

Ensemble learning, Bagging, Boosting

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Slides adapted from David Sontag, Luke Zettlemoyer,
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Jaakkola

Ensemble methods

Machine learning competition with a \$1 million prize

Leaderboard

Display top 20 leaders.

Rank	Team Name	Best Score	% Improvement	Last Submit Time
1	The Ensemble	0.8553	10.10	2009-07-26 18:38:22
2	BellKor's Pragmatic Chaos	0.8554	10.09	2009-07-26 18:18:28

Grand Prize - RMSE <= 0.8563

3	Grand Prize Team	0.8571	9.91	2009-07-24 13:07:49
4	Opera Solutions and Vandelay United	0.8573	9.89	2009-07-25 20:05:52
5	Vandelay Industries !	0.8579	9.83	2009-07-26 02:49:53
6	PragmaticTheory	0.8582	9.80	2009-07-12 15:09:53
7	BellKor in BigChaos	0.8590	9.71	2009-07-26 12:57:25
8	Dace	0.8603	9.58	2009-07-24 17:18:43
9	Opera Solutions	0.8611	9.49	2009-07-26 18:02:08
10	BellKor	0.8612	9.48	2009-07-26 17:19:11
11	BigChaos	0.8613	9.47	2009-06-23 23:06:52
12	Feeds2	0.8613	9.47	2009-07-24 20:06:46

Progress Prize 2008 - RMSE = 0.8616 - Winning Team: BellKor in BigChaos

13	xianqiang	0.8633	9.26	2009-07-21 02:04:40
14	Gravity	0.8634	9.25	2009-07-26 15:58:34
15	Ces	0.8642	9.17	2009-07-25 17:42:38
16	Invisible Ideas	0.8644	9.14	2009-07-20 03:26:12
17	Just a guy in a garage	0.8650	9.08	2009-07-22 14:10:42
18	Craig Carmichael	0.8656	9.02	2009-07-25 16:00:54
19	J Dennis Su	0.8658	9.00	2009-03-11 09:41:54
20	acmehill	0.8659	8.99	2009-04-16 06:29:35

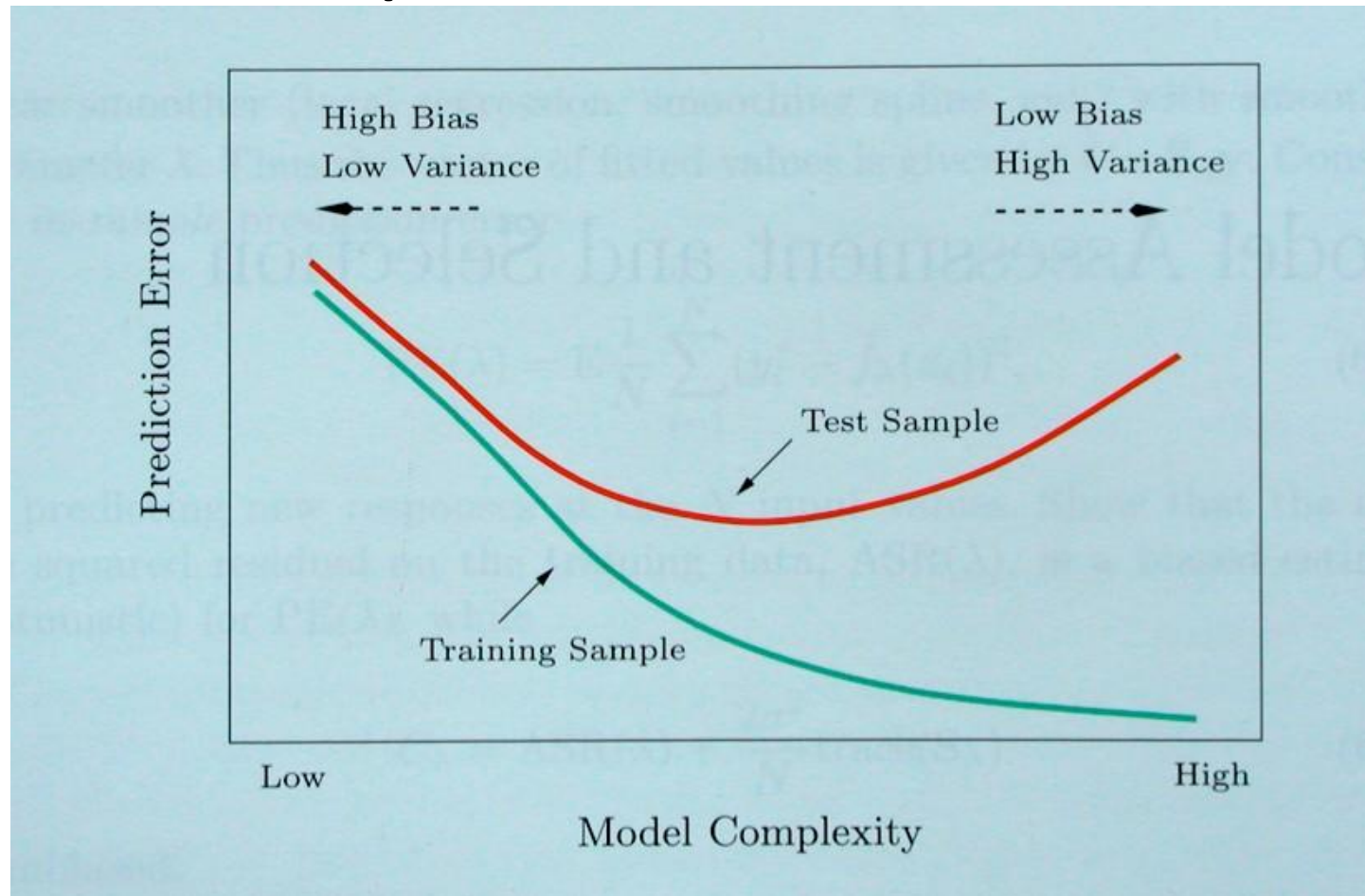
Progress Prize 2007 - RMSE = 0.8712 - Winning Team: KorBell

Cinematch score on quiz subset - RMSE = 0.9514

The diagram illustrates the matrix factorization process for recommendation systems. It shows a matrix where rows represent movies and columns represent users. The matrix is divided into two parts: a visible part (left) and a hidden part (right). The visible part contains ratings (e.g., 1, 4, 3, 5, 2, 4, 5, ?). The hidden part contains predicted ratings (e.g., ?, 1, 4, 4, 5, ?). The process involves finding latent factors for movies and users, which are then combined to predict missing ratings.

