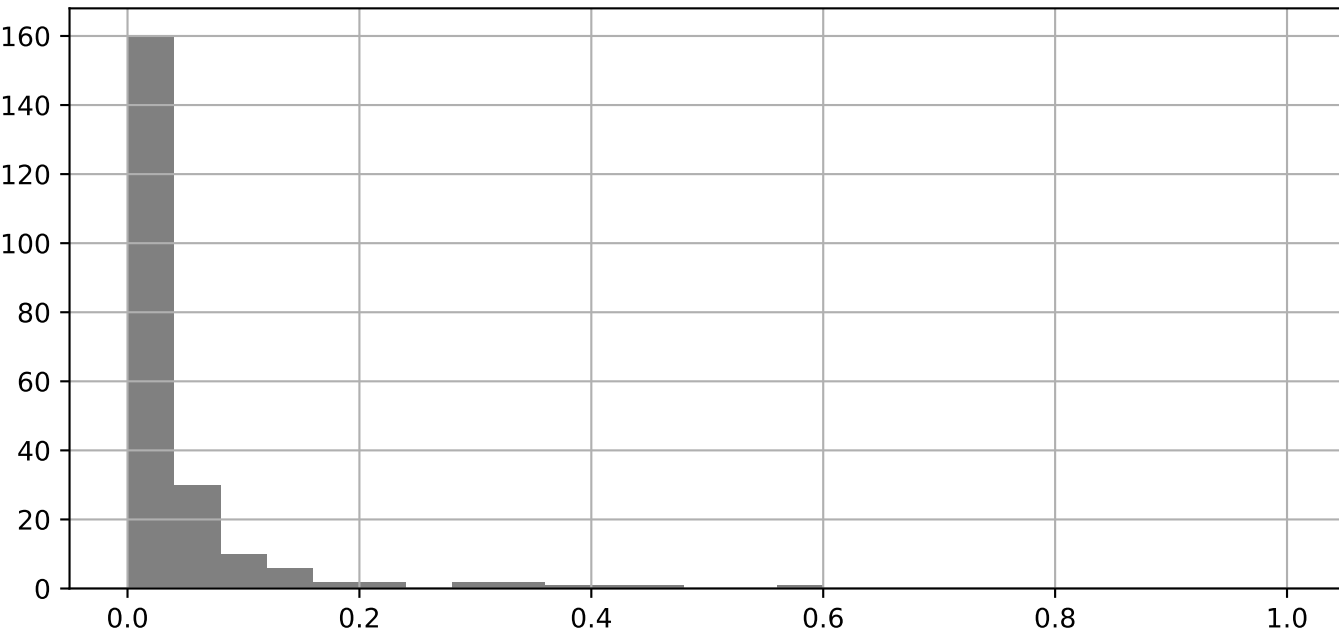


Probability values for ground truth=1 (LR_is_reply)



Probability values for ground truth=0 (LR_is_reply)

