Solutions to Reinforcement Learning by Sutton Chapter 5

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Exercise 5.1

- 1. It is due to the strategy that player will not stop until meeting 20 or 21. That indicates player would face the risk of failing by hitting, which results the low value part right before 20 and 21. On the 20 and 21, however, the player stops and has a very high opportunity to win, especially when dealer will stop at 17 or higher.
- 2. It drop off for the whole last row on the left because if Dealer showing an ACE, It has very high possibility of getting higher score than the player when it counts as 11. Thus, the value of dealer's A has contained the dealer's winning rate of making it usable or not. Other cards have no such condition thus A is a special which makes the gap.
- Frontmost values are higher in the upper diagrams because A represent dual values of being used as 1 and 11 in the upper diagram. It makes the player better off and is similar with the condition of having drop in the leftmost rows.

Exercise 5.2

No. Black jack does not contain two duplicate state in any episode, making first-visit and every-visit method essentially the same thing.

Drawing problem. I will not draw it here. The diagram has max of q_π in the bottom.

Recall from Chapter 2.4:

$$Q_{n+1} = \frac{1}{n} \sum_{i=1}^{n} R_i$$

$$= \frac{1}{n} \left(R_n + \sum_{i=1}^{n-1} R_i \right)$$

$$= \frac{1}{n} \left(R_n + (n-1) \frac{1}{n-1} \sum_{i=1}^{n-1} R_i \right)$$

$$= \frac{1}{n} \left(R_n + (n-1)Q_n \right)$$

$$= \frac{1}{n} \left(R_n + nQ_n - Q_n \right)$$

$$= Q_n + \frac{1}{n} \left(R_n - Q_n \right)$$

Then, the pseudo-code for Monte Carlo ES has similar improvement:

$$Q_n(S_t, A_t) = \frac{1}{n} \sum_{i=1}^n G_i(S_t, A_t)$$

$$= \frac{1}{n} \Big(G_n(S_t, A_t) + \sum_{i=1}^{n-1} G_i(S_t, A_t) \Big)$$

$$= \frac{1}{n} \Big(G_n(S_t, A_t) + (n-1) \frac{1}{n-1} \sum_{i=1}^{n-1} G_i(S_t, A_t) \Big)$$

$$= \frac{1}{n} \Big(G_n(S_t, A_t) + (n-1) Q_{n-1}(S_t, A_t) \Big)$$

$$= \frac{1}{n} \Big(G_n(S_t, A_t) + nQ_{n-1}(S_t, A_t) - Q_{n-1}(S_t, A_t) \Big)$$

$$= Q_{n-1}(S_t, A_t) + \frac{1}{n} \Big(G_n(S_t, A_t) - Q_{n-1}(S_t, A_t) \Big)$$

Because

$$|J(s)| = \sum_{t \in J(s)} \rho_{t:T(t)-1} = 10$$

 $\rho_{t:T(t)-1} = 1$

We have off-policy = on-policy, thus:

first-visit:

$$v_s = 10$$

all-visit:

$$v_s = \frac{1}{10}(1+2+3+4+5+6+7+8+9+10) = 5.5$$

Exercise 5.6

eq (5.6):

$$V(s) \doteq \frac{\sum_{t \in J(s)} \rho_{t:T(t)-1} G_t}{\sum_{t \in J(s)} \rho_{t:T(t)-1}}$$

For Q:

$$Q(s, a) \doteq \frac{\sum_{t \in J(s, a)} \rho_{t:T(t) - 1} G_t}{\sum_{t \in J(s, a)} \rho_{t:T(t) - 1}}$$

The weighted average algorithm will need few episodes to decrease its bias. Especially when the $\rho_{t:T(t)-1}$ is big, the weighted average algorithm would be shifted by those data. When we get enough episodes, the average begins to be stable and decreasing the bias.

Exercise 5.8

For first visit, we have:

$$\mathbb{E}_b \left[\left(\prod_{t=0}^{T-1} \frac{\pi(A_t|S_t)}{b(A_t|S_t)} G_0 \right)^2 \right]$$

For every visit, we will some difference

$$\mathbb{E}_{b} \left[\left(\frac{1}{T-1} \sum_{k=1}^{T-1} \prod_{t=0}^{k} \frac{\pi(A_{t}|S_{t})}{b(A_{t}|S_{t})} G_{0} \right)^{2} \right]$$

