Unsupervised Learning

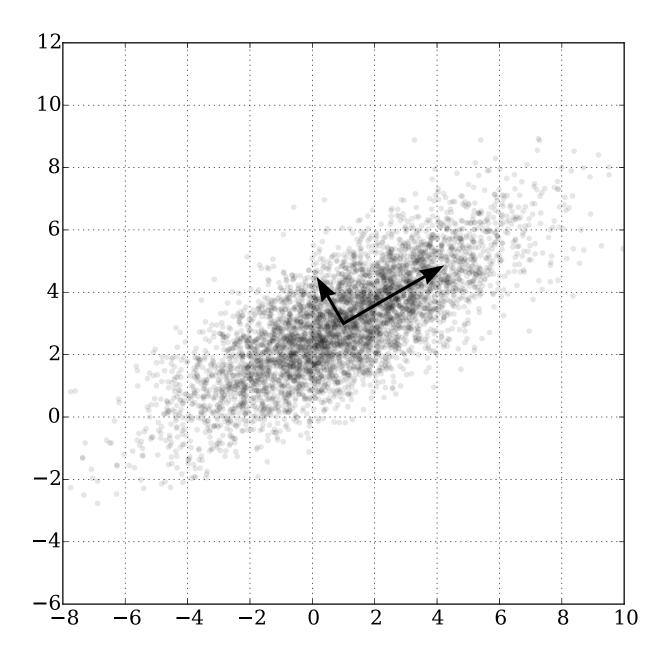
- Question: Which of the follow are unsupervised learning methods? (choose all that apply)
 - A. Principal components analysis
 - B. Causal Discovery
 - C. T-tests
 - D. GLMs
 - E. K-means
- All of the previous lectures have been on supervised learning
 - Supervised learning is the class of data method for mapping inputs to outputs, like prediction or inference
 - Supervised learning data: $(X_1, Y_1), \dots, (X_n, Y_n)$
 - Goal: Minimize some loss function: L(f(X), Y)
 - Typically, we think of X and Y as a joint distribution, P(X,Y) = P(Y|X)P(X)
 - In supervised learning, we are more interested P(Y|X) (or E(Y|X)) than P(X)
- Unsupervised learning is a class of data methods for unlabeled data
 - Here, we are interested in learning properties of P(X) without using labels, Y
 - examples: clustering, anomaly detection, latent variable analysis

Dimensionality Reduction

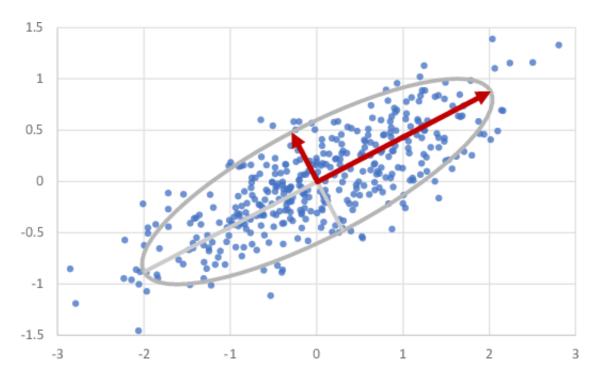
Methods for reducing the number of variables in a dataset

Principle Components Analysis (PCA)

- Question: Have you ever used PCA?
 - A. Yes
 - B. No
- PCA tries to explain variance in the data using linear combinations of the variables



• Developed in 1901 by Pearson (https://en.wikipedia.org/wiki/Principal_component_analysis)



- PCA can be thought of as fitting a p-dimensional ellipsoid to the data, where each axis of the ellipsoid represents a principal component
- . If some axis of the ellipsoid is small, then the variance along that axis is also small
- Assume X is an $n \times p$ standardized data matrix
 - standardized data: for each column, X_j of X, replace with $\frac{X_j \bar{X}_j}{\widehat{\text{var}(X_i)}}$
- First principal component: find unit-vector (direction), w, that best fits the data
 - find the directions within the data with the greatest variance
- · Optimization:

$$w^* = \arg\max_{\|w\|=1} \widehat{\mathrm{var}}(Xw) = \arg\max_{\|w\|=1} \|Xw\| = \arg\max_{w} \frac{w^T X^T X w}{w^T w}$$
 where $\|w\| = \sqrt{\sum_i w_i^2}$ is the Euclidean norm

