

Econ 110A: Lecture 6

Carlos Góes¹

¹UC San Diego

UCSD, Summer Session II

Growth without growth?

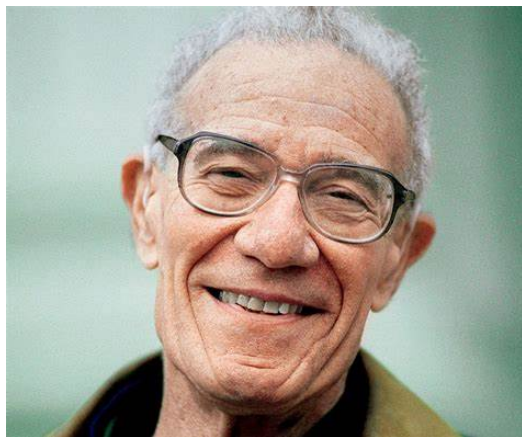
So far we talked about growth without actually talking about growth...

We tried to explain income levels across differences at a given moment, not growth rates, which only indirectly speaks about growth.

An introduction to Growth Dynamics

Robert (Bob) Solow

1924-



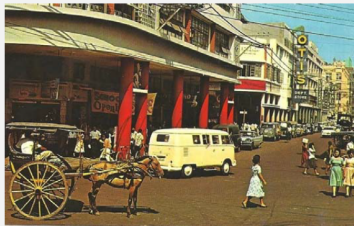
Nobel Prize in Economics, 1987

An introduction to Growth Dynamics

Questions we asked:

- Why some countries are so much richer than others?
- Capital matters but only partially. TFP plays a much bigger role.
- Why do some countries grow faster than others?
- Can the answer to this question help understand the role of TFP?

Two Pictures from 1960



Two Pictures from 1960

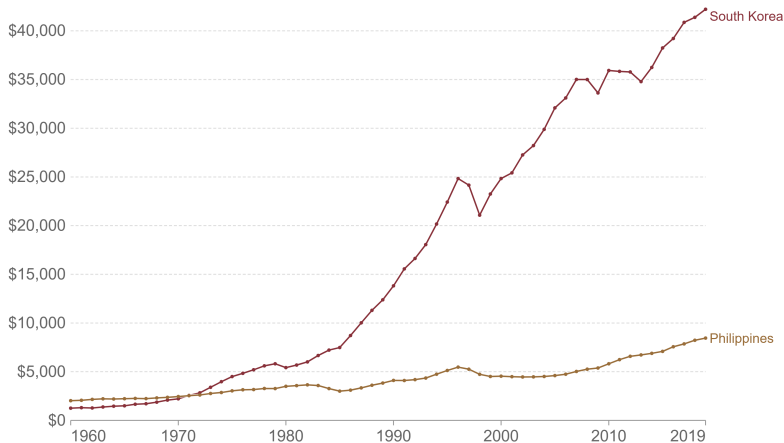
	South Korea	Philippines
Per Capita GDP	\$1,500	\$1,500
Population	25M	25M
Working Age Population	50%	50%
Attending College at 20	5%	13%

Two Pictures from 1960

GDP per capita, 1960 to 2019



This data is adjusted for inflation and for differences in the cost of living between countries.



Source: Feenstra et al. (2015), Penn World Table (2021)

OurWorldInData.org/economic-growth • CC BY

Note: This data is expressed in international-\$¹ at 2017 prices, using multiple benchmark years to adjust for differences in the cost of living between countries over time.

¹ International dollars: International dollars are a hypothetical currency that is used to make meaningful comparisons of monetary indicators of living

An introduction to Growth Dynamics

More specific questions:

- Can differences in capital accumulation explain differences in growth of GDP per capita across countries?
- Is capital accumulation the ultimate source of sustained growth in GDP per capita?

The Solow Growth Model

We add the time dimension!

- Production:

$$Y_t = \bar{A}K_t^\alpha L_t^{1-\alpha}, \quad \alpha \in (0, 1), \quad t \in \{0, 1, 2, \dots\}$$

The Solow Growth Model

We add the time dimension!

