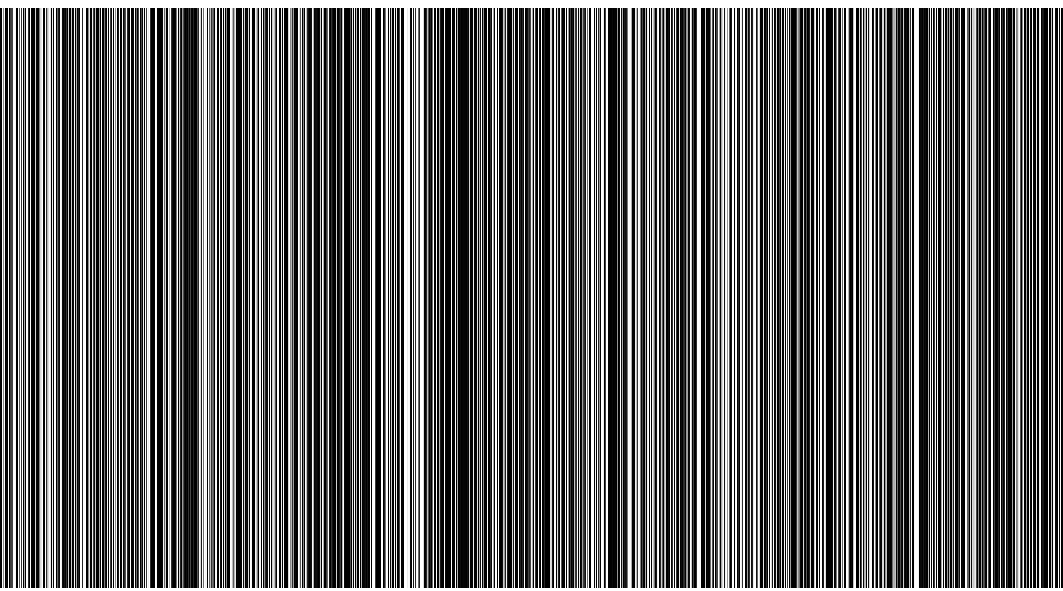


Probability values for ground truth=1 (LR\_is\_like)



Probability values for ground truth=0 (LR\_is\_like)

