

TA 7

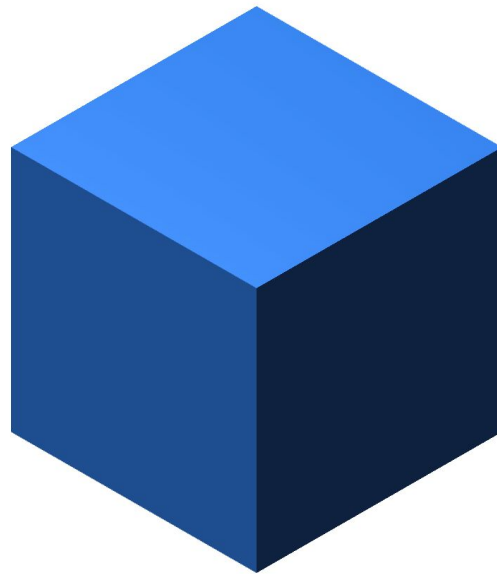
- Catmull-Clark Subdivision
- EX3
- C# Collections and Data Structures

Subdivision Surfaces

Computer Graphics 2020

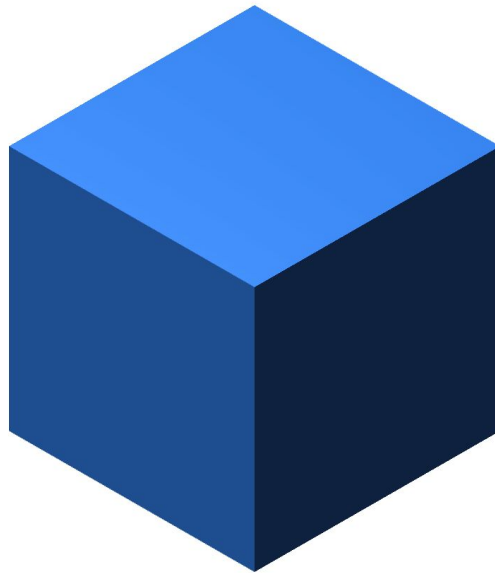
Catmull-Clark Subdivision

- A technique used in 3D computer graphics to create smooth surfaces by using a type of *subdivision surface* modeling



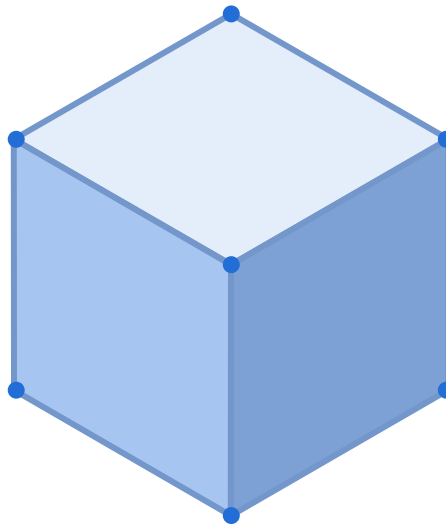
Catmull-Clark Subdivision

- Devised by Edwin Catmull and Jim Clark in 1978
- Edwin Catmull later went on to become president of Pixar and Walt Disney Animation Studios



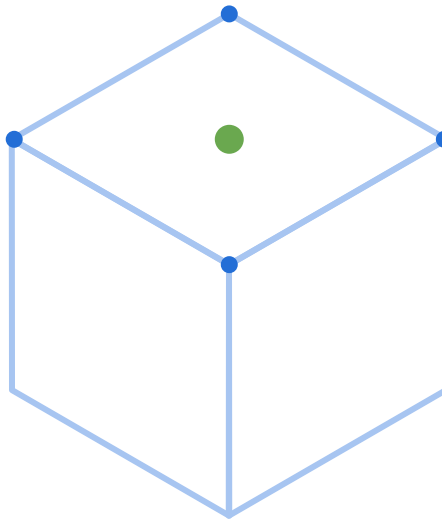
Catmull-Clark Subdivision

- Start with a mesh of an arbitrary polyhedron. All the vertices in this mesh shall be called *original points*



