

Title: Bit Banging EEPROM with Arduino Nano

Deliverable 1

	Create a console program to interface with an EEPROM chip. You will be manually					
Resou	irces:					
	☐ Bit Banging SPI Tutorial: https://youtu.be/9hMsNOwY5AQ					
	EEPROM Datasheet: http://ww1.microchip.com/downloads/en/DeviceDoc/doc5140.pdf					
	Logic Analyzer Install and doc: https://sigrok.org/wiki/Getting_started_with_a_logic_analyzer					
Requi	ired Hardware:					
	Arduino Nano					
	Protocol Analyzer, 8 Channel 24MHz					
	EEPROM AT93C46					
	Breadboard, jumper wires and headers					
Requi	ired Software:					
	PulseView (For use with Protocol Analyzer)					
	Arduino IDE					
Setup	Protocol Analyzer					
	Install Arduino IDE and make sure you can upload to Arduino					
	Install PulseView (includes Zadig Program)					
	Use the Zadig program to install driver (just plug in analyzer and click Install driver)					
	Connect to Device -> fx2lafw (generiv driver for FX2 based LAs)(fx2lafw) -> Scan -> CWave USBee AX					
	Monitor the protocol using the analyzer for a digital output					
	Use the protocol analyzer to debug SPI communication with the EEPROM					



Create an interactive console:

☐ Use the EWEN/READ/WRITE/ERASE instructions of the EEPROM to create an interactive console that allows the user to read and write data to specific addresses.

Examples:

- O WRITE 02 r should write an 'r' character to address 0x02
- O READ 7A should read the data at address 0x7A
- ☐ Implement the ERAL and WRAL instructions.
- □ NOTE: Make sure to use Teraterm to access the serial interface. Do not rely on the built-in Arduino serial monitor as it does not behave like industry standard console interfaces.
- ☐ Control the ORG pin via software so user can switch between x8 and x16 organization
- Add a memory dump feature that outputs the entire memory structure. The memory dump should output in x8 organization only. The output should include hex and ASCII representation of the data similar to below:

NOTE: Non-printable characters can be shown as a period (.)



Deliverable 2

ملاء مداء ch time

	a motion detector that senses when an object is nearby and increments a counter each ect is within a specific distance.				
Resou	rces:				
	LED&KEY Datasheet: https://jetpackacademy.com/wp-content/uploads/2018/06/TM1638_cheat_sheet_download.pdf				
	Ultrasonic Sensor Datasheet: https://www.electroschematics.com/wp-content/uploads/2013/07/HCSR04-datasheet-version-1.pdf				
Requi	red Hardware:				
	LED&KEY (8 x LED/Digit/Button)				
Requi	red Software: None				
Contr	ol LED&KEY Screen:				
	The digits will start at 0 and increment every time an object enters within a 3 foot threshold				
	Zero out the counter whenever a specific button is pressed.				
	Add a button to increase the distance threshold				
	Add a button to decrease the distance threshold				
	NOTE: Do not use Arduino's built in shiftOut/shiftIn/pulseIn functions. You will be manually shifting using the digitalWrite() and digitalRead() functions.				



Deliverable 3

Resources:

- □ Small Device C Compiler (SDCC): https://www.instructables.com/8051-Programming-Using-Small-Device-C-Compiler-SDC/
- □ STC89 Datasheet: http://www.stcmcudata.com/datasheet/stc/STC-AD-PDF/STC89C51RC-english.pdf
- □ STC ISP Programming Software: https://www.stcmicro.com/rjxz.html

STC89 Demo Board:

☐ Implement the functionality for deliverable 1 and 2 using Small Device C Compiler



bit-banging

Project Outline for Bit-Banging EEPROM, LED&KEY and STC89 Development

	Policy	Document No	Date	Version	4
	Quality Procedure	39910.1339615	01/20/2023	Version	4
Х	Working Instruction			Pages w/o Cover	4
	MGR Approval:	R_M - 09/22/2023	ISO Approval:	- 09/22/2023	

Version	Date	Employee	Revision Summary
4	01/20/2023	RCH	Made clear the code should not use built in shiftOut, shiftIn, pulseIn function calls.
3	01/17/2023	RCH	Updated STC datasheet, added WRITE/READ examples and now require ERAL/WRAL instructions.
2	01/05/2023	RCH	Initial Upload
1	01/05/2023	RCH	Initializing Document