

Q1	Q2	Q3	Q4	Q5	Q6	Q7	Q8	Q9	Q10	Q11	Total
6	4	10	4	4	4	12	15	6	15	20	100

CMPE 224 / 343 – Practice Exam 1 (Voluntary)

Date: 01.06.2023

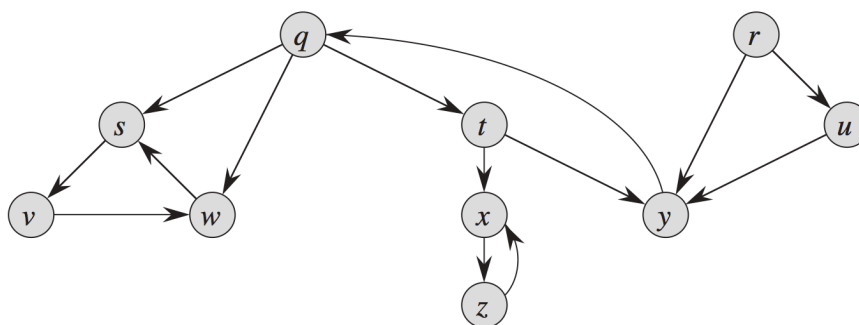
Name:

Student ID:

You have 120 minutes for this practice exam. The exam is closed book, closed notes, except that you can use an **A4-size, double sided, handwritten** cheat sheet.

- (6 points) Consider the following digraph. Assume the vertex adjacency lists are in sorted order: For example, when iterating through the edges pointing from t , consider the edge $t \rightarrow x$ before $t \rightarrow y$.

- Run depth-first search on the digraph, starting from vertex q . List the vertices in *postorder*.



Vertices: _____

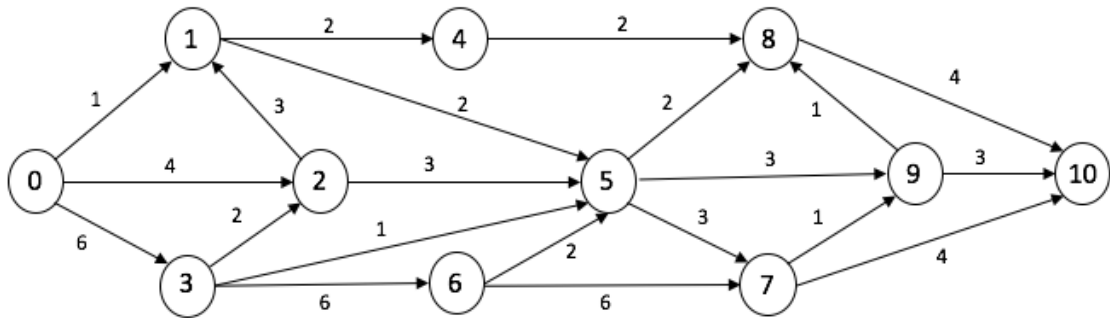
- Run breadth-first search on the digraph, starting from vertex q . List the vertices in the order in which they are de-queued from the FIFO queue.

Vertices: _____

- (4 points) What is a collision in a hash table implementation of a symbol table? Check the best definition (check only one answer).

- ___ Two key-value pairs that have equal keys but different values.
- ___ Two key-value pairs that have different keys and hash to different indices.
- ___ Two key-value pairs that have different keys but hash to the same index.
- ___ Two key-value pairs that have equal keys but hash to different indices.

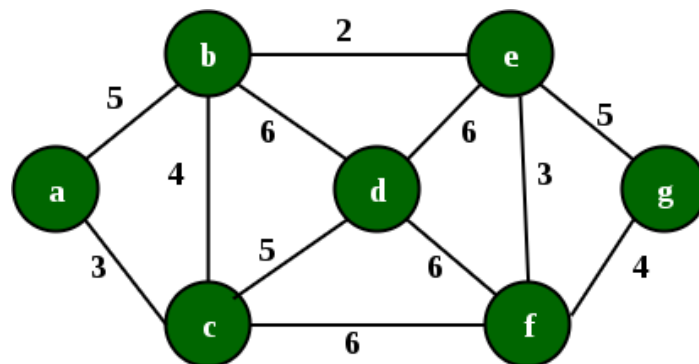
3. (10 points) Find the topological ordering of the graph below, using the *topological sort algorithm that we discussed in class*. Assume that each adjacency list is in order: for example, when iterating through the edges of vertex 5, process the edges (5,7), (5,8), (5,9) in order.



Vertices: _ _ _ _ _ _ _ _ _ _

4. (4 points) Which one of the following is **NOT** a possible sequence of edges added to the minimum spanning tree using Kruskal's algorithm? Mark all that apply.

- (A) $(b,e), (e,f), (a,c), (b,c), (f,g), (c,d)$
 (B) $(b,e), (e,f), (a,c), (f,g), (b,c), (c,d)$
 (C) $(b,e), (a,c), (e,f), (b,c), (f,g), (d,e)$
 (D) $(b,e), (e,f), (b,c), (a,c), (f,g), (c,d)$



5. (4 points) Let G be an undirected connected graph with distinct edge weights. Let e_{\max} be the edge with maximum weight and e_{\min} the edge with minimum weight. Which of the following statements are **true** and which are **false**? Mark T or F below.

- ☐ Every minimum spanning tree of G must contain e_{\min} .
☐ If e_{\max} is in a minimum spanning tree, then its removal must disconnect G .
☐ No minimum spanning tree contains e_{\max} .
☐ G has a unique minimum spanning tree.

