

Lecture 22 - Orthogonal factorizations of matrices

$$Ax = b$$

$$\underline{QR}x = b$$

$$Q^T Q R x = Q^T b$$

$$Rx = Q^T b$$

QR factorization
Orthogonal \swarrow upper triangular \searrow

$$\begin{matrix} A \\ m \times n \end{matrix} \begin{matrix} x \\ n \times 1 \end{matrix} = b$$

$$A \rightarrow A^{-1}$$

$$LU \rightarrow A \Rightarrow \underline{A^{-1}}$$

backward
Substitution

Eigenvalue decomposition

$$E \Lambda E^T = A$$

↓ ↗ diagonal
orthogonal

Symmetric matrices
Square $n \times n$

Singular value
decomposition

SVD $\xrightarrow{\text{diagonal}}$

$$U S V^T = A$$

↓ ↓
orthogonal

$m \times n$

Orthogonalization of matrices

Gram-Schmidt orthogonalization

$$A = \left[\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \right]$$

↓ ↓

orthogonalize vectors

$$A^{\circ} = \left[\vec{u}_1, \vec{u}_2, \dots, \vec{u}_k \right]$$

$$\vec{u}_1 \cdot \vec{u}_2 = 0$$

$$\vec{u}_1 \cdot \vec{u}_1 = \|\vec{u}_1\|^2$$

$$\vec{u}_1 \cdot \vec{u}_2 = \vec{v}_1 \cdot \vec{v}_2 - \underbrace{\langle \vec{v}_2, \vec{v}_1 \rangle}_{\langle \vec{v}_1, \vec{v}_1 \rangle}$$

$$= \vec{v}_1 \cdot \vec{v}_2 - \vec{v}_2 \cdot \vec{v}_1 = 0$$

$$\vec{u}_1 = \vec{v}_1$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1$$

$$\vec{u}_3 = \vec{v}_3 - \frac{\langle \vec{v}_3, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1 - \frac{\langle \vec{v}_3, \vec{u}_2 \rangle}{\langle \vec{u}_2, \vec{u}_2 \rangle} \vec{u}_2$$

$$\vec{u}_k = \vec{v}_k - \sum_{j=1}^{k-1} \frac{\langle \vec{v}_k, \vec{u}_j \rangle}{\langle \vec{u}_j, \vec{u}_j \rangle} \vec{u}_j$$

$$\vec{v}_1 x_1 + \vec{v}_2 x_2 + \vec{v}_3 x_3 \dots + \vec{v}_k x_k = \underline{b}$$

Algorithm

$$\begin{aligned} & \vec{v}_2 \\ & \vec{v}_1 \\ & \langle \vec{v}_1, \vec{v}_2 \rangle \\ & = \vec{v}_1 \cdot \vec{v}_2 \end{aligned}$$

$$\vec{u}_1 = \vec{v}_1$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1$$

$$\vec{u}_2 = \vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\|\vec{u}_1\|} \hat{e}_{u_1}$$

vector
inner product

$$\vec{u}_k = \vec{v}_k - \sum_{j=1}^{k-1} \frac{\langle \vec{v}_k, \vec{u}_j \rangle}{\langle \vec{u}_j, \vec{u}_j \rangle} \vec{u}_j$$

$\underbrace{\hspace{10em}}$

$\underbrace{\hspace{10em}}$

$\text{proj}_{\vec{u}_j}(\vec{v}_k)$

$$\vec{u}_k = \vec{v}_k - \sum_{j=1}^{k-1} \text{proj}_{\vec{u}_j} (\vec{v}_k)$$

Gram-Schmidt \rightarrow very accurate

\vec{u}_1, \vec{u}_2 + orthogonal

$$Ax = b$$

$$QR_x = b \Rightarrow R_x = Q^T b$$

→ Solve x by backward substitution

QR factorization using Gram-Schmidt

$$A = [\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots, \vec{v}_k]$$

$$A = \begin{bmatrix} \vec{e}_{u_1}, \vec{e}_{u_2}, \vec{e}_{u_3}, \dots, \vec{e}_{u_k} \end{bmatrix} \begin{bmatrix} v_1 \cdot \vec{e}_{u_1} & v_2 \cdot \vec{e}_{u_1} & v_3 \cdot \vec{e}_{u_1} & \dots & v_k \cdot \vec{e}_{u_1} \\ 0 & v_2 \cdot \vec{e}_{u_2} & v_3 \cdot \vec{e}_{u_2} & \dots & v_k \cdot \vec{e}_{u_2} \\ 0 & 0 & v_3 \cdot \vec{e}_{u_3} & \dots & v_k \cdot \vec{e}_{u_3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \end{bmatrix}$$

Householder reflections

$P \rightarrow$ projection matrix

orthogonal

symmetric

square.

$$P = P^T$$

$$PP^T = I$$

$$PP = I$$

$$Px = x$$

$$P = I - 2 \underbrace{uu^T}_{\text{one inner product}} \leftarrow$$

Identity matrix

few to find u ?

