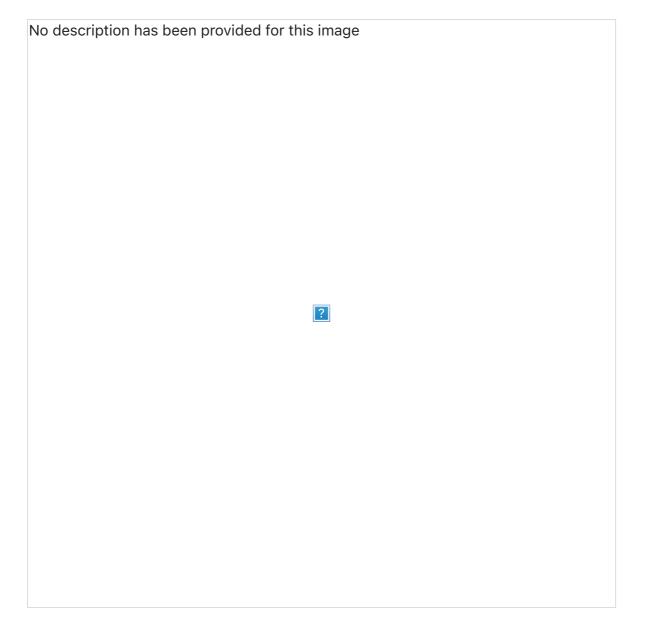
Import Libraries

```
In [1]: import torch
import torch.nn as nn
import torch.optim as optim
import torchvision
from torchvision import datasets, transforms
import matplotlib.pyplot as plt
import numpy as np
```

Configuration

```
In [2]: DEVICE = torch.device("cuda" if torch.cuda.is_available() else "mps")
```

Loss Function



Discriminator Model

```
In [3]: class Discriminator(nn.Module):
```

```
def __init__(self):
    super(Discriminator, self).__init__()
    self.conv1 = nn.Conv2d(1,64,5,stride=2,padding=2)
    self.conv2 = nn.Conv2d(64,128,5,stride=2,padding=2)
    self.leaky_relu = nn.LeakyReLU(0.3)
    self.drop out = nn.Dropout(0.3)
    self.fc = nn.Linear(6272,1)
def forward(self, input):
    # 28 x 28 - (1 Channel)
    output = self.conv1(input)
    output = self.leaky_relu(output)
    output = self.drop_out(output)
    # 14 x 14 - (64 Channel)
    output = self.conv2(output)
    output = self.leaky_relu(output)
    output = self.drop out(output)
    # 7 x 7 - (128 Channel)
    output = output.view(output.size(0),1,-1)
    # 6272 Vector
    output = self.fc(output)
    output = torch.sigmoid(output)
    return output
```

Generator Model

```
In [4]: class Generator(nn.Module):
            def __init__(self):
                super(Generator, self).__init__()
                self.fc = nn.Linear(100,7*7*256,bias=False)
                self.bn0 = nn.BatchNorm1d(7*7*256)
                self.conv1 = nn.ConvTranspose2d(256,128,4,stride=2,padding=1,bias
                self.bn1 = nn.BatchNorm2d(128)
                self.conv2 = nn.ConvTranspose2d(128,64,4,stride=2,padding=1,bias=
                self.bn2 = nn.BatchNorm2d(64)
                self.conv3 = nn.ConvTranspose2d(64,1,3,stride=1,padding=1,bias=Fa
                self.leaky relu = nn.LeakyReLU(0.3)
                self.tanh = nn.Tanh()
            def forward(self, input):
                # 100 Vector
                output = self.fc(input)
                output = self.bn0(output)
                output = self.leaky_relu(output)
                # 7*7*256 Vector
                output = output.view(output.size(0),256,7,7)
                #7 \times 7 - (256 Channel)
                output = self.conv1(output)
                output = self.bn1(output)
                output = self.leaky relu(output)
                # 7 x 7 - (128 Channel)
                output = self.conv2(output)
                output = self.bn2(output)
                output = self.leaky_relu(output)
```

```
# 14 x 14 - (64 Channel)
output = self.conv3(output)
output = self.tanh(output)
# 28 x 28 - (1 Channel)
return output
```