- Recall that $\boldsymbol{X}^T\boldsymbol{X}$ is the empirical covariance matrix
- Eigenvectors of X^TX solve the problem
 - Lagrangian:

$$\mathcal{L}(w,\lambda) = w^T X^T X w - \lambda w^T w$$

Gradient with respect to w:

$$\nabla_w \mathcal{L} = 2X^T X w - 2\lambda w = 0$$

- Then $X^TXw = \lambda w$, so principal components are eigenvectors of X^TX
- The first principal component has largest corresponding eigenvalue, λ
- The second principal component has second largest, etc

- Notice that there will be p total principal components
 - it is common to use the first k principal components with the that explain the majority of the variance, above some pre-set cutoff
- If w_1, w_2, \ldots, w_k are the first k < p components, we can regress an outcome on Xw_1, \ldots, Xw_k in place of X
- All principal component vectors, w_1, \dots, w_p are mutually orthogonal (zero dot product or forming right angles)
- PCA is an old method that is still sometimes used but it has inspired many other methods

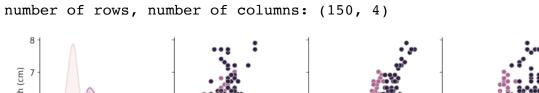
Iris Data

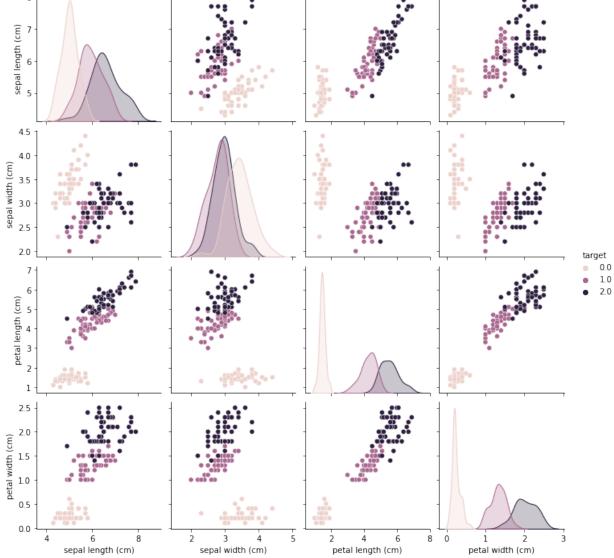
- 150 rows, 4 features
- Label (target): 0,1,2 (flower type)
- We only label for color coding but won't use in analysis
- Below is are scatter and density plots

```
In [1]: import numpy as np
   import matplotlib.pyplot as plt
   import seaborn as sns
   import pandas as pd
   from sklearn.decomposition import PCA

from sklearn.datasets import load_iris
   iris = load_iris()
   label_data = pd.DataFrame(
        data= np.c_[iris['data'], iris['target']],
        columns= iris['feature_names'] + ['target'])
   data = iris['data']

print(f'number of rows, number of columns: {data.shape}')
   sns.pairplot(label_data, hue="target");
```





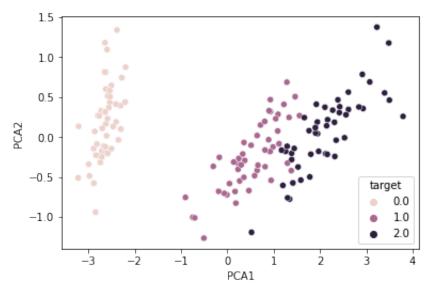
Below: Using PCA to explain variance in data with sklearn

```
In [2]: pca = PCA()
    pca.fit(data)
    print(f'Variance explained in each component: \
        {pca.explained_variance_ratio_}')
    print(f'lambda values: {pca.singular_values_}')
    print(f'All components: {pca.components_}')

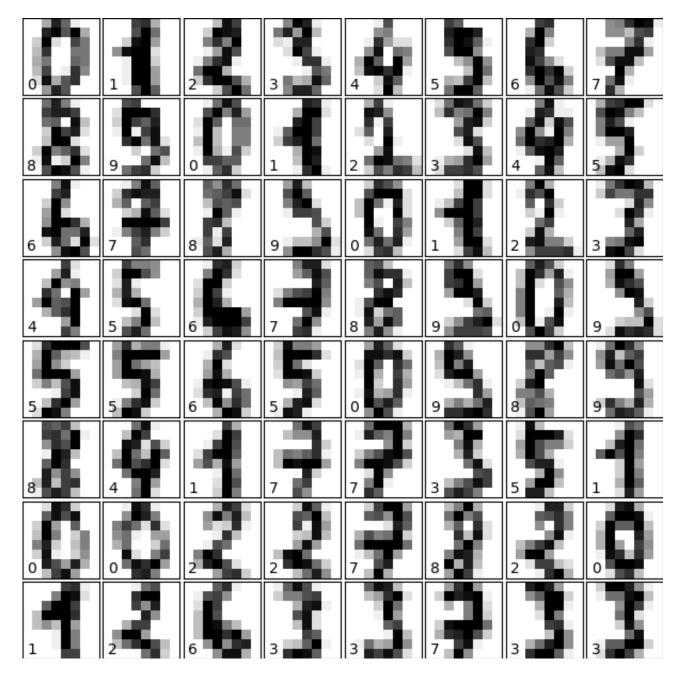
Variance explained in each component: [0.92461872 0.05306648 0.01710 261 0.00521218]
    lambda values: [25.09996044 6.01314738 3.41368064 1.88452351]
    All components: [[ 0.36138659 -0.08452251 0.85667061 0.3582892 ]
        [ 0.65658877 0.73016143 -0.17337266 -0.07548102]
        [ -0.58202985 0.59791083 0.07623608 0.54583143]
        [ -0.31548719 0.3197231 0.47983899 -0.75365743]]
```

