

CSE 344
SYSTEMS PROGRAMMING

HOMEWORK 02

REPORT

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1. Part 1

In that part, program.c starts to read inputPath.txt as parent process **P1**. At the same time fork() syscall creates a child process which runs the **P2**.

P1 process reads input file line by line and parses to the ASCII values of coordinates x and y. For each line it evaluates the **least squares method** in critical section that no signals can interrupts using **sigprocmask()** syscall. There are two signal handlers which handles **SIGTERM** signal to close files and remove input and temp files. The parent process communicates with child process which is P2, using **kill()** syscall and sends **SIGUSR2** signal. To wait the child process **sigsuspend()** syscall is used. While evaluating the result of least squares method, it writes to temp file which is created via **mkstemp** syscall. After all these success steps, P1 prints to screen that how many bytes that it read, how many lines that it read and which signals handled.

While P1 is writing in temp file, **P2** is the child process of P1 creates an outputPath.txt file to write the contents to it and starts to read temp file. For each line that it read is deleted after parsing operations. Then parsed values are evaluated by error calculator functions which are blocked to get interrupt by any signals using **sigprocmask()** system call. P2 is communicated with P1 using **SIGUSR1** signal with **kill()** system call. Each errors are written to outputPath.txt line by line as appending temp file's content. After the succeed writing operations and reading operations, P2 prints to screen index of each line, MAE, MSE and RMSE errors. After all errors' prints, it prints to screen the MAE, MSE and RMSE errors' means. Then prints to screen the standart deviations of that MAE, MSE and RMSE errors.

Signal handler functions are handled using struct of sigaction and **sigaction()** syscall. If **SIGTERM** signal becomes in execution time, then signal handler closes all opened files and removes the input and temp files. After the success of each lines are printed to temp file and read and deleted back to temp file is deleted end of the P2. All files are closed after operations clearly. Input file is deleted after P2 finishes its job.

Compiler Result:

inputPath.txt:

program.c	inputPath.txt	×	outputPath.txt	Makefile
1	24355779992435577999			
2	01444567660120956789			
3	09506501646235489513			
4	95654106981065978937			
5	12292853953712701287			
6	29481047223175329209			
7	24355779992435577999			
8	01444567660120956789			
9	09506501646235489513			
10	95654106981065978937			
11	12292853953712701287			
12	29481047223175329209			
13	24355779992435577999			
14	01444567660120956789			
15	09506501646235489513			
16	95654106981065978937			
17	12292853953712701287			
18	29481047223175329209			
19	24355779992435577999			
20	01444567660120956789			
21	09506501646235489513			
22	95654106981065978937			
23	12292853953712701287			
24	29481047223175329209			
25	24355779992435577999			
26	01444567660120956789			
27	09506501646235489513			
28	95654106981065978937			
29	12292853953712701287			
30	29481047223175329209			
31	24355779992435577999			
32	01444567660120956789			
33	09506501646235489513			
34	95654106981065978937			
35	12292853953712701287			
36	29481047223175329209			
37	24355779992435577999			
38	01444567660120956789			
39	09506501646235489513			
40	95654106981065978937			
41	12292853953712701287			
42	29481047223175329209			
43	24355779992435577999			

outputPath.txt:

program.c	inputPath.txt	outputPath.txt	Makefile
1	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
2	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
3	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
4	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
5	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
6	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
7	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
8	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
9	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
10	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
11	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
12	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
13	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
14	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
15	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
16	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
17	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
18	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
19	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
20	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
21	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
22	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
23	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
24	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
25	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
26	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
27	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
28	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
29	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
30	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
31	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
32	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
33	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
34	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
35	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
36	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
37	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		
38	(48, 49), (52, 52), (52, 53), (54, 55), (54, 54), (48, 49), (50, 48), (57, 53), (54, 55), (56, 57), 0.815x+9.711, 1.200, 2.304, 1.518		
39	(48, 57), (53, 48), (54, 53), (48, 49), (54, 52), (54, 50), (51, 53), (52, 56), (57, 53), (49, 51), -0.087x+56.750, 3.400, 7.299, 2.702		
40	(57, 53), (54, 53), (52, 49), (48, 54), (57, 56), (49, 48), (54, 53), (57, 55), (56, 57), (51, 55), 0.444x+29.551, 2.400, 5.390, 2.322		
41	(49, 50), (50, 57), (50, 56), (53, 51), (57, 53), (51, 55), (49, 50), (55, 48), (49, 50), (56, 55), 0.017x+51.604, 3.400, 8.647, 2.941		
42	(50, 57), (52, 56), (49, 48), (52, 55), (50, 50), (51, 49), (55, 53), (51, 50), (57, 50), (48, 57), -0.203x+62.955, 3.600, 10.776, 3.283		
43	(50, 52), (51, 53), (53, 55), (55, 57), (57, 57), (50, 52), (51, 53), (53, 55), (55, 57), (57, 57), 0.768x+13.927, 1.600, 0.288, 0.536		