- Production:

$$Y_t = \bar{A} K_t^\alpha L_t^{1-\alpha}, \quad \alpha \in (0, 1), \quad t \in \{0, 1, 2, \dots\}$$

- Resource constraint:

$$Y_t = \underbrace{C_t}_{\text{consumption}} + \underbrace{S_t}_{\text{savings}}, \quad t \in \{0, 1, 2, \dots\}$$

The Solow Growth Model

We add the time dimension!

- Production:

$$Y_t = \bar{A} K_t^\alpha L_t^{1-\alpha}, \quad \alpha \in (0, 1), \quad t \in \{0, 1, 2, \dots\}$$

- Resource constraint:

$$Y_t = \underbrace{C_t}_{\text{consumption}} + \underbrace{S_t}_{\text{savings}}, \quad t \in \{0, 1, 2, \dots\}$$

- Capital Accumulation:

$$K_{t+1} = K_t + \underbrace{I_t}_{\text{investment}} - \underbrace{\bar{d} \cdot K_t}_{\text{depreciation}}, \quad \bar{d} \in (0, 1), \quad t \in \{0, 1, 2, \dots\}$$

$$K_{t+1} - K_t \equiv \Delta K_{t+1} = I_t - \bar{d} \cdot K_t$$

The Solow Growth Model

We add the time dimension!

- Production:

$$L_t = \bar{L}, \quad t \in \{0, 1, 2, \dots\}$$

The Solow Growth Model

We add the time dimension!

- Production:

$$L_t = \bar{L}, \quad t \in \{0, 1, 2, \dots\}$$

- Investment:

$$I_t = S_t = \bar{s}Y_t, \quad \bar{s} \in (0, 1), \quad t \in \{0, 1, 2, \dots\}$$

The Solow Growth Model: Taking Stock

Normalizing the price of the output good $P_t = 1$ each period, for each period $t \in \{0, 1, 2, \dots\}$, given parameters \bar{d} , \bar{s} , \bar{A} , \bar{L} , α and the initial value of capital K_0 there are five unknowns Y_t , K_{t+1} , L_t , C_t , I_t and five equations:

$$Y_t = \bar{A}K_t^\alpha L_t^{1-\alpha} \quad (1)$$

$$Y_t = C_t + I_t \quad (2)$$

$$\Delta K_{t+1} = I_t - \bar{d} \cdot K_t \quad (3)$$

$$L_t = \bar{L} \quad (4)$$

$$I_t = \bar{s}Y_t \quad (5)$$

that characterize the solution to this model.

The Solow Growth Model: Factor Markets?

What about factor markets?

- We can add factor markets, satisfying:

$$w_t = MPL_t = (1 - \alpha) \frac{Y_t}{L_t}$$

$$r_t = MPK_t = \alpha \frac{Y_t}{K_t}$$

- But nothing else would change in the model.
- So to simplify, we keep these two equations and unknowns out!

Solving the Solow Growth Model

Solving fully the model with equations is very hard. We usually do that numerically, using a computer. But here are some things we can do with pen and paper to simplify the problem:

- Reduce equations to strictly necessary
- Show solution on a diagram (Solow Diagram)
- Solve for the “Long Run” of the model (Steady State)

Solving the Solow Growth Model

Strategy: Reduce system of equations from five to two

- Equations (2) and (5) are redundant, not independent ("Walras' Law"; reduces the system to 4)

Solving the Solow Growth Model

Strategy: Reduce system of equations from five to two

- Equations (2) and (5) are redundant, not independent ("Walras' Law"; reduces the system to 4)
- Plug-in (4) into (1), becomes $Y_t = \bar{A}K_t^\alpha \bar{L}^{1-\alpha}$ (reduces the system to 3)

Solving the Solow Growth Model

Strategy: Reduce system of equations from five to two

- Equations (2) and (5) are redundant, not independent ("Walras' Law"; reduces the system to 4)
- Plug-in (4) into (1), becomes $Y_t = \bar{A}K_t^\alpha \bar{L}^{1-\alpha}$ (reduces the system to 3)
- Plug-in (5) into (3), using above, becomes $\Delta K_{t+1} = \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t$ (reduces the system to 2)

Solving the Solow Growth Model

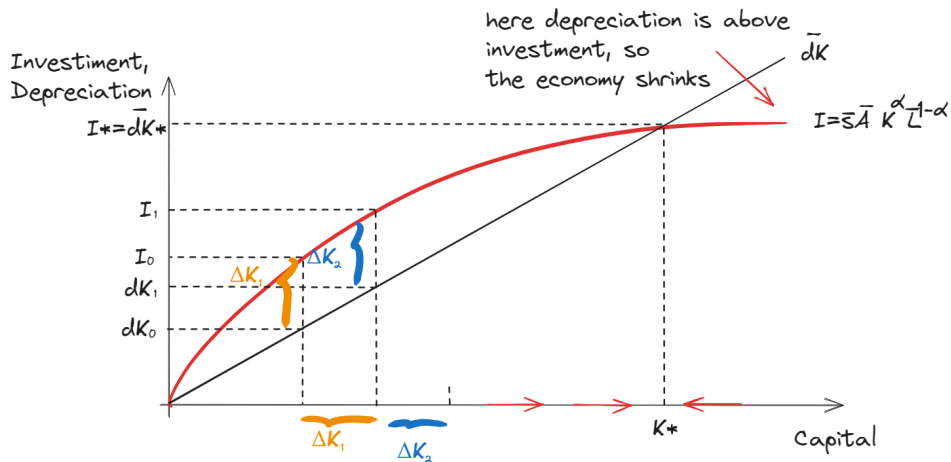
Strategy: Reduce system of equations from five to two

- Equations (2) and (5) are redundant, not independent ("Walras' Law"; reduces the system to 4)
- Plug-in (4) into (1), becomes $Y_t = \bar{A}K_t^\alpha \bar{L}^{1-\alpha}$ (reduces the system to 3)
- Plug-in (5) into (3), using above, becomes $\Delta K_{t+1} = \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t$ (reduces the system to 2)

Final system:

$$\begin{aligned}Y_t &= \bar{A}K_t^\alpha \bar{L}^{1-\alpha} \\ \Delta K_{t+1} &= \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t\end{aligned}$$

Solow Diagram: Capital Dynamics



Solow Model: The Steady State

$$\begin{aligned}Y_t &= \bar{A}K_t^\alpha \bar{L}^{1-\alpha} \\ \Delta K_{t+1} &= \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t\end{aligned}$$

Solow Model: The Steady State

$$\begin{aligned}Y_t &= \bar{A}K_t^\alpha \bar{L}^{1-\alpha} \\ \Delta K_{t+1} &= \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t\end{aligned}$$

At the Steady-State (SS), $\Delta K_{t+1} = 0$ and $K_{t+1} = K_t$, so we might as well call it K^* . The same is true for Y , so we call it Y^* . Let us look for K^* , Y^* that satisfy the definition of a SS in the system above:

Solow Model: The Steady State

$$\begin{aligned}Y_t &= \bar{A}K_t^\alpha \bar{L}^{1-\alpha} \\ \Delta K_{t+1} &= \bar{s}\bar{A}K_t^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K_t\end{aligned}$$

At the Steady-State (SS), $\Delta K_{t+1} = 0$ and $K_{t+1} = K_t$, so we might as well call it K^* . The same is true for Y , so we call it Y^* . Let us look for K^* , Y^* that satisfy the definition of a SS in the system above:

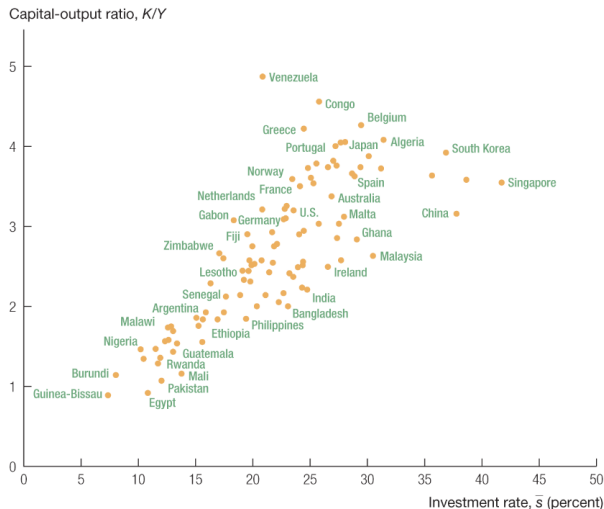
$$\begin{aligned}\bar{s}\bar{A}(K^*)^\alpha \bar{L}^{1-\alpha} - \bar{d} \cdot K^* &= 0 \iff K^* = \left(\frac{\bar{s}\bar{A}}{\bar{d}}\right)^{\frac{1}{1-\alpha}} \bar{L} \\ \implies Y^* &= \bar{A}^{\frac{1}{1-\alpha}} \left(\frac{\bar{s}}{\bar{d}}\right)^{\frac{\alpha}{1-\alpha}} \bar{L}\end{aligned}$$

Solow Model: The Steady State

Note that the model predicts that the capital-to-output ratio is increasing in the investment rate:

$$\frac{K^*}{Y^*} = \frac{\bar{s}}{\bar{d}}$$

In the data, there is indeed a positive correlation between those variables.



Source: Penn World Tables, Version 9.1. The capital-output ratio is measured in the year 2017, while the investment rate is averaged over the period 1990 to 2017.

Solow Model: The Steady State

Other predictions of the model do not have a great fit...

$$y^* \equiv \frac{Y^*}{\bar{L}} = \bar{A}^{\frac{1}{1-\alpha}} \left(\frac{\bar{s}}{\bar{d}} \right)^{\frac{\alpha}{1-\alpha}}$$

Solow Model: The Steady State

Other predictions of the model do not have a great fit...

$$y^* \equiv \frac{Y^*}{\bar{L}} = \bar{A}^{\frac{1}{1-\alpha}} \left(\frac{\bar{s}}{\bar{d}} \right)^{\frac{\alpha}{1-\alpha}}$$

Now assume $\bar{d}_{rich} = \bar{d}_{poor}$ and let us make a similar decomposition as we did with the production model:

$$\underbrace{\frac{y_{rich}^*}{y_{poor}^*}}_{64} = \underbrace{\left(\frac{\bar{A}_{rich}}{\bar{A}_{poor}} \right)^{\frac{3}{2}}}_{32} \times \underbrace{\left(\frac{\bar{s}_{rich}}{\bar{s}_{poor}} \right)^{\frac{1}{2}}}_{2}$$

Solow Model: The Steady State

Other predictions of the model do not have a great fit...

$$y^* \equiv \frac{Y^*}{\bar{L}} = \bar{A}^{\frac{1}{1-\alpha}} \left(\frac{\bar{s}}{\bar{d}} \right)^{\frac{\alpha}{1-\alpha}}$$

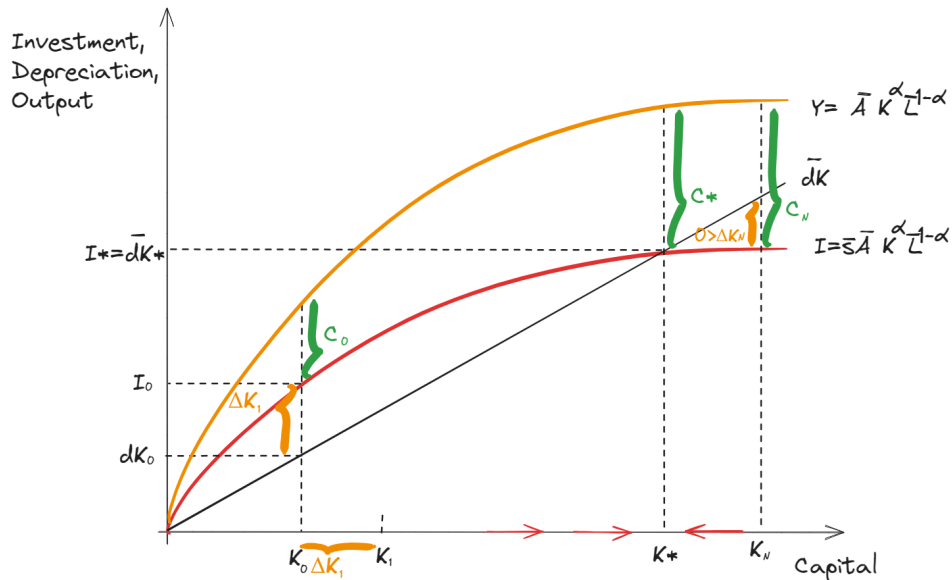
Now assume $\bar{d}_{rich} = \bar{d}_{poor}$ and let us make a similar decomposition as we did with the production model:

$$\underbrace{\frac{y_{rich}^*}{y_{poor}^*}}_{64} = \underbrace{\left(\frac{\bar{A}_{rich}}{\bar{A}_{poor}} \right)^{\frac{3}{2}}}_{32} \times \underbrace{\left(\frac{\bar{s}_{rich}}{\bar{s}_{poor}} \right)^{\frac{1}{2}}}_{2}$$

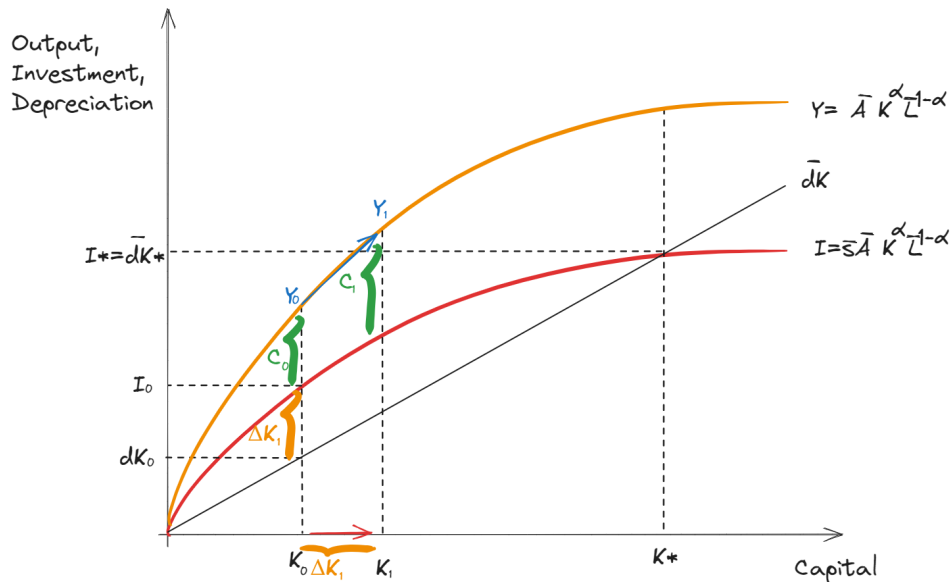
while in the production model

$$\underbrace{\frac{y_{rich}^*}{y_{poor}^*}}_{64} = \underbrace{\frac{\bar{A}_{rich}}{\bar{A}_{poor}}}_{13} \times \underbrace{\left(\frac{\bar{k}_{rich}^*}{\bar{k}_{poor}^*} \right)^{\frac{1}{3}}}_{5}$$

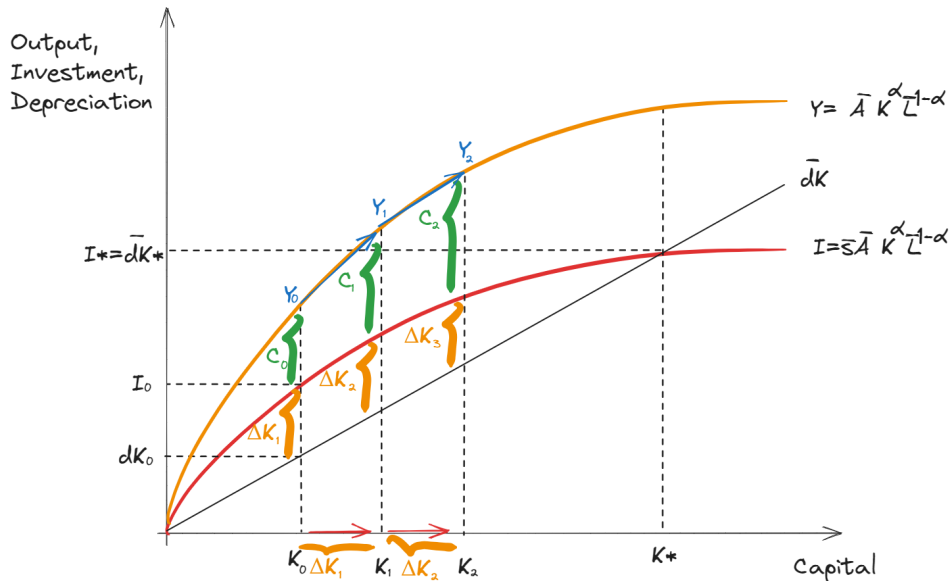
Solow Model: The Complete Diagram



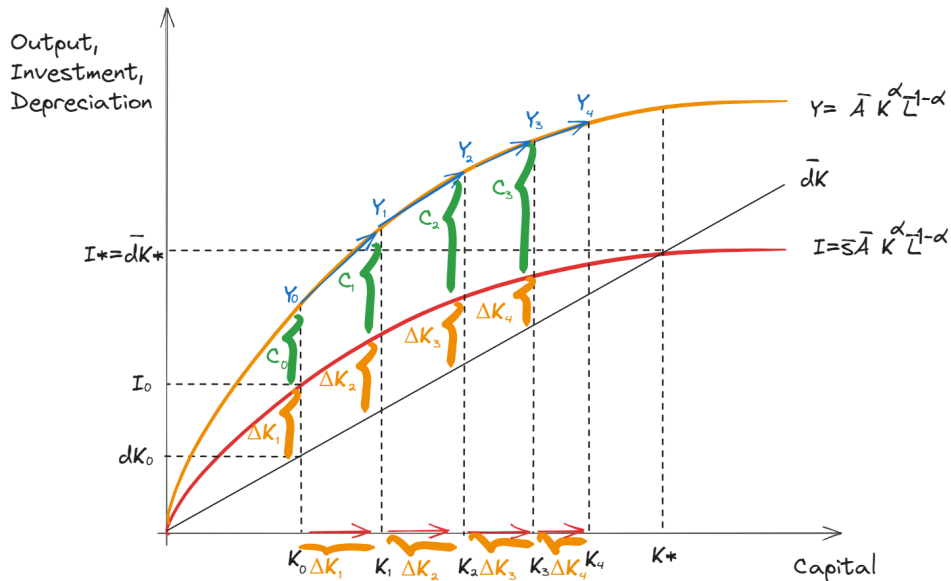
Solow Model: The Complete Diagram, tracing out the dynamics



Solow Model: The Complete Diagram, tracing out the dynamics



Solow Model: The Complete Diagram, tracing out the dynamics

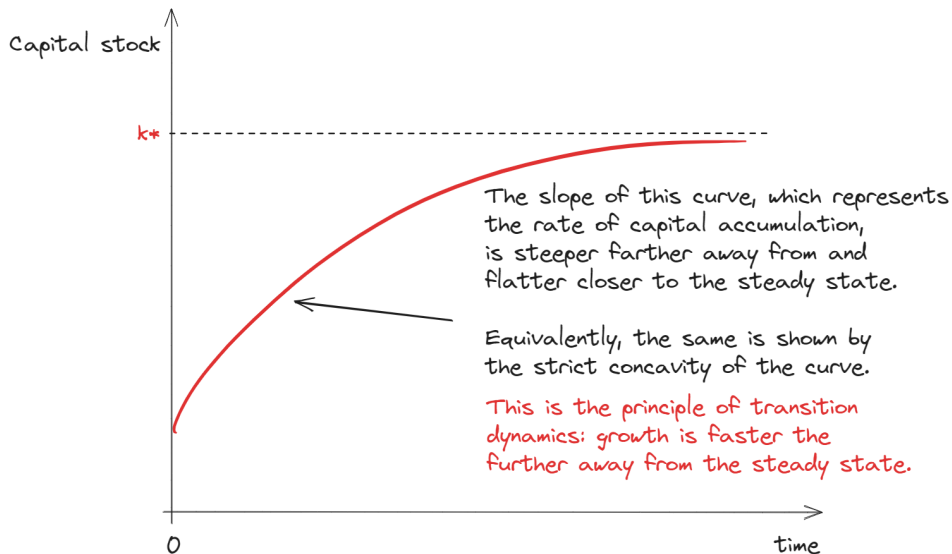


Solow Model: tracing out the dynamics

Assume $\alpha = 1/3$, $\bar{L} = 100$, $\bar{s} = .2$, $\bar{d} = .1$.

t	K_t	$\bar{d}K_t$	Y_t	I_t	ΔK_{t+1}
0	250	$250 \cdot 0.1 = \mathbf{25}$	$250^{\frac{1}{3}} 100^{\frac{2}{3}} = \mathbf{135.7}$	$135.7 \cdot 0.2 = \mathbf{27.1}$	$(27.1 - 25) = \mathbf{2.1}$
1	$250 + 2.1 = \mathbf{252.1}$	$252.1 \cdot 0.1 = \mathbf{25.2}$	$252.1^{\frac{1}{3}} 100^{\frac{2}{3}} = \mathbf{136.1}$	$136.1 \cdot 0.2 = \mathbf{27.2}$	$(27.2 - 25.2) = \mathbf{2}$
2	$252.1 + 2 = \mathbf{254.1}$	$254.1 \cdot 0.1 = \mathbf{25.4}$	$254.1^{\frac{1}{3}} 100^{\frac{2}{3}} = \mathbf{136.5}$	$136.5 \cdot 0.2 = \mathbf{27.3}$	$(27.3 - 25.4) = \mathbf{1.9}$
3	$254.1 + 1.9 = \mathbf{256}$	$256 \cdot 0.1 = \mathbf{25.6}$	$256^{\frac{1}{3}} 100^{\frac{2}{3}} = \mathbf{136.8}$	$136.8 \cdot 0.2 = \mathbf{27.4}$	$(27.4 - 25.6) = \mathbf{1.8}$

Solow Model: principle of transition dynamics



Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\Delta K_{t+1} = \bar{s}Y_t - \bar{d}K_t$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\begin{aligned}\Delta K_{t+1} &= \bar{s}Y_t - \bar{d}K_t \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s}\frac{Y_t}{K_t} - \bar{d}\end{aligned}$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\begin{aligned}\Delta K_{t+1} &= \bar{s}Y_t - \bar{d}K_t \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s}\frac{Y_t}{K_t} - \bar{d} \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s}\frac{Y_t}{K_t} - \bar{s}\frac{Y^*}{K^*} \quad \left(\because \frac{K^*}{Y^*} = \frac{\bar{s}}{\bar{d}} \implies \bar{d} = \bar{s}\frac{Y^*}{K^*} \right)\end{aligned}$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\begin{aligned}\Delta K_{t+1} &= \bar{s}Y_t - \bar{d}K_t \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s}\frac{Y_t}{K_t} - \bar{d} \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s}\frac{Y_t}{K_t} - \bar{s}\frac{Y^*}{K^*} \quad \left(\because \frac{K^*}{Y^*} = \frac{\bar{s}}{\bar{d}} \implies \bar{d} = \bar{s}\frac{Y^*}{K^*} \right) \\ \Delta \frac{K_{t+1}}{K_t} &= \bar{s} \times \left(\frac{Y_t}{K_t} - \frac{Y^*}{K^*} \right)\end{aligned}$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\Delta K_{t+1} = \bar{s}Y_t - \bar{d}K_t$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y_t}{K_t} - \bar{d}$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y_t}{K_t} - \bar{s} \frac{Y^*}{K^*} \quad \left(\because \frac{K^*}{Y^*} = \frac{\bar{s}}{\bar{d}} \implies \bar{d} = \bar{s} \frac{Y^*}{K^*} \right)$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \times \left(\frac{Y_t}{K_t} - \frac{Y^*}{K^*} \right)$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y^*}{K^*} \times \left(\frac{Y_t/K_t}{Y^*/K^*} - 1 \right)$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Solow Model: principle of transition dynamics

