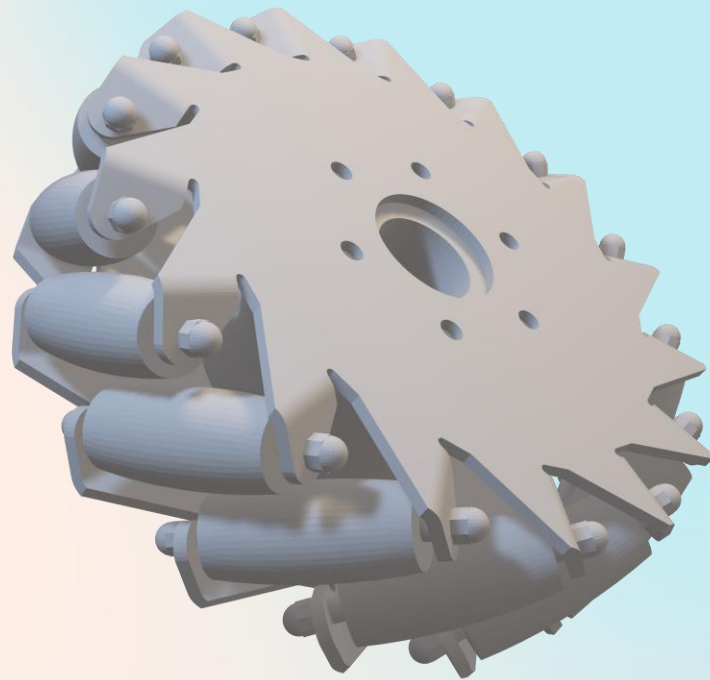


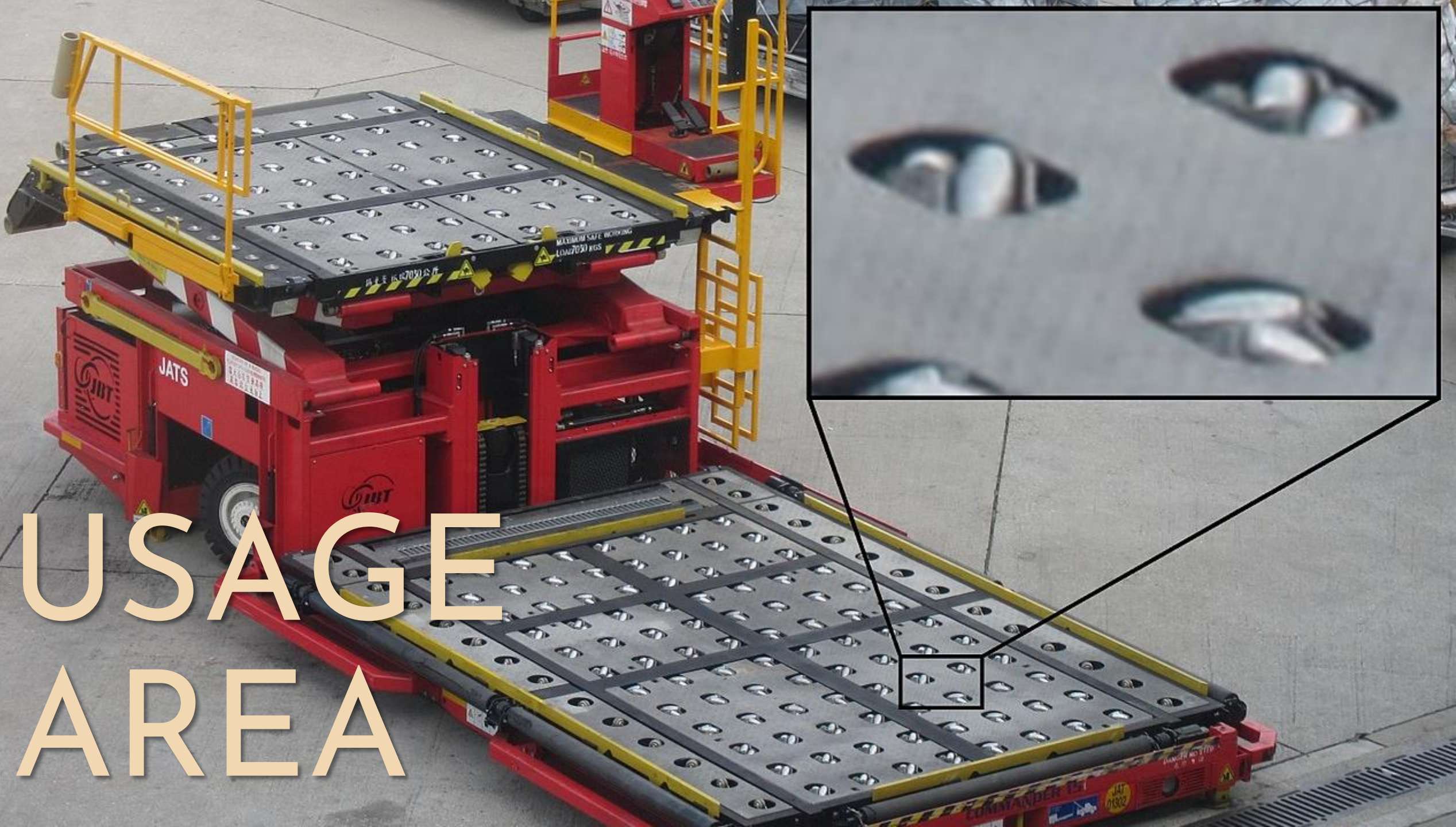
Mecanum Wheel



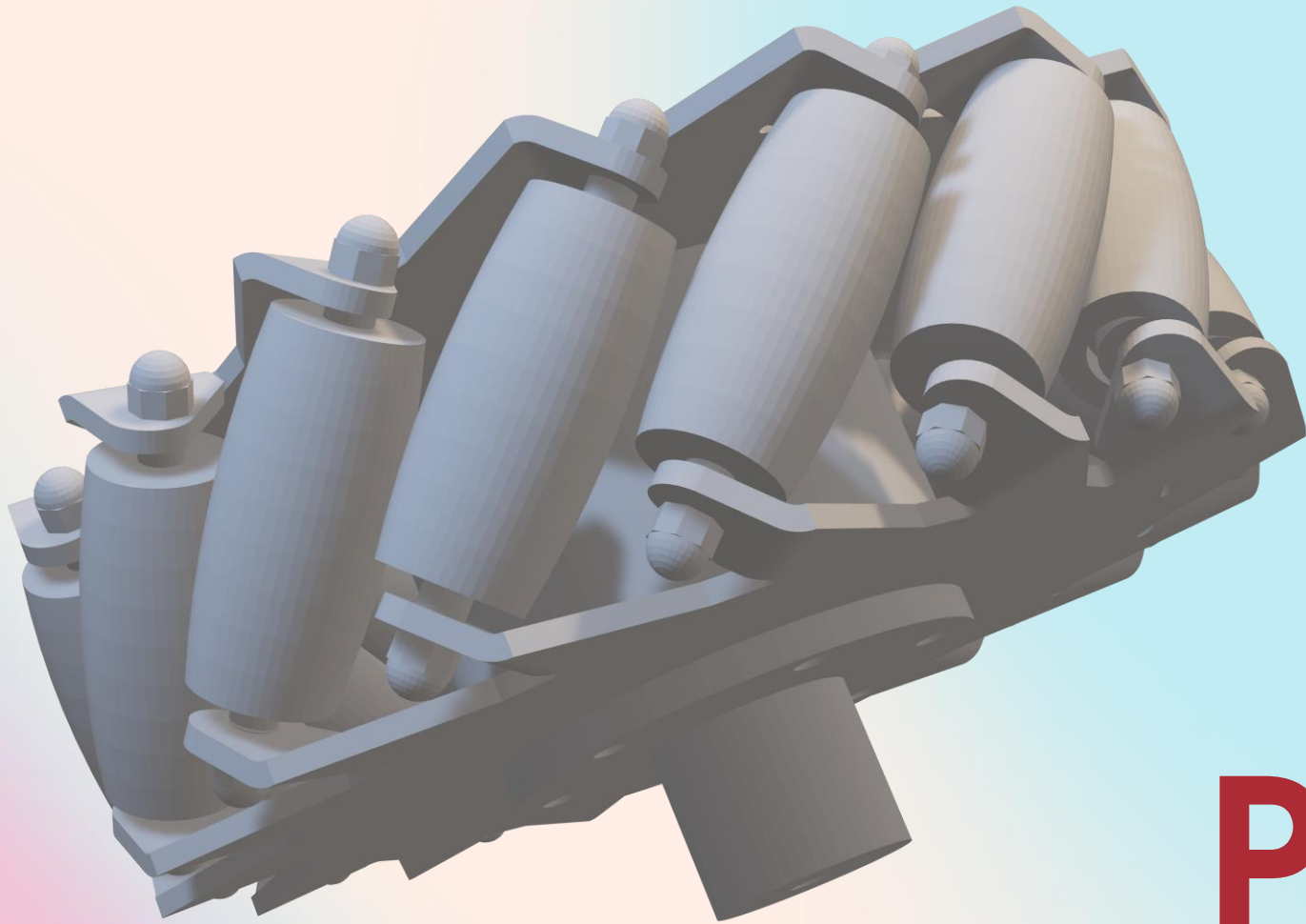