$$\begin{split} &= 0.5 \, (\text{policy possibility}) \cdot 0.1 \, (\text{length of 1 possibility}) \cdot 2^{2 \cdot 1} \, (\text{square of } \rho) \\ &+ \frac{1}{2} \big[0.5 \cdot 0.9 \cdot 0.5 \cdot 0.1 \cdot 2^{2 \cdot 2} (\text{second visit}) + 0.5 \cdot 0.1 \cdot 2^{2 \cdot 1} (\text{first visit}) \big] \\ &+ \frac{1}{3} \big[0.5 \cdot 0.9 \cdot 0.5 \cdot 0.9 \cdot 0.5 \cdot 0.1 \cdot 2^{2 \cdot 3} (\text{third visit}) \\ &+ 0.5 \cdot 0.9 \cdot 0.5 \cdot 0.1 \cdot 2^{2 \cdot 2} (\text{second visit}) + 0.5 \cdot 0.1 \cdot 2^{2 \cdot 1} (\text{first visit}) \big] \end{split}$$

$$= 0.1 \sum_{k=1}^{\infty} \frac{1}{k} \sum_{l=0}^{k-1} 0.9^{l} \cdot 2^{l} \cdot 2$$
$$= 0.2 \sum_{k=1}^{\infty} \frac{1}{k} \sum_{l=0}^{k-1} 1.8^{l} = \infty.$$

On the other hand, considering weighted average method:

$$\mathbb{E}_{b} \left[\left(\frac{1}{|J(s)|} \sum_{k=1}^{T-1} \prod_{t=0}^{k} \frac{\pi(A_{t}|S_{t})}{b(A_{t}|S_{t})} G_{0} \right)^{2} \right]$$

. . .

$$\leq 0.1 \sum_{k=1}^{\infty} \frac{1}{k} \frac{1}{(\sum_{i=0}^{k} 2^{i})^{2}} \sum_{l=0}^{k-1} 0.9^{l} \cdot 2^{l} \cdot 2$$

$$\leq 0.2 \sum_{k=1}^{\infty} \frac{1}{k} \frac{1}{2^{2k}} \sum_{l=0}^{k-1} 1.8^{l}$$

$$\leq 0.2 \sum_{k=1}^{\infty} \frac{1}{k} 2^{-2k} k 1.8^{k}$$

$$\leq \sum_{k=1}^{\infty} \frac{1}{k} 2^{-2k} k 2^{k}$$

$$= \sum_{k=1}^{\infty} 2^{-k} = 1$$

Exercise 5.9

Similar with Exercise 5.4:

$$V_n(S_t) = \frac{1}{n} \sum_{i=1}^n G_i(t)$$
= ...
= $V_{n-1}(S_t) + \frac{1}{n} \left(G_n(t) - V_{n-1}(S_t) \right)$

$$V_{n+1} \doteq \frac{\sum_{k=1}^{n} W_k G_k}{\sum_{k=1}^{n} W_k}$$

$$= \frac{W_n G_n + \sum_{k=1}^{n-1} W_k G_k}{\sum_{k=1}^{n-1} W_k} \frac{\sum_{k=1}^{n-1} W_k}{\sum_{k=1}^{n} W_k}$$

$$= \left[\frac{W_n G_n}{C_{n-1}} + V_n \right] \frac{C_{n-1}}{C_n}$$

$$= \frac{W_n G_n}{C_n} + \frac{V_n C_{n-1}}{C_n}$$

$$= V_n + \frac{W_n G_n}{C_n} + \frac{V_n C_{n-1}}{C_n} - V_n$$

$$= V_n + \frac{W_n G_n}{C_n} + \frac{V_n C_{n-1} - V_n C_n}{C_n}$$

$$= V_n + \frac{W_n G_n}{C_n} + \frac{-V_n W_n}{C_n}$$

$$= V_n + \frac{W_n G_n}{C_n} + \frac{-V_n W_n}{C_n}$$

$$= V_n + \frac{W_n G_n}{C_n} + \frac{-V_n W_n}{C_n}$$

Because π , the target policy, is deterministic and is redefined as the $\arg\max_a Q(S_t,a)$ just before the update of W happens. Thus we always have $\pi(A_t|S_t)=1$.

Exercise 5.12

Programming problem. See Github

Exercise 5.13

from 5.12

$$\rho_{t:T-1}R_{t+1} = \frac{\pi(A_t|S_t)}{b(A_t|S_t)} \frac{\pi(A_{t+1}|S_{t+1})}{b(A_{t+1}|S_{t+1})} \frac{\pi(A_{t+2}|S_{t+2})}{b(A_{t+2}|S_{t+2})} \dots \frac{\pi(A_{T-1}|S_{T-1})}{b(A_{T-1}|S_{T-1})} R_{t+1}$$

However, we have 5.13

$$\mathbb{E}\left[\frac{\pi(A_t|S_t)}{b(A_t|S_t)}\right] \doteq \sum_a \pi(a|S_k) = 1$$

And, we know after t, any importance-sampling ratio becomes independent with R_{t+1} . This must follows:

$$E(XY) = E(X)E(Y)$$

Go back to 5.12 using 5.13, we will have 5.14 indeed:

$$\mathbb{E}[\rho_{t:T-1}R_{t+1}] = \mathbb{E}[\rho_t R_{t+1}]$$

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