

Series 4

The following *Lax-Milgram lemma*¹ holds:

Let H be a Hilbert space with its norm $\|\cdot\|_H$ and let $V \subset H$ be a closed subspace. Furthermore, let $a(\cdot, \cdot) : H \times H \rightarrow \mathbb{R}$ be a bilinear form such that the following conditions hold true:

1. (Continuity) There exists $C_1 > 0$ such that $|a(u, v)| \leq C_1 \|u\|_H \|v\|_H$ for any $u, v \in H$.
2. (Coercivity) There exists $C_2 > 0$ such that $a(u, u) \geq C_2 \|u\|_H^2$ for any $u \in H$.

Then for any bounded linear functional $l \in H^*$ there exists a unique solution $u \in V$ to the following variational problem: Find $u \in V$ such that

$$a(u, v) = l(v), \quad \forall v \in V.$$

1. Spaces $H_0^1(0, 1)$ and $H^{-1}(0, 1)$

The space $H^{-1}(0, 1)$ is defined as the dual space of $H_0^1(0, 1)$ (that is, $H^{-1}(0, 1)$ contains all bounded linear functionals on $H_0^1(0, 1)$).

a) For any function $f \in H_0^1(0, 1)$, define $\delta_{0.5}(f) = \tilde{f}(0.5)$, where \tilde{f} denotes the unique continuous modification of f . Show that $\delta_{0.5} \in H^{-1}(0, 1)$.

b) Given a $F \in H^{-1}(0, 1)$, consider the following PDE: Find $u \in H_0^1(0, 1)$ such that

$$-\Delta u = F \quad \text{on } (0, 1).$$

Its variational problem is of the following form: Find $u \in H_0^1(0, 1)$ such that for any $v \in H_0^1(0, 1)$,

$$\int_{(0,1)} u' v' dx = F(v). \quad (1)$$

Use the Lax-Milgram lemma and the Poincaré inequality (slides 2) to show that the variational problem (1) has a unique solution $u \in H_0^1(0, 1)$.

Let $F \in H^{-1}(0, 1)$ be arbitrary. With u as in Equation (1), we may write $u = (-\Delta)^{-1}F$, and hence obtain a mapping $(-\Delta)^{-1} : H^{-1}(0, 1) \rightarrow H_0^1(0, 1)$.

c) Verify that

$$(-\Delta)^{-1}\delta_{0.5} = \begin{cases} x/2, & x \in (0, 0.5), \\ 1/2 - x/2, & x \in [0.5, 1). \end{cases}$$

d) Show that we could establish a one-to-one correspondence between $H^{-1}(0, 1)$ and $H_0^1(0, 1)$ with $(-\Delta)^{-1}$ by verifying that it is injective and surjective. In this sense we may identify $H_0^1(0, 1)$ with its dual $H^{-1}(0, 1)$.

Important remark: Do not simply regard this result as $H_0^1(0, 1) = H^{-1}(0, 1)$! This would lead to wrong conclusions, e.g. the Gelfand triplet $H_0^1(0, 1) \subset L^2(0, 1) \subset H^{-1}(0, 1)$ becomes $H_0^1(0, 1) = L^2(0, 1) = H^{-1}(0, 1)$. We will see in the following question that $H^{-1}(0, 1)$, as a Hilbert space, could be equipped with an inner product different from the one used in $H_0^1(0, 1)$.

¹See e.g. Corollary 5.8 in Brezis' book.

e) Define the map $((\cdot, \cdot)): H^{-1}(0, 1) \times H^{-1}(0, 1) \rightarrow \mathbb{R}; (f, g) \mapsto f((-\Delta)^{-1}g)$. Show that $((\cdot, \cdot))$ defines an inner product on $H^{-1}(0, 1)$.