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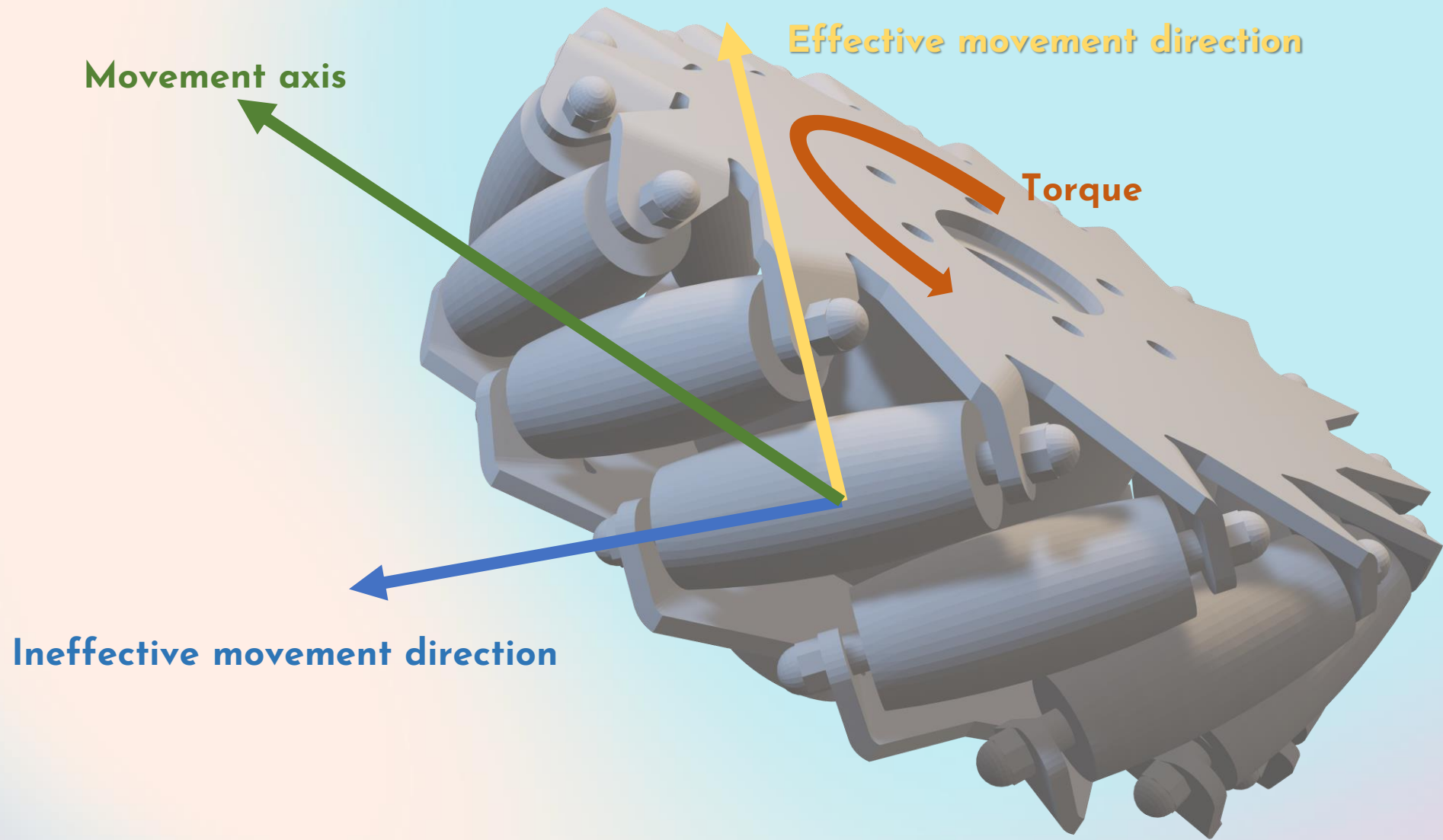
AREA

