OM GAIKWAD

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EDUCATION

Stevens Institute of Technology | Hoboken, NJ

Master of Engineering - Applied Artificial Intelligence, Computer Eng Concentration

Bachelor of Engineering - Mechanical Engineering, Robotics Concentration

Leadership: Chi Phi Fraternity (President), Society of Physics Students (Secretary)

Expected Dec 2025
Expected May 2025

WORK EXPERIENCE

SIT Prototype Object Fabrication (ProOF) Lab, Robotics Engineer Intern | Hoboken, NJ

May 2024 - Present

- Built a virtual testing environment for **DOOSAN H2515** collaborative robot using **MATLAB** and **ROS 2.0** that enabled pre-deployment testing and accelerated lab operations
- Developed isoparametric mapping of the robot workspace using **OpenCV** with **0.04 mm** precision
- Programmed a Path Planning Algorithm for Automated Fiber Placement (AFP) using Python as a research project
- Designed an AFP compaction roller end-effector in **SolidWorks**, equipped with **pneumatic force/tow tension control**

Charter Machine Company, Mechanical Engineer Intern | Metuchen, NJ

Jan 2023 - Jul 2023

- Designed brackets, support frames, pneumatic components in Autodesk Inventor, performed FEA, and produced 100+ fabrication drawings to meet ASME Y14.5 GD&T Standards
- Optimized the hydraulic control system to facilitate flow and pressure control simultaneously in a single manifold, reducing the manufacturing cost by \$400 per project
- Produced 150+ technical deliverables with appropriate DFMA principles; worked with Senior Engineers to co-author Operation Manuals

Spartificial, AI Intern | Hoboken, NJ (Remote)

Jun 2022 - Aug 2022

- Conducted a detailed analysis of lunar topography datasets to classify safe landing sites for spacecraft using image processing techniques with **TensorFlow and OpenCV**
- Independently built Convolutional Neural Network algorithms and analyzed 20+ lunar image datasets
- Managed a team of 6, to develop, test and validate the algorithm that achieved an total accuracy rating of 93%

ENGINEERING PROJECTS

Soft Exosuit for Spinal Muscular Atrophy (SESMA 3.0), ME Capstone

Jul 2024 - Present

- Building a bio-mechanical exosuit to assist patients with Spinal Muscular Atrophy with sit-to-stand motion
- Integrated an **IMU sensor** and **force-sensing resistor** to a custom PCB for monitoring the user's position in real time; facilitated with the vector calculations of the recorded data in **MATLAB**
- Developed and implemented **control theory algorithms** in **C++** to optimize **IMU filtering**, reducing CPU load by 20x and increasing accuracy, achieving a **20% faster** motor control response time

Stevens Ankle-Foot Electromechanical (SAFE) Orthosis, Prototyping Team

May 2024 - Present

- Collaborated on development of a powered Ankle-Foot Orthosis (AFO) for gait training/rehabilitation
- Developed and refined 3D CAD models in Artec 3D; conducted rapid prototyping and assembly of 5 PLA-CF models
- Assisted with failure mode analysis of the prototype and implemented design refinements, achieving a 15% reduction in the structural weight while maintaining integrity and performance

Modeling Vehicle Dynamics using MATLAB, Personal Project

Aug 2023 - Oct 2023

- Modeled vehicle dynamics and developed both nonlinear and linear state-space representations using **Euler-Lagrange equation** to simulate its lateral and longitudinal dynamics in **MATLAB**
- Incorporated elements such as tire forces, propulsion, braking, and steering angle inputs into the **control system design** using **Simulink** that enabled real-time vehicle simulations

SKILLS

Mechanical: AutoCAD, SolidWorks, ANSYS, Creo, LabVIEW, 3D Printing, DFMA, GD&T, Artec 3D, Lean Six Sigma

Electrical: Embedded Systems, PCB Design, PWM Control

Programming: Python, C, C++, MATLAB, Javascript, ROS, Open3D