Model Initialization

```
In [5]: discriminator = Discriminator().to(DEVICE)
generator = Generator().to(DEVICE)
```

Training Data

```
In [6]: train_batch_size = 64

transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,), (0.5,)) # Normalizing with mean and std devi
])

train_data = torchvision.datasets.FashionMNIST('./FashionMNIST/',train=Tr
    train_loader = torch.utils.data.DataLoader(train_data,batch_size=train_ba
```

Training Setup

```
In [7]: criterion = nn.BCELoss().to(DEVICE)
lr = 0.0001
real_label_value = 1.0
fake_label_value = 0.0

discriminator_optimizer = optim.Adam(discriminator.parameters(), lr=lr, b
generator_optimizer = optim.Adam(generator.parameters(), lr=lr, betas=(0.
```

Training

```
In [8]:
    num_epochs = 50
    generator_loss_history = []
    discriminator_loss_history = []
    fixed_noise = torch.randn(16, 100, device=DEVICE)

for epoch in range(num_epochs):

    discriminator.train()
    generator_total_loss = 0.0
    discriminator_total_loss = 0.0
    total_real_discriminator = 0.0
    total_fake_discriminator = 0.0
    n = 0

    for i, (real_batch, _) in enumerate(train_loader):
        batch_size = real_batch.size(0)
        n += batch_size
```

```
# Discriminator Forward on Real Batch
    real batch = real batch.to(DEVICE)
    discriminator.zero_grad()
    discriminator_output = discriminator(real_batch).view(-1)
    total real discriminator += torch.sum(discriminator output)
    real_label = torch.full((batch_size,), real_label_value, dtype=to
    # Discriminator Loss on Real Batch
    discriminator_real_loss = criterion(discriminator_output,real_lab
    discriminator real loss.backward()
    # Generator Forward on Latent Noise Vector
    noise = torch.rand(batch_size,100).to(DEVICE)
    fake_batch = generator(noise).to(DEVICE)
    # Discriminator Forward on Fake Batch
    discriminator_output = discriminator(fake_batch.detach()).view(-1
    total_fake_discriminator += torch.sum(discriminator_output)
    fake_label = torch.full((batch_size,), fake_label_value, dtype=to
    # Discriminator Loss on Fake Batch
    discriminator_fake_loss = criterion(discriminator_output,fake_lab
    discriminator fake loss.backward()
    # Discriminator Backward
    discriminator_loss = discriminator_real_loss.item() + discriminat
    discriminator_optimizer.step()
    # Generator Backward
    generator.zero grad()
    discriminator_output = discriminator(fake_batch).view(-1)
    generator_loss = criterion(discriminator_output, real_label)
    generator_loss.backward()
    generator_optimizer.step()
if i == len(train_loader) - 1:
    generator_loss_history.append(generator_loss)
    discriminator_loss_history.append(discriminator_loss)
if (epoch*10==0 \text{ or } epoch == 49) \text{ and } i == len(train_loader) - 1:
    generator.eval()
    output = generator(fixed noise)
    output = output.view(16, 28, 28)
    output = output.detach().cpu().numpy()
    generator_loss_history.append(generator_loss)
    discriminator_loss_history.append(discriminator_loss)
    plt.figure(figsize=(5, 5))
    print("Epoch: ", epoch+1)
    for i in range(16):
        current_output = output[i]
        plt.subplot(4, 4, i + 1)
        plt.imshow(output[i], cmap='gray')
        plt.axis('off')
        plt.title(f'Image {i + 1}')
```

