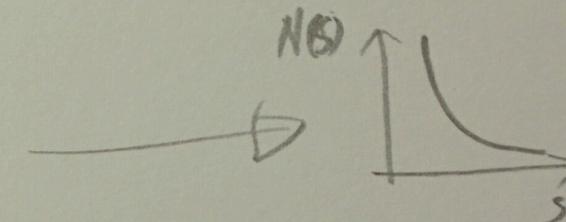


Kundenfeedback
per Smartphone und Tablet



A. 37.

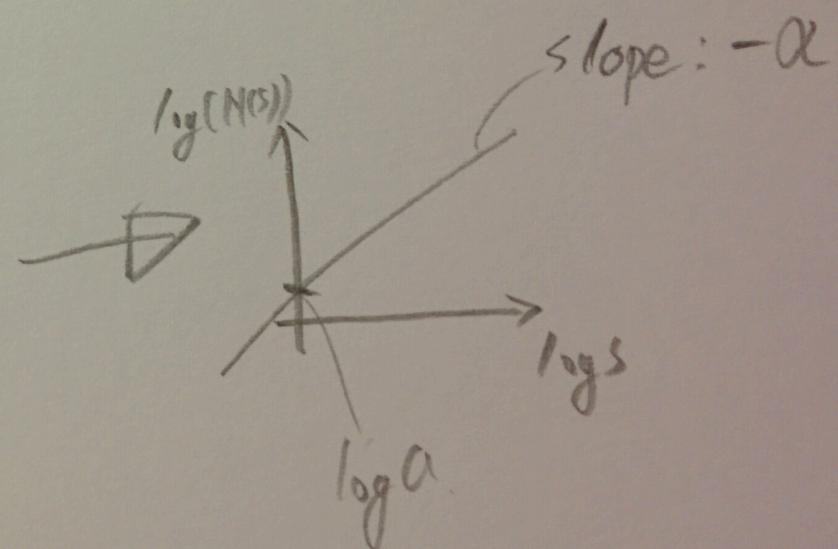
$$N(s) = a \frac{1}{s^\alpha}$$



$$\underline{\log N(s)} = \log(a \cdot \frac{1}{s^\alpha})$$

$$= \log a + \log s^{-\alpha}$$

$$= \underline{\log a} + -\alpha \cdot \underline{\log s}$$



A. 38. . $N(s) = a \cdot \frac{1}{s^\alpha}$

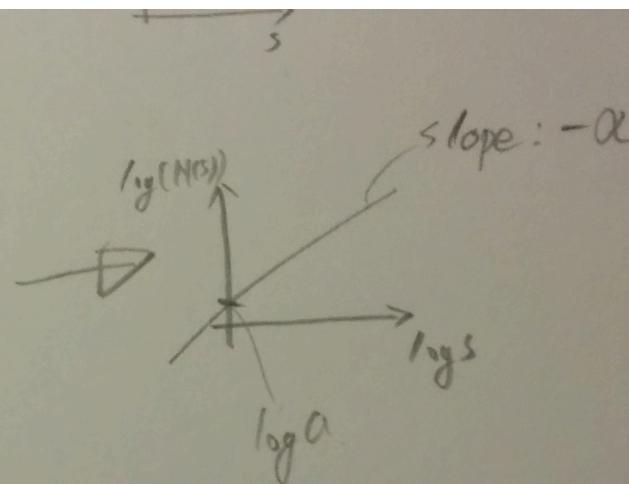
$$N(k \cdot s) = a \cdot \frac{1}{(k \cdot s)^\alpha} = a \cdot k^{-\alpha} \cdot \frac{1}{s^\alpha} = a \cdot k^{-\alpha} \cdot N(s) \Rightarrow$$

$$N(s) = a \cdot s^\alpha$$

$$\log N(s) = \log(a \cdot \frac{1}{s^\alpha})$$

$$= \log a + \log s^{-\alpha}$$

$$= \log a + -\alpha \cdot \underline{\log s}$$



$$A.38. \quad N(s) = a \cdot \frac{1}{s^\alpha}$$

$$N(k \cdot s) = a \cdot \frac{1}{(ks)^\alpha} = a \cdot k^{-\alpha} \cdot \frac{1}{s^\alpha} = a \cdot k^{-\alpha} \cdot N(s) \Rightarrow \text{scale invariant}$$

$$f(x) = x^n$$

$$f(k \cdot x) = (k \cdot x)^n = k^n \cdot x^n = k^n \cdot f(x) \Rightarrow \text{scale invariant}$$

$$f(k \cdot x) = (k \cdot x)^n = k^n \cdot x^n = k^n \cdot f(x)$$

A.41. RS, RO

Common: numerical optimization that does not require the gradient of the function or functions not continuous or differentiable

$$N(k \cdot s) = a \cdot \overline{(ks)^a} = a \cdot k^a \cdot s^a$$

$f(x) = x^n$

$$f(k \cdot x) = (k \cdot x)^n = k^n \cdot x^n = k^n \cdot f(x) \rightarrow \text{scale invariant}$$

A.41. RS, RO

Common: numerical optimization that does not require the gradient of the problem.

- used on functions not continuous or differentiable
- iteratively moving to better position in the search-space
- y : new position sample, x : current position \rightarrow if $f(y) < f(x)$, move to the new position by setting $x=y$

Differences:

Sampling: RS

hypersphere surrounding
current position

RO

normal distribution surrounding
current position

~~y : new position sample~~

$$P_{\text{step}} = \mu^n \cdot P_0 \quad (\text{P}_{\text{step}} \text{ is Pheromore concentration after } n \text{ step})$$

A.42

$$P_{\text{step}} = \mu^n \cdot P_0$$

$$n=42, P_0=1, P_{42}=0.1$$

A.41 RS, RO

Common • numerical optimization that does not require the gradient of the problem

- used on functions not continuous or differentiable
- iteratively moving to better position in the search-space
- y : new position sample, x : current position \rightarrow if $f(y) < f(x)$, move to the new position by setting $x=y$

Differences:

RS

sampling : hypersphere surrounding
current position

RO

normal distribution surrounding
current position

~~y : new position sample~~

A.42

$$P_{\text{stop}} = \mu^n \cdot P_0 \quad (P_{\text{stop}} \text{ is Phasmire concentration after } n \text{ stop})$$

$$n = 42, P_0 = 1, P_{42} = 0.1$$

$$\Rightarrow \mu \approx 0.946$$