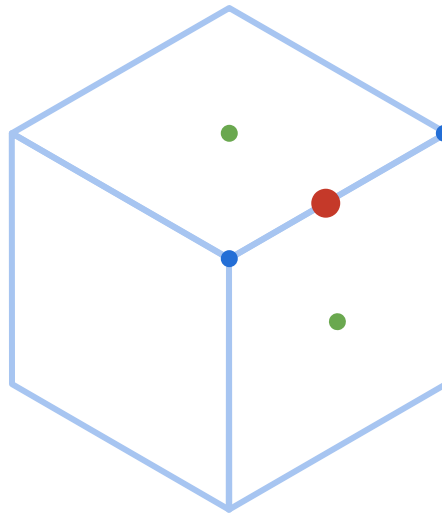
Catmull-Clark Subdivision

- For each face, add a *face point* at the average position of all *original points* of the respective face



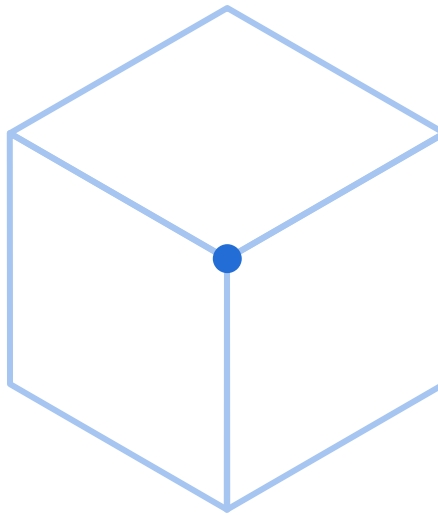
Catmull-Clark Subdivision

- For each edge, add an **edge point** at the average of the two neighbouring **face points** and its two **original endpoints**



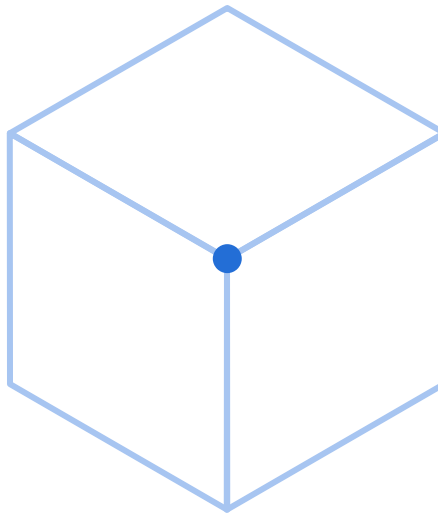
Catmull-Clark Subdivision

- To calculate the new position of each **original point**, we need to define some averages



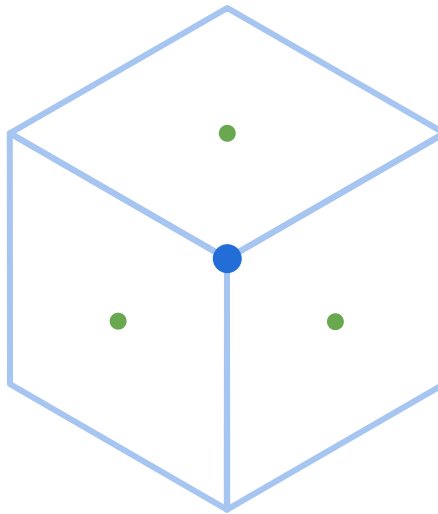
Catmull-Clark Subdivision

- For a vertex p , the number of edges neighboring p is also the number of adjacent faces
- Denote this number n



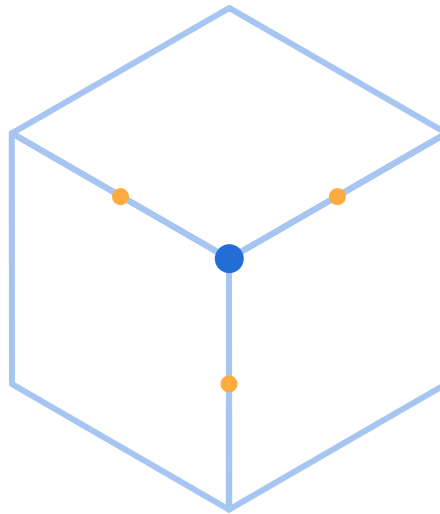
Catmull-Clark Subdivision

- Let f be the average of all n (recently created) face points for faces touching p



