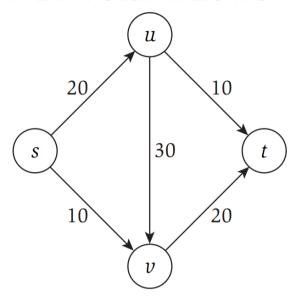


READING



Sections 7.1-7.3, 7.5 of the textbook.

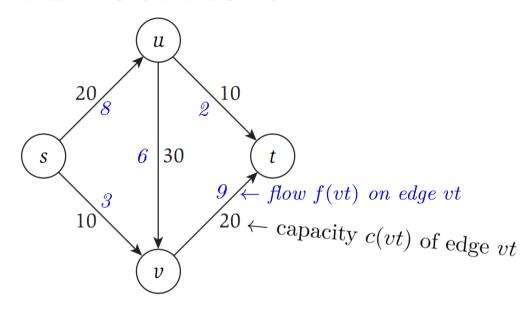
Suggested. As many exercises as you can do from Chapter 7 of the textbook.



We are given a directed graph G = (V, E) with a source node s, a sink node t and capacities on the edges.

Goal. Find the maximum "flow" from s to t without violating the capacity constraints.

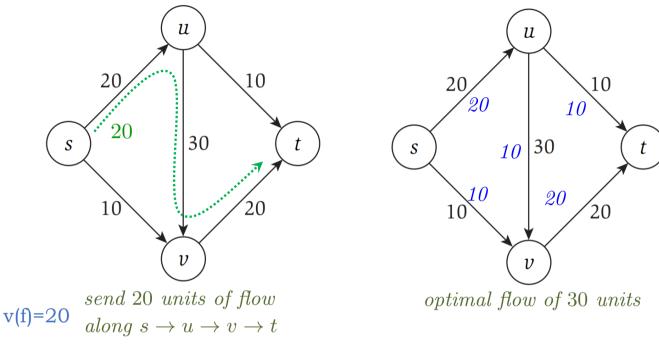
Intuition: Material flowing through a transportation network; material originates at source and is sent to sink.



A flow is described by a function $f: E \mapsto \mathbb{R}^+$ s.t.

- (Capacity constraints) $0 \le f(e) \le c(e) \leftarrow capacity \ of \ edge \ e$
- (Flow conservation) $\forall v \in V \setminus \{s, t\}, \sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e).$

The value of a flow
$$f$$
 is: $\nu(f) = \sum_{e \text{ out of } s} f(e) = \sum_{e \text{ into } t} f(e)$.



IS THIS AN OPTIMAL SOLUTION?

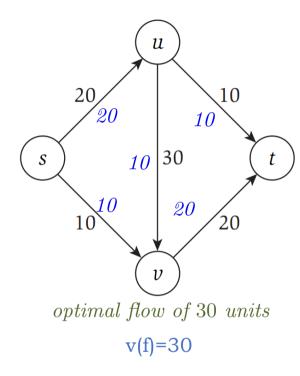
Goal. Find the maximum "flow" from s to t without violating the capacity constraints.

Would simple greedy approaches work here?

May not produce an antimal solution

PUSH THE MAXIMUM YOU CAN
ON THE HIGHEST CAPACITY EDGE

May not produce an optimal solution.



Goal. Find the maximum "flow" from s to t without violating the capacity constraints.

HOW CAN WE FORMALIZE WHAT WE JUST DID?

FORD FULKERSON ALGORITHM

Residual Graph.

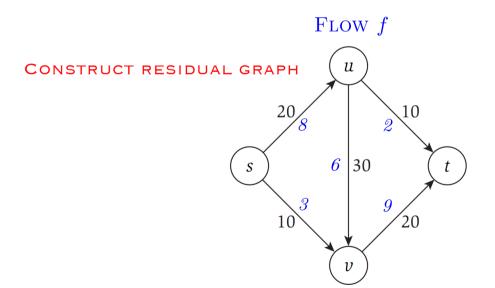
Given a flow network G, and a flow f on G, we define the residual Graph G_f of G with respect to f as follows:

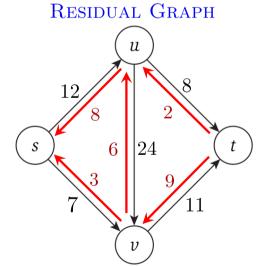
- The node set of G_f is the same as that of G
- For each edge e = (u, v) of G on which $f(e) < c_e$, there are $c_e f(e)$ "leftover" units of capacity on which we could try pushing flow forward. So we include the edge e = (u, v) in G_f , with a capacity of $c_e f(e)$. We will call edges included this way forward edges.
- For each edge e = (u, v) of G on which f(e) > 0, there are f(e) units of flow that we can "undo" if we want to, by pushing flow backward. So we include the edge e' = (v, u) in G_f , with a capacity of f(e). Note that e' has the same ends as e, but its direction is reversed. We will call edges included this way backward edges.

Residual Graph.

In residual graph corresponding to a flow f, for every edge $u \to v$ in the original network, we have:

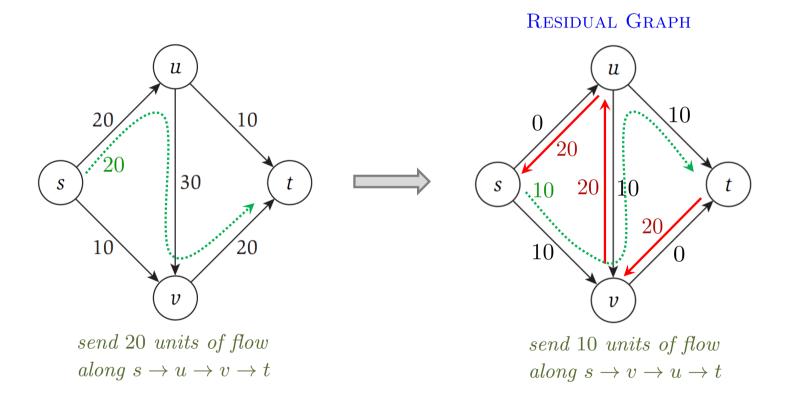
- an edge $u \to v$ with capacity c(e) f(e)
- an edge $v \to u$ with capacity f(e)





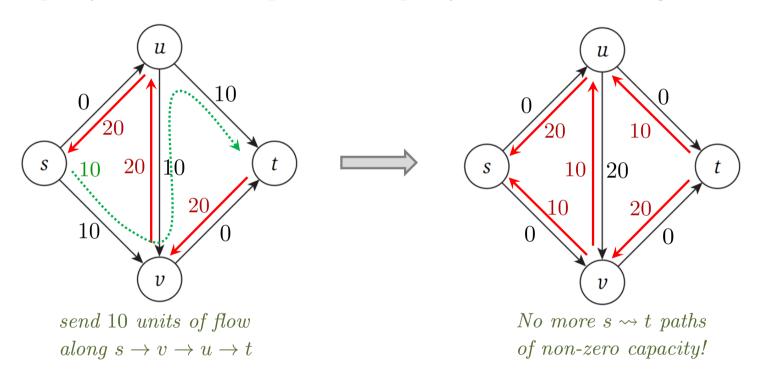
Ford Fulkerson Algorithm.

Repeatedly find a path in G_f from s to t in which all edges have some leftover capacity and send flow equal to the capacity of the bottleneck edge.



Ford Fulkerson Algorithm.

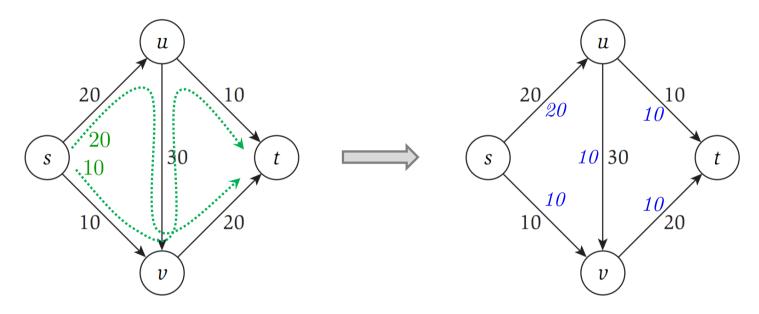
Repeatedly find a path in G_f from s to t in which all edges have some leftover capacity and send flow equal to the capacity of the bottleneck edge.



Total flow: 30 units.

Ford Fulkerson Algorithm.

Repeatedly find a path in G_f from s to t in which all edges have some leftover capacity and send flow equal to the capacity of the bottleneck edge.



The paths along which we sent flows are called *augmenting paths*.

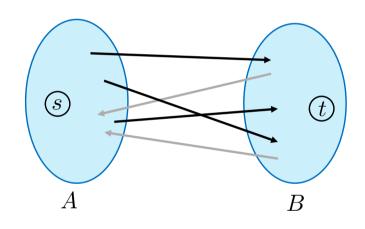
EXERCISE

NETWORK FLOWS

```
Max-Flow
                   Initially f(e) = 0 for all e in G
                   While there is an s-t path in the residual graph G_f
                       Let P be a simple s-t path in G_f
LOOPS OVER
                       f' = augment(f, P)
PATHS IN THE
                       Update f to f'
RESUDUAL
                       Update the residual grapgh G_f to be G_f'
GRAPH
                   EndWhile
                   Return f
               augment(f, P):
                  Let b = bottleneck(P, f)
                  For each edge (u,v) P
                       If e = (u, v) is a forward edge then
USES THE PATH
                           increase f(e) in G by b
TO FORM THE
                       Else ((u, v) is a backward edge, and let e = (u, v))
FLOW
                           decrease f(e) in G by b
                       Endif
                   Endfor
                   Return(f)
```

OBSERVATION

An **s-t cut** in the graph is a partition (A, B) of the vertices into two sets A and B s.t. $s \in A$ and $t \in B$.



The capacity of the s-t cut, denoted c(A, B) is the sum of the capacities of the edges going from A to B.

Observation. No flow can have value more than the capacity of an s-t cut.