2. FEM for parabolic PDEs: Implementation

We continue studying the numerical solution of the following parabolic equation which was introduced in the previous exercise sheet for $G = J = (0, 1)$. Consider:

$$\begin{aligned} \partial_t u - \partial_x(\alpha(x)\partial_x u) + \beta(x)\partial_x u + \gamma(x)u &= f(t, x) && \text{in } J \times G \\ u &= 0 && \text{on } J \times \partial G \\ u|_{t=0} &= u_0 && \text{in } G, \end{aligned} \quad (2)$$

where $u_0 \in L^2(G)$, $f(t, x) \in L^2(J, H^{-1}(G))$, $\alpha, \gamma \in C(\overline{G})$ and $\beta \in C^1(\overline{G})$ such that with some $\underline{\alpha} > 0$ the bound $\alpha(x) > \underline{\alpha}$ holds for all $x \in G$.

Recall that for fixed $N, M \in \mathbb{N}$, we set $h = \frac{1}{N+1}$, $k = \frac{1}{M}$, the spatial mesh points $x_i := hi$, $i = 1, 2, \dots, N$ and discrete time points $t_j = kj$, $j = 0, 1, \dots, M$. We also define the spatial intervals $K_i = (h(i-1), hi)$, for $i = 1, 1, \dots, N+1$.

Following the same steps as for the heat equation in Problem 2 of the Exercise Sheet 2, we obtain the following full discretization using the finite element basis $V_N = \{\phi_{N,j}\}_{1 \leq j \leq N}$ for (2):

$$\begin{aligned} \text{Find } \underline{u}_N^m \in \mathbb{R}^N \text{ such that for } m = 1, \dots, M \\ (\mathbf{M} + k\vartheta \mathbf{A})\underline{u}_N^m &= (\mathbf{M} - k(1 - \vartheta)\mathbf{A})\underline{u}_N^{m-1} + k\underline{F}^m, \\ \underline{F}^m &= (\vartheta \underline{f}^m + (1 - \vartheta)\underline{f}^{m-1}), \\ \underline{u}_N^0 &= \underline{u}_0. \end{aligned} \quad (3)$$

a) Verify that the matrices \mathbf{M}, \mathbf{A} are given by

$$\mathbf{M}_{i,j} = (\phi_{N,j}, \phi_{N,i})_{L^2(G)} = \begin{cases} \frac{2h}{3}, & i = j \\ \frac{h}{6}, & |i - j| = 1 \\ 0, & \text{otherwise} \end{cases}$$

and

$$\mathbf{A}_{i,j} = \int_G \alpha(x) \partial_x \phi_{N,i} \partial_x \phi_{N,j} + \beta(x) (\partial_x \phi_{N,j}) \phi_{N,i} + \gamma(x) \phi_{N,i} \phi_{N,j} dx, \quad 1 \leq i, j \leq N. \quad (4)$$

As for the heat equation, \underline{f}^m is the column vector given by

$$\underline{f}_i^m(t) = (f(t_m), \phi_{N,i})_{L^2(G)}, \quad 1 \leq i \leq N.$$

Unlike for heat equation from the previous sheet, the coefficients α, β, γ are non-constant, which has to be taken into account when assembling the stiffness matrix \mathbf{A} .

b) Set $u = e^{-t} \sin(\pi x)$, $\alpha(x) = 1 + x^2$, $\beta(x) = 2x$ and $\gamma(x) = \pi^2 x^2$. Assuming that u is the classical solution to (2), determine $f(t, x)$.

c) Modify the template solution file "FEM_parabolic.py" so that it is suitable for solving (2) numerically. To do this, you should implement the function "build_rigidityMatrix" which additionally takes the coefficient functions "alpha,beta,gamma" as inputs.