Catmull-Clark Subdivision

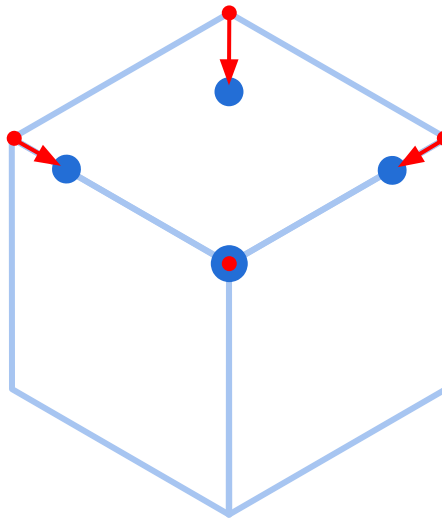
- Let r be the average of all n edge midpoints for (original) edges touching p
- Not to be confused with new edge points!



Catmull-Clark Subdivision

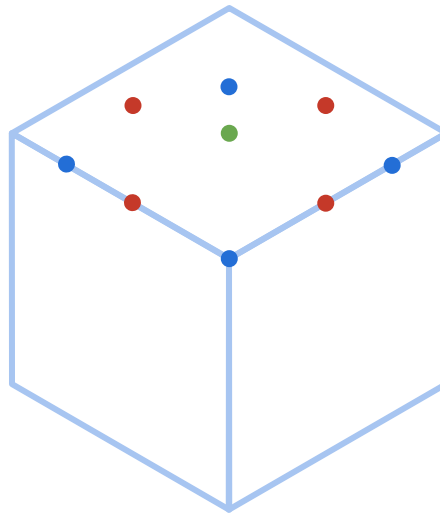
- The new position is given by:

$$\frac{f + 2r + (n - 3)p}{n}$$



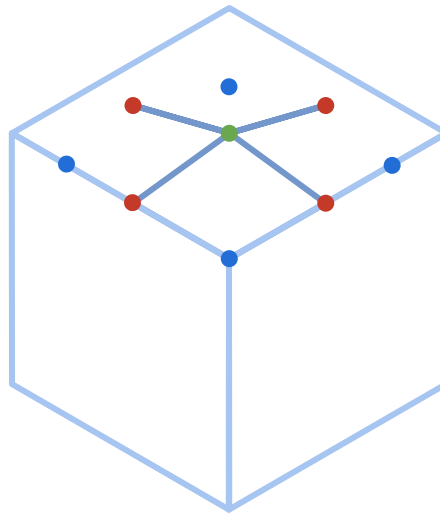
Catmull-Clark Subdivision

- We now have all new vertices in their final positions!



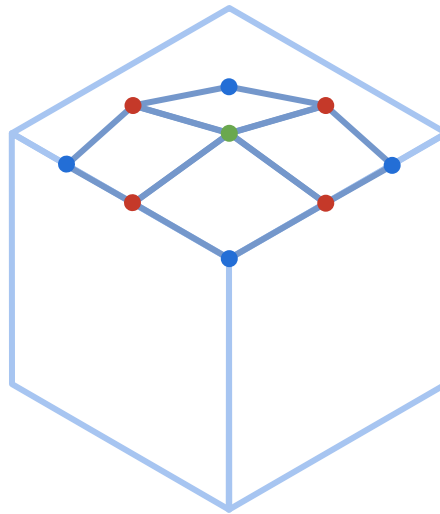
Catmull-Clark Subdivision

- Connect each **face point** to its corresponding **edge points**



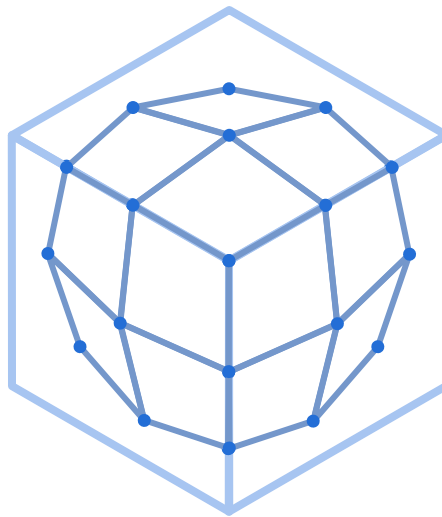
Catmull-Clark Subdivision

- Connect newly positioned **original point** to the **edge points** neighboring it



