

# Lecture 21 - Gauss-Seidel method

Iterative method

↳ Open methods for roots  
of equations

$$\left\{ \begin{array}{l} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1 \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2 \\ a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3 \end{array} \right.$$

$$x_1 = \frac{b_1 - a_{12}x_2 - a_{13}x_3}{a_{11}}$$

$$x_2 = \frac{b_2 - a_{21}x_1 - a_{23}x_3}{a_{22}}$$

$$x_3 = \frac{b_3 - a_{31}x_1 - a_{32}x_2}{a_{33}}$$

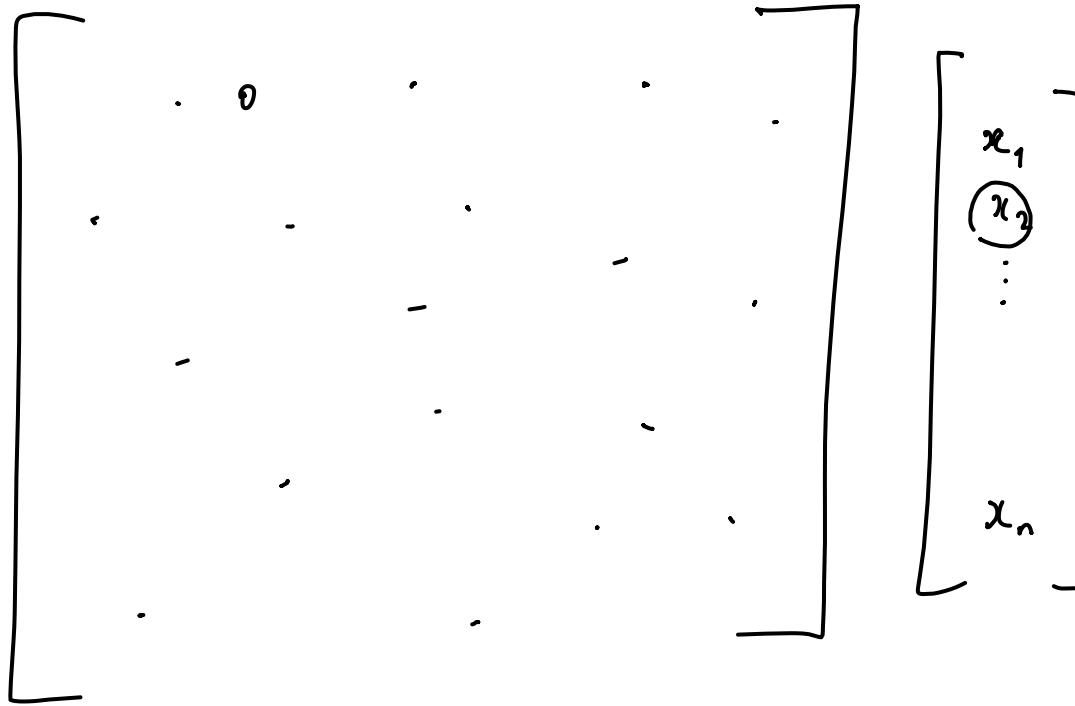
System

Convergence criteria / Stopping criterion

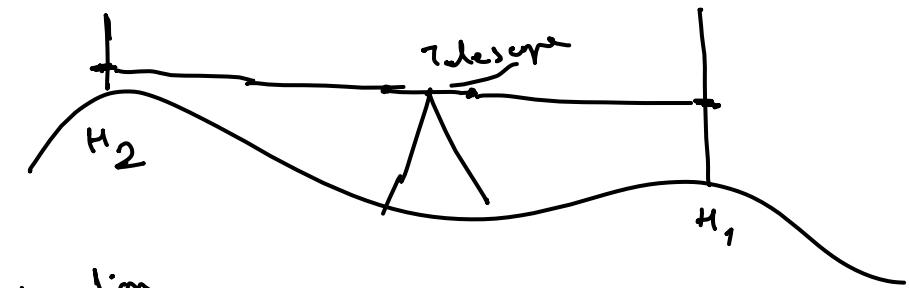
$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

diagonally  
dominant  
matrix

Gauss-Seidel  $\rightarrow$  Sparse linear system



Jacobi iteration



$$H_2 - H_1 = \frac{\Delta H_{12}}{\Delta H_{11}} \text{ observation}$$

Iteration 0  $x_1, x_2, x_3$  - Initial guess

Iteration 1  $x_1^{(1)}, x_2^{(1)}, x_3^{(1)}$   
 $x_1^{(2)}, x_2^{(2)}, x_3^{(2)}$

