Verilog® Quick Reference Card

1. Module

```
module module_name (list of ports);
input / output / inout declarations
net / reg declarations
integer declarations
parameter declarations

gate / switch instatnces
hierarchical instances
parallel statements
endmodule
```

2. Parallel Statements

```
Following statements start executing simultaneously inside module initial begin {sequential statements} end always begin {sequential statements} end
```

3. Basic Data Types

a Nets

```
e.g. wire, wand, tri, wor
```

assign wire_name = [expression]};

- Continuously driven
- Gets new value when driver changes
- LHS of continuous assignment

```
tri [15:0] data;
```

// unconditional assign data[15:0] = data in;

// conditional

assign data[15:0] = enable ? data_in : 16'bz;

b. Registers

```
e.g. reg
```

- Represents storage
- Always stores last assigned value
- LHS of an assignment in procedural block.

```
reg signal;
@(posedge clock) signal = 1'b1;
```

// positive edge @(reset) signal = 1'b0; // event (both edges)

4. Sequential Statements

Given below are some examples instead of BNF type of definitions.

```
■ if (reset == 0) begin data = 8'b00; end
```

case (operator)

```
2'd0 : z = x + y;

2'd1 : z = x - y;

2'd2 : z = x * y;

default : $display ("Invalid Operation");
```

endcase

```
■ initial begin // 50 MHz clock

clock = 0;

forever #10 clock = ~clock;

end // precission 1 ns

■ repeat (2) @(posedge clk) data;
```

- repeat (2) @(poseage cik) data;bus <= repeat (5) @ (poseage cik) data
 - // evaluate data when the assignment is // encountered and assign to bus after 5 // clocks.
- repeat (flag) begin // looping

.... action

■ **while** (i < 10) begin action

end

for (i = 0; i < 9; i = i + 1) begin action

end

- wait (!oe) #5 data = d_in;
- @(negedge clock) q = d;
- **begin** // finishes at time #25

#10 x = y;#15 a = b;

end

fork

```
#10 x = y;
#15 a = b;
```

join

5. Gate Primitives

```
and
        (out, in_1, ..., in_n);
                                  nand (out, in_1, ..., in_n);
        (out, in_1, ..., in_n);
                                  nor
                                           (out, in_1, ..., in_n);
\mathbf{or}
xor
        (out, in_1, ..., in_n);
                                  xnor
                                           (out, in_1, ..., in_n);
        (out_1, ..., out_n, in);
                                  not
                                           (out_1, ..., out_n, in);
bufif0 (out, in, control):
                                  bufif1 (out, in, control):
notif0 (out, in, control);
                                  notif0 (out, in, control);
pullup (out);
                                  pulldown (out);
```

```
6. Delays
```

```
Single delay : and #5 my_and (...);
Rise/ Fall : and #(5, 7) my_and (...);
Rise/ Fall / Transport : bufif1 #(10, 15, 5) my_buf (...);
All delays as min:tvp:max : or #(4:5:6, 6:7:8) my_or (...);
Compiler options for delays
+maxdelays, +typdelays(detault), +mindelays
e.g. verilog +maxdelays test.v
```

7. Declarations

```
{}, {{}}
               concatenation
+ - * /
               arithmetic
%
               modulus
               relational
               logical negation
&&
               logical and
               logical or
               logical equality
==
               logical inequality
!=
               case equality
===
!==
               case inequality
               bit-wise negation
&
               bit-wise and
               bit-wise inclusive or
               bit-wise exclusive or
^{\wedge}\sim or \sim^{\wedge}
               bit-wise equivalence
&
               reduction and
               reduction nand
~&
               reduction or
               reduction nor
               reduction xor
~^ or ^~
               reduction xnor
               left shift
<<
               right shift
>>
               condition
               event or
```

8. Attributes specify

// simple pin to pin path delay
(a => out) = 9; // => means parallel connection
// edge sensitive pin to pin path delay
(posedge clock => (out +: in)) = (10, 8);

// state dependent pin to pin path delay if (state_a == 2'b01) (a, b *> out) = 15;
// *> means full connection

endspecify

9. Memory Instantiation

```
module mem_test;

reg [7: 0] memory [0: 10];  // memory declaration integer i; initial begin

// reading the memory content file

$readmemh ("contents.dat", memory);

// display contents of initialized memory

for (i = 0; i < 9, i = i + 1)

$display ("Memory [%d] = %h", i, memory[i]); end endmodule
```

"contents.dat" contains

@02abda@060001

- This simple memory model can be used for feeding input data values to simulation environment.
- \$readmemb can be used for feeding binary values from contents file.

10. Blocking and Non-blocking Statements

```
// These blocking statements exhibit race condition.
always @(posedge clock)
    a = b;
always @(posedge clock)
    b = a;
// This Non-blocking statement removes above race
// condition and gives true swapping operation
always @(posedge clock)
    a <= b;
always @(posedge clock)
    b <= a:
```

11. Functions and Tasks

Function

- A function can enable another function but not another task.
- Functions always execute in 0 simulation time.
- Functions must not contain any delay, event, or timing control statements.
- Functions must have at least one input argument. They can have more than one input.
- Functions always return a single value. They cannot have output or inout argument.

```
e.g.
....
parity = calc_parity (addr);
....
function calc_parity;
input [31: 0] address;
begin
    calc_parity = ^address;
end
endfunction
```

Task

endtask

- A task can enable other tasks and functions.
- Tasks may execute in non-zero simulation time.
- Tasks may contain delay, event, or timing control statements.
- Tasks may have zero or more arguments of type input, output, or inout.
- Tasks do not return with a value, but can pass multiple values through output and inout arguments.

```
Cycle_read (read_in, oe_in, data, addr);
....

task Cycle_read;
input read, oe; // notice the order
output [7: 0] data;
input [15: 0] address;
begin

#10 read_pin = read;
#05 oe_pin = oe;
data = some_funtion (address);
end
```

12. Commonly Used Compiler Directives

```
'define word_size 32

'include ./header.v

'timescale 100ns/1ns // ref_time_unit / precision

'ifdef, 'else, 'endif
e.g.

module and_op (a, b, c);
output a;
input b, c;
'ifdef behavioral
wire a = b & c;
'else
and (a, b, c);
'endif
endmodule
```

13. Observing Outputs

14. Simulation Control

```
initial begin
    $dumpfile ("my.dump");
                                  // dump in this file
    $dumpvars;
                                  // dump all signals
    $dumpvars (1, top);
              // dump variables in module instance top
    $dumpvars (2, top.m1); // dump 2 levels below top.m1
    #1000 dumpoff;
                                  // stop dump
    #500 dumpon;
                                  // start / restart dump
     $stop;
                      // stop for interaction
     #1000 $finish:
                     // come out of simulation
 end
```

15. Language Constructs Not Supported By Most Synthesis Tools

```
Most Synthesis Tools
Declarations and Definitions
    time declaration
    event declaration
    triand, trior, tri1, tri0, and trireg net types
    Ranges and arrays for integers
    primitive definition
Statements
    initial statement
    delay control
    event control
     wait statement
    repeat statement
    fork statement
    deassign statement
    force statement
    release statement
    defparam statement
    Division and modulus operators for variables
    Case equality and inequality operators (=== and !==)
Gate-Level Constructs
    pullup, pulldown,
    tranif0, tranif1, rtran, rtranif0, rtranif1
Miscellaneous Constructs
    Compiler directives like 'ifdef, 'endif, and 'else
```

Hierarchical names within a module