6. (4 points) Let $e = v \rightarrow w$ be an edge with weight 17.0. Suppose that during the generic shortest paths algorithm, $\text{distTo}[v] = \infty$ and $\text{distTo}[w] = 15.0$. What will $\text{distTo}[w]$ be after calling $\text{relax}(e)$?
7. (12 points) Suppose that you are running Dijkstra's algorithm on the edge-weighted digraph (Table A, below left), starting from a source vertex s . Table B gives the $\text{edgeTo}[]$ and $\text{distTo}[]$ values immediately after vertex 2 has been deleted from the priority queue and relaxed.

Table A				Table B		
<i>edge</i>	<i>weight</i>	<i>edge</i>	<i>weight</i>	<i>v</i>	<i>distTo[]</i>	<i>edgeTo[]</i>
0 \rightarrow 2	6.0	5 \rightarrow 1	12.0	0	1.0	3 \rightarrow 0
0 \rightarrow 4	6.0	5 \rightarrow 2	1.0	1	17.0	5 \rightarrow 1
0 \rightarrow 5	17.0	5 \rightarrow 4	3.0	2	6.0	5 \rightarrow 2
1 \rightarrow 3	17.0	5 \rightarrow 7	10.0	3	0.0	<i>null</i>
2 \rightarrow 5	11.0	5 \rightarrow 8	4.0	4	7.0	0 \rightarrow 4
2 \rightarrow 7	6.0	6 \rightarrow 0	12.0	5	5.0	10 \rightarrow 5
3 \rightarrow 0	1.0	6 \rightarrow 1	5.0	6	13.0	3 \rightarrow 6
3 \rightarrow 10	3.0	6 \rightarrow 2	1.0	7	12.0	2 \rightarrow 7
3 \rightarrow 1	25.0	6 \rightarrow 4	9.0	8	9.0	3 \rightarrow 8
3 \rightarrow 6	13.0	6 \rightarrow 9	4.0	9	∞	<i>null</i>
3 \rightarrow 8	9.0	7 \rightarrow 1	7.0	10	3.0	3 \rightarrow 10
4 \rightarrow 5	3.0	7 \rightarrow 5	11.0			
4 \rightarrow 6	4.0	7 \rightarrow 9	6.0			
4 \rightarrow 7	3.0	10 \rightarrow 1	15.0			
4 \rightarrow 8	1.0	10 \rightarrow 5	2.0			
4 \rightarrow 9	15.0	10 \rightarrow 8	7.0			

- a) Give the order in which the first 5 vertices were deleted from the priority queue and relaxed.

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- b) Modify Table B above to show the values of the $\text{edgeTo}[]$ and $\text{distTo}[]$ arrays immediately after the next vertex has been deleted from the priority queue and relaxed. Circle those values that changed.

8. (15 pts) Give a **static Java method** that gets as input a directed graph G and checks if there are any vertices v so that there is a path from v to **at most 10 vertices** in the graph. The program should print the id's of such vertices v that are found.

Use the following Digraph data structure. Assume that the graph is represented via adjacency lists. Hint: modify one of the *search* strategies for digraphs that we discussed in class.

public class Digraph		
Digraph(int V)		<i>create an empty digraph with V vertices</i>
Digraph(In in)		<i>create a digraph from input stream</i>
void addEdge(int v, int w)		<i>add a directed edge $v \rightarrow w$</i>
Iterable<Integer> adj(int v)		<i>vertices pointing from v</i>
int V()		<i>number of vertices</i>
int E()		<i>number of edges</i>

What is the computational complexity of your algorithm, in big-O notation? Explain your answer.

9. (6 points) Suppose that your hash function does not satisfy the uniform hashing assumption. Which of the following can result? Check all that apply.

☐ Poor performance for insert.

☐ Poor performance for search hit.

☐ Poor performance for search miss.

☐ Uneven distribution of lengths of chains in separate-chaining hash table.

☐ Large clusters in linear-probing hash table.

☐ Linear-probing hash table can become 100% full, causing a resize operation.

10. (15 points) Given three linked lists, write an efficient algorithm (**in pseudocode**) to find all common elements among the three unsorted linked lists. Your algorithm **must run in $O(N)$** time in the worst case (N : the total number of elements in the linked lists). First, explain your algorithm in sufficient detail; then, discuss the computational complexity of your algorithm. (Hint: you may want to use one of the data structures we covered in class, e.g. Binary Search Trees, 2-3 Trees, AVL Trees, Hash Tables, Red-Black Tries, etc. You may assume that its implementation is available, you do not need to implement it from scratch)

Examples:

Input :

25 20 10 15 12

10 13 12 15

10 24 25 12 15 26

Output : 10 12 15

Input :

2 1 3 4 5

6 4 3 1 2 9 8

1 10 4 5 2

Output : 1 2 4

11. (20 pts) Write a **static Java method** that will take an adjacency matrix for an undirected graph (which can be cyclic) and finds components. The function should display on the screen, one per line, a single representative vertex id of each connected component, and finally return the number of connected components.

The input matrix is passed as a parameter called **data** which is an $n \times n$ array of booleans where `data[i][j]` is true when there is an edge between vertices i and j , and false when there is no edge. Note that the matrix is full and symmetric (i.e. `data[i][j]=data[j][i]`).

You may implement an *iterative* or *recursive* solution and *may use helper functions*. Additionally, you may assume that stack and queue templates are available for your implementation. However, the primary method should have the following header:

```
public static int printRepresentatives(boolean[][] data, int n) {
```