

# FIT-ME: IMAGE-BASED VIRTUAL TRY-ON WITH ARBITRARY POSES

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## ABSTRACT

The image-based virtual try-on system has raised research attention recently, but it still requires to upload an image of a user with the target pose. We present a novel learning model, Fit-Me network, to seamlessly fit in-shop clothing into a person image and simultaneously transform the pose of the person image to another given one. The proposed Fit-Me network helps users not only save the time used to change clothes physically but also provide comprehensive information about how suitable the clothes are. By facilitating the arbitrary pose transformation, we can generate consecutive poses to help users get more information for deciding whether to buy the clothes or not from different aspects.

**Index Terms**— Virtual try-on, pose transformation, image synthesis

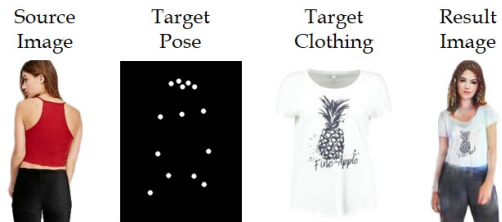
## 1. INTRODUCTION

The revenue of e-commerce market has increased recently, where the market's largest segment is Fashion with a market volume of \$598,631 million in 2019 and it is expected to present a market volume of US \$835,781 million by 2023.<sup>1</sup> Although people get used to going online shopping for fashion items, the average conversion rate of online shopping platforms worldwide in 2018 is only 2.42%.<sup>2</sup> One of the major reasons is that people cannot try fashion items to find whether they are suitable or not when shopping online. Therefore, it is desirable for fashion industry to develop a virtual try-on system for improving the conversion rates and boosting sales.

To facilitate virtual try-on services, image-based virtual try-on [1, 2, 3, 4, 5, 6] and pose transformation [7, 8, 9, 10, 11, 12] are both popular nowadays. For example, Han et al. [3] presented an image-based virtual try-on network (VITON) to put a target clothing item onto the target person. Based on VITON, Wang et al. [4] further presented CP-VTON to preserve the characteristics of clothes by new warping and refining modules. For pose transformation, Balakrishnan et al. [7] separated end-to-end network into four segments to synthesize unseen pose via the modular generative neural network.

<sup>1</sup><https://www.statista.com/outlook/244/100/fashion/worldwide>

<sup>2</sup><https://www.statista.com/statistics/439576/online-shopper-conversion-rate-worldwide/>



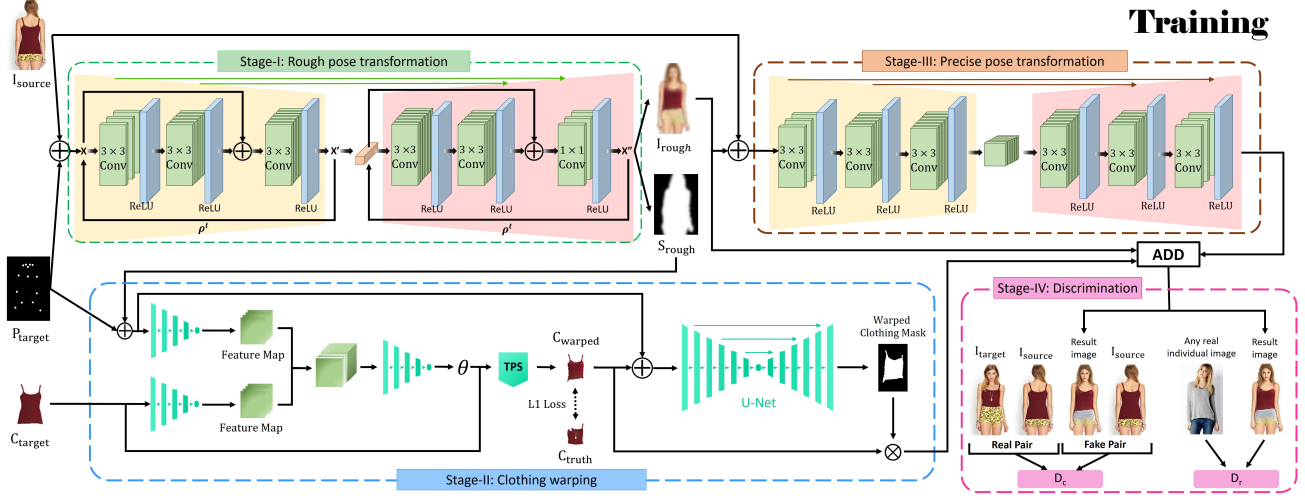
**Fig. 1. Examples of virtual try-on with arbitrary poses**

Liqian Ma et al. [10] constructed a coarse-to-fine architecture to generate images of different posture for people. All the existing works only focus on either virtual try-on or pose transformation but do not consider to try-on and to transform different poses simultaneously.