- Choosing the top two components
- Jointly they explain ~98% of the variance in features

Below: Labeled scatter plot of first two principal components



<u>Handwritten Digit Data (https://archive.ics.uci.edu/ml/datasets/Pen-Based+Recognition+of+Handwritten+Digits)</u>



- 250 samples from 44 writers (according to UCI data repo)
- 1797 8x8 images transformed into feature vectors of length 64
- There is variation in writing style, thickness, and orientation

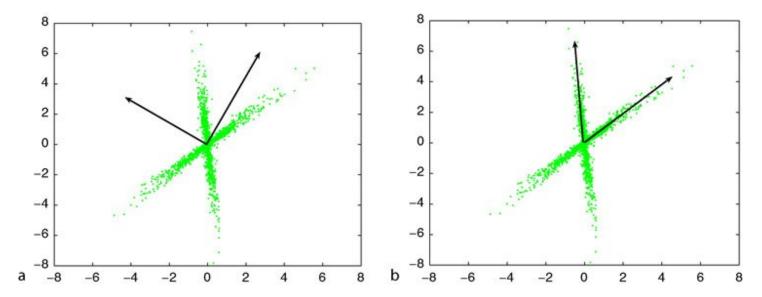
```
In [5]: from sklearn.datasets import load digits
        X, y = load digits(return X y=True)
        print(f'Dimensions of X: {X.shape}')
        print(f'Dimensions of y: {y.shape}')
        print('Looking at top left corner of data:')
        X[0:5,0:10]
        Dimensions of X: (1797, 64)
        Dimensions of y: (1797,)
        Looking at top left corner of data:
Out[5]: array([[ 0.,
                     0.,
                          5., 13., 9., 1., 0., 0., 0., 0.]
              [ 0.,
                     0., 0., 12., 13., 5., 0.,
                                                   0.,
                                                       0.,
                                                             0.],
              [ 0., 0., 0., 4., 15., 12., 0., 0., 0.,
                                                             0.1,
              [ 0., 0., 7., 15., 13., 1., 0., 0.,
                                                       0.,
               [ 0., 0., 0., 1., 11., 0., 0.,
                                                   0.,
                                                        0., 0.11)
In [6]: pca = PCA()
        pca.fit(X)
        print(f'Variance explained in first 10 components:\n\
        {np.round(pca.explained variance ratio [0:10], 4)}')
        print(f'Variances of first 10: \n\
        {np.round(pca.singular values [0:10], 2)}')
        Variance explained in first 10 components:
        [0.1489 0.1362 0.1179 0.0841 0.0578 0.0492 0.0432 0.0366 0.0335 0.03
        081
        Variances of first 10:
        [567.01 542.25 504.63 426.12 353.34 325.82 305.26 281.16 269.07 257.
        82]
```

- How well do the first 10 principal components predict the digit compared to the entire data?
- Below we'll use random forest on the full data and on the PCA transformed data
- Rather than using cross (or held out) validation, we will use out of bag sample accuracy