Console:

```
omer@omer:~/Desktop/HW02/HW02$ make
gcc -o program program.c -lm
./program -i inputPath.txt -o outputPath.txt
P1 Total read bytes : 3000
P1 Total read lines : 150
P1 Signals : SIGUSR1, SIGUSR2, SIGTERM
```

INDEX	MAE	MSE	RMSE

[0]	1.600	0.288	0.536
[1]	1.200	2.304	1.518
[2]	3.400	7.299	2.702
[3]	2.400	5.390	2.322
[4]	3.400	8.647	2.941
[5]	3.600	10.776	3.283
[6]	1.600	0.288	0.536
[7]	1.200	2.304	1.518
[8]	3.400	7.299	2.702
[9]	2.400	5.390	2.322
[10]	3.400	8.647	2.941
[11]	3.600	10.776	3.283
[12]	1.600	0.288	0.536
[13]	1.200	2.304	1.518
[14]	3.400	7.299	2.702
[15]	2.400	5.390	2.322
[16]	3.400	8.647	2.941
[17]	3.600	10.776	3.283
[18]	1.600	0.288	0.536
[19]	1.200	2.304	1.518
[20]	3.400	7.299	2.702
[21]	2.400	5.390	2.322
[22]	3.400	8.647	2.941
[23]	3.600	10.776	3.283
[24]	1.600	0.288	0.536

[23]	3.600	10.776	3.283
[24]	1.600	0.288	0.536
[25]	1.200	2.304	1.518
[26]	3.400	7.299	2.702
[27]	2.400	5.390	2.322
[28]	3.400	8.647	2.941
[29]	3.600	10.776	3.283
[30]	1.600	0.288	0.536
[31]	1.200	2.304	1.518
[32]	3.400	7.299	2.702
[33]	2.400	5.390	2.322
[34]	3.400	8.647	2.941
[35]	3.600	10.776	3.283
[36]	1.600	0.288	0.536
[37]	1.200	2.304	1.518
[38]	3.400	7.299	2.702
[39]	2.400	5.390	2.322
[40]	3.400	8.647	2.941
[41]	3.600	10.776	3.283
[42]	1.600	0.288	0.536
[43]	1.200	2.304	1.518
[44]	3.400	7.299	2.702
[45]	2.400	5.390	2.322
[46]	3.400	8.647	2.941
[47]	3.600	10.776	3.283
[48]	1.600	0.288	0.536
[49]	1.200	2.304	1.518
[50]	3.400	7.299	2.702
[51]	2.400	5.390	2.322
[52]	3.400	8.647	2.941
[53]	3.600	10.776	3.283
[54]	1.600	0.288	0.536
[55]	1.200	2.304	1.518
[56]	3.400	7.299	2.702
[57]	2.400	5.390	2.322

[57]	2.400	5.390	2.322
[58]	3.400	8.647	2.941
[59]	3.600	10.776	3.283
[60]	1.600	0.288	0.536
[61]	1.200	2.304	1.518
[62]	3.400	7.299	2.702
[63]	2.400	5.390	2.322
[64]	3.400	8.647	2.941
[65]	3.600	10.776	3.283
[66]	1.600	0.288	0.536
[67]	1.200	2.304	1.518
[68]	3.400	7.299	2.702
[69]	2.400	5.390	2.322
[70]	3.400	8.647	2.941
[71]	3.600	10.776	3.283
[72]	1.600	0.288	0.536
[73]	1.200	2.304	1.518
[74]	3.400	7.299	2.702
[75]	2.400	5.390	2.322
[76]	3.400	8.647	2.941
[77]	3.600	10.776	3.283
[78]	1.600	0.288	0.536
[79]	1.200	2.304	1.518
[80]	3.400	7.299	2.702
[81]	2.400	5.390	2.322
[82]	3.400	8.647	2.941
[83]	3.600	10.776	3.283
[84]	1.600	0.288	0.536
[85]	1.200	2.304	1.518
[86]	3.400	7.299	2.702
[87]	2.400	5.390	2.322
[88]	3.400	8.647	2.941
[89]	3.600	10.776	3.283
[90]	1.600	0.288	0.536