When customers go shopping for fashion items, it is natural for them to take arbitrary poses for determining whether it looks good on them from different aspects, e.g., the frontage, side views, or even the reverse side. Therefore, pose transformation plays a key role in improving image-based virtual try-on. However, it is tedious if the customers have to upload their photos with different poses. In this paper, we propose to synthesize the virtual try-on with arbitrary poses defined by joint coordinates which can be predefined according to frequent poses in the database. Take Fig. 1 as an example. Given a source image (depicting a user's details), a target pose (using joint coordinates), and a target image of in-shop clothing (specified by the user), the goal is to generate a result image with the user's details in the target pose wearing the target clothing.

Nevertheless, it is challenging to synthesize virtual try-on images with arbitrary poses. One basic approach is to use a two-phase approach, i.e., apply the existing pose transformation first and then image-based virtual try-on. However, the two-phase approach may suffer from the problem of training data sparsity and generate images with visual artifacts since the combinations of different clothes and poses are much greater than that of try-on only or pose transformation only.

To achieve the goal of virtual try-on with arbitrary poses, we propose a new network, namely, Fit-Me, comprised of four stages: (I) rough pose transformation, (II) clothing warping, (III) precise pose transformation, and (IV) dis-



**Fig. 2. The training overview of our Fit-Me network**, which consists of four stages. Stage-I (*Rough pose transformation*) generates the rough image according to the target pose, where  $p^t$  represent  $t$  layers of convolutional neural layers. Stage-II (*Clothing warping*) warps the clothes to fit the target pose, stage-III (*Precise pose transformation*) generates detailed appearance, and stage-IV (*Discrimination*) learns to differentiate the real/fake images and image pairs to help stage-II and stage-III generate better results.

crimination. Specifically, Fit-Me generates the rough target pose transformation from the source image and target pose in stage-I. Afterward, we exploit thin plate spline to warp the clothing for fitting the target pose in stage-II, and then generates detailed appearance in stage-III. Lastly, Fit-Me adopts two discriminators to 1) select the most realistic image, for which a lot of training data exist and thus alleviate the data sparsity problem, and 2) select the real try-on image, which helps our model to precisely generate a detailed and refined result.

The contributions of this paper are summarized as follows. (1) We have identified an unprecedented task of virtual try-on with arbitrary poses, which can be a value-added service for fashion e-commerce platforms and improve the conversion rates. (2) A novel Fit-Me network is proposed to solve the complex task of virtual try-on with arbitrary poses, while two discriminators are utilized to alleviate the problem of training data sparsity. (3) Experimental results show that Fit-Me generates results with greater inception scores.

## 2. FIT-ME NETWORK

Given a source image  $I_{source}$  of a user, a target pose  $P_{target}$  defined by joint coordinates<sup>3</sup>, and target in-shop clothing  $C_{target}$ , our goal is to generate a new image of the user virtually trying on target clothing and holding the same posture.

<sup>3</sup>Pre-trained joint detector [13, 14] can be applied to estimate  $(x, y)$  joint coordinates from images. In our experiment, the following joints are used: nose, eyes, ears, neck, shoulders, elbows, wrists, hips, knees, and ankles.

A naïve way is to train a deep neural network with the dataset including triplet images: one in-shop clothing image, one image of a user wearing different clothing, and one image of a user wearing the in-shop clothing in different posture. However, such dataset does not exist. Therefore, our training dataset only contains the images of a person wearing the same clothing with different poses and in-shop clothing images.

### 2.1. Rough pose transformation

The first task of Fit-Me is to transform the pose of the person in the source image into the target pose. To achieve the transformed task, conditional GANs[15, 16] can be utilized to generate a realistic image. Since the task is challenging, in stage-I, we use a generative model  $G_r$  to generate a rough result  $I_{rough}$ . Specifically, we concatenate the  $I_{source} \in \mathbb{R}^{w \times h \times 3}$  and the  $P_{target} \in \mathbb{R}^{w \times h \times J}$  ( $J$  confidence maps for joints) as input for stage-I. Afterward, we construct  $G_r$  via an U-Net-like architecture [17] to: 1) encode  $I_{source}$  and  $P_{target}$  and transform the pose based on the encoded vector, and 2) highlight minor changes by sequential convolution-ReLU with local skip connections, which improve the generator performance [18]. Let  $I_{target}$  denote the groundtruth image of the user in the target pose, the loss for  $G_r$  is derived as follows.

$$\mathcal{L}_{G_r} = \sum_{i=1}^n \|G_r(I_{source}, P_{target}) - I_{target}\|_1, \quad (1)$$

where  $n$  is the number of image pairs with a user in two different poses. Note that L1 loss is adopted here since it measures the difference at low frequencies well. The details of clothing are refined in stage-II, while the edges of the body and the facial details are improved in stage-III.