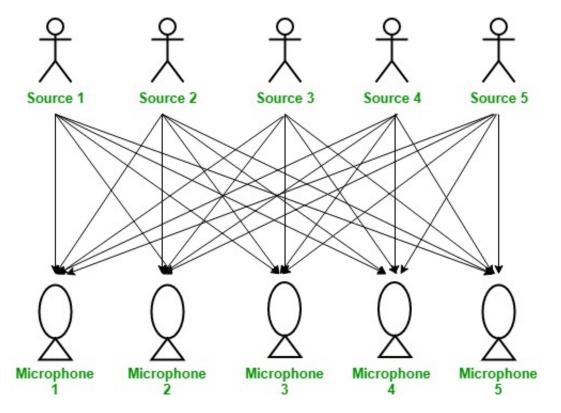
Out of bag accuracy for full data: 0.7835281023928771
Out of bag accuracy PCA transformed data: 0.7857540345019477

Independent Componenets Analysis (ICA)

- Question: Have you heard of ICA before?
 - A. Yes
 - B. No
- What if the sources of noise in the data are not orthogonal?
- Image below: left panel is PCA; right panel is ICA



- ICA attempts to factor a random matrix X = AS where X is the $n \times p$ data matrix
- S is an $n \times p$ matrix called the latent source matrix
- A is a $p \times p$ matrix called the mixing matrix
- ullet Goal: Estimate A so that the columns of S are mutually independent
- Interestingly, this is only possible for non-Gaussian distributions
- Cocktail Party Example: Assume that there are p mircophones placed around a room with p people speaking at the same time
 - Goal: Use signal from each mircophone to distinguish each speaker



• Without loss of generality, we can assume that E(S) = 0 and $Cov(S) = I_p$ (this covariance assume uncorrelated, not independent!)

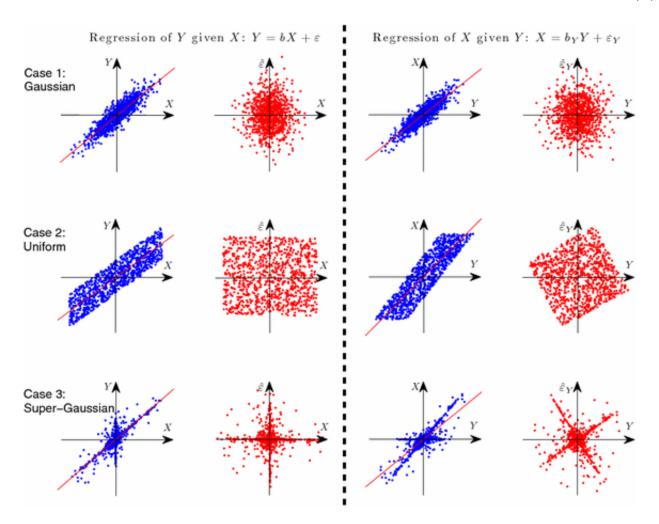
• Then

$$Cov(X) = Cov(AS) = AA^T$$

• If R is any orthogonal $p \times p$ matrix ($R^{-1} = R^T$), then

$$X = AS = AR^T RS = (AR^T)(RS)$$

- And, $Cov(RS) = RI_pR^T = I_p$, because correlation is not unique under rotations
- For Gaussian distribution, it is perfectly characterized by its first and second moments
 - For Gaussian distributions uncorrelated implied independent, which is why we assume non-Gaussian
- ICA uses third and higher moments to estimate A
 - In fact, it attempts to maximize divergence from Gaussianity
- ICA can be used for causal discovery
 - Causal discovery methods estimate a causal Bayesian network from data
 - Assume $X \to Y$ as $Y = bX + \epsilon$ where X and ϵ are independent random variables, and $E[\epsilon] = 0$ (zero-mean noise)
 - We only observe X and Y in the data but X and ϵ are the independent components
 - If X and ϵ are non-Gaussian, we can use ICA to determine causal ordering



Optimization

- There is a <u>lot of literature (https://www.wiley.com/en-us/Independent+Component+Analysis-p-9780471405405)</u> on ways to optimize ICA
- Using entropy and mutual information:
 - Recall entropy $H(Y) = -\int p(y) \log p(y) dy$ where $Y \sim p$
 - If $Y=(Y_1,\ldots,Y_p)$, then the multivariate mutual information between all variables is

$$I(Y) = \sum_{j=1}^{p} H(Y_j) - H(Y)$$

- Recall that if I(Y) = 0 then all Y_i are mutually independent
- If $\mathrm{Cov}(X) = I_p$ and W is a $p \times p$ orthogonal matrix, we can minimize

$$W^* = \arg\min_{W} I(WX) = \arg\min_{W} \sum_{i=1}^{p} H(w_j^T X) - H(X)$$

where w_j is the jth row of W

- Then use $A^* = (W^*)^{-1}$
- Unfortunately, estimating entropy can be challenging and sometimes computationally expensive
- FastICA:

