



Paper



Code & Dataset



Project Page

Endo-4DGX: Robust Endoscopic Scene Reconstruction and Illumination Correction with Gaussian Splatting

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Motivations

- The endoscopic workspace is **dynamic** and **unpredictable**; **illumination changes** quickly due to factors such as the **occlusion**, **reflections**, **low-light** and **over-exposure**.
- Due to the rapid variation of the surgical environment, **2D restoration methods fail to produce consistent results** in real-time, leading to corrupted results.
- Existing 3DGS-based illumination correction solutions** for general scenes, they are not applicable for surgical scenarios due to the **lack of ability** to model the **sub-area** and **spatial-level illumination changes** for deformable tissue.

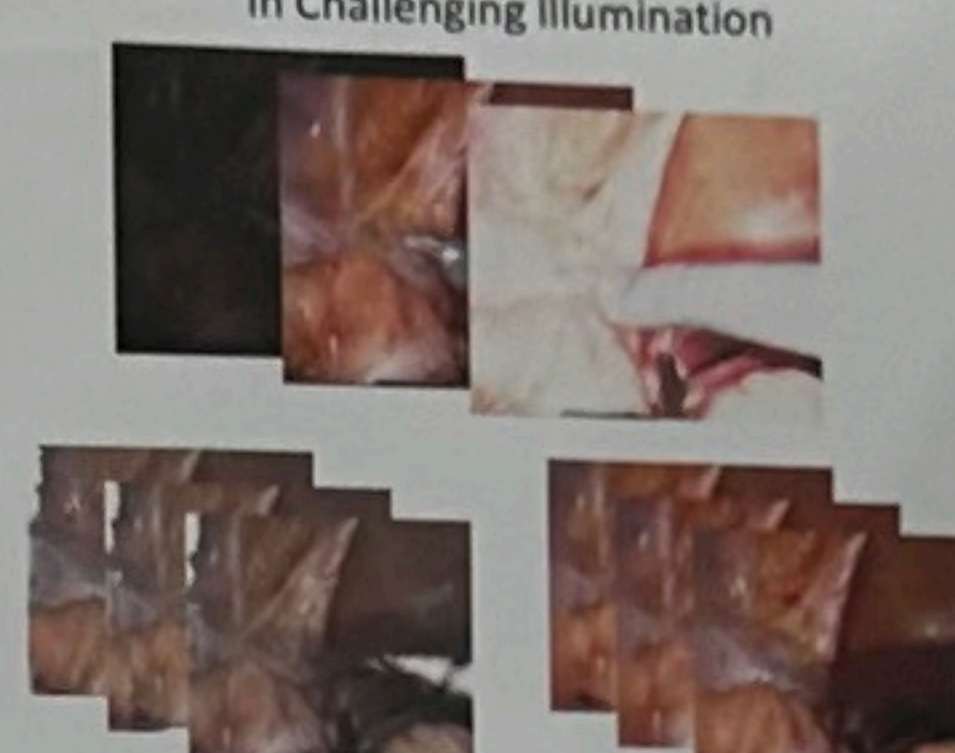
3D Reconstruction in Challenging Illumination (Occlusion, Reflection, Over/Under exposure)