Use Simpson quadrature, to approximate the integral in (4) for the entries of \mathbf{A} and construct the approximated matrix $\hat{\mathbf{A}} \in \mathbb{R}^{N \times N}$. The output of this Python functions shall be $\hat{\mathbf{A}}$, i.e. for $K_i = (x_{i-1}, x_i)$ and $g \in C(\overline{K_i})$

$$\int_{K_i} g(x) dx \approx \frac{h}{6} \left[g(x_{i-1}) + 4g\left(\frac{x_{i-1} + x_i}{2}\right) + g(x_i) \right].$$

We now repeat the numerical tests in the third question of Exercise Sheet 2.

d) Repeat 3f) in Exercise Sheet 2 and report the result.

e) Repeat 3e) in Exercise Sheet 2 with $l = \{5, 6, 7, 8, 9\}$ (N, M will then be different from those in Exercise Sheet 2!) and report the result.

Due: Wednesday, March 27th, at 2pm.

1. Spaces $H_0^1(0,1)$ and $H^{-1}(0,1)$

The space $H^{-1}(0,1)$ is defined as the dual space of $H_0^1(0,1)$ (that is, $H^{-1}(0,1)$ contains all bounded linear functionals on $H_0^1(0,1)$).

a) For any function $f \in H_0^1(0,1)$, define $\delta_{0.5}(f) = \tilde{f}(0.5)$, where \tilde{f} denotes the unique continuous modification of f . Show that $\delta_{0.5} \in H^{-1}(0,1)$.

a) We need to show $\delta_{0.5}$ is linear and bounded. And $\delta_{0.5}: H_0^1 \rightarrow \mathbb{R}$

The last statement is clear as $f \in H_0^1(0,1)$.

Linearity: $f, g \in H_0^1(0,1)$ and $\forall \lambda \in \mathbb{R}$, we have

$$\begin{aligned} \delta_{0.5}(\lambda f + g) &= (\lambda \tilde{f} + \tilde{g})(0.5) = \lambda \tilde{f}(0.5) + \tilde{g}(0.5) \\ &= \lambda \delta_{0.5}(f) + \delta_{0.5}(g) \end{aligned}$$

Boundedness:

$$|\delta_{0.5}(f)| = |\tilde{f}(0.5)| \leq \|\tilde{f}\|_{C^0(0,1)} = \|f\|_{C^0(0,1)} \quad \uparrow \quad \text{definition of } f.$$

To conclude, we use the exercise 3.1.6 which states that $\exists C = C(\Omega)$ it

$$\|f\|_{C^0(0,1)} \leq C \|f\|_{H_0^1} \Rightarrow |\delta_{0.5}(f)| \leq C \|f\|_{H_0^1}$$

$$\Rightarrow \|\delta_{0.5}\| \leq C$$

operator norm.

b) Given a $F \in H^{-1}(0,1)$, consider the following PDE: Find $u \in H_0^1(0,1)$ such that

$$-\Delta u = F \quad \text{on } (0,1).$$

Its variational problem is of the following form: Find $u \in H_0^1(0,1)$ such that for any $v \in H_0^1(0,1)$,

$$\int_{(0,1)} u'v' dx = F(v). \quad (1)$$

Use the Lax-Milgram lemma and the Poincaré inequality (slides 2) to show that the variational problem (1) has a unique solution $u \in H_0^1(0,1)$.

The following Lax-Milgram lemma holds:

Let H be a Hilbert space with its norm $\|\cdot\|_H$ and let $V \subset H$ be a closed subspace. Furthermore, let $a(\cdot, \cdot): H \times H \rightarrow \mathbb{R}$ be a bilinear form such that the following conditions hold true:

1. (Continuity) There exists $C_1 > 0$ such that $|a(u, v)| \leq C_1 \|u\|_H \|v\|_H$ for any $u, v \in H$.
2. (Coercivity) There exists $C_2 > 0$ such that $a(u, u) \geq C_2 \|u\|_H^2$ for any $u \in H$.

