

BaseOpenCVStreamer

```
graph BT; A[sofa::rgbdtracking::RealSenseVirtualCam] --> B[sofa::rgbdtracking::RealSenseStreamer]; B --> C[BaseOpenCVStreamer];
```

sofa::rgbdtracking  
::RealSenseStreamer

sofa::rgbdtracking  
::RealSenseVirtualCam