vector

$$A = \underbrace{P_k P_{k-1} \dots P_2 P_3}_P A$$

$$u \rightarrow \vec{v}_1 \Rightarrow u = \|\vec{v}_1\| \vec{e}_{v_1}$$

$$u = \begin{bmatrix} \|\vec{v}_1\| \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} & & 5 \times 4 \\ x & x & x & x \end{bmatrix}$$

$$A_1 = P_1 A = \begin{bmatrix} R' \\ 5 \times 5 & 5 \times 4 \end{bmatrix} = \begin{bmatrix} & & R' \\ x & x & x & x \\ 0 & x & x & x \end{bmatrix}$$

P_2

$$A_2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & P_2' & & \\ 0 & & & \\ 0 & & & \\ 0 & & & \end{bmatrix} \begin{bmatrix} & A_1 \end{bmatrix} = \begin{bmatrix} & & & \\ x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & x \\ 0 & 0 & x & x \\ 0 & 0 & x & x \end{bmatrix}$$

length of the column vectors

$QR \rightarrow QR$
 $\rightarrow QR \text{ with pivoting}$

$P_2' \rightarrow 4 \times 4$

$P_4 P_3 P_2 P_1$

R

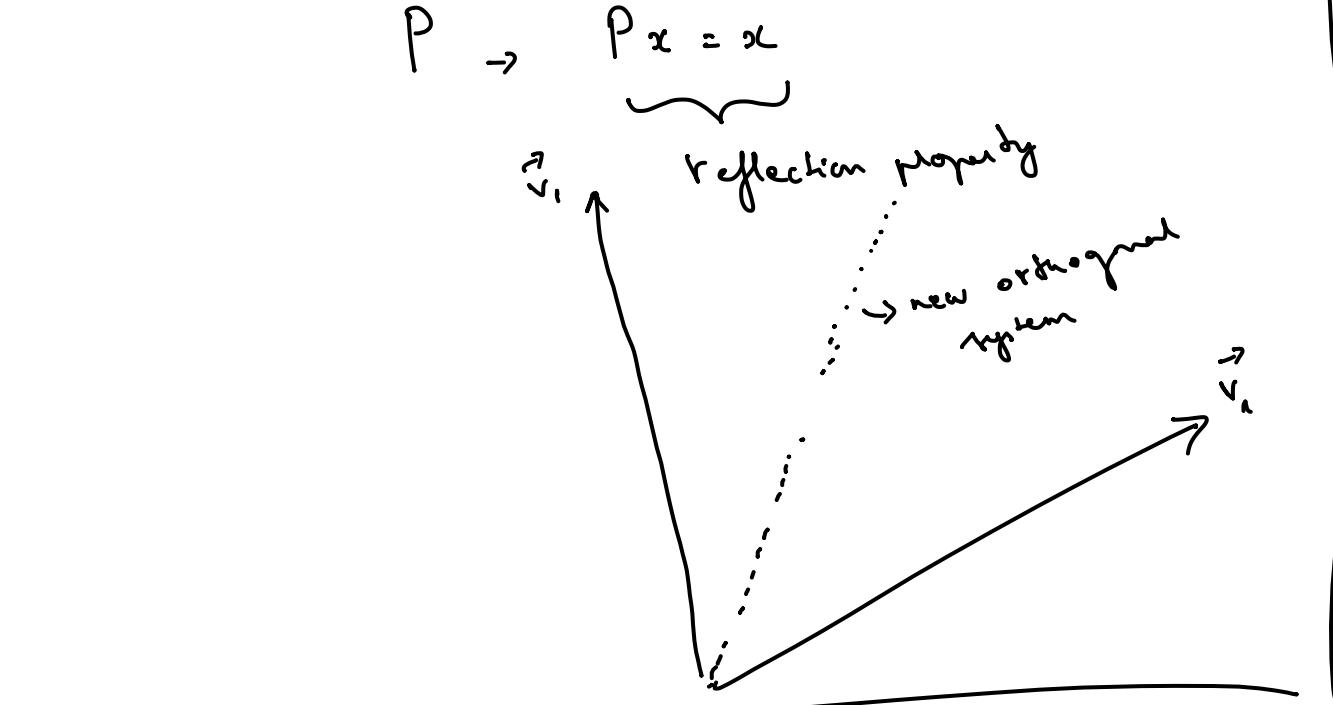
$$Q = \prod_{j=1}^{k-1} P_j$$

$$P_j = I - 2u_j u_j^T$$

$$u_k = \frac{\vec{v}_k + \alpha \vec{e}_j}{\|\vec{v}_k + \alpha \vec{e}_j\|}$$

where $\alpha = -\text{sign}(\vec{v}_k(1)) \|\vec{v}_k\|$

Householder reflections - Geometry



Givens Rotation

Matrix Computations - Golub & van Loan