

RVSP

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LTI Systems

Random Signal  
response of  
Linear Systems

System  
response-Convolution

Mean value of System  
response

Mean-Squared value of  
system response

Autocorrelation of  
Response

Cross-Correlation  
functions of Input and  
Output

# Random Process: Spectral Characteristics



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# LTI Systems



# LTI System Block Diagram

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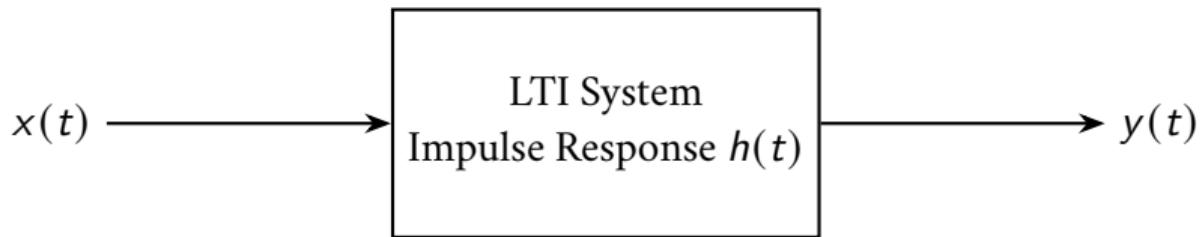
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$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau) d\tau$$



# The General Linear System

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Consider a linear system operating on  $x(t)$  to cause  $y(t)$  and write

$$y(t) = L[x(t)] \quad (1)$$

Here  $L$  is an *operator* representing the action of the system on  $x(t)$ .

A system is said to be linear if

$$y(t) = L\left[\sum_{n=1}^N \alpha_n x_n(t)\right] = \sum_{n=1}^N \alpha_n L[x_n(t)] = \sum_{n=1}^N \alpha_n y_n(t) \quad (8.1-2)$$

where the  $\alpha_n$  are arbitrary constants and  $N$  is a finite number.

From the properties of the impulse function we may write

$$x(t) = \int_{-\infty}^{\infty} x(\xi) \delta(t - \xi) d\xi \quad (2)$$



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By substituting  $x(t)$  into eqn (1) and observing that the operator acts on the time function, we obtain

$$\begin{aligned}y(t) &= L[x(t)] = L\left[\int_{-\infty}^{\infty} x(\xi)\delta(t - \xi) d\xi\right] \\&= \int_{-\infty}^{\infty} x(\xi)L[\delta(t - \xi)] d\xi\end{aligned}\tag{8.1-4}$$

Let us define a new function  $h(t, \xi)$  as the **impulse response** of the linear system; that is,

$$L[\delta(t - \xi)] = h(t, \xi)\tag{8.1-5}$$

$y(t)$  becomes

$$y(t) = \int_{-\infty}^{\infty} x(\xi)h(t, \xi) d\xi$$



# If linear System is time-invariant

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A general linear system is said to be time-invariant if the impulse response is time-invariant

$$h(t, \xi) = h(t - \xi) \quad (3)$$

now the output  $y(t)$  becomes

$$y(t) = \int_{-\infty}^{\infty} x(\xi) h(t - \xi) d\xi$$

The above equation is known as *convolution integral* of  $x(t)$  and  $h(t)$ . The convolution is given by

$$y(t) = x(t) * h(t)$$



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# Random Signal response of Linear Systems



# System response-Convolution

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Even if  $x(t)$  is a random signal, the network's response  $y(t)$  is given by the convolution integral

$$y(t) = \int_{-\infty}^{\infty} x(\xi) h(t - \xi) d\xi \quad (4)$$

$$= \int_{-\infty}^{\infty} h(\xi) x(t - \xi) d\xi \quad (5)$$

Since  $x(t)$  is a sample function of random process  $X(t)$ , the convolution results in a new random process  $Y(t)$

$$Y(t) = \int_{-\infty}^{\infty} h(\xi) X(t - \xi) d\xi \quad (6)$$



# Mean value of System response

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We know the output  $Y(t)$  is given by

$$Y(t) = \int_{-\infty}^{\infty} h(\xi)X(t - \xi) d\xi$$

Let us assume  $X(t)$  is wide-sense stationary

$$E[Y(t)] = E\left[\int_{-\infty}^{\infty} h(\xi)X(t - \xi) d\xi\right] = \int_{-\infty}^{\infty} h(\xi) \underbrace{E[X(t - \xi)]}_{\bar{X}} d\xi$$

$$E[Y(t)] = \bar{X} \int_{-\infty}^{\infty} h(\xi) d\xi$$



# Mean-Squared value of system response

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$$\begin{aligned} E[Y^2(t)] &= E \left[ \int_{-\infty}^{\infty} h(\xi_1) X(t - \xi_1) d\xi_1 \int_{-\infty}^{\infty} h(\xi_2) X(t - \xi_2) d\xi_2 \right] \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E[X(t - \xi_1) X(t - \xi_2)] h(\xi_1) h(\xi_2) d\xi_1 d\xi_2 \end{aligned}$$

If  $X(t)$  is wide-sense stationary

$$R_{XX}(\xi_1 - \xi_2) = E[X(t - \xi_1) X(t - \xi_2)]$$

the mean-squared value of the output becomes independent of  $t$

$$\bar{Y}^2 = E[Y^2(t)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R_{XX}(\xi_1 - \xi_2) h(\xi_1) h(\xi_2) d\xi_1 d\xi_2$$



# Autocorrelation of Response

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The autocorrelation function of  $Y(t)$  is given by

$$R_{YY}(t, t + \tau) = E[Y(t)Y(t + \tau)]$$

$$= E \left[ \int_{-\infty}^{\infty} h(\xi_1)X(t - \xi_1) d\xi_1 \int_{-\infty}^{\infty} h(\xi_2)X(t + \tau - \xi_2) d\xi_2 \right]$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E[X(t - \xi_1)X(t + \tau - \xi_2)] h(\xi_1)h(\xi_2) d\xi_1 d\xi_2$$

If  $X(t)$  is wide-sense stationary

$$R_{YY}(\tau) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R_{XX}(\tau + \xi_1 - \xi_2) h(\xi_1)h(\xi_2) d\xi_1 d\xi_2$$



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## Two important conclusions

- If  $X(t)$  is wide-sense stationary, then  $Y(t)$  is also wide-sense stationary ( $R_{YY}(\tau)$  does not depend on  $t$ ,  $E[Y(t)]$  is constant)
- $R_{YY}(\tau)$  is the twofold convolution of the input autocorrelation function with the network's impulse response

$$R_{YY}(\tau) = R_{XX}(\tau) * h(-\tau) * h(\tau) \quad (7)$$



# Cross-Correlation functions of Input and Output

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The cross-correlation function of  $X(t)$  and  $Y(t)$  is

$$\begin{aligned} R_{XY}(t, t + \tau) &= E[X(t)Y(t + \tau)] = E \left[ X(t) \int_{-\infty}^{\infty} h(\xi)X(t + \tau - \xi) d\xi \right] \\ &= \int_{-\infty}^{\infty} E[X(t)X(t + \tau - \xi)]h(\xi)d\xi \end{aligned}$$

If  $X(t)$  is wide-sense stationary, the above equation reduces to

$$R_{XY}(\tau) = \int_{-\infty}^{\infty} R_{XX}(\tau - \xi)h(\xi)d\xi = R_{XX}(\tau) * h(\tau)$$



# Cross-Correlation functions of Input and Output

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Similarly we can show

$$R_{YX}(\tau) = \int_{-\infty}^{\infty} R_{XX}(\tau - \xi) h(-\xi) d\xi = R_{XX}(\tau) * h(-\tau)$$

**Conclusion:** Since cross-correlation functions are independent of  $t$ ,  $X(t)$  and  $Y(t)$  are jointly wide-sense stationary.



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## Consider

$$R_{YY}(\tau) = \underbrace{R_{XX}(\tau) * h(\tau) * h(-\tau)}_{R_{XY}(\tau)} \quad (8)$$

$$= R_{XY}(\tau) * h(-\tau) \quad (9)$$

$$R_{YY}(\tau) = \underbrace{R_{XX}(\tau) * h(-\tau) * h(\tau)}_{R_{YX}(\tau)} \quad (10)$$

$$= R_{YX}(\tau) * h(\tau) \quad (11)$$



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Acknowledge various sources for the images.  
Thankyou