	In this notebook, you will create a neural network that classifies real-world images digits. You will use concepts from throughout this course in building, training, testing, validating and saving your Tensorflow classifier model. This project is peer-assessed. Within this notebook you will find instructions in each section for how to complete the project. Pay close attention to the instructions as the peer review will be carried out according to a grading rubric that checks key parts of the project instructions. Feel free to add extra cells into the notebook as required. How to submit When you have completed the Capstone project notebook, you will submit a pdf of the notebook for peer review. First ensure that the notebook has been fully executed from beginning to end, and all of the cell outputs are visible. This is important, as the grading rubric
In [1]:	depends on the reviewer being able to view the outputs of your notebook. Save the notebook as a pdf (File -> Download as -> PDF via LaTeX). You should then submit this pdf for review. Let's get started! We'll start by running some imports, and loading the dataset. For this project you are free to make further imports throughout the notebook as you wish. import tensorflow as tf from scipy.io import loadmat from tensorflow.compat.vl import InteractiveSession # This is needed to run on Windows 10 laptop with uda from tensorflow.keras.models import Sequential from tensorflow.keras.models import Dense, Flatten, Conv2D, MaxPooling2D, BatchNormalization
In [2]:	# This is needed to run on Windows 10 laptop with Cuda print(tfversion) config = tf.compat.v1.ConfigProto() config.gpu_options.allow_growth = True session = InteractiveSession(config=config) 2.1.0 SVHN overview image
In [3]:	For the capstone project, you will use the SVHN dataset . This is an image dataset of over 600,000 digit images in all, and is a harder dataset than MNIST as the numbers appear in the context of natural scene images. SVHN is obtained from house numbers in Google Street View images. • Y. Netzer, T. Wang, A. Coates, A. Bissacco, B. Wu and A. Y. Ng. "Reading Digits in Natural Images with Unsupervised Feature Learning". NIPS Workshop on Deep Learning and Unsupervised Feature Learning, 2011. Your goal is to develop an end-to-end workflow for building, training, validating, evaluating and saving a neural network that classifies a reaworld image into one of ten classes. # Run this cell to load the dataset train = loadmat('data/train_32x32.mat') test = loadmat('data/test 32x32.mat')
	Both train and test are dictionaries with keys x and y for the input images and labels respectively. 1. Inspect and preprocess the dataset • Extract the training and testing images and labels separately from the train and test dictionaries loaded for you. • Select a random sample of images and corresponding labels from the dataset (at least 10), and display them in a figure. • Convert the training and test images to grayscale by taking the average across all colour channels for each pixel. Hint: retain the channel dimension, which will now have size 1. • Select a random sample of the grayscale images and corresponding labels from the dataset (at least 10), and display them in a figure
<pre>In [4]:</pre> <pre>In [5]:</pre>	<pre># Extract the training and testing images and labels separately from the train and test dictionaries aded for you. import numpy as np X_train = train['X'] y_train = train['y'] X_test = test['X'] y_test = test['Y'] print(X_train.shape) print(Y_train.shape) print(Y_test.shape) print(Y_test.shape) (32, 32, 3, 73257) (73257, 1) (32, 32, 3, 26032) (26032, 1) from sklearn.preprocessing import OneHotEncoder</pre>
In [7]: In [8]:	<pre>enc = OneHotEncoder().fit(y_train) y_train = enc.transform(y_train).toarray() y_test = enc.transform(y_test).toarray() print(y_train.shape) print(y_train[0]) (73257, 10) [1. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.] # Task: # Convert the training and test images to grayscale by taking the average across all colour channels # for each pixel. Hint: retain the channel dimension, which will now have size 1 X_train_avg = np.swapaxes(X_train, 3,0) print(X_train_avg.shape) X_train_avg = np.swapaxes(X_train_avg, 3,2) X_train_avg = np.swapaxes(X_train_avg, 1,2) print(X_train_avg.shape) (73257, 32, 3, 32) (73257, 32, 3, 32) (73257, 32, 3, 32) X_train_avg = np.mean(X_train_avg,axis=3)</pre>
In [10]:	<pre>X_train_avg =X_train_avg[, np.newaxis] print(X_train_avg.shape) print(X_train_avg[1].shape) (73257, 32, 32, 1) # Task: # Select a random sample of images and corresponding labels from the dataset (at least 10), and displathem in a figure. import numpy as np import matplotlib.pyplot as plt import random w=10</pre>
	<pre>h=2 fig=plt.figure(figsize=(8,4)) columns = 5 rows = 2 shp=(X_train.shape)[0] #print(random.randint(0,shp)) for i in range(1, columns*rows+1): indx = random.randint(0,shp) img = X_train[,indx] fig.add_subplot(rows,columns, i) plt.imshow(img) plt.show()</pre>
In [11]:	# Task: # Select a random sample of the grayscale images and corresponding labels # from the dataset (at least 10), and display them in a figure.
