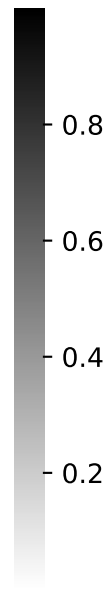
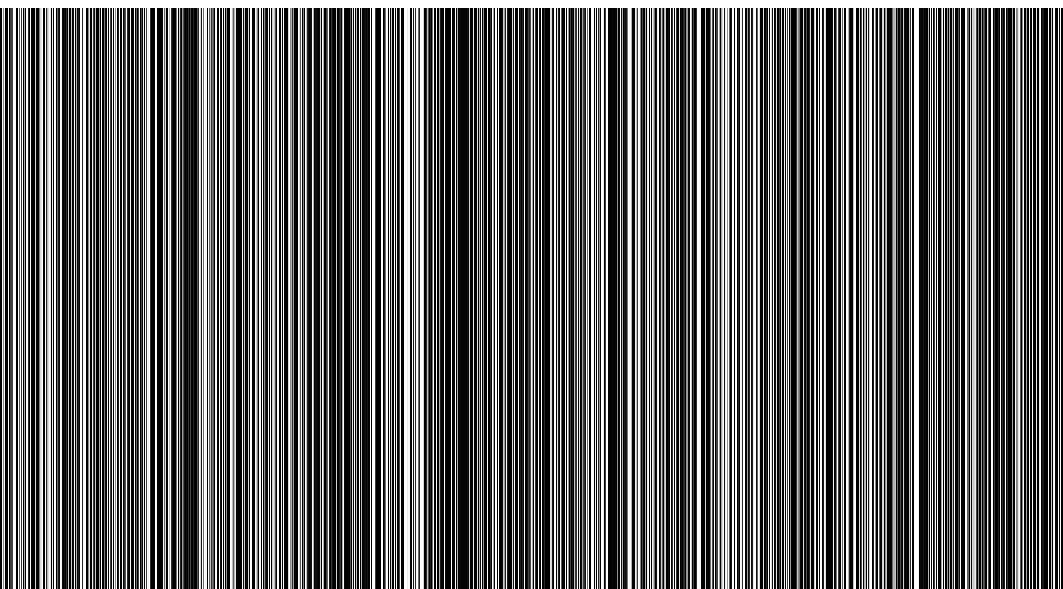


Probability values for ground truth=1 (LR_is_like)



Probability values for ground truth=0 (LR_is_like)