	← users →					
↑ movies ↓	1		?	3	5	?
	?	1				2
		4		4	5	?

Bias/Variance Tradeoff



Hastie, Tibshirani, Friedman "Elements of Statistical Learning" 2001

Reduce Variance Without Increasing Bias

- We can sample m independent training sets. Then, we can compute y by averaging all the m predictions from m models $y = \frac{1}{m} \sum_{i=1}^m y_i$

- ▶ **Bias: unchanged**, since the averaged prediction has the same expectation

$$\mathbb{E}[y] = \mathbb{E} \left[\frac{1}{m} \sum_{i=1}^m y_i \right] = \mathbb{E}[y_i]$$

- ▶ **Variance: reduced**, since we're averaging over independent samples

$$\text{Var}[y] = \text{Var} \left[\frac{1}{m} \sum_{i=1}^m y_i \right] = \frac{1}{m^2} \sum_{i=1}^m \text{Var}[y_i] = \frac{1}{m} \text{Var}[y_i].$$

- **Averaging** reduces variance:

$$\text{Var}(\bar{X}) = \frac{\text{Var}(X)}{N}$$

When predictions are independent

Average models to reduce model variance

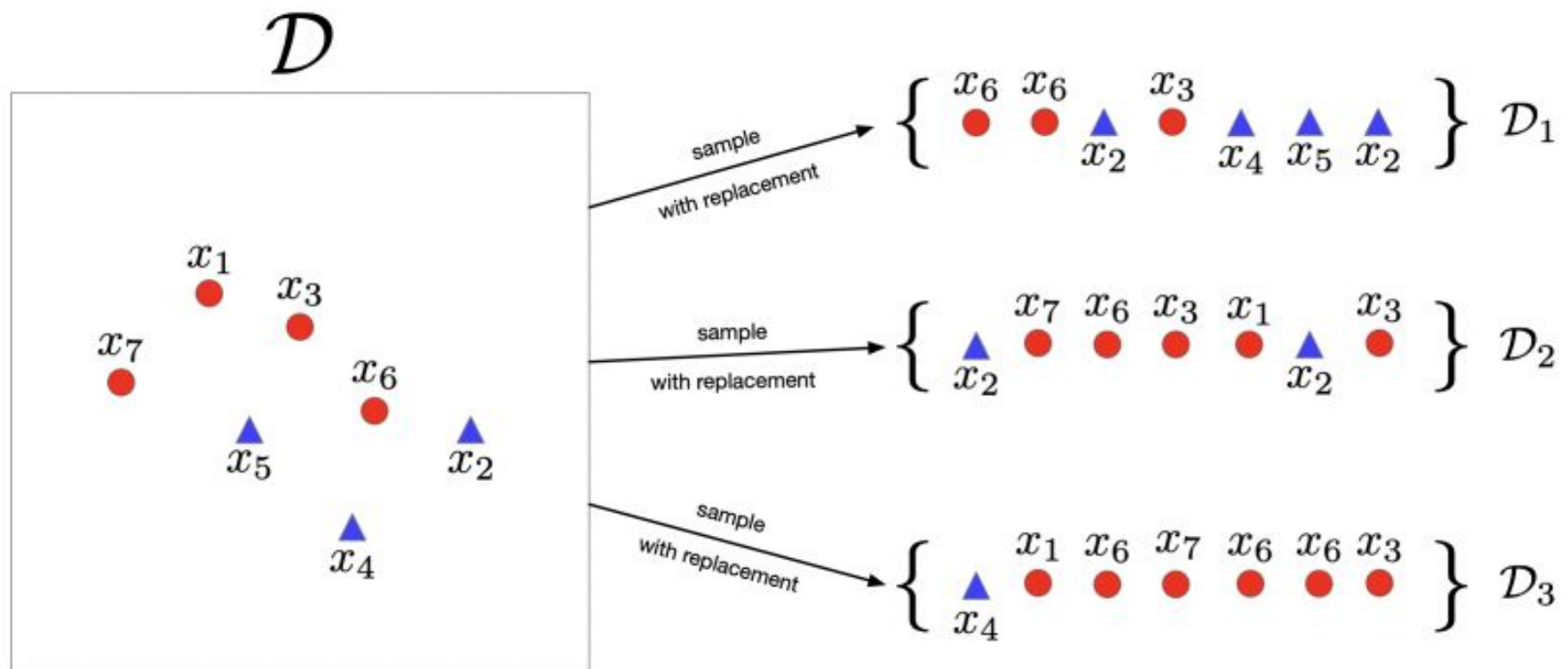
One problem: only one training set, where do multiple models come from?