- Interestingly, minimizing I(WX) is equivalent to maximizing the departure of each w_j^TX from Gaussianity
- Negentropy $J(Y_j) = H(Y_j) H(Z_j)$ where Z_j is a Gaussian random variable with the same variance as Y_j (measure departure from Gaussianity)
- FastICA approximates negentropy with

$$J(w_j^T) \approx \left(E[G(w_j^TX)] - E[G(w_j^TZ)]\right)$$
 where $G(y) = \frac{1}{a}\log\cosh y$ for $a \in (1,2)$

ICA notes based on these slides (http://statweb.stanford.edu/~tibs/sta306bfiles/ica.pdf)

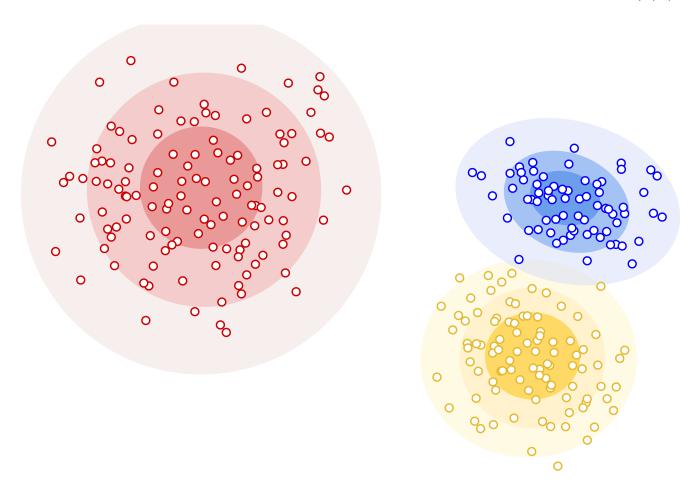
- The code below uses FastICA to transform the the data
- Again, we use random forest to see how well the transformed data predicts the label
- Note: it can be difficult to optimize ICA

Out of bag accuracy for ICA transformed data: 0.7835281023928771

Cluster Analysis (clustering)

- Clustering attempts to group together observations that are close to each other
- This can take different forms
- It might be that data points are grouped around central points

4/14/22, 11:55 AM unsupervised



• In other cases, groups are formed by proximity to other points in the group, like a chain



K-means

- ullet Goal: group points using proximity to K unknown cluster centers
- This approach would work better for data in the top image, but not the bottom image
- Assume X_1,\ldots,X_n is a sample where $X_i\in\mathbb{R}^d$ for $i=1,\ldots,n$ Let $C=\{c_1,\ldots,c_K\},c_k\in\mathbb{R}^d$, be variable point that we will use to find cluster centers

- Lloyd's algorithm (https://en.wikipedia.org/wiki/Lloyd%27s_algorithm) has two steps:
 - 1. Assign a cluster: for each point, $i=1,\ldots,n$, find the closest $c_k\in C$, $z_i=\arg\min_{1\leq k\leq K}\|X_i-c_k\|$
 - 2. Recenter cluster: update each c_k with the new group,

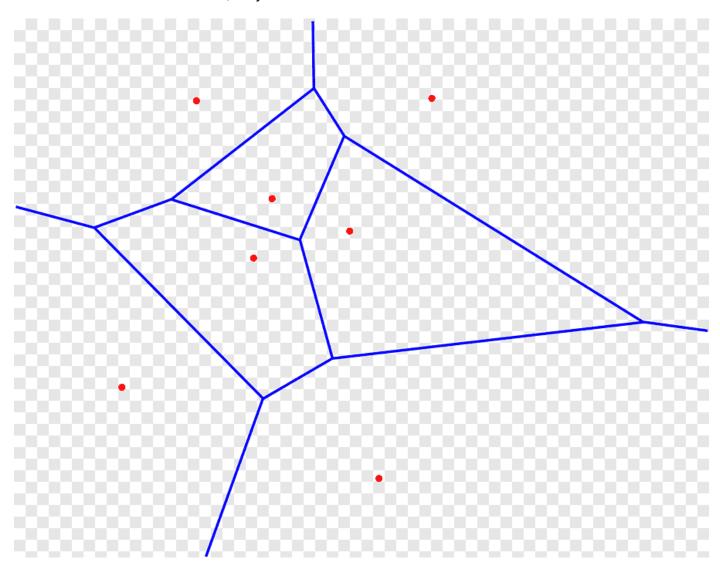
$$c_k \leftarrow \frac{1}{n_k} \sum_{i: z_i = k} X_i$$