4DGS
PSNR: 26.98

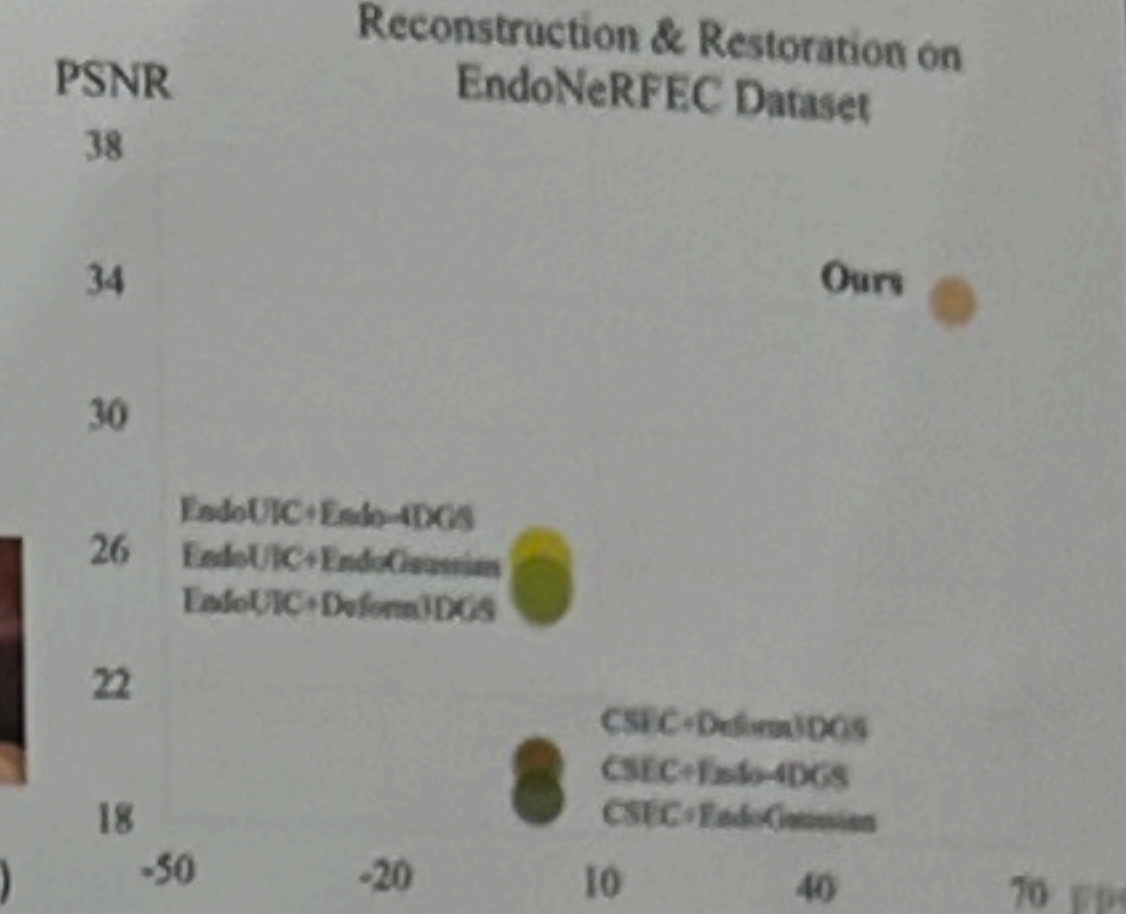
Ours (Corrected)
PSNR: 32.70

Reconstruction & Restoration in Challenging Illumination



4DGS+2D Restoration
PSNR: 23.05

Ours (Corrected)
PSNR: 34.06



Key Contributions

- Endo-4DGX, a novel endoscopic reconstruction method with illumination adaptive Gaussian Splatting. Endo-4DGX achieves illumination correction and reconstruction in challenging uneven illumination, providing robust reconstruction result that align well with the need of challenging surgical environment.
- We introduce a **region-aware enhancement** module to resolve uneven lighting problems at the Gaussian level. Our region-aware module decodes the view specific embedding to model the **sub-area lightness changes**, refining the sub-area illumination changes for the small tissue areas.
- We design a **spatial-aware adjustment** module for spatial-level lightness adjustment, which focuses on the illumination refinement of the whole image. Our spatial-aware adjustment account for the rapid changes of the whole endoscope view, ensuring consistency for robust reconstruction.
- We provide **experiment results on three real surgical datasets** with Endo-4DGX for surgical scene reconstruction under challenging illumination, ensuring the robustness for robot-assisted surgery.

Methodology

4D Gaussians Representation:

$$\mathcal{G}' = \{\mu', r', s', o', c\}$$

Appearance and Depth Rendering with Rasterization of 4DGS:

$$C(x) = \sum_i \alpha_i c_i \prod_{j=1}^{l-1} (1 - \alpha_j),$$

$$D(x) = \sum_i \alpha_i d_i \prod_{j=1}^{l-1} (1 - \alpha_j),$$

Illumination Classification for Illumination Embedding Initialization:

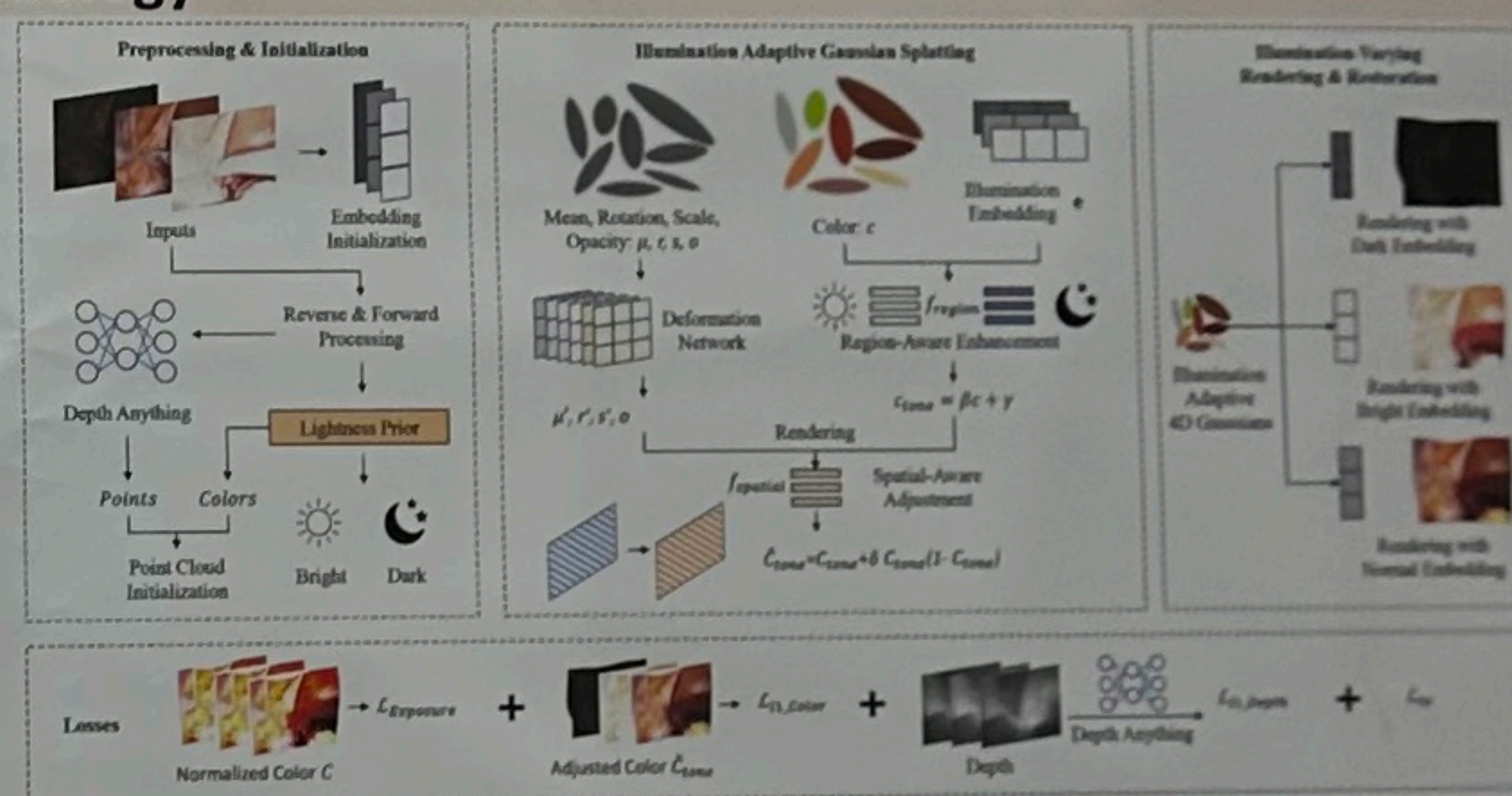
$$IC(I) = \begin{cases} \text{Bright}, & \text{if } \text{mean}(I) > \text{mean}(\mathbf{p}) \\ \text{Dark}, & \text{if } \text{mean}(I) \leq \text{mean}(\mathbf{p}) \end{cases}$$

Region-Aware Enhancement:

$$c_{\text{tone}} = \beta \cdot c + \gamma_r \cdot \{\beta \cdot \gamma\} = f_{\text{region}}(c, e)$$

Spatial-Aware Adjustment:

$$\tilde{c}_{\text{tone}} = c_{\text{tone}} + \delta \cdot c_{\text{tone}}(1 - c_{\text{tone}}) \mid \delta = f_{\text{spatial}}(e)$$