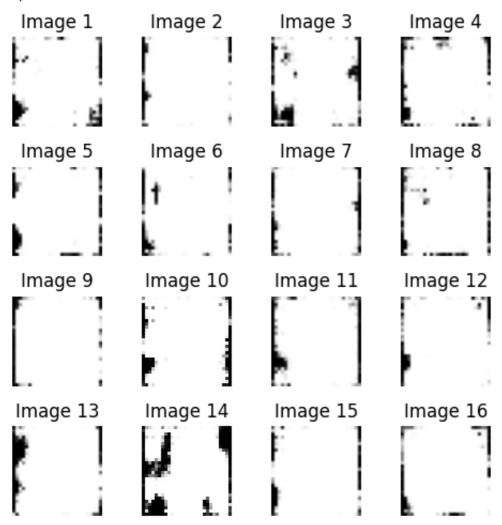
```
plt.tight_layout() # Adjust layout
plt.show()

print(f"Epoch: {epoch+1}, G_Loss: {generator_loss:.4f}, D_Loss: {
    f"Average D(x): {total_real_discriminator/n:.4f}, Average D(G(z))
```

/ext3/miniconda3/lib/python3.12/site-packages/torch/autograd/graph.py:744: UserWarning: Plan failed with a cudnnException: CUDNN_BACKEND_EXECUTION_PL AN_DESCRIPTOR: cudnnFinalize Descriptor Failed cudnn_status: CUDNN_STATUS_ NOT_SUPPORTED (Triggered internally at ../aten/src/ATen/native/cudnn/Conv_ v8.cpp:919.)

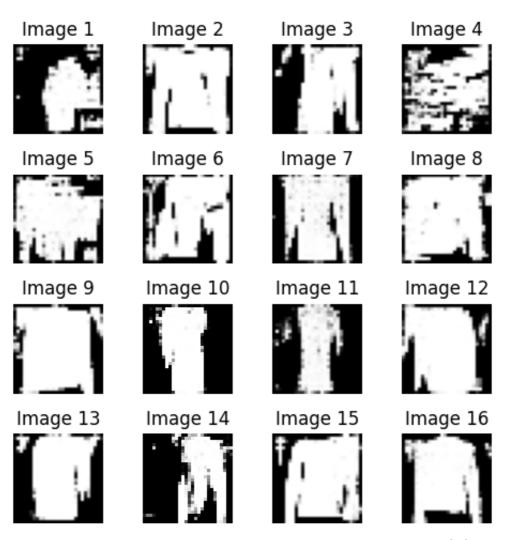
return Variable._execution_engine.run_backward(# Calls into the C++ en gine to run the backward pass

Epoch: 1



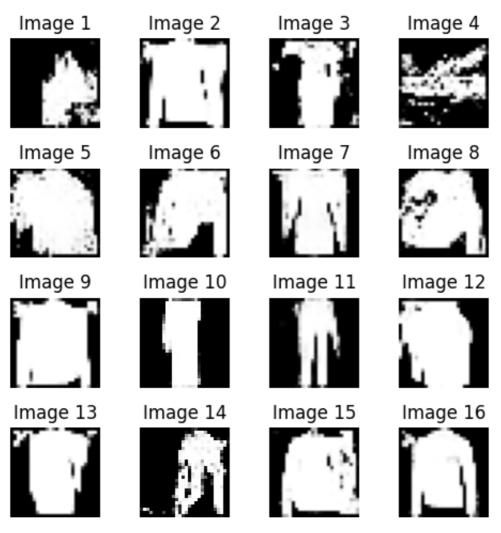
Epoch: 1, G_Loss: 0.7871, D_Loss: 1.3156, Average D(x): 0.5478, Average D(

G(z)): 0.4549 Epoch: 11



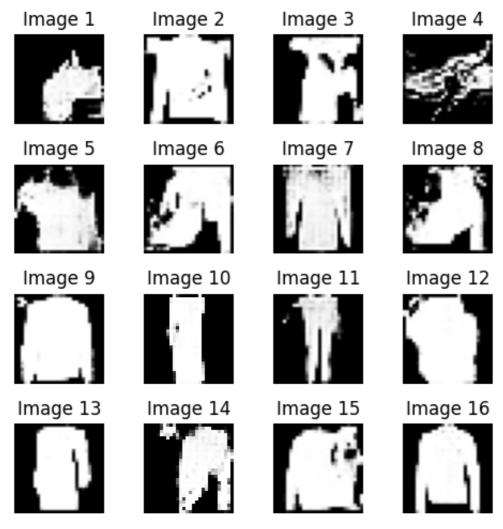
Epoch: 11, G_Loss: 1.0322, D_Loss: 1.1737, Average D(x): 0.5537, Average