$$n_k = \#\{i : z_i = k\}$$

- We can initialize this algorithm with K random points in \mathbb{R}^d
- These two steps are repeated until *C*, the cluster center points, converge (until they stop moving between steps)
- Optimization:

$$\frac{1}{n} \sum_{i=1}^{n} \min_{1 \le k \le K} \|X_i - c_{z_i}\|^2$$

• Once the cluster centers are set, they create a Voronoi Tessellation:



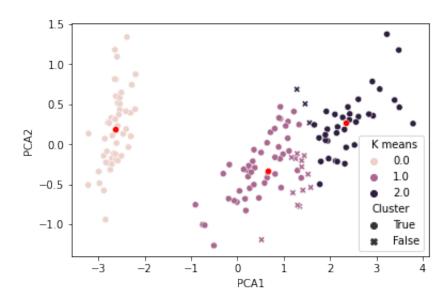
• Below: we run this algorithm on Iris PCA-transformed data

```
In [9]: from sklearn.cluster import KMeans
        kmeans = KMeans(n clusters=3, random state=0).fit(pca iris)
        # switching labels to match
        def switch 1 2(x):
            if x==0.0:
                return 0.0
            if x==1.0:
                return 2.0
            if x==2.0:
                return 1.0
        kmeans labs = np.vectorize(switch 1 2)(kmeans.labels )
        pca label = pd.DataFrame(
            data= np.c [pca_iris, iris['target'], kmeans_labs],
            columns= ['PCA1', 'PCA2', 'True Label', 'K means'])
        def class error(row):
            return row['True Label'] == row['K means']
        pca label['Cluster'] = pca label.apply(class error, axis=1)
        sns.scatterplot(data=pca label, x='PCA1', y='PCA2', hue='K means',
                       style='Cluster', style order=[True,False]);
        centers = pd.DataFrame(
            kmeans.cluster_centers_, columns=['PCA1', 'PCA2'])
        sns.scatterplot(data=centers, x='PCA1', y='PCA2', color='red');
        print(f'Number of misclassifications:')
        pca label.Cluster.value counts()
```

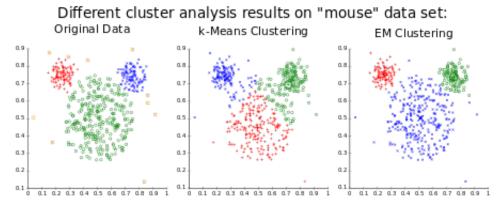
Number of misclassifications:

Out[9]: True 133 False 17

Name: Cluster, dtype: int64

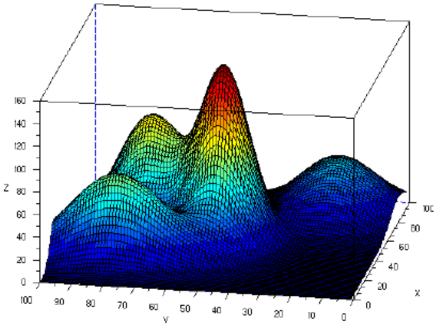


- Above: Showing K means groups with error as 'x' point markers
- The red points show the cluster centers
- This model does not account for different sized cluster



Gaussian Mixture Model and EM Clustering

Another way to think about clustering is with a Gaussian <u>mixture model</u> (https://en.wikipedia.org/wiki/Mixture_model) (GMM)