Experiment Results

| Method | FPS↑ | GPU↓ | Pulling PSNR↑ | SSIM↑ | LPIPS↓ | Cutting PSNR↑ | SSIM↑ | LPIPS↓ |
|-------------------------------|------|--------|---------------|-------|--------|---------------|-------|--------|
| EndoUIC [1]+Deform3DGS [25] | 2.02 | 8 GB | 27.15 | 0.892 | 0.180 | 22.74 | 0.842 | 0.231 |
| EndoUIC [1]+Endo-4DGS [11] | 2.0 | 12 GB | 28.79 | 0.929 | 0.097 | 23.30 | 0.890 | 0.116 |
| EndoUIC [1]+EndoGaussian [15] | 2.03 | 12 GB | 27.49 | 0.904 | 0.244 | 23.05 | 0.867 | 0.257 |
| CSEC [14]+Deform3DGS [25] | 1.29 | 3.8 GB | 20.03 | 0.855 | 0.194 | 20.18 | 0.809 | 0.251 |
| CSEC [14]+Endo-4DGS [11] | 1.27 | 7.8 GB | 19.89 | 0.876 | 0.140 | 20.14 | 0.838 | 0.186 |
| CSEC [14]+EndoGaussian [11] | 1.29 | 7.8 GB | 18.63 | 0.838 | 0.283 | 19.41 | 0.800 | 0.339 |
| DarkGS* [30] | 524 | 2 GB | 6.04 | 0.001 | 0.655 | 6.66 | 0.002 | 0.635 |
| Gaussian-DK* [27] | 41.0 | 2 GB | 13.13 | 0.705 | 0.528 | 10.26 | 0.543 | 0.579 |
| WildGaussians [13] | 108 | 2 GB | 15.28 | 0.724 | 0.431 | 17.71 | 0.752 | 0.376 |
| Ours | 61 | 6.5 GB | 34.94 | 0.946 | 0.048 | 34.06 | 0.950 | 0.043 |

Quantitative results on EndoNeRF-EC Dataset for illumination correction.

| Method | EndoNeRF-EC | | | | StereoMIS | | | | C3VD | | | |
|-------------------|---------------|---------------|-------|-------|------------|------------|------------------|--------------------|---------------|---------------|-------|-------|
| | Pulling PSNR↑ | Cutting PSNR↑ | SSIM↑ | SSIM↑ | P1_1 PSNR↑ | P1_2 PSNR↑ | Cecum t2_b PSNR↑ | Sigmoid t2_a PSNR↑ | Pulling PSNR↑ | Cutting PSNR↑ | SSIM↑ | SSIM↑ |
| Deform3DGS [25] | 30.63 | 0.922 | 26.86 | 0.831 | 28.55 | 0.846 | 32.28 | 0.887 | 33.07 | 0.898 | 27.92 | 0.749 |
| Endo-4DGS [11] | 28.51 | 0.909 | 26.88 | 0.850 | 26.98 | 0.817 | 32.48 | 0.890 | 30.55 | 0.878 | 32.03 | 0.830 |
| EndoGaussian [15] | 12.93 | 0.327 | 12.49 | 0.289 | 27.61 | 0.841 | 32.20 | 0.896 | 5.10 | 0.001 | 5.99 | 0.001 |
| Ours | 39.95 | 0.966 | 39.64 | 0.968 | 28.73 | 0.853 | 32.70 | 0.899 | 33.55 | 0.904 | 33.13 | 0.838 |

