

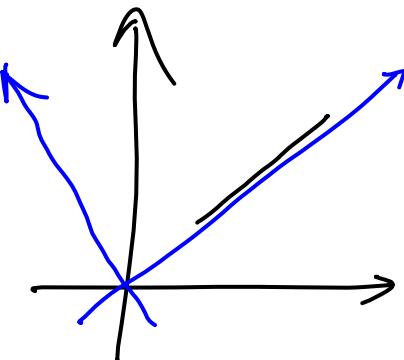
# Lecture 24 - Singular value decomposition

Eigenvalue decompositions

Similarity transformation of matrices

Similar matrices

Matrix similarity



Scale  
translation  
rotation

Gauss elimination

LU

$L L^T$

$L D L^T$

Q R

$[1 \dots]$

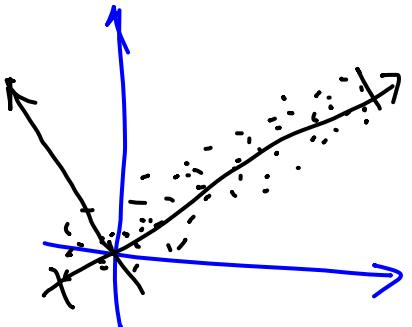
diagonal

$U S V^T$

orthogonal

Non-orthogonal  
decompositions

orthogonal  
decomposition



$$\begin{bmatrix} M^{-1} \\ n \times n \end{bmatrix} A \begin{bmatrix} M \\ n \times n \end{bmatrix} = \underline{B}$$

A is similar to B

$$\underline{M^{-1} A M = B \text{ has to be diagonal}}$$

Eigenvalue decomposition

$$M^{-1} = M^T \Rightarrow M^T A M = B \rightarrow \text{diagonal}$$

↳ orthogonal

$$Ax = b$$

$$\left[ \begin{array}{c} \vec{a}_1 \\ \hline x_1 \end{array} \right] + \left[ \begin{array}{c} \vec{a}_2 \\ \hline x_2 \end{array} \right] + \dots + \left[ \begin{array}{c} \vec{a}_n \\ \hline x_n \end{array} \right] = b$$

$$Ax = 0$$

↳ homogeneous  
linear system

Eigenvalue decomposition

- square matrices only
- Eigenvectors need not be orthogonal

Linear system

under determined

$\overset{A}{\underset{m \times n}{\text{lack of information}}}$

uniquely determined  $m = n$  sufficient information.

over determined

$m > n$

redundant  
information

$$A = U S V^T$$

↳ orthogonal

$$A \vec{v}_k = \vec{u}_k \sigma_k \rightarrow \text{singular values}$$

↳ orthogonal

↳ orthogonal

$$A \vec{v} = U S [v_k] \rightarrow [\sigma_k \dots]$$

$m \times n$

$$\overset{\vec{A}^T A, A \vec{A}^T}{\downarrow}$$

symmetric

Eigenvalue  
decomposition

$m > n \rightarrow \text{rank} \leq n$

$$\left\{ \begin{array}{l} A^T A \\ \text{nxn} \\ AA^T \\ \text{mxm} \end{array} \right.$$

*same rank as A*

$$A^T A \Rightarrow M_I^T A^T A M_I = \sum_{I=1}^r M_I^T$$

$$AA^T \Rightarrow M_0^T AA^T M_0 = \sum_{0=1}^{m-r} M_0^T$$

(1)

$\left. \begin{array}{l} r \text{ eigenvalues} \\ n-r \text{ zeros} \\ r \text{ eigenvalues} \\ m-r \text{ zeros} \end{array} \right\}$

$$A = USV^T$$

$$\begin{aligned} A^T A &= \sqrt{S} U \frac{U^T S V^T}{I} \\ &= \sqrt{S^2} V^T \end{aligned}$$

$$\begin{aligned} AA^T &= USV^T V S U^T \\ &= U S^2 U^T \end{aligned}$$

$$S^2 = \sum \text{eigenvalues}$$

$$U = M_0$$

$$V = M_I$$

(2)

$$A_{m \times n} = \begin{bmatrix} U \\ | | | | \end{bmatrix} \begin{bmatrix} S \\ \vdots & \ddots & 0 \\ 0 & \ddots & \ddots \\ \hline 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{c} \uparrow \\ n \\ \downarrow \\ m-n \end{array} \begin{bmatrix} \quad \\ \quad \\ \quad \\ \quad \end{bmatrix}^{n \times n}$$

Orthogonalize A

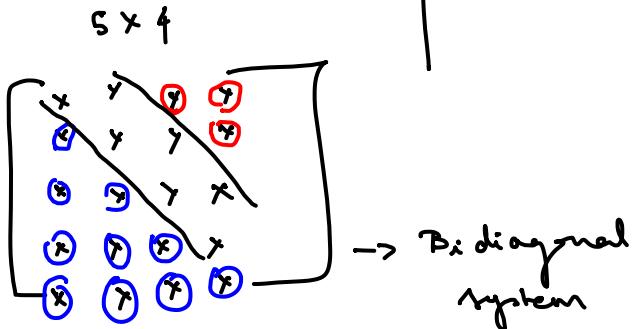
$$QR = A$$

Gram-Schmidt      Householder      Givens rotation

SVD  
 $P_1 P_2 P_3 P_4$

Householder(A)

Householder( $A^T$ )



Orthogonalization

$$\begin{bmatrix} * & & & \\ 0 & * & & \\ 0 & 0 & * & \\ 0 & 0 & 0 & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- Making particular values of the system 0
- Finding orthogonal vectors for each column vector via -Proj
  - Reflection
  - Rotation

$$B = P_1 P_2 P_3 A P_1' P_2' P_3' \dots P_{n-1}'$$

$$B = U^T A V'$$

$$\begin{aligned} LU &\rightarrow \det(A) \rightarrow \prod_{i=1}^n a_{ii} \\ QR &\rightarrow \det(R) \rightarrow \prod_{i=1}^n R_{ii} \\ USV^T &\rightarrow \det(A) \rightarrow (\prod_{i=1}^n s_i)^2 \end{aligned}$$

Matrix Computations  
 - Chapter 2  
 - Chapter 5 - 5.1, 5.2

Algorithm for SVD

1) Bi-diagonalization - Golub-Kahan algorithm

$$\left. \begin{array}{l} \text{Householder}(A) \\ \text{Householder}(A^T) \end{array} \right\} B$$

2) Givens Rotation to make the upper diagonal zero

$$\begin{aligned} \Rightarrow A &= USV^T & \therefore U^T A V' &= B \\ A &= U' B a_1 a_2 \dots a_n V'^T & \therefore B a_1 a_2 \dots &= S \end{aligned}$$

$$A = USV^T$$