- Assume that our data points are each generated from different Gaussian distributions
- All we see is the location, not the *latent* variable which determines which distribution each sample was generated from
- x_1, \ldots, x_n is a random sample
- Each x_i is associated with a latent random variable, z_i , that indicates the cluster/distribution of x_i
- Density of z is multinomial with probabilities, π_1, \ldots, π_K
- Let (μ_k, Σ_k) for j = 1, ..., K be the mean vector and covariance matrix for K multivariate Gaussian distributions
- In a Gaussian mixture model, each data point is generated from one of the K multivariate Gaussian distribution,

$$x_i \sim \text{Gaussian}(\mu_k, \Sigma_k)$$

with probability π_k

• For $i = 1, \ldots, n$, if $z_i = k$ then

$$x_i \sim \text{Gaussian}(\mu_k, \Sigma_k) := p(x_i | z_i = k)$$

Joint distribution of x and z

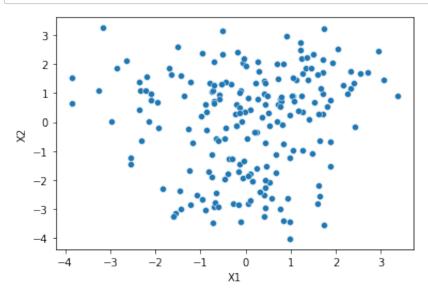
$$p(x, z) = \prod_{k=1}^{K} \pi_k^{I(z=k)} \cdot [\text{Gaussian}(x; \mu_k; \Sigma_k)]^{I(z=k)}$$

Marginal distribution x (summing over the values of z)

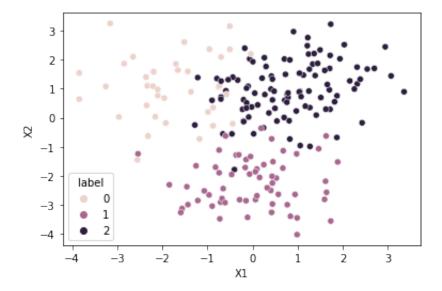
$$p(x) = \sum_{k=1}^{K} \pi_k \cdot \text{Gaussian}(x; \mu_k, \Sigma_k)$$

Each point is generated from one of these Gaussian distributions but we won't know which

```
In [10]:
         dist_probs = [0.2, 0.3, 0.5]
         data = []
         samp size = 200
         for in range(samp size):
             k = np.random.choice(np.arange(0, 3), p=dist probs)
             if k==0:
                 obs = np.random.multivariate normal(
                     [-2,1], [[1,0.2], [0.2,1]]).tolist()
             elif k==1:
                 obs = np.random.multivariate normal(
                     [0,-2], [[1,0], [0,1]]).tolist()
             else:
                 obs = np.random.multivariate normal(
                     [1,1], [[1,0.3], [0.3,1]]).tolist()
             obs.append(k)
             data.append(tuple(obs))
         df = pd.DataFrame(data, columns=['X1', 'X2', 'label'])
         sns.scatterplot(x='X1', y='X2', data=df);
```



Below: color by label



EM Algorithm

- EM stands for Expectation Maximization
- We assume that the sample is generated from a Gaussian mixture model
- Using the Gaussian mixture likelihood, cycle between
 - Imputing the expected cluster (probability) of each point, i = 1, ..., n
 - Recalculate GMM parameters, π_k , μ_k , Σ_k for $k=1,\ldots,K$, to maximize the likelihood
- Cosma Shalizi: "one man's vicious circle is another man's successive approximation procedure"
- Sample marginal likelihood of x:

$$L(\pi,\mu,\Sigma) = \prod_{i=1}^n \sum_{k=1}^K \pi_k \cdot \operatorname{Gaussian}(x_i;\mu_k,\Sigma_k)$$
 where $\pi = (\pi_1,\ldots,\pi_K), \, \mu = (\mu_1,\ldots,\mu_K), \, \Sigma = (\Sigma_1,\ldots,\Sigma_K)$

• **E step**: Calculate expected value of cluster assignments for each point, x_i , using the values of π , μ , Σ from last step,

$$p^{\text{new}}(z_i = k) \leftarrow E[z_i = k | \pi, \mu, \Sigma]$$

- This expected value is really $P(z_i = k)$ (expected value of an indicator function is a probability)
- Calculate these probabilities as

$$p^{\text{new}}(z_i = k) \leftarrow \frac{\pi_k^{\text{old}} \cdot \text{Gaussian}(x_i; \mu_k^{\text{old}}, \Sigma_k^{\text{old}})}{\sum_{j=1}^K \pi_k^{\text{old}} \cdot \text{Gaussian}(x_i; \mu_j^{\text{old}}, \Sigma_j^{\text{old}})}$$

• To make the notation in the next step clearer, let

$$r_i(k) \leftarrow p^{\text{new}}(z_i = k)$$

For each point, we have a vector of assignment probabilities

$$[r_i(1), \ldots, r_i(K)]$$

- We can think about this vector as the *responsibility* that the GMM takes for explaining observation *i*
- **M step**: Calculate maximum likelihood estimates for all parameters, π , μ , Σ using the expected cluster assignments, $[r_i(1), \ldots, r_i(K)]$
 - Goal: optimize likelihood of joint distribution p(x, z)

$$\pi^{\text{new}}, \mu^{\text{new}}, \Sigma^{\text{new}} \leftarrow \arg\max_{\pi,\mu,\Sigma} E \left[\log \left(\prod_{i=1}^{n} p(x_i, z_i) \right) \right]$$

- This can be hard because L is not convex with respect to π, μ, Σ
- Conditional density of x_i given z_i:

$$p(x_i|z_i) = \prod_{k=1}^{K} \left[\text{Gaussian}(x_i; \mu_k, \Sigma_k) \right]^{I(z_i = k)}$$

• Density of z_i :

$$p(z_i) = \prod_{k=1}^K \pi_k^{I(z_i = k)}$$

Likelihood:

$$E\left[\log\left(\prod_{i=1}^{n} p(x_{i}, z_{i})\right)\right]$$

$$= E\left[\log\left(\prod_{i=1}^{n} p(z_{i})p(x_{i}|z_{i})\right)\right]$$

$$= E\left[\log\left(\prod_{i=1}^{n} \prod_{k=1}^{K} \pi_{k}^{I(z_{i}=k)} \cdot \left[\operatorname{Gaussian}(x_{i}; \mu_{k}, \Sigma_{k})\right]^{I(z_{i}=k)}\right)\right]$$

$$= E\left[\sum_{i=1}^{n} \sum_{k=1}^{K} I(z_{i}=k) \log \pi_{k} + I(z_{i}=k) \log[\operatorname{Gaussian}(x_{i}; \mu_{k}, \Sigma_{k})]\right]$$

$$= \sum_{i=1}^{n} \sum_{k=1}^{K} r_{i}(k) \log \pi_{k} + r_{i}(k) \log[\operatorname{Gaussian}(x_{i}; \mu_{k}, \Sigma_{k})]$$

- This can be solved using Lagrange multiplier with the constraint that $\sum_{k=1}^K \pi_k = 1$

$$\mathcal{L} = \sum_{i=1}^{n} \sum_{k=1}^{K} r_i(k) \log \pi_k + r_i(k) \log[\text{Gaussian}(x_i; \mu_k, \Sigma_k)] - \lambda \left(\sum_{k=1}^{K} \pi_k - 1\right)$$

- Differentiate with respect to parameters, π , μ , Σ and λ then set equal to zero
- Solutions:

$$n_k^{\text{new}} \leftarrow \sum_{i=1}^n r_i(k)$$

$$\pi_k^{\text{new}} \leftarrow \frac{n_k^{\text{new}}}{n}$$

$$\mu_k^{\text{new}} \leftarrow \frac{1}{n_k^{\text{new}}} \sum_{i=1}^n r_i(k) x_i$$

$$\Sigma_k^{\text{new}} \leftarrow \frac{1}{n_k} \sum_{i=1}^n r_i(k) (x_i - \mu_k^{\text{new}}) (x_i - \mu_k^{\text{new}})^T$$

- The algorithm must begin initialized with parameters, π , μ , Σ
- The algorithm cycles through these steps until the parameters converge

```
In [12]:
         from sklearn.mixture import GaussianMixture
         # n components here is number of clusters
         gm = GaussianMixture(n components=3, random state=0).fit(pca iris)
         # switching cluster labels
         gm labs = np.vectorize(switch 1 2)(gm.fit predict(pca iris))
         pca label gm = pd.DataFrame(
             data= np.c [pca iris, iris['target'], gm labs],
             columns= ['PCA1', 'PCA2', 'True Label', 'GM'])
         def class error(row):
             return row['True Label'] == row['GM']
         pca label gm['Cluster'] = pca label gm.apply(class error, axis=1)
         sns.scatterplot(data=pca label gm, x='PCA1', y='PCA2', hue='GM',
                         style='Cluster', style order=[True,False]);
         centers = pd.DataFrame(
             gm.means , columns=['PCA1', 'PCA2'])
         sns.scatterplot(data=centers, x='PCA1', y='PCA2', color='red');
         print(f'Number of misclassifications:')
         pca label gm.Cluster.value counts()
```

Number of misclassifications:

Out[12]: True 147 False 3

Name: Cluster, dtype: int64