## 2.2. Clothing warping

To warp the in-shop clothing for better fitting the target shape, inspired by [4, 19], we adjust their framework for stage-II of Fit-Me network. As illustrated in Fig.2, stage-II consists of: (1) two extraction modules: one extracts features from  $P_{target}$  and  $S_{rough}$  to retrieve the details of human body, and the other extracts the high-level information of  $C_{target}$ , (2) correlation matching module: combining two feature tensors to a single correlation tensor, (3) estimating network: predicting the parameter,  $\theta$ , of spatial transformation from the correlation tensor, and (4) thin plate spline transformation  $\mathcal{T}$ : warping the target clothing  $C_{target}$  to the warped clothing  $C_{warped}$  with  $\theta$ , i.e.,  $C_{warped} = \mathcal{T}(C_{target}, \theta)$ . The loss is then computed as pixel-wise L1 loss between  $C_{warped}$  and  $C_{truth}$  as follows:

$$\mathcal{L}_{clothing}(C_{warped}, C_{truth}) = \|\mathcal{T}(C_{target}, \theta) - C_{truth}\|_1 \quad (2)$$

Moreover, we put the concatenated  $P_{target}$ ,  $S_{rough}$  and  $C_{warped}$  into U-Net [20] for generating more detailed warped clothing mask to fit people more properly. The final clothing, denoted as  $\hat{C}$ , is obtained by compositing  $C_{warped}$  with warped clothing mask.

## 2.3. Precise pose transformation

To alleviate the blurry artifacts on  $I_{rough}$  derived from  $G_r$ , as well as integrate the results from the warped clothing  $C_{warped}$ , we construct a network  $G_p$  in stage-III to generate the absent information and to rectify the erroneous pixels in  $I_{rough}$ . We modify the network architecture of  $G_r$  for  $G_p$  by removing residual blocks to reduce the quantity of information and focus on preserving details. With  $I_{rough}$  and  $I_{source}$  as input,  $G_p$  generates a residual output  $r = G_p(I_{source}, I_{rough})$ . After processing images through stage-I to stage-III, we derive the final result by adding  $r$ ,  $I_{rough}$  and  $\hat{C}$  together.

## 2.4. Discrimination

In traditional GAN [21, 22, 23, 24, 25], the training loss is minimized by alternatively optimizing the discriminator and generator. However, it is challenging to synthesize virtual try-on images with arbitrary poses since it requires pose transformation and clothing warping at the same time. Therefore, we adopt a similar idea but construct two discriminators to complete the GAN architecture and fine-tune the final result from

our network. Our conditional GAN consists of two generative networks and two discriminators to achieve a natural and convincing result image. Specifically, the first discriminator is denoted as  $D_c$  for examining the correctness of our result comparing to the groundtruth  $I_{target}$ . The first adversarial loss  $\mathcal{L}_{correct}(G_p, D_c)$  is derived as follows.

$$\begin{aligned} \mathcal{L}_{correct}(G_p, D_c) = & \mathbb{E}_{(I_{source}, I_{target})} [\log D_c(I_{source}, I_{target})] \\ & + \mathbb{E}_{(I_{source}, \hat{x})} [\log(1 - D_c(I_{source}, G_p(\hat{x}) + I_{rough} + \hat{C}))], \end{aligned} \quad (3)$$

where  $\hat{x}$  represents  $I_{source}$  concatenating with  $I_{rough}$ .

However, when only using the pairwise discriminator  $D_c$ ,  $D_c$  can differentiate the real and fake pairs by the correctness of clothing and pose warping, as well as the realness of images, which makes  $D_c$  too strong for the generator. Moreover, since real individual images are much more accessible, we construct the other auxiliary discriminator  $D_r$  to enhance the realness of our results via distinguishing our results with real individual images. Here, the second adversarial loss  $\mathcal{L}_{real}(G_p, D_r)$  is derived as follows.

$$\begin{aligned} \mathcal{L}_{real}(G_p, D_r) = & \mathbb{E}_{I_{real}} [\log D_r(I_{real})] \\ & + \mathbb{E}_{\hat{x}} [\log(1 - D_r(G_p(\hat{x}) + I_{rough} + \hat{C}))], \end{aligned} \quad (4)$$

where  $I_{real}$  represents any real individual image. Afterward, two discriminators of the proposed Fit-Me network are optimized with a hyperparameter  $\alpha$  as follows.

$$\min_{G_p} \max_{D_c, D_r} \left( \frac{\alpha}{2} \mathcal{L}_{correct}(G_p, D_c) + \frac{1 - \alpha}{2} \mathcal{L}_{real}(G_p, D_r) \right)$$

First, we set a larger  $\alpha$  to encourage our discriminators focusing on  $D_c$  dwindling the difference between our result and  $I_{target}$  instead of naturalness. Then, we gradually decrease  $\alpha$  to improve the significance of  $D_r$  to concentrate more on the realness of the result image.

## 3. EXPERIMENTS

In this section, we evaluate the Fit-Me network on two real datasets. We first present the details of the datasets and implementation. Afterward, quantitative and qualitative analysis are conducted with baselines. Finally, the limitation of Fit-Me are discussed for future research.

### 3.1. Experiment setup

To evaluate the proposed Fit-Me network, two real datasets are used in the experiment. The first dataset is DeepFashion[26] containing about 140K pairs of the same person with different poses and 50K in-shop clothing images which are required to train with our Fit-Me network. The second dataset is collected by VITON [3] containing about 16K frontal-view

**Table 1. Comparison on our virtual try-on dataset between different methods.**

Method	CP-VTON[4]	Pose-Guide[28]	Fit-Me (Ours)	Real Images
Mean	2.5733	3.0064	3.3360	3.6744
Variance	0.0050	0.0094	0.0162	0.0171

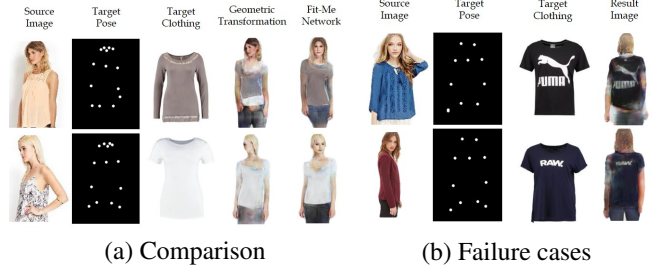


**Fig. 3. Experiment results of virtual try-on with arbitrary poses.** Fit-Me network precisely transforms the source image to the target pose with detailed target clothing.

woman and top clothing image pairs. All the images are cropped and resized to  $256 \times 192$ . We train our Fit-Me network with the DeepFashion dataset because two different poses of the same person and one in-shop clothing image are required, and use 5-fold cross-validation. Moreover, the second dataset (VITON) is used to test that our model has the ability to work well on the different dataset. We use the Adam [27] as the optimizer with  $\beta_1 = 0.5$  and  $\beta_2 = 0.999$ . The learning rate is set to be 0.00002 for 200K steps with a batch size of 8. We use PyTorch for the network implementation, where all convolutional layers are followed by a ReLU except the output convolutional layer.

### 3.2. Quantitative Analysis

Since none of the previous works can perform virtual try-on with arbitrary poses, we first compare Fit-Me with CP-VTON [4] and Pose-Guide [28] in terms of Inception Score (IS)[23] to evaluate the generated image quality. Table 1 shows that the proposed Fit-Me network outperforms other methods on two datasets because we extract human and clothing information separately and make them focus on their respective priorities to achieve comparable results. The IS value of Fit-Me is the closest to that of real images among all methods.



**Fig. 4. (a) Comparison against geometric transformation.** The three columns at left are inputs. The fourth column presents results with geometric transformation, and the right-most column presents the results by Fit-Me network (b) **Failure cases of Fit-Me network.**

### 3.3. Qualitative Analysis

Fig. 3 shows the results of the Fit-Me network. Our network accurately transforms slight posture changes (column 3) as well as dramatic posture changes, e.g., turning from back to the front (columns 1, 2, and 5). Moreover, it is conspicuous that Fit-Me network not only succeeds in transforming poses but also preserves the detailed characteristics of clothing such as texture (lace in column 3) and patterns (camouflage, flecks and alphabets in columns 4, 5 and 6).

Additionally, we further replace  $G_r$  in Fit-Me network with spatial transformation [7]. We translate, rotate, and scale each limb pixel-to-pixel via geometric transformation. Because geometric transformation only considers the two-dimension transformation of body parts, it fails to warp the head naturally to the target position. As shown in the 4-th column of Fig. 4a, the result images show that geometric transformation network is able to change body poses with the target clothing successfully but fail to precisely fit the clothing to the target pose. Whereas our Fit-Me network preserves facial details, especially in the fifth column of Fig. 4a. Fig. 4b shows our failure cases due to a few training data of transforming the posture to the backside. Therefore, it always considers backside to be front when warping clothing.

## 4. CONCLUSION

In this work, we propose a new virtual try-on system (Fit-Me) that can generate virtual try-on images with arbitrary customer poses. By first transforming the pose of the user to a target pose according to the joints of the target pose, we warp the in-shop clothing to fit the target pose and preserve characteristics of both customers and clothing. Experimental results show that the proposed Fit-Me network outperforms the state-of-the-art methods both qualitatively and quantitatively. In the future, we plan to take the human segmentation information into consideration for generating better results.

## 5. ACKNOWLEDGEMENT

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