Then for any bounded linear functional $l \in H^*$ there exists a unique solution $u \in V$ to the following variational problem: Find $u \in V$ such that

$$a(u, v) = l(v), \quad \forall v \in V.$$

To use the Lax-Milgram lemma we need a bilinear form. We define

$$\begin{aligned} a(\cdot, \cdot) : H_0^1(0,1) \times H_0^1(0,1) &\rightarrow \mathbb{R} \\ a(u, v) &\mapsto \int_0^1 u'v' dx \end{aligned}$$

Now we show that a is cts and coercive.

cts: $|a(u, \varphi)| = \left| \int_0^1 u' \varphi' dx \right| \leq \int_0^1 |u' \varphi'| dx = \|u' \varphi'\|_{L^1(0,1)} \stackrel{\text{Hölder}}{\leq} \|u'\|_{L^2} \cdot \|\varphi'\|_{L^2}$

$$\leq \|u\|_{H_0^1} \cdot \|\varphi\|_{H_0^1}$$

coercive: $a(u, u) = \int_0^1 (u')^2 dx = \|u'\|_{L^2}^2 =$

$$= \frac{1}{2} \|u'\|_{L^2}^2 + \frac{1}{2} \|u'\|_{L^2}^2 \geq$$

$$\geq \frac{1}{2} \|u'\|_{L^2}^2 + \frac{1}{2C} \|u'\|_{L^2}^2$$

$$\geq \frac{1}{2} \min\{C^{-1}, 1\} \|u\|_{H_0^1}^2(0,1)$$

Theorem (Poincaré inequality)

Assume that $G \subset \mathbb{R}$ is bounded and let $1 \leq p < \infty$. Then, there exists $C(G, p)$ such that $\|u\|_{L^p(G)} \leq C \|u'\|_{L^p(G)}$ for all $u \in W_0^{1,p}(G)$.

$$a(u, u) = \int_G |u'(x)|^2 dx = \frac{1}{2} \|u'\|_{L^2(G)}^2 + \frac{1}{2} \|u'\|_{L^2(G)}^2$$

$$\geq \frac{1}{2C} \|u'\|_{L^2(G)}^2 + \frac{1}{2} \|u'\|_{L^2(G)}^2$$

$$\geq \frac{1}{2} \min\{C^{-1}, 1\} (\|u'\|_{L^2(G)}^2 + \|u'\|_{L^2(G)}^2) = C_1 \|u\|_{H^1(G)}^2$$

Given $F \in H^{-1}(0,1)$, Lax-Milgram lemma implies that

$\exists! u \in H_0^1$ st $F(\varphi) = a(u, \varphi)$

Let $F \in H^{-1}(0,1)$ be arbitrary. With u as in Equation (1), we may write $u = (-\Delta)^{-1}F$, and hence obtain a mapping $(-\Delta)^{-1} : H^{-1}(0,1) \rightarrow H_0^1(0,1)$.

c) Verify that

$$(-\Delta)^{-1} \delta_{0.5} = \begin{cases} x/2, & x \in (0, 0.5), \\ 1/2 - x/2, & x \in [0.5, 1). \end{cases}$$

i.e. we need to show $u = \begin{cases} x/2 & 0 \leq x < 1/2 \\ 1/2 - x/2 & 1/2 \leq x < 1 \end{cases}$ is the unique

solution to the variational problem $\int_0^1 u' \varphi' dx = \int_{0.5} (\varphi) = \tilde{\varphi}(0.5)$

$$u' = \begin{cases} 1/2 & 0 \leq x < 1/2 \\ -1/2 & 0.5 \leq x < 1 \end{cases} \Rightarrow \int_0^1 u' \varphi' dx = \frac{1}{2} \int_0^{1/2} \varphi' dx - \frac{1}{2} \int_{1/2}^1 \varphi' dx$$

$$= \frac{1}{2} [\tilde{\varphi}(1/2) - \tilde{\varphi}(0)] - \frac{1}{2} [\tilde{\varphi}(1) - \tilde{\varphi}(1/2)]$$

$$= \tilde{\varphi}(1/2)$$

$\Rightarrow a(u, \varphi) = \int_{0.5} (\varphi)$ as intended.

d) Show that we could establish a one-to-one correspondence between $H^{-1}(0,1)$ and $H_0^1(0,1)$ with $(-\Delta)^{-1}$ by verifying that it is injective and surjective. In this sense we may identify $H_0^1(0,1)$ with its dual $H^{-1}(0,1)$.

We will show that $(-\Delta)^{-1}$ is both injective and surjective.

Notice at point b we showed that there exists a solution which implies surjectivity and also that the solution is unique which implies injectivity.

Formally: suppose $u_1, u_2 \in H^{-1}(0,1)$ st $(-\Delta)^{-1}(u_1) = u = (-\Delta)^{-1}(u_2)$

then using the PDE formulation we get:

$$u_1 = -\Delta(-\Delta)^{-1}(u_1) = -\Delta u = -\Delta(-\Delta)^{-1}(u_2) = u_2$$

which shows injectivity.

Now take $u \in H_0^1(0,1)$ we want to show $\exists F \in H^{-1}(0,1)$ st $(-\Delta)^{-1}F = u$.

So we take $F : H_0^1(0,1) \rightarrow \mathbb{R}$, $\varphi \mapsto \int_0^1 u' \varphi' dx$. Defined like this

F is a bounded linear operator. (Bounded by b) linearity is clear) $\Rightarrow F \in H^{-1}(0,1)$

Furthermore by the previous points, clearly $(-\Delta^{-1})F = u \Rightarrow (-\Delta)^{-1}$ surjective

Thus we found the desired F , and we can conclude that $(-\Delta)^{-1}$ is indeed bijective.

e) Define the map $((\cdot, \cdot)) : H^{-1}(0,1) \times H^{-1}(0,1) \rightarrow \mathbb{R}; (f, g) \mapsto f((-\Delta)^{-1}g)$. Show that $((\cdot, \cdot))$ defines an inner product on $H^{-1}(0,1)$.

We verify that $((\cdot, \cdot))$ satisfies the properties of an inner product. Take $g \in H^{-1}(0,1)$

$$\bullet (g, g) = g((-\Delta)^{-1}g) = \int_0^1 \underbrace{((-\Delta^{-1})g)'}_{\geq 0}^2 dx \geq 0$$

$$\text{and } (g, g) = 0 \Rightarrow (-\Delta)^{-1}g = 0 \text{ (by the previous line)}$$

$$\Rightarrow g = 0 \text{ since } (-\Delta)^{-1} \text{ is bijective and } (-\Delta)^{-1}0 = 0$$

\bullet symmetric is clear so we just show bilinearity: $f, g_1, g_2 \in H^{-1}(0,1)$, $\lambda \in \mathbb{R}$

$$(f, g_1 + \lambda g_2) = \int (-\Delta^{-1})f \cdot (-\Delta^{-1}g_1 + (-\Delta)^{-1}\lambda g_2) = \int (-\Delta)^{-1}f (-\Delta)^{-1}g_1 + \int (-\Delta)^{-1}f (-\Delta)^{-1}\lambda g_2$$

$$= (f, g_1) + \lambda (f, g_2) \quad \text{note: } (-\Delta)^{-1}\lambda g_2 = \lambda (-\Delta)^{-1}g_2 \text{ because } \Delta u = g_2 \Leftrightarrow \lambda \Delta u = \lambda g_2$$

a) Verify that the matrices \mathbf{M}, \mathbf{A} are given by

$$\mathbf{M}_{i,j} = (\phi_{N,j}, \phi_{N,i})_{L^2(G)} = \begin{cases} \frac{2h}{3}, & i = j \\ \frac{h}{6}, & |i - j| = 1 \\ 0, & \text{otherwise} \end{cases}$$

and

$$\mathbf{A}_{i,j} = \int_G \alpha(x) \partial_x \phi_{N,i} \partial_x \phi_{N,j} + \beta(x) (\partial_x \phi_{N,j}) \phi_{N,i} + \gamma(x) \phi_{N,i} \phi_{N,j} dx, \quad 1 \leq i, j \leq N. \quad (4)$$

As for the heat equation, \underline{f}^m is the column vector given by

$$\underline{f}_i^m(t) = (f(t_m), \phi_{N,i})_{L^2(G)}, \quad 1 \leq i \leq N.$$

Unlike for heat equation from the previous sheet, the coefficients α, β, γ are non-constant, which has to be taken into account when assembling the stiffness matrix \mathbf{A} .

b) Set $u = e^{-t} \sin(\pi x)$, $\alpha(x) = 1 + x^2$, $\beta(x) = 2x$ and $\gamma(x) = \pi^2 x^2$. Assuming that u is the classical solution to (2), determine $f(t, x)$.

$$a) \quad \phi_{N,i} = \begin{cases} \frac{x - x_{i-1}}{x_i - x_{i-1}} & \text{if } x \in [x_{i-1}, x_i] \\ \frac{x_{i+1} - x}{x_{i+1} - x_i} & \text{if } x \in [x_i, x_{i+1}] \\ 0 & \text{o.w.} \end{cases}$$

$$\text{Then if } |i - j| > 1 \Rightarrow (\phi_{N,i}, \phi_{N,j})_G = 0.$$

$$\begin{aligned} \text{For } i = j: \quad (\phi_{N,i}, \phi_{N,i})_G &= \int_0^1 \left(\left(\frac{x - x_{i-1}}{x_i - x_{i-1}} \right) \mathbb{1}_{[x_{i-1}, x_i]} + \left(\frac{x_{i+1} - x}{x_{i+1} - x_i} \right) \mathbb{1}_{[x_i, x_{i+1}]} \right)^2 dx \\ &= \frac{1}{h^2} \left[\int_{x_{i-1}}^{x_i} (x - x_{i-1})^2 dx + \int_{x_i}^{x_{i+1}} (x_{i+1} - x)^2 dx \right] \\ &= \frac{2}{3} h. \end{aligned}$$

$$\text{for } j = i + 1:$$

$$\begin{aligned} (\phi_{N,i}, \phi_{N,i+1})_G &= \int_0^1 \left(\left(\frac{x - x_{i-1}}{x_i - x_{i-1}} \right) \mathbb{1}_{[x_{i-1}, x_i]} + \left(\frac{x_{i+1} - x}{x_{i+1} - x_i} \right) \mathbb{1}_{[x_i, x_{i+1}]} \right) \\ &\quad \cdot \left(\left(\frac{x - x_i}{x_{i+1} - x_i} \right) \mathbb{1}_{[x_i, x_{i+1}]} + \left(\frac{x_{i+2} - x}{x_{i+2} - x_{i+1}} \right) \mathbb{1}_{[x_{i+1}, x_{i+2}]} \right) dx \\ &= \frac{1}{h^2} \int_{x_i}^{x_{i+1}} (x_{i+1} - x)(x - x_i) dx = \frac{1}{6} h. \end{aligned}$$

$$\text{For } A_{i,j} \text{ we calculate the above expression w/ } \phi'_{N,i} = \begin{cases} 1 & x \in [x_{i-1}, x_i] \\ -1 & x \in [x_i, x_{i+1}] \\ 0 & \text{o.w.} \end{cases}$$

b) we compute the PDE by plugging in the solution.

$$f(t, x) = \partial_t u - \partial_x (\alpha(x) \partial_x u) + \beta(x) \partial_x u + \gamma(x) u$$

$$= -e^{-t} \sin(\pi x) - \partial_x ((1+x^2) \pi e^{-t} \cos(\pi x)) + 2x (\pi e^{-t} \cos(\pi x)) + \pi^2 x^2 e^{-t} \sin(\pi x)$$

$$= (\pi^2 + 2\pi^2 x^2 - 1) e^{-t} \sin(\pi x)$$