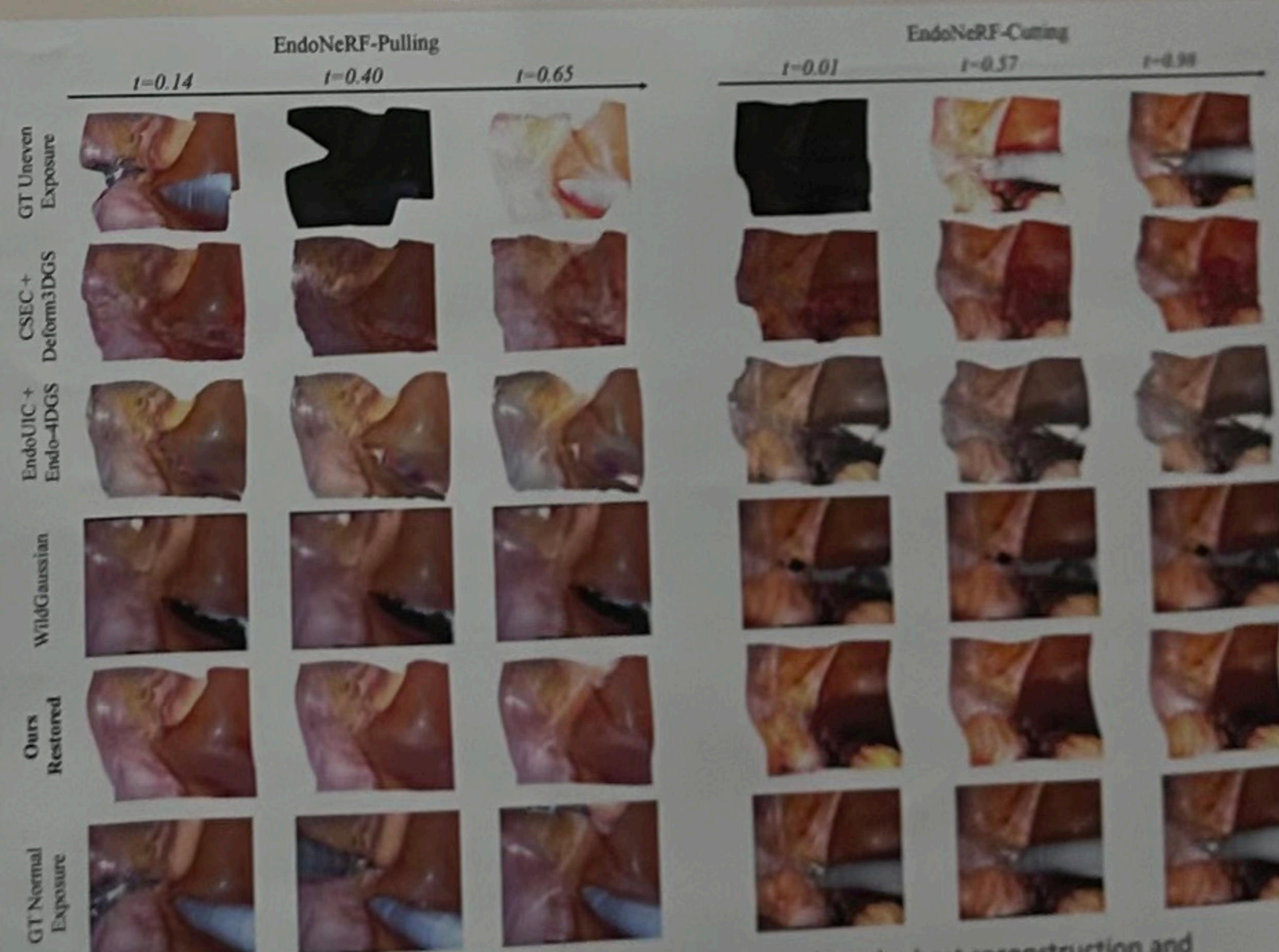
Quantitative results on StereoMIS and C3VD datasets for uneven illumination scene reconstruction. Our method surpasses all state-of-the-art methods.

| Illumination Embedding | Region-Aware Enhancement | Spatial-Aware Adjustment | Pulling | | Cutting | | Pulling-Correction | | Cutting-Correction | |
|------------------------|--------------------------|--------------------------|---------|-------|---------|-------|--------------------|-------|--------------------|-------|
| | | | PSNR↑ | SSIM↑ | PSNR↑ | SSIM↑ | PSNR↑ | SSIM↑ | PSNR↑ | SSIM↑ |
| × | × | × | 26.95 | 0.892 | 27.59 | 0.856 | 22.88 | 0.770 | 20.53 | 0.734 |
| × | ✓ | × | 10.40 | 0.535 | 14.64 | 0.624 | 12.66 | 0.579 | 13.96 | 0.712 |
| × | × | ✓ | 24.56 | 0.840 | 30.53 | 0.895 | 23.46 | 0.815 | 19.93 | 0.692 |
| × | ✓ | × | 39.64 | 0.965 | 37.33 | 0.957 | 34.79 | 0.945 | 32.66 | 0.933 |
| ✓ | ✓ | × | 34.87 | 0.952 | 34.52 | 0.939 | 28.44 | 0.910 | 25.09 | 0.865 |
| × | ✓ | ✓ | 14.36 | 0.627 | 31.06 | 0.925 | 21.94 | 0.804 | 24.26 | 0.740 |
| ✓ | ✓ | ✓ | 39.95 | 0.966 | 39.64 | 0.968 | 34.94 | 0.946 | 34.06 | 0.950 |

Ablation experiments on EndoNeRF-EC dataset

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Reconstruction Results



Qualitative Result on EndoNeRF-EC Dataset. Our method provides the best reconstruction and illumination correction results for challenging illumination.

Conclusions

- We propose **Endo-4DGX**, an illumination-aware Gaussian Splatting framework for endoscopic 3D reconstruction and real-time rendering under challenging lighting conditions.
- The framework include illumination correction of dynamic lighting scenarios by unifying **region-aware** illumination enhancement and **spatial-aware** illumination adjustment, promoting the **precision** and **safety** of surgical procedures.