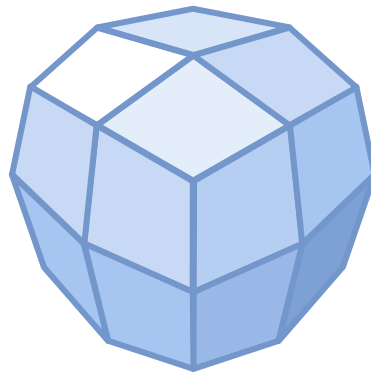
Catmull-Clark Subdivision

- Define new faces as enclosed by edges



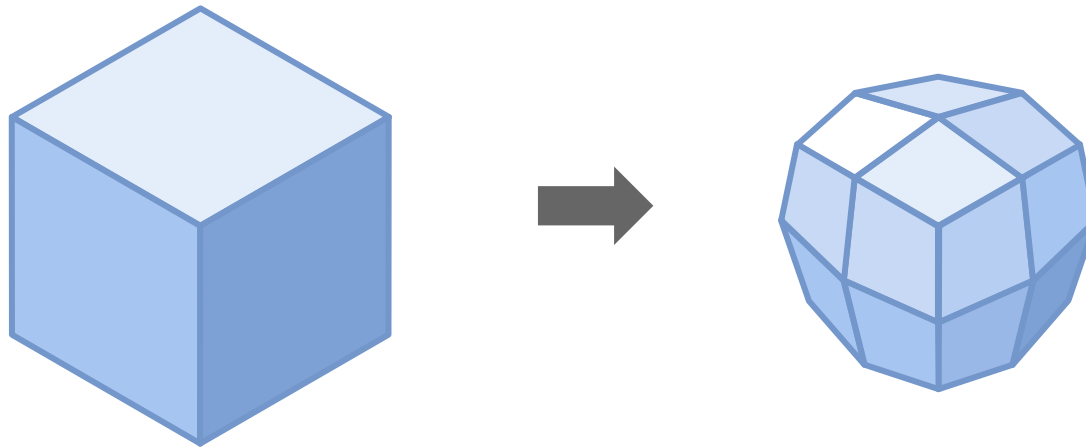
Catmull-Clark Subdivision

- We completed one iteration of Catmull-Clark subdivision!



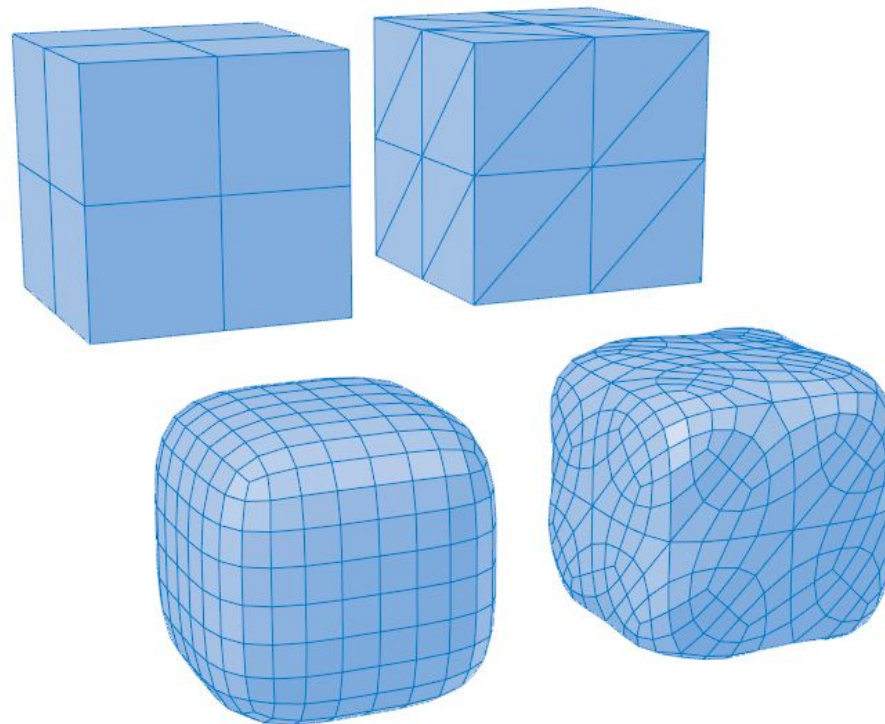
Catmull-Clark Subdivision

- The new mesh will generally look smoother
- The new mesh will consist only of quads, which in general **will not be planar**



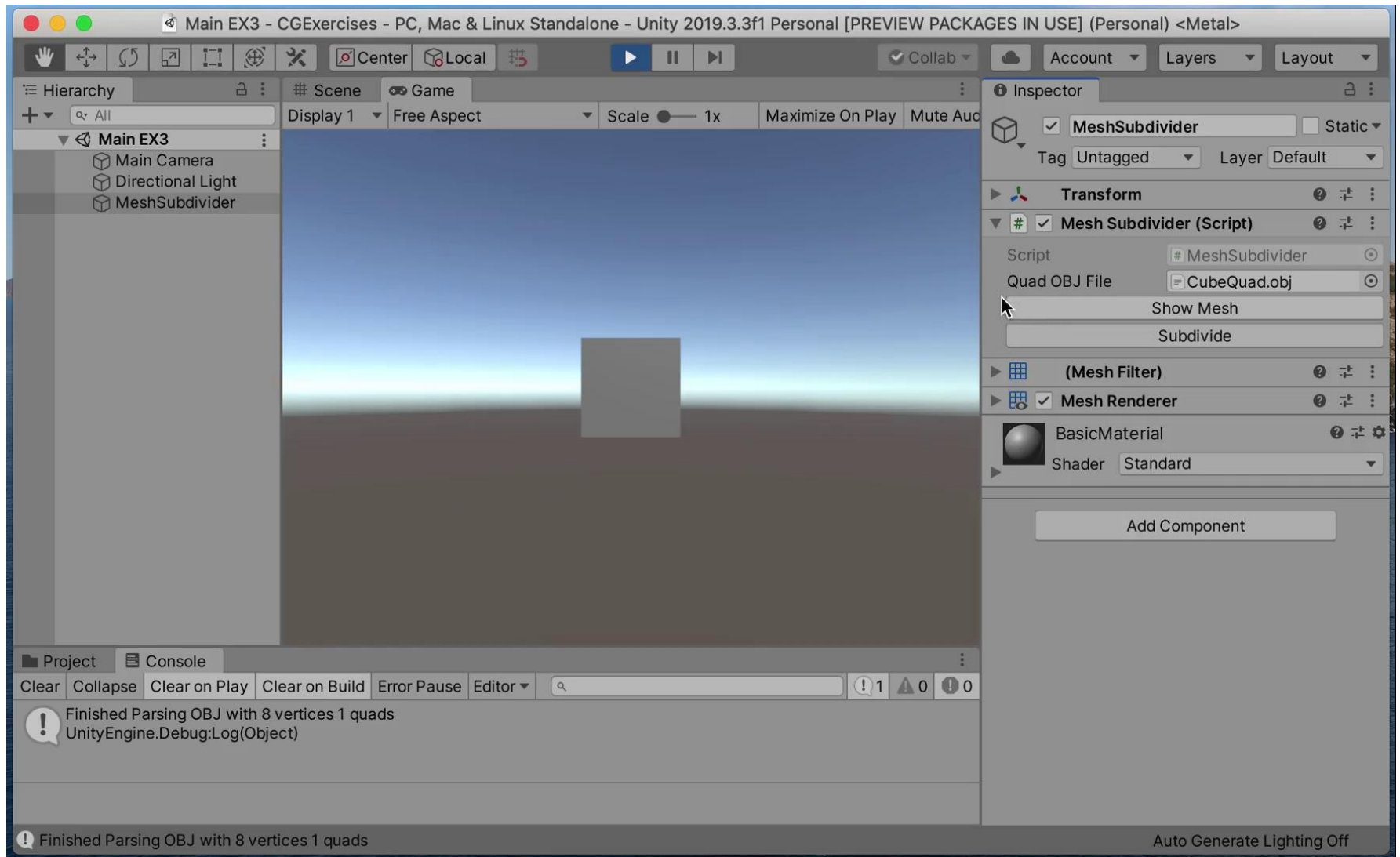
Catmull-Clark Subdivision

- For example, if we split a cube into triangles then subdivide:



EX3

- In this exercise you will implement Catmull-Clark subdivision algorithm
- You will be working only with quad meshes
- You **must** submit this exercise in pairs



EX3

- There are all kinds of ways to implement the algorithm exactly
- Efficiency is important - you may lose points for inefficient code!
- Meshes are data structures - C# provides classes that can help when working with meshes

C# Collections and Data Structures

- C# provides various useful data structures in its `System.Collections.Generic` namespace
- All collections provide methods for adding, removing, or finding items in the collection
- C# Collections docs:

docs.microsoft.com/en-us/dotnet/standard/collections/

C# Collections and Data Structures

- A few common C# data structures:
 - `List<T>`
 - `Queue<T>`
 - `Stack<T>`
 - `Dictionary<TKey, TValue>`
 - `SortedList<TKey, TValue>`

C# Comparisons and Sorts

- The `System.Collections` classes perform many comparisons when managing collections
- Methods such as `Contains`, `IndexOf` and `Remove` use an ***equality comparer***
- Methods such as `BinarySearch` and `Sort` use an ***ordering comparer***

Equality Comparer

- Subclass of `EqualityComparer<T>`
- Must implement 2 methods:
 - `Equals(T o1, T o2)`
Returns `true` if `o1` is equal to `o2`, `false` otherwise
 - `GetHashCode(T o)`
Returns a 32-bit integer representation of the object `o`

Equality Comparer Usage

```
1 public class Vec3Comparer : EqualityComparer<Vector3>
2 {
3     private static readonly float EPSILON = 0.001f;
4
5     public override bool Equals(Vector3 v1, Vector3 v2) {
6         if (Vector3.Distance(v1, v2) < EPSILON) {
7             return true;
8         }
9         return false;
10    }
11
12    public override int GetHashCode(Vector3 v) {
13        return 0;
14    }
15 }
```

Equality Comparer Usage

```
1  Vec3Comparer c = new Vec3Comparer();
2  Dictionary<Vector3, int> d = new Dictionary<Vector3, int>(c);
3
4  Vector3 v1 = new Vector3(1f, 1f, 1f);
5  Vector3 v2 = new Vector3(1.0001f, 1f, 1f);
6  Vector3 v3 = new Vector3(2f, 2f, 2f);
7
8  d.Add(v1, 1);
9
10 print(d[v1]); // prints "1"
11 print(d[v2]); // prints "1"
12 print(d[v3]); // KeyNotFoundException: key was not present
```

Equality Comparer

- When comparing vectors in Unity *approximately*, the convention is to use EPSILON = $1e-5f$ i.e. EPSILON = $0.00001f$
- Any vectors of distance \leq EPSILON from each other can be considered identical
- C# Docs: [EqualityComparer<T> Class](#)

Ordering Comparer

- For ordering, we just need to implement a comparison method with the signature:

```
int Compare(T o1, T o2)
```

- The method returns:
 - $o1 < o2 \Rightarrow -1$
 - $o1 == o2 \Rightarrow 0$
 - $o1 > o2 \Rightarrow 1$

Ordering Comparer Usage

```
1 public static int Vec3CompareCoordZ(Vector3 v1, Vector3 v2)
2 {
3     if (v1.z < v2.z)
4         return -1;
5     else if (v1.z == v2.z)
6         return 0;
7     else
8         return 1;
9 }
10
11 // ...
12 List<Vector3> l = new List<Vector3>();
13 l.Add(new Vector3(1, 1, 1));
14 l.Add(new Vector3(1, 1, 2));
15 l.Add(new Vector3(1, 1, 0)); // [(1,1,1), (1,1,2), (1,1,0)]
16
17 l.Sort(Vec3CompareCoordZ); // [(1,1,0), (1,1,1), (1,1,2)]
```

C# Comparisons and Sorts

- C# ordering comparer documentation:

docs.microsoft.com/en-us/dotnet/api/system.comparison

- C# general documentation about comparisons and sorts:

docs.microsoft.com/en-us/dotnet/standard/collections/comparisons-and-sorts-within-collections

Good luck!