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y2 = y2 + i[1]
                     x2 = x2/len(cluster2)
                     centroid2 = [x2, y2]
                     C1 = centroid1
C2 = centroid2
                       \textbf{if} \ \ centroid1[\emptyset] == c1[\emptyset] \ \ \textbf{and} \ \ centroid1[1] == c1[1] \ \ \textbf{and} \ \ centroid2[\emptyset] == c2[\emptyset] \ \ \textbf{and} \ \ centroid2[1] == c2[1] : 
                            print("Clusters are:")
print("Cluster 1: ", cluster1)
print("Cluster 2: ", cluster2)
                            if P6 in cluster1:
   print("Point P6 belongs to cluster 1")
                            else:
                                  print("Point P6 belongs to cluster 2")
                            print("The population of cluster around m2 : ", len(cluster2))
                            print("Updated value of m1 and m2")
                            print("m1/c1 : ", C1)
print("m2/c2 : ", C2)
                            C = [C1, C2]
C_arr = np.array(C)
                            P = list()
                            for i in points:
    if i in cluster1:
                                        P.append(0)
                                  else:
P.append(1)
                            X = np.array(points)
                            colors = list(map(lambda x: 'blue' if x==1 else 'red', P))
plt.scatter(X[:,0], X[:,1], c=colors, marker="o")
plt.scatter(C_arr[:,0], C_arr[:,1], c='g', marker="x")
plt.show()
                     else:
   cluster(C1, C2)
In [29]: print("Initial Data Points and their centroids : ")
print("Points : ", points)
              C1 = P1
C2 = P8
               C = [C1, C2]
               C_arr = np.array(C)
              plt.scatter(X[:,0], X[:,1], marker="o")
plt.scatter(C_arr[:,0], C_arr[:,1], c='r', marker="x")
plt.show()
               cluster(C1, C2)
               Initial Data Points and their centroids :
               Points: [[0.1, 0.6], [0.15, 0.71], [0.08, 0.9], [0.16, 0.85], [0.2, 0.3], [0.25, 0.5], [0.24, 0.1], [0.3, 0.2]]
                 0.9
                0.8
                 0.7
                0.6
                0.5
                0.4
                0.3
                0.2
                0.1
                                           0.15
                                                         0.20
                                                                       0.25
               Clusters are:
              Clusters are:
Cluster 1: [[0.1, 0.6], [0.15, 0.71], [0.08, 0.9], [0.16, 0.85], [0.25, 0.5]]
Cluster 2: [[0.2, 0.3], [0.24, 0.1], [0.3, 0.2]]
Point P6 belongs to cluster 1
The population of cluster around m2 : 3
Updated value of m1 and m2
m1/c1 : [0.148, 0.712]
m2/c2 : [0.2466666666666667, 0.2000000000000000]
                 0.9
                 0.8
                0.7
                 0.6
                0.5
                 0.4
                 0.3
                 0.2
                0.1
                            0.10
                                          0.15
                                                         0.20
                                                                        0.25
 In [ ]:
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