The mathematics behind the principle

$$\Delta K_{t+1} = \bar{s}Y_t - \bar{d}K_t$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y_t}{K_t} - \bar{d}$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y_t}{K_t} - \bar{s} \frac{Y^*}{K^*} \quad \left(\because \frac{K^*}{Y^*} = \frac{\bar{s}}{\bar{d}} \implies \bar{d} = \bar{s} \frac{Y^*}{K^*} \right)$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \times \left(\frac{Y_t}{K_t} - \frac{Y^*}{K^*} \right)$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y^*}{K^*} \times \left(\frac{Y_t/K_t}{Y^*/K^*} - 1 \right)$$

$$\Delta \frac{K_{t+1}}{K_t} = \bar{s} \frac{Y^*}{K^*} \times \left(\left[\frac{K^*}{K_t} \right]^{1-\alpha} - 1 \right) \quad \left(\because Y^* = \bar{A}(K^*)^\alpha (\bar{L})^{1-\alpha}, \quad Y_t = \bar{A}(K_t)^\alpha (\bar{L})^{1-\alpha} \right)$$

So $\Delta \frac{K_{t+1}}{K_t}$ will be large if the gap $\frac{K^*}{K_t}$ is large.

Important aside: there are no banks, but there is still a real interest rate

Real interest rate: the amount of output a person can earn by saving one unit of output for a year, or the amount of output a person must pay to borrow one unit of output for a year.

Important aside: there are no banks, but there is still a real interest rate

Real interest rate: the amount of output a person can earn by saving one unit of output for a year, or the amount of output a person must pay to borrow one unit of output for a year.

- **Financial view:** save 1 unit at time $t \rightarrow$ receive $1 + R$ units at time $t + 1$
- **Production view:** save 1 unit at time $t \rightarrow$ invest 1 unit $I_t \rightarrow$ get 1 unit of K_{t+1} : rented at $r = MPK$, but depreciates at $(1 - \bar{d})$.

Important aside: there are no banks, but there is still a real interest rate

Real interest rate: the amount of output a person can earn by saving one unit of output for a year, or the amount of output a person must pay to borrow one unit of output for a year.

- **Financial view:** save 1 unit at time $t \rightarrow$ receive $1 + R$ units at time $t + 1$
- **Production view:** save 1 unit at time $t \rightarrow$ invest 1 unit $I_t \rightarrow$ get 1 unit of K_{t+1} : rented at $r = MPK$, but depreciates at $(1 - \bar{d})$.

If markets are fully integrated, by nonarbitrage, the following must hold:

$$1 + R = r + (1 - \bar{d}) \implies r = R + \bar{d}$$

The forces behind the Solow Model

- If a society has some endowment of capital, it can save and invest to grow, accumulate capital stock and grow richer.
- However, with a fixed population and diminishing marginal returns to capital, growth cannot go on forever in this mode.
- In fact, in this “growth model” there is no long-run growth: is a unique steady-state in which the economy **does not grow!**
- The Solow model does a good job of explaining differences in capital accumulation across countries.
- Income per capita does not depend on the size of the country in this model – and it does a worse job than the production model in explaining differences in GDP per capita.

It has limits but it was a breakthrough

All theory depends on assumptions which are not quite true. That is what makes it theory. The art of successful theorizing is to make the inevitable simplifying assumptions in such a way that the final results are not very sensitive"

Bob Solow (1956)