Bagging: Bootstrap

Aggregation

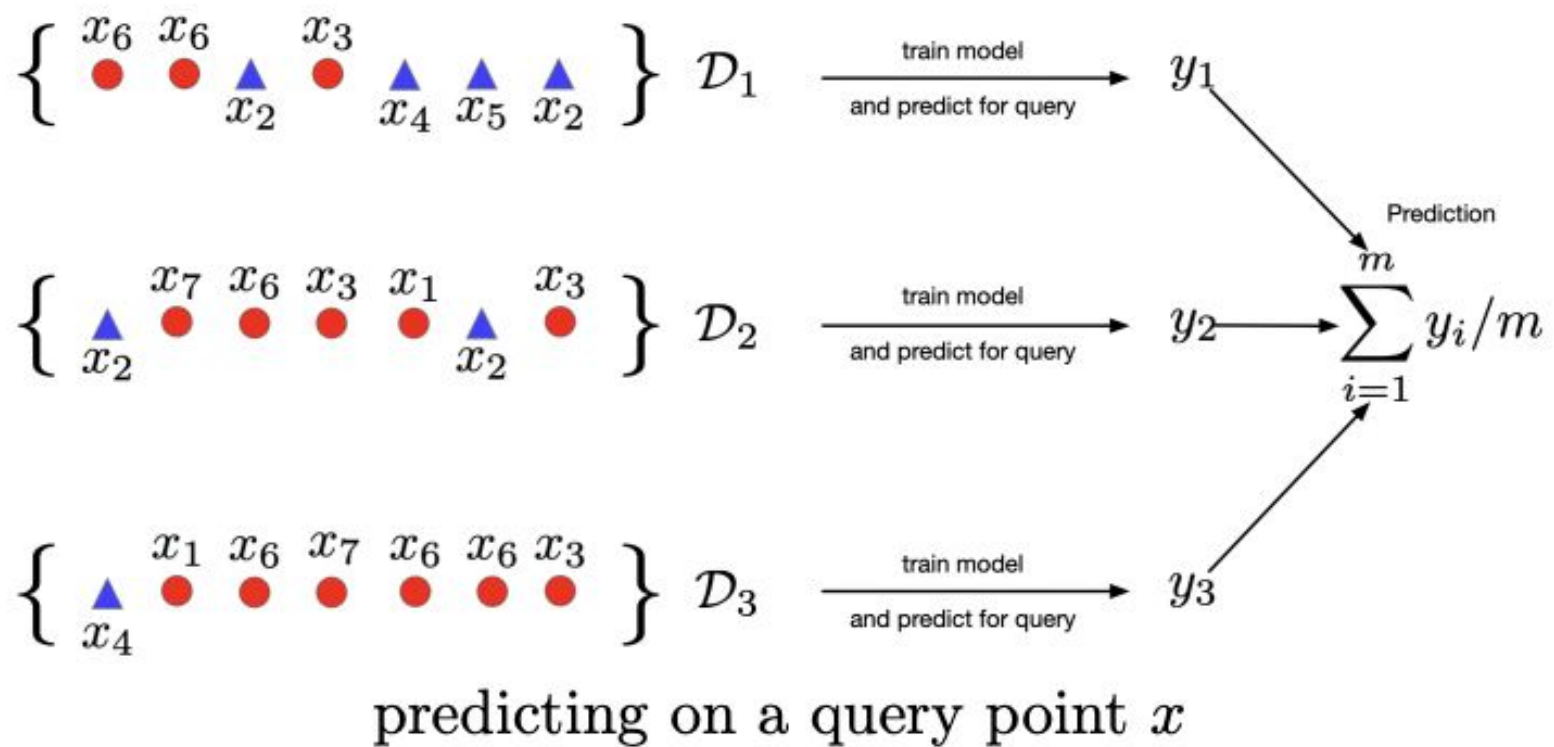
- Leo Breiman (1994)
- Take repeated **bootstrap samples** from training set D .
- *Bootstrap sampling*: Given set D containing N training examples, create D' by drawing N examples at random **with replacement** from D .
- Bagging:
 - Create k bootstrap samples $D_1 \dots D_k$.
 - Train distinct classifier on each D_i .
 - Classify new instance by majority vote / average.

Bagging



in this example $n = 7, m = 3$

Bagging



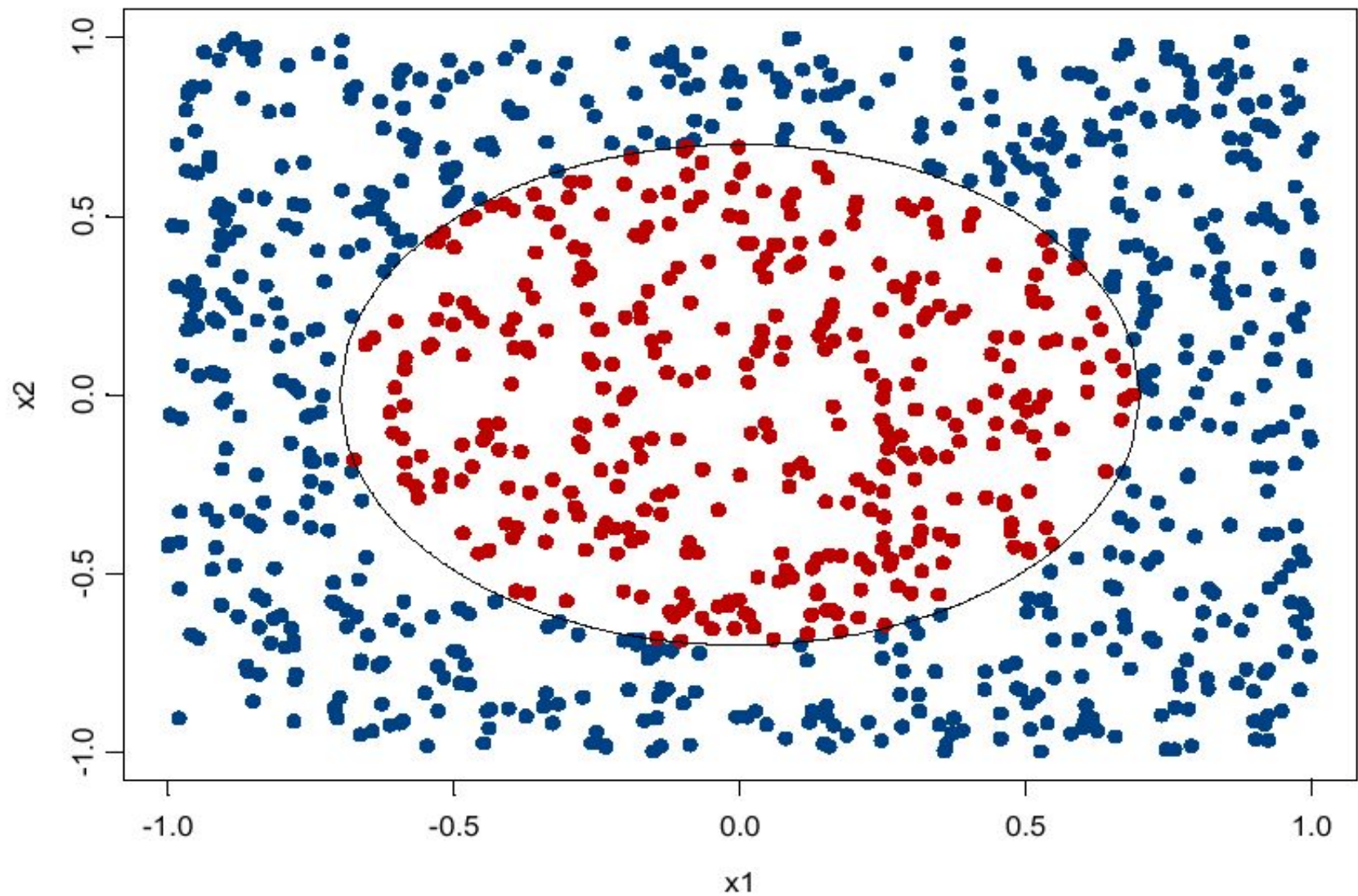
Bagging

- Best case:
$$\text{Var}(\text{Bagging}(L(x, D))) = \frac{\text{Variance}(L(x, D))}{N}$$

In practice:

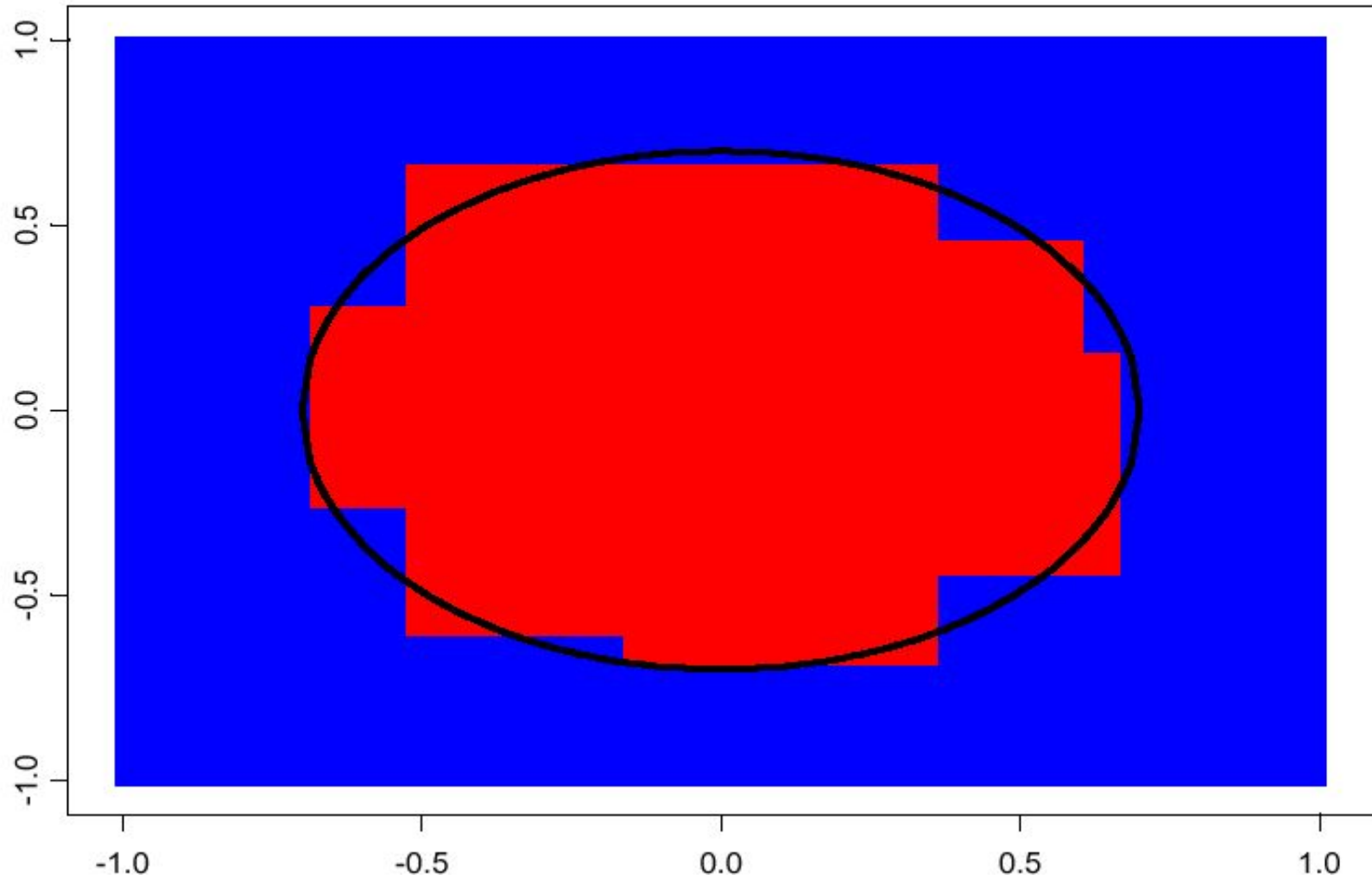
models are correlated, so reduction is smaller than $1/N$
variance of models trained on fewer training cases
usually somewhat larger

Bagging Example

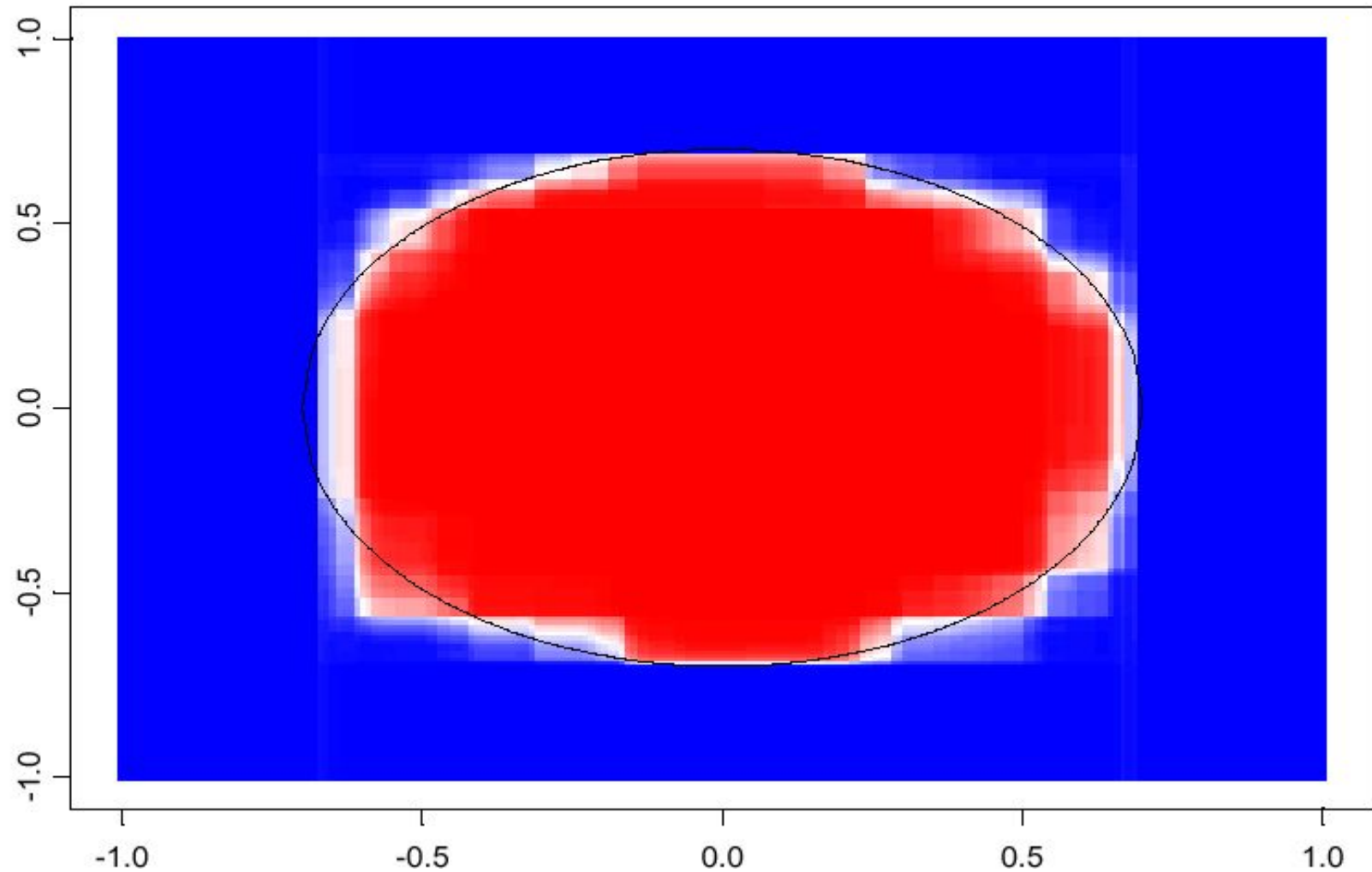


decision tree learning algorithm; very similar to ID3

CART decision boundary



100 bagged trees



shades of blue/red indicate strength of vote for particular classification

Reduce Bias² and Decrease Variance?

- Bagging reduces variance by averaging
- Bagging has little effect on bias
- Can we average *and* reduce bias?
- Yes:

- Boosting

Theory and Applications of Boosting

Rob Schapire

Example: “How May I Help You?”

[Gorin et al.]

- **goal:** automatically categorize type of call requested by phone customer (`Collect`, `CallingCard`, `PersonToPerson`, etc.)
 - yes I'd like to place a collect call long distance please (`Collect`)
 - operator I need to make a call but I need to bill it to my office (`ThirdNumber`)
 - yes I'd like to place a call on my master card please (`CallingCard`)
 - I just called a number in sioux city and I musta rang the wrong number because I got the wrong party and I would like to have that taken off of my bill (`BillingCredit`)
- **observation:**
 - **easy** to find “rules of thumb” that are “often” correct
 - e.g.: “IF ‘card’ occurs in utterance
THEN predict ‘CallingCard’ ”
 - **hard** to find **single** highly accurate prediction rule

The Boosting Approach

- devise computer program for deriving rough rules of thumb
- apply procedure to subset of examples
- obtain rule of thumb
- apply to 2nd subset of examples
- obtain 2nd rule of thumb
- repeat T times

Key Details

- how to choose examples on each round?
- concentrate on “hardest” examples
 - (those most often misclassified by previous rules of thumb)
- how to combine rules of thumb into single prediction rule?
 - take (weighted) majority vote of rules of thumb

Boosting

- **boosting** = general method of converting rough rules of thumb into highly accurate prediction rule
- **technically:**
 - **assume** given “**weak**” **learning algorithm** that can consistently find classifiers (“rules of thumb”) at least slightly better than random, say, accuracy $\geq 55\%$
 - (in two-class setting) [“**weak learning assumption**”]
 - given sufficient data, a **boosting algorithm** can **provably** construct single classifier with very high accuracy, say, 99%

Strong and Weak Learnability

- boosting's roots are in “PAC” learning model [Valiant '84]
- get random examples from unknown, arbitrary distribution
- **strong** PAC learning algorithm:
 - for **any** distribution
with high probability
given polynomially many examples (and polynomial time)
can find classifier with **arbitrarily small** generalization error
- **weak** PAC learning algorithm
 - same, but generalization error only needs to be **slightly better than random guessing** ($\frac{1}{2} - \gamma$)
- [Kearns & Valiant '88]:
 - does weak learnability imply strong learnability?

If Boosting Possible, Then...

- can use (fairly) **wild** guesses to produce highly accurate predictions
- if can learn “part way” then can learn “all the way”
- should be able to improve **any** learning algorithm
- for any learning problem:
 - **either** can always learn with nearly **perfect accuracy**
 - **or** there exist cases where **cannot** learn even slightly better than **random guessing**

First Boosting Algorithms

- [Schapire '89]:
 - first provable boosting algorithm
- [Freund '90]:
 - “optimal” algorithm that “boosts by majority”
- [Drucker, Schapire & Simard '92]:
 - first experiments using boosting
 - limited by practical drawbacks
- [Freund & Schapire '95]:
 - introduced “AdaBoost” algorithm
 - strong practical advantages over previous boosting algorithms

Application: Detecting Faces

[Viola & Jones]

- **problem:** find **faces** in photograph or movie
- **weak classifiers:** detect light/dark rectangles in image



- many clever tricks to make extremely fast and accurate

Basic Algorithm and Core Theory

- introduction to AdaBoost
- analysis of training error
- analysis of test error and the margins theory
- experiments and applications

Adaboost

Given: a class $\mathcal{F} = \{f : \mathcal{X} \mapsto \{-1, 1\}\}$ of weak learners and the data $\{(x_1, y_1), \dots, (x_n, y_n)\}$, $y_i \in \{-1, 1\}$. Initialize the weights as $w_1(i) = 1/n$.

For $t = 1, \dots, T$:

1. Find a weak learner f_t based on weights $w_t(i)$;
2. Compute the *weighted* error $\epsilon_t = \sum_{i=1}^n w_t(i) I(y_i \neq f_t(x_i))$;
3. Compute the *importance* of f_t as $\alpha_t = 1/2 \ln \left(\frac{1-\epsilon_t}{\epsilon_t} \right)$;
4. Update the distribution $w_{t+1}(i) = \frac{w_t(i) e^{-\alpha_t y_i f_t(x_i)}}{Z_t}$,
 $Z_t = \sum_{i=1}^n w_t(i) e^{-\alpha_t y_i f_t(x_i)}$.

A Formal Description of Boosting

- given **training set** $(x_1, y_1), \dots, (x_m, y_m)$
- $y_i \in \{-1, +1\}$ correct label of instance $x_i \in X$
- for $t = 1, \dots, T$:
 - construct distribution D_t on $\{1, \dots, m\}$, Initialize $D_t = \frac{1}{m}$
 - find **weak classifier** (“rule of thumb”) based on weights D_t
 - $h_t : X \rightarrow \{-1, +1\}$
 - with **error** ϵ_t on D_t :
 - $\epsilon_t = \Pr_{i \sim D_t} [h_t(x_i) \neq y_i] = \sum_{i=1}^m D_t(i) I[y_i \neq h_t(x_i)]$
 - Compute importance of h_t as $\alpha_t = \frac{1}{2} \ln((1 - \epsilon_t)/\epsilon_t)$
 - Update the data distribution $D_{t+1}(i) = \frac{D_t(i) e^{-\alpha_t y_i h_t(x_i)}}{Z_t}$, $Z_t = \sum_{i=1}^m D_t(i) e^{-\alpha_t y_i h_t(x_i)}$
- output **final/combined classifier** H_{final} (weighted mix of all h_t 's)

AdaBoost

[with Freund]

- constructing D_t :
 - $D_1(i) = 1/m$
 - given D_t and h_t :

$$\begin{aligned} D_{t+1}(i) &= \frac{D_t(i)}{Z_t} \times \begin{cases} e^{-\alpha_t} & \text{if } y_i = h_t(x_i) \\ e^{\alpha_t} & \text{if } y_i \neq h_t(x_i) \end{cases} \\ &= \frac{D_t(i)}{Z_t} \exp(-\alpha_t y_i h_t(x_i)) \end{aligned}$$

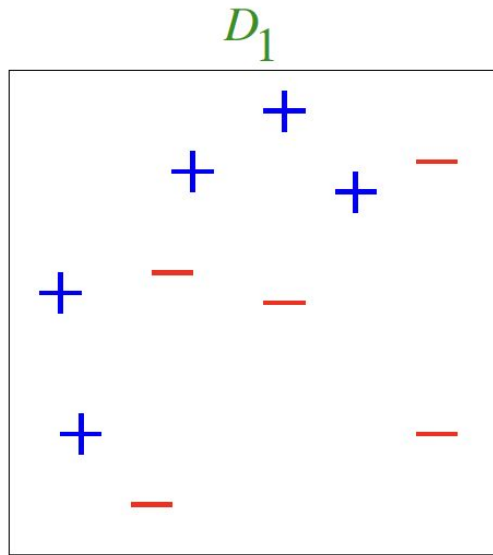
where Z_t = normalization factor

$$\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right) > 0$$

- final classifier:

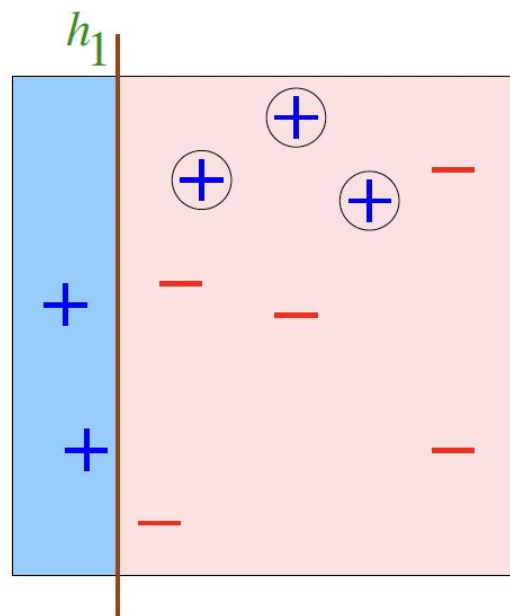
- $H_{\text{final}}(x) = \text{sign} \left(\sum_t \alpha_t h_t(x) \right)$

Toy Example



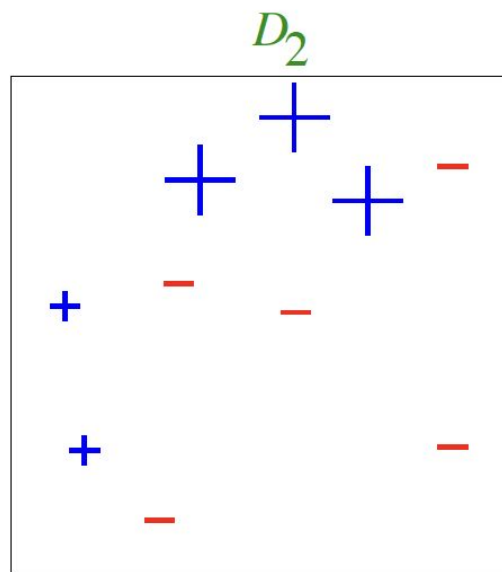
weak classifiers = vertical or horizontal half-planes

Round 1

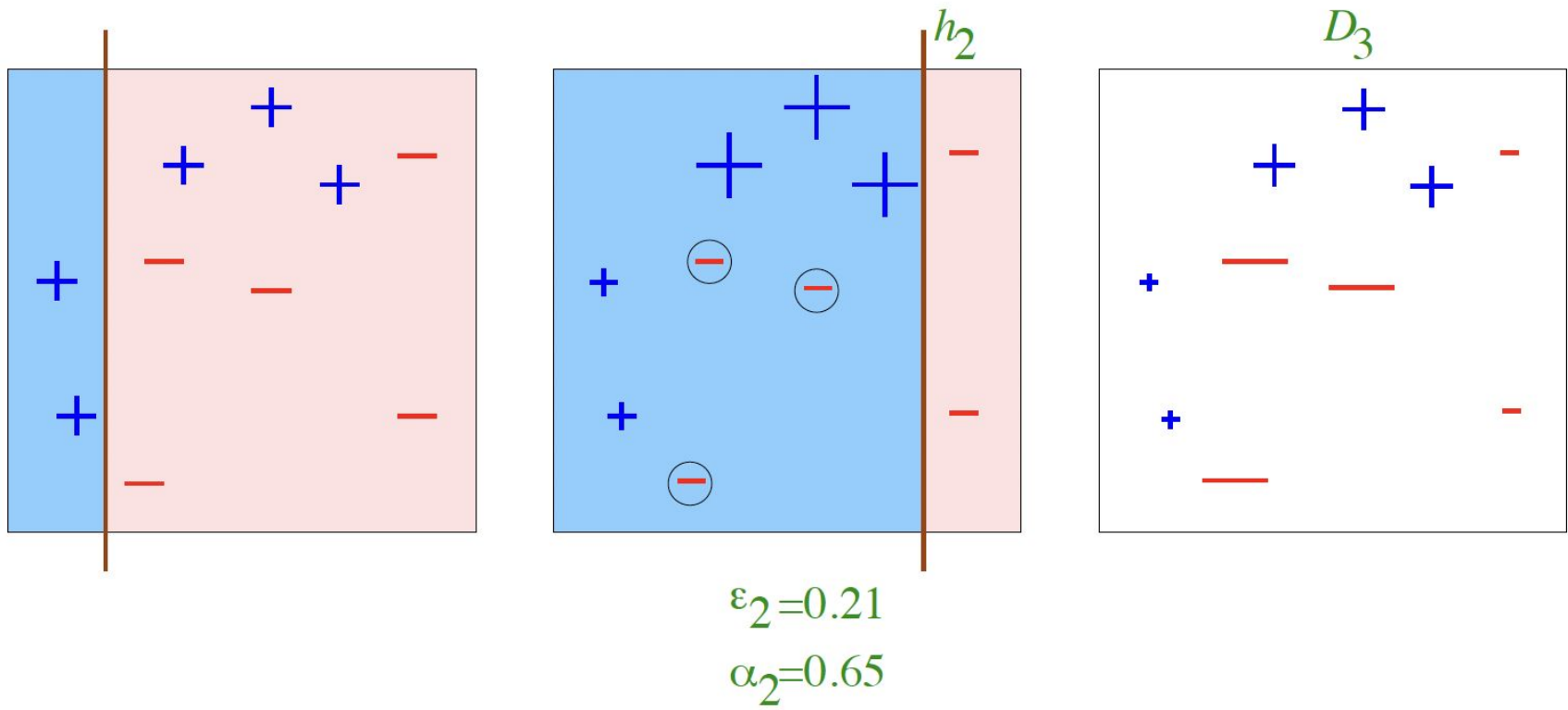


$$\varepsilon_1 = 0.30$$

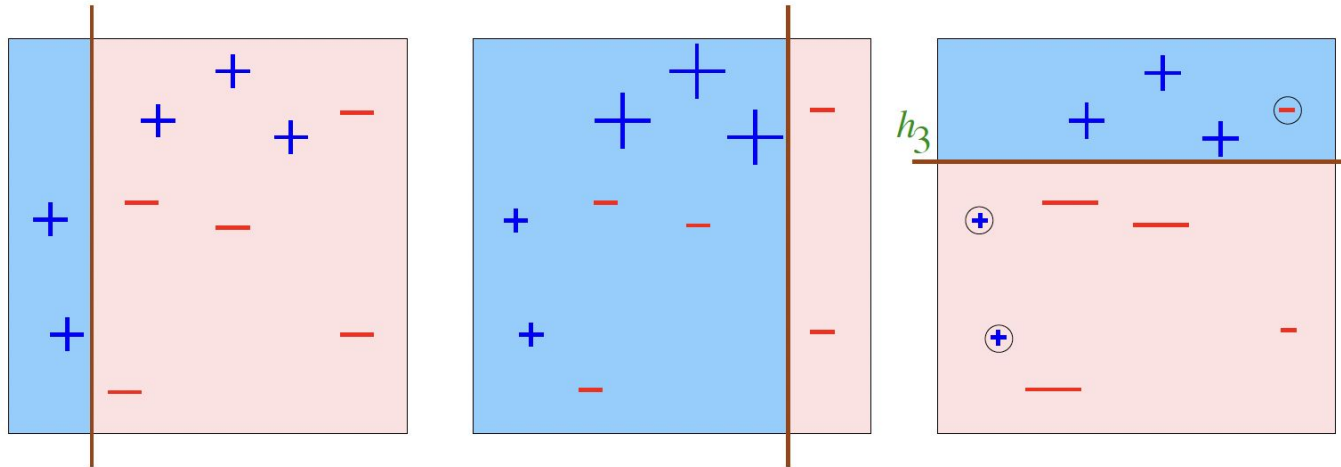
$$\alpha_1 = 0.42$$



Round 2



Round 3

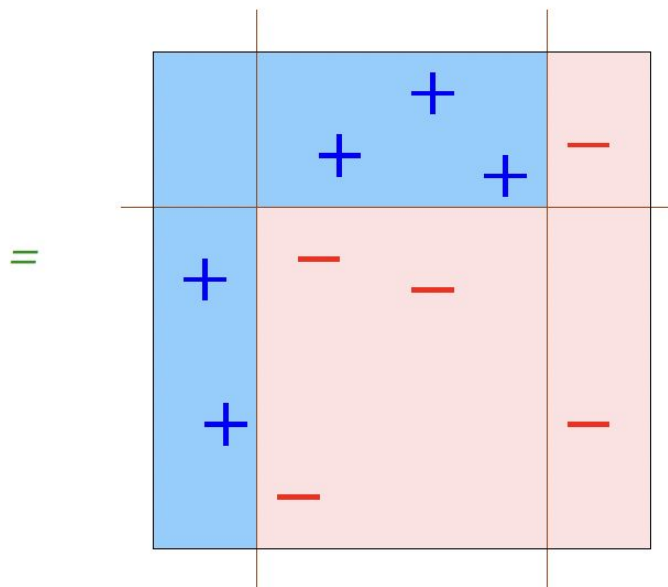


$$\epsilon_3 = 0.14$$

$$\alpha_3 = 0.92$$

Final Classifier

$$H_{\text{final}} = \text{sign} \left(0.42 \begin{array}{|c|} \hline \text{blue} \\ \hline \end{array} + 0.65 \begin{array}{|c|} \hline \text{blue} \\ \hline \end{array} + 0.92 \begin{array}{|c|} \hline \text{blue} \\ \hline \end{array} \right)$$



Voted combination of classifiers

- The general problem here is to try to combine many simple “weak” classifiers into a single “strong” classifier
- We consider voted combinations of simple binary ± 1 comp
$$h_m(\mathbf{x}) = \alpha_1 h(\mathbf{x}; \theta_1) + \dots + \alpha_m h(\mathbf{x}; \theta_m)$$

where the (non-negative) votes α_i can be used to emphasize component classifiers that are more reliable than others

Components: decision

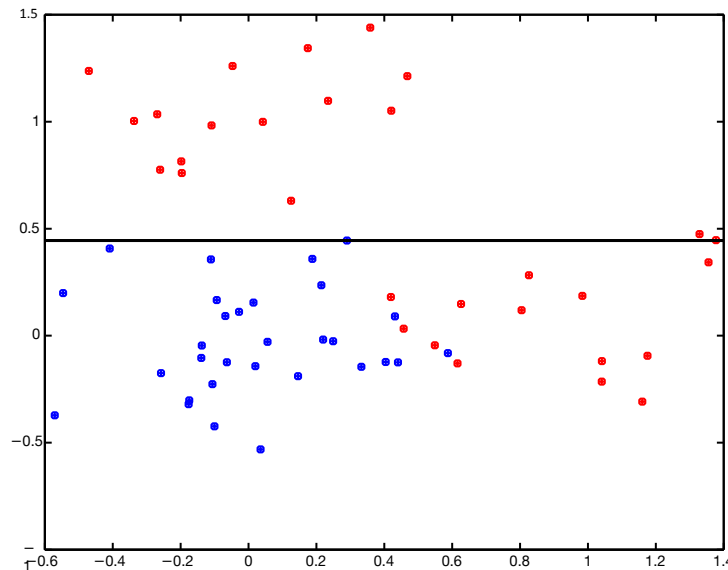
stumps

- Consider the following simple family of component classifiers generating ± 1 labels:

$$h(\mathbf{x}; \theta) = \text{sign}(w_1 x_k - w_0)$$

where $\theta = \{k, w_1, w_0\}$. These are called *decision stumps*.

- Each decision stump pays attention to only a single component of the input vector



Voted combination

- We need to define a loss function for the combination so we can determine which new component $h(\mathbf{x}; \theta)$ to add and how many votes it should receive

$$h_m(\mathbf{x}) = \alpha_1 h(\mathbf{x}; \theta_1) + \dots + \alpha_m h(\mathbf{x}; \theta_m)$$

- While there are many options for the loss function we consider here only a simple exponential loss

$$\exp\{ -y h_m(\mathbf{x}) \}$$

Modularity, errors, and loss

- Consider adding the m^{th} component:

$$\begin{aligned} & \sum_{i=1}^n \exp\{ -y_i[h_{m-1}(\mathbf{x}_i) + \alpha_m h(\mathbf{x}_i; \theta_m)] \} \\ &= \sum_{i=1}^n \exp\{ -y_i h_{m-1}(\mathbf{x}_i) - y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \end{aligned}$$

Modularity, errors, and loss

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$$\begin{aligned} & \sum_{i=1}^n \exp\{ -y_i[h_{m-1}(\mathbf{x}_i) + \alpha_m h(\mathbf{x}_i; \theta_m)] \} \\ &= \sum_{i=1}^n \exp\{ -y_i h_{m-1}(\mathbf{x}_i) - y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \\ &= \sum_{i=1}^n \underbrace{\exp\{ -y_i h_{m-1}(\mathbf{x}_i) \}}_{\text{fixed at stage } m} \exp\{ -y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \end{aligned}$$

Modularity, errors, and

- Consider adding the m^{th} component:

$$\begin{aligned} & \sum_{i=1}^n \exp\{ -y_i[h_{m-1}(\mathbf{x}_i) + \alpha_m h(\mathbf{x}_i; \theta_m)] \} \\ &= \sum_{i=1}^n \exp\{ -y_i h_{m-1}(\mathbf{x}_i) - y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \\ &= \sum_{i=1}^n \underbrace{\exp\{ -y_i h_{m-1}(\mathbf{x}_i) \}}_{\text{fixed at stage } m} \exp\{ -y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \\ &= \sum_{i=1}^n W_i^{(m-1)} \exp\{ -y_i \alpha_m h(\mathbf{x}_i; \theta_m) \} \end{aligned}$$

So at the m^{th} iteration the new component (and the votes) should optimize a weighted loss (weighted towards mistakes).

Empirical exponential loss cont'd

- To increase modularity we'd like to further decouple the optimization of $h(\mathbf{x}; \theta_m)$ from the associated votes α_m
- To this end we select $h(\mathbf{x}; \theta_m)$ that optimizes the rate at which the loss would decrease as a function of α_m

$$\begin{aligned} \frac{\partial}{\partial \alpha_m} \Big|_{\alpha_m=0} \sum_{i=1}^n W_i^{(m-1)} \exp\{-y_i \alpha_m h(\mathbf{x}_i; \theta_m)\} &= \\ \left[\sum_{i=1}^n W_i^{(m-1)} \exp\{-y_i \alpha_m h(\mathbf{x}_i; \theta_m)\} \cdot (-y_i h(\mathbf{x}_i; \theta_m)) \right]_{\alpha_m=0} &= \\ = \left[\sum_{i=1}^n W_i^{(m-1)} (-y_i h(\mathbf{x}_i; \theta_m)) \right] \end{aligned}$$

Empirical exponential loss cont'd

- We find $h(\mathbf{x}; \hat{\theta}_m)$ that minimizes

$$-\sum_{i=1}^n W_i^{(m-1)} y_i h(\mathbf{x}_i; \theta_m)$$

We can also normalize the weights:

$$\begin{aligned} & -\sum_{i=1}^n \frac{W_i^{(m-1)}}{\sum_{j=1}^n W_j^{(m-1)}} y_i h(\mathbf{x}_i; \theta_m) \\ & = -\sum_{i=1}^n \tilde{W}_i^{(m-1)} y_i h(\mathbf{x}_i; \theta_m) \end{aligned}$$

so that $\sum_{i=1}^n \tilde{W}_i^{(m-1)} = 1$.

Selecting a new component:

summary

- We find $h(\mathbf{x}; \hat{\theta}_m)$ that minimizes

$$-\sum_{i=1}^n \tilde{W}_i^{(m-1)} y_i h(\mathbf{x}_i; \theta_m)$$

where $\sum_{i=1}^n \tilde{W}_i^{(m-1)} = 1$.

- α_m is subsequently chosen to minimize

$$\sum_{i=1}^n \tilde{W}_i^{(m-1)} \exp\{-y_i \alpha_m h(\mathbf{x}_i; \hat{\theta}_m)\}$$

The AdaBoost algorithm

0) Set $\tilde{W}_i^{(0)} = 1/n$ for $i = 1, \dots, n$

1) At the m^{th} iteration we find (any) classifier $h(\mathbf{x}; \hat{\theta}_m)$ for which the *weighted classification error* ϵ_m

$$\epsilon_m = 0.5 - \frac{1}{2} \left(\sum_{i=1}^n \tilde{W}_i^{(m-1)} y_i h(\mathbf{x}_i; \hat{\theta}_m) \right)$$

is better than chance.

2) The new component is assigned votes based on its error:

$$\hat{\alpha}_m = 0.5 \log((1 - \epsilon_m) / \epsilon_m)$$

3) The weights are updated according to (Z_m is chosen so that the new weights $\tilde{W}_i^{(m)}$ sum to one):

$$\tilde{W}_i^{(m)} = \frac{1}{Z_m} \cdot \tilde{W}_i^{(m-1)} \cdot \exp\{ -y_i \hat{\alpha}_m h(\mathbf{x}_i; \hat{\theta}_m) \}$$