D(G(z)): 0.4465



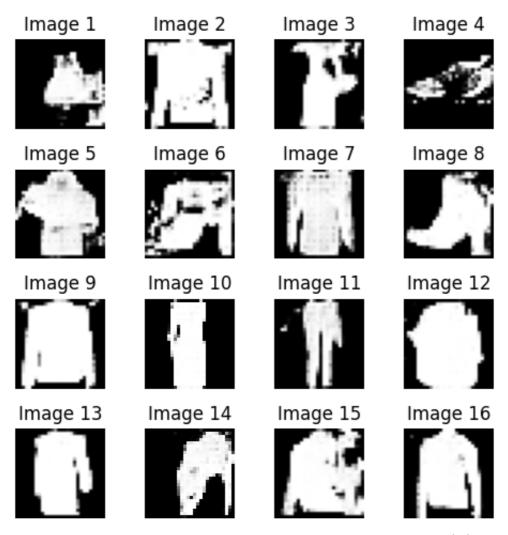
Epoch: 21, G_Loss: 0.8813, D_Loss: 1.2715, Average D(x): 0.5433, Average

D(G(z)): 0.4562



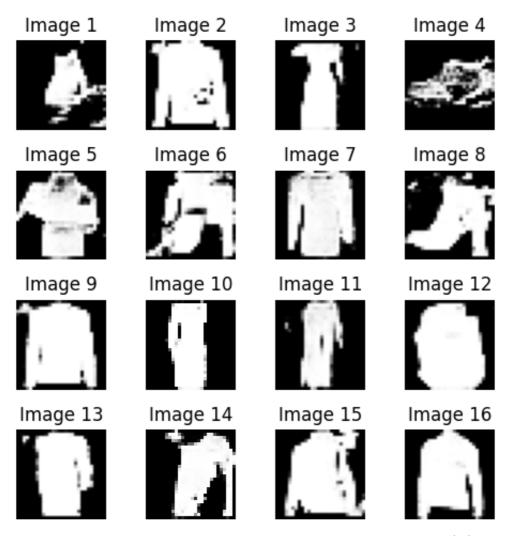
Epoch: 31, G_Loss: 0.7990, D_Loss: 1.4575, Average D(x): 0.5348, Average

D(G(z)): 0.4648



Epoch: 41, G_Loss: 0.8108, D_Loss: 1.3390, Average D(x): 0.5298, Average

D(G(z)): 0.4697



Epoch: 50, G_{Loss} : 0.8072, D_{Loss} : 1.3288, Average D(x): 0.5274, Average D(G(z)): 0.4721

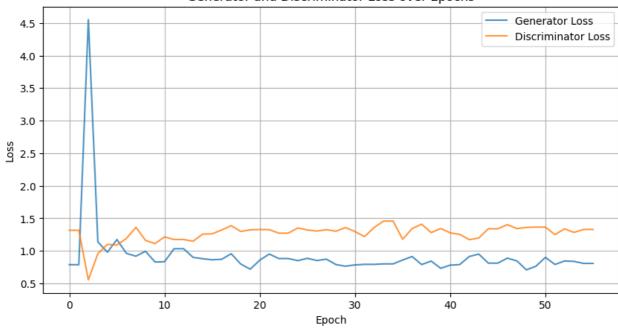
generator_loss_history = [loss.cpu().item() for loss in generator_loss_hi

```
generator_loss_history = np.array(generator_loss_history)

In [10]: plt.figure(figsize=(10, 5))
    plt.plot(generator_loss_history, label='Generator Loss', alpha=0.8)
    plt.plot(discriminator_loss_history, label='Discriminator Loss', alpha=0.plt.xlabel('Epoch')
    plt.ylabel('Loss')
    plt.title('Generator and Discriminator Loss over Epochs')
    plt.legend()
    plt.grid(True)
    plt.show()
```

In [9]:

Generator and Discriminator Loss over Epochs



In []: