and the two eigenvectors $p \pm \delta q$ of Q . Let v_{\pm} be the unit vectors proportional to $p \pm \delta q$. Then v_{\pm} form an orthonormal basis for the row space of A , and

$$A^t A = \lambda_+ v_+ \otimes v_+ + \lambda_- v_- \otimes v_-.$$

Let $\sigma_{\pm} = \sqrt{\lambda_{\pm}}$. From this, it follows the singular value decomposition of A is

$$A = \sigma_+ u_+ \otimes v_+ + \sigma_- u_- \otimes v_-.$$

PROOF OF THE THEOREM

The proof is presented as a series of Lemmas, some of whose proofs are left to the reader. The euclidean space $\mathbf{R}^{N \times d}$ is the set of real matrices X with shape (N, d) . The dot product and norm squared in $\mathbf{R}^{N \times d}$ are

$$X \cdot Y = \text{trace}(X^t Y), \quad \|X\|^2 = X \cdot X.$$

If X is in $\mathbf{R}^{N \times d}$, then X^t is in $\mathbf{R}^{d \times N}$, and $\|X\|^2 = \|X^t\|^2$. If X is in $\mathbf{R}^{N \times d}$, A is in $\mathbf{R}^{d \times N}$, and B is in $\mathbf{R}^{d \times d}$, then $AX - B$ and $XA - B$ are in $\mathbf{R}^{d \times d}$ and $\mathbf{R}^{N \times N}$.

Since the row and null spaces of A are orthogonal, $AV = 0$ iff $P_r V = 0$. Since $V \cdot A^t AV = AV \cdot AV = \|AV\|^2$, $AV = 0$ iff $A^t AV = 0$. Let X be in $\mathbf{R}^{N \times d}$.

Lemma 1. $\|X\|^2 \leq \|X + V\|^2$ for all V in $\mathbf{R}^{N \times d}$ satisfying $AV = 0$ iff $P_r X = X$.

Let $f(X)$ be a scalar function defined on a euclidean space \mathcal{E} of matrices. If X_0 in \mathcal{E} satisfies $f(X_0) \leq f(X)$ for all X in \mathcal{E} , then X_0 is a *minimizer* of $f(X)$ on \mathcal{E} . When \mathcal{E} is not specified, we assume $\mathcal{E} = \mathbf{R}^{N \times d}$.

A function $f(X)$ is *proper* on \mathcal{E} if for every sequence X_n in \mathcal{E} ,

$$\|X_n\| \rightarrow \infty \implies f(X_n) \rightarrow +\infty.$$

If $f(X)$ is continuous and proper on \mathcal{E} , a basic calculus result [2] guarantees the existence of a minimizer of $f(X)$ on \mathcal{E} .

Lemma 2. Given A and B in $\mathbf{R}^{d \times N}$ and $\mathbf{R}^{d \times d}$, there is a minimizer X_0 of $\|AX - B\|^2$ satisfying $P_r X_0 = X_0$.

Proof. Let \mathcal{E} be the subspace of $\mathbf{R}^{N \times d}$ of matrices X satisfying $P_r X = X$. We show $f(X) = \|AX - B\|^2$ is proper on \mathcal{E} , arguing by contradiction.

If $f(X)$ is not proper on \mathcal{E} , there is a sequence of matrices X_n in \mathcal{E} with $f(X_n)$ bounded and $X_n \rightarrow \infty$, hence with $\|AX_n\| \leq c$ for some finite c .

Let $r_n = \|X_n\|$ and $X'_n = X_n/r_n$. Since $\|X'_n\| = 1$, X'_n is a bounded sequence, hence a subsequence X'_n converges to some X' . By continuity, $\|X'\| = 1$ and $P_r X' = X'$. Since

$$\|AX'\| = \lim_{n \rightarrow \infty} \|AX'_n\| = \lim_{n \rightarrow \infty} \frac{\|AX_n\|}{r_n} \leq \lim_{n \rightarrow \infty} \frac{c}{r_n} = 0,$$

$AX' = 0$, hence $P_r X' = 0$, hence $X' = 0$, which contradicts $\|X'\| = 1$.

Thus there is a minimizer X_0 of $f(X)$ on \mathcal{E} . For X in $\mathbf{R}^{N \times d}$, $P_r X$ is in \mathcal{E} , and $f(X) = f(P_r X)$, hence X_0 is a minimizer of $f(X)$. \square

Lemma 3. There is a unique least norm minimizer X of $\|AX - B\|^2$, and the least norm minimizer X of $\|AX - B\|^2$ equals the unique solution of $A^t AX = A^t B$, $P_r X = X$.

Proof. Since $f(X) = \|AX - B\|^2$ is convex, X is a minimizer of $f(X)$ iff the derivative of $f(X + tV)$ at $t = 0$ vanishes for all V . Writing this out, $(AX - B) \cdot AV = 0$ for all V , which happens iff $A^t AX = A^t B$.

By Lemma 2, there is a minimizer X satisfying $P_r X = X$. If X and X_0 are minimizers, then $V = X - X_0$ satisfies $A^t AV = 0$, hence $AV = 0$. By Lemma 1, a minimizer X is least norm iff $P_r X = X$, hence there is a least norm minimizer.

If X and X_0 are both least norm minimizers, then $P_r V = V$, so $V = 0$, establishing uniqueness of the least norm minimizer. Since $f(X)$ is quadratic, the steps are reversible, establishing uniqueness of the solution of $A^t AX = A^t B$, $P_r X = X$. \square

Lemma 4. *If X_0 is the least norm minimizer of $\|AX - I\|^2$, then X_0B is the least norm minimizer of $\|AX - B\|^2$.*

Lemma 5. *The least norm minimizer X of $\|AX - I\|^2$ equals the unique least norm solution of $AX = P_c$.*

Proof. It is enough to show $A^t AX = A^t$ iff $AX = P_c$. If $P = AX$ and $A^t AX = A^t$, then $A = P^t A$. Right-multiplying by X yields $P = P^t P$. It follows P satisfies $P^t = P$ and $P^2 = P$, hence P is a projection.

Since $A = PA$ and $P = AX$, the column spaces of A and P agree, hence $P = P_c$, showing $AX = P_c$. Conversely, if $AX = P_c$, then $AXA = P_c A = A$, so $A^t(AX) = (AXA)^t = A^t$. \square

Lemma 6. *There is a unique least norm minimizer X of $\|XA - I\|^2$, and the least norm minimizer X of $\|XA - I\|^2$ equals the unique least norm solution of $XA = P_r$.*

Lemma 7. *X is the least norm minimizer of $\|AX - I\|^2$ iff X satisfies the Penrose axioms.*

Proof. If X is the least norm minimizer of $\|AX - I\|^2$, then $AX = P_c$ and $P_r X = X$. Thus $AXA = P_c A = A$, yielding **A**. Since P_c is symmetric, we also have **C**. From Lemma 4, XP_c is the least norm minimizer of $\|AX - P_c\|^2$. Since $\|AX - I\|^2$ and $\|AX - P_c\|^2$ differ by a constant, their minimizers agree, hence they have the same least norm minimizer. This shows $XP_c = X$, or $XAX = X$, yielding **B**. Let $P = XA$. Then $P_r P = P$. By **A**, $A(I - P) = 0$, so $P_r(I - P) = 0$. This shows $P = P_r$, hence P is symmetric, obtaining **D**.

Conversely, assume X satisfies the Penrose axioms. Then **A** and **C** imply $A^t AX = (AXA)^t = A^t$, hence X is a minimizer of $\|AX - I\|^2$. If $P = XA$, **B** and **D** imply P is a projection, hence $P = A^t X^t$. By **A**, $A^t = (AXA)^t = PA^t$. Since $P = A^t X^t$ and $A^t = PA^t$, the column spaces of P and A^t agree, hence the column space of P equals the row space of A . Thus $P = P_r$, hence $P_r X = PX = XAX = X$. Hence X is the least norm minimizer of $\|AX - I\|^2$. \square

Lemma 8. *The least norm minimizer of $\|XA - I\|^2$ equals the least norm minimizer of $\|AX - I\|^2$.*

Proof. If X is the least norm minimizer of $\|XA - I\|^2$, X^t is the least norm minimizer of $\|A^t X - I\|^2$, hence X^t satisfies the Penrose axioms for A^t . But X^t satisfies the Penrose axioms for A^t iff X satisfies the Penrose axioms for A . Thus X is the least norm minimizer of $\|AX - I\|^2$. \square

REFERENCES

- [1] Bjerhammar, A.: Application of calculus of matrices to method of least squares; with special references to geodetic calculations. *Trans. Roy. Inst. Tech. Stockholm* **49** (1951)
- [2] Hijab, O.: *Math for Data Science*. Springer, Cham (2025)
- [3] Moore, E.H.: On the reciprocal of the general algebraic matrix. *Bulletin of the American Mathematical Society* **26**, 394–395 (1920)
- [4] Penrose, R.: A generalized inverse for matrices. *Proceedings of the Cambridge Philosophical Society* **51**, 406–413 (1955)
- [5] Wikipedia: Moore-Penrose inverse. https://en.wikipedia.org/wiki/Moore-Penrose_inverse