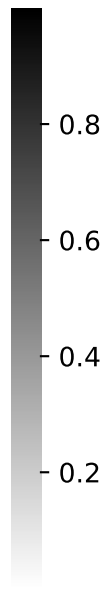
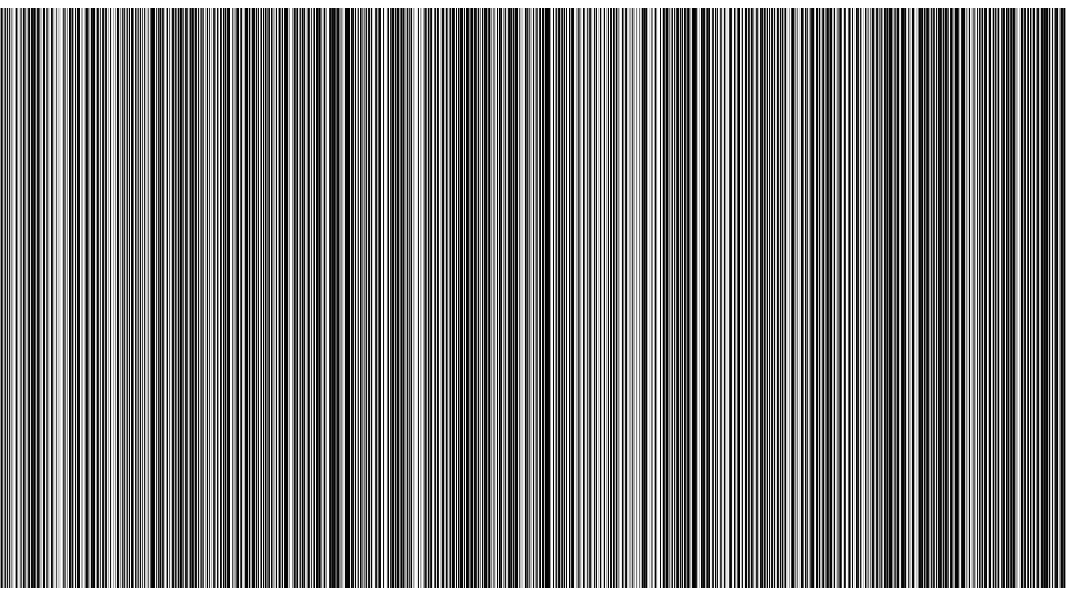


Probability values for ground truth=1 (Baseline_is_like)



Probability values for ground truth=1 (Baseline_is_like)