	<pre>print(X_train_avg[1].squeeze(axis=2).shape) w=10 h=2 fig=plt.figure(figsize=(8,4)) columns = 5 rows = 2 shp=(X_train_avg.shape)[0] #print(random.randint(0,shp)) for i in range(1, columns*rows+1): indx = random.randint(0,shp) img = X_train_avg[indx].squeeze(axis=2) fig.add_subplot(rows,columns, i) plt.imshow(img,cmap='gray',vmin=0,vmax=255,label=y_train[indx]) plt.show()</pre>
	(32, 32) 0 10 10 10 10 10 10 10 10 10
	 2. MLP neural network classifier Build an MLP classifier model using the Sequential API. Your model should use only Flatten and Dense layers, with the final layer having a 10-way softmax output. You should design and build the model yourself. Feel free to experiment with different MLP architectures. Hint: to achieve a reasonable accuracy you won't need to use more than 4 or 5 layers. Print out the model summary (using the summary() method) Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback.
In [12]:	 As a guide, you should aim to achieve a final categorical cross entropy training loss of less than 1.0 (the validation loss might be higher). Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets. Compute and display the loss and accuracy of the trained model on the test set. def get_seq_model(input_shape):
In [13]: In [14]:	<pre>model.compile(optimizer='adam',</pre>
In [15]: In [15]:	<pre>earlystop = EarlyStopping(patience=5, monitor='loss')</pre>
	Compile_seq_model(model) model.summary() (32, 32, 1) [1. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.] Model: "sequential" Layer (type) Output Shape Param # ====================================
	batch_normalization (BatchNo (None, 64) 256 dense_2 (Dense) (None, 64) 4160 dense_3 (Dense) (None, 64) 4160 dropout (Dropout) (None, 64) 0 dense_4 (Dense) (None, 10) 650 ===================================
In [17]:	Non-trainable params: 128 history = train_seq_model(model, X_train_avg, y_train, 30) (32, 32, 1) [1. 0. 0. 0. 0. 0. 0. 0. 0. 0.] Train on 62268 samples, validate on 10989 samples Epoch 1/30 62200/62268 [====================================
	ss: 1.5295 - val_acc: 0.4964 Epoch 2/30 62240/62268 [====================================
	62240/62268 [====================================
	62268/62268 [====================================
	Epoch 9/30 62240/62268 [====================================
	Epoch 00011: val_loss did not improve from 1.02338 62268/62268 [====================================
	ss: 1.2846 - val_acc: 0.6721 Epoch 14/30 62240/62268 [====================================
	Epoch 16/30 62200/62268 [====================================
	Epoch 00018: val_loss did not improve from 0.94243 62268/62268 [====================================
	62268/62268 [====================================
	Epoch 23/30 62240/62268 [====================================
	Epoch 00025: val_loss did not improve from 0.94243 62268/62268 [====================================
	<pre>ss: 0.9856 - val_acc: 0.6920 Epoch 28/30 62240/62268 [====================================</pre>
	<pre>Epoch 00030: val_loss improved from 0.93458 to 0.89641, saving model to SeqModel\mySeqModel 62268/62268 [====================================</pre>
Out[19]:	Text(0.5, 1.0, 'Loss') 18 10 10 14 11 12
In [22]:	plt.plot(history.history['acc']) plt.plot(history.history['val_acc']) plt.plot(history.history['val_acc']) plt.xlabel('Epochs') plt.ylabel('Acc') plt.legend(['loss','val_acc'], loc='lower right') plt.title("Accuracy")
Out[22]:	Text(0.5, 1.0, 'Accuracy') Accuracy 0.70 0.65 0.60 2 0.55 0.50
	0.45 - 0.40 - loss val_acc val_acc Epochs
	 3. CNN neural network classifier Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten
	 Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten Dense and Dropout layers. The final layer should again have a 10-way softmax output. You should design and build the model yourself. Feel free to experiment with different CNN architectures. Hint: to achieve a reasonal accuracy you won't need to use more than 2 or 3 convolutional layers and 2 fully connected layers.) The CNN model should use fewer trainable parameters than your MLP model. Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback. You should aim to beat the MLP model performance with fewer parameters! Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets.
In [23]:	 Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten Dense and Dropout layers. The final layer should again have a 10-way softmax output. You should design and build the model yourself. Feel free to experiment with different CNN architectures. Hint: to achieve a reasonal accuracy you won't need to use more than 2 or 3 convolutional layers and 2 fully connected layers.) The CNN model should use fewer trainable parameters than your MLP model. Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback. You should aim to beat the MLP model performance with fewer parameters! Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets. Compute and display the loss and accuracy of the trained model on the test set. def get conv_model (input_shape):
	 Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten Dense and Dropout layers. The final layer should again have a 10-way softmax output. You should design and build the model yourself. Feel free to experiment with different CNN architectures. Hint: to achieve a reasonal accuracy you won't need to use more than 2 or 3 convolutional layers and 2 fully connected layers.) The CNN model should use fewer trainable parameters than your MLP model. Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback. You should aim to beat the MLP model performance with fewer parameters! Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets. Compute and display the loss and accuracy of the trained model on the test set. def get_conv_model(input_shape):
In [24]:	 Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten Dense and Dropout layers. The final layer should again have a 10-way softmax output. You should design and build the model yourself. Feel free to experiment with different CNN architectures. Hint: to achieve a reasonal accuracy you won't need to use more than 2 or 3 convolutional layers and 2 fully connected layers.) The CNN model should use fewer trainable parameters than your MLP model. Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. Your model should track at least one appropriate metric, and use at least two callbacks during training, one of which should be a ModelCheckpoint callback. You should aim to beat the MLP model performance with fewer parameters! Plot the learning curves for loss vs epoch and accuracy vs epoch for both training and validation sets. Compute and display the loss and accuracy of the trained model on the test set. def get_conv_xcdal(input_shape): model = Sequential({
[n [24]:	 Build a CNN classifier model using the Sequential API. Your model should use the Conv2D, MaxPool2D, BatchNormalization, Flatten Dense and Dropout layers. The final layers should again have a 10-way softmax output. You should design and build the model yourset. Feel free to experiment with different CNN architectures. Hint to achieve a reasonal accuracy you won't need to use more than 2 or 2 convolutional layers and 2 fully connected layers.) The CNN model should the fewer trainable parameters than your MLP model. Compile and train the model (we recommend a maximum of 30 epochs), making use of both training and validation sets during the training run. You should aim to beat the MLP model performance with fewer parameters! Piel the learning curves for loss vis epoch and accuracy vis epoch for both training and validation sets. Compute and display the loss and accuracy of the trained model on the last set. Convalled the convalled track of the trained model on the last set. def get_conv_model tingut_stape): <pre>model = Sequential(f(</pre>
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