[90]	1.600	0.288	0.536
[91]	1.200	2.304	1.518
[92]	3.400	7.299	2.702
[93]	2.400	5.390	2.322
[94]	3.400	8.647	2.941
[95]	3.600	10.776	3.283
[96]	1.600	0.288	0.536
[97]	1.200	2.304	1.518
[98]	3.400	7.299	2.702
[99]	2.400	5.390	2.322
[100]	3.400	8.647	2.941
[101]	3.600	10.776	3.283
[102]	1.600	0.288	0.536
[103]	1.200	2.304	1.518
[104]	3.400	7.299	2.702
[105]	2.400	5.390	2.322
[106]	3.400	8.647	2.941
[107]	3.600	10.776	3.283
[108]	1.600	0.288	0.536
[109]	1.200	2.304	1.518
[110]	3.400	7.299	2.702
[111]	2.400	5.390	2.322
[112]	3.400	8.647	2.941
[113]	3.600	10.776	3.283
[114]	1.600	0.288	0.536
[115]	1.200	2.304	1.518
[116]	3.400	7.299	2.702
[117]	2.400	5.390	2.322
[118]	3.400	8.647	2.941
[119]	3.600	10.776	3.283
[120]	1.600	0.288	0.536
[121]	1.200	2.304	1.518
[122]	3.400	7.299	2.702
[123]	2.400	5.390	2.322

[122]	3.400	7.299	2.702
[123]	2.400	5.390	2.322
[124]	3.400	8.647	2.941
[125]	3.600	10.776	3.283
[126]	1.600	0.288	0.536
[127]	1.200	2.304	1.518
[128]	3.400	7.299	2.702
[129]	2.400	5.390	2.322
[130]	3.400	8.647	2.941
[131]	3.600	10.776	3.283
[132]	1.600	0.288	0.536
[133]	1.200	2.304	1.518
[134]	3.400	7.299	2.702
[135]	2.400	5.390	2.322
[136]	3.400	8.647	2.941
[137]	3.600	10.776	3.283
[138]	1.600	0.288	0.536
[139]	1.200	2.304	1.518
[140]	3.400	7.299	2.702
[141]	2.400	5.390	2.322
[142]	3.400	8.647	2.941
[143]	3.600	10.776	3.283
[144]	1.600	0.288	0.536
[145]	1.200	2.304	1.518
[146]	3.400	7.299	2.702
[147]	2.400	5.390	2.322
[148]	3.400	8.647	2.941
[149]	3.600	10.776	3.283

MAE Errors Mean : 2.600

MSE Errors Mean : 5.784

RMSE Errors Mean : 2.217

MAE Errors Standart Deviation : 0.938

```

[125]      3.600      10.776      3.283
[126]      1.600       0.288      0.536
[127]      1.200       2.304      1.518
[128]      3.400       7.299      2.702
[129]      2.400       5.390      2.322
[130]      3.400       8.647      2.941
[131]      3.600      10.776      3.283
[132]      1.600       0.288      0.536
[133]      1.200       2.304      1.518
[134]      3.400       7.299      2.702
[135]      2.400       5.390      2.322
[136]      3.400       8.647      2.941
[137]      3.600      10.776      3.283
[138]      1.600       0.288      0.536
[139]      1.200       2.304      1.518
[140]      3.400       7.299      2.702
[141]      2.400       5.390      2.322
[142]      3.400       8.647      2.941
[143]      3.600      10.776      3.283
[144]      1.600       0.288      0.536
[145]      1.200       2.304      1.518
[146]      3.400       7.299      2.702
[147]      2.400       5.390      2.322
[148]      3.400       8.647      2.941
[149]      3.600      10.776      3.283

```

```

MAE Errors Mean : 2.600
MSE Errors Mean : 5.784
RMSE Errors Mean : 2.217

```

```

MAE Errors Standart Deviation : 0.938
MSE Errors Standart Deviation : 3.603
RMSE Errors Standart Deviation : 0.933

```

```

omer@omer:~/Desktop/HW02/HW02$ _

```

Notes:

- To run the program, I write a Makefile which exactly compiles and runs **program.c** using “**make**” command. Input file name is “**inputPath.txt**” and output file name is “**outputPath.txt**”.
- I send my input files and Makefile in .zip file.
- No errors, no warnings I caught showed in test results.
- All lockings works using signals.
- In my input file there are 150 lines to test which includes 20 character in each line (ignored new line characters).
- (*) If there is something wrong with deadlock, please kill the processes and restart to compile and run.