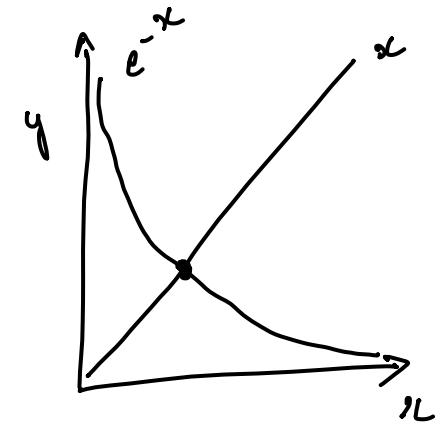
$x_1 = \frac{b_1 - a_{12}x_2 - a_{13}x_3}{a_{11}} \rightarrow x_1^{(1)}$   
 $x_2 = \frac{b_2 - a_{21}x_1 - a_{23}x_3}{a_{22}} \rightarrow x_2^{(1)}$   
 $x_3 = \frac{b_3 - a_{31}x_1 - a_{32}x_2}{a_{33}} \rightarrow x_3^{(1)}$

Open method  $\rightarrow$  Fixed-point method

$$f(x) = e^{-x} - x = 0$$

$$\Rightarrow x = e^{-x}$$

initial guess  $x=0$



$$x^0 = e^{-0}$$

$$x^1 = 1$$

$$x^2 = e^{-1}$$

$$x^3 = e^{-\left(\frac{1}{e}\right)}$$

Convergence of the method

$$\left| \frac{\partial u_1}{\partial x_1} \right| + \left| \frac{\partial u_1}{\partial x_2} \right| + \left| \frac{\partial u_1}{\partial x_3} \right| < 1$$

↳ absolute value

$$\left| \frac{\partial u_2}{\partial x_1} \right| \dots$$

$$x_1 = \frac{b_1 - a_{12}x_2 - a_{13}x_3}{a_{11}}$$

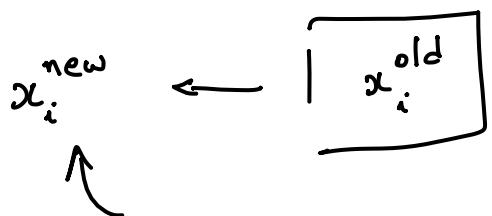
$$0 + \left| \frac{a_{12}}{a_{11}} \right| + \left| \frac{a_{13}}{a_{11}} \right| < 1$$

sufficient condition

$$\Rightarrow |a_{12}| + |a_{13}| < \frac{|a_{12}| + |a_{13}|}{|a_{11}|} < 1$$

not a necessary condition

## Techniques for improving speed of convergence



Relaxation  
technique

$$\tilde{x}_i^{\text{new}} = \lambda x_i^{\text{new}} + (1-\lambda) x_i^{\text{old}} \quad \lambda \in [0, 2]$$

↳ Oscillating systems

0, 1  
underrelaxation

1, 2  
overrelaxation

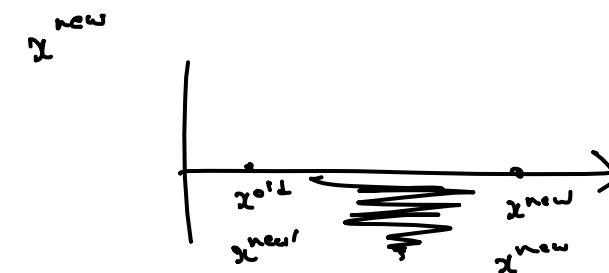


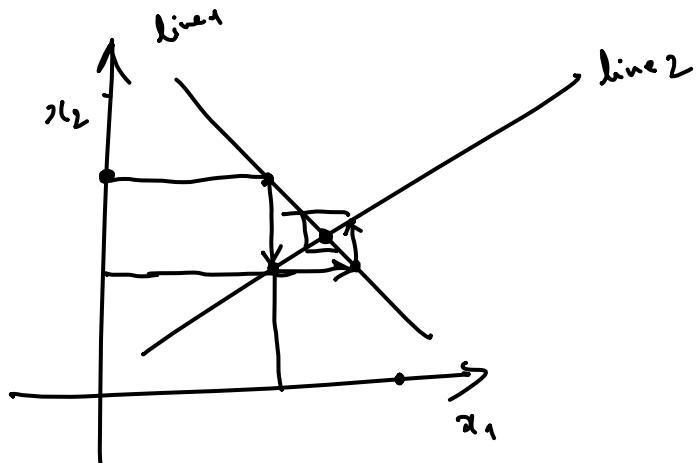
Figure 11.5 of 6<sup>th</sup> Edn. Chapra & Canale

$$u(x_1, x_2)$$

$$x_1, x_2$$

$$\text{line 1 } a_{11}x_1 + a_{12}x_2 = b_1$$

$$\text{line 2 } a_{21}x_1 + a_{22}x_2 = b_2$$



$$x_1$$

Limited applicability



Gauss-Seidel

Factorizations  
QR  
SVD → Eigenval  
Decom.

Rank of a matrix

Gaussian elimination → Row echelon form

$$\begin{bmatrix} & & \\ & & \\ \vdots & & \\ 0 & & \\ & & \end{bmatrix}$$

= row rank  
= column rank

$n \times n$   
Gaussian elimination with pivoting  
row of zeros → rank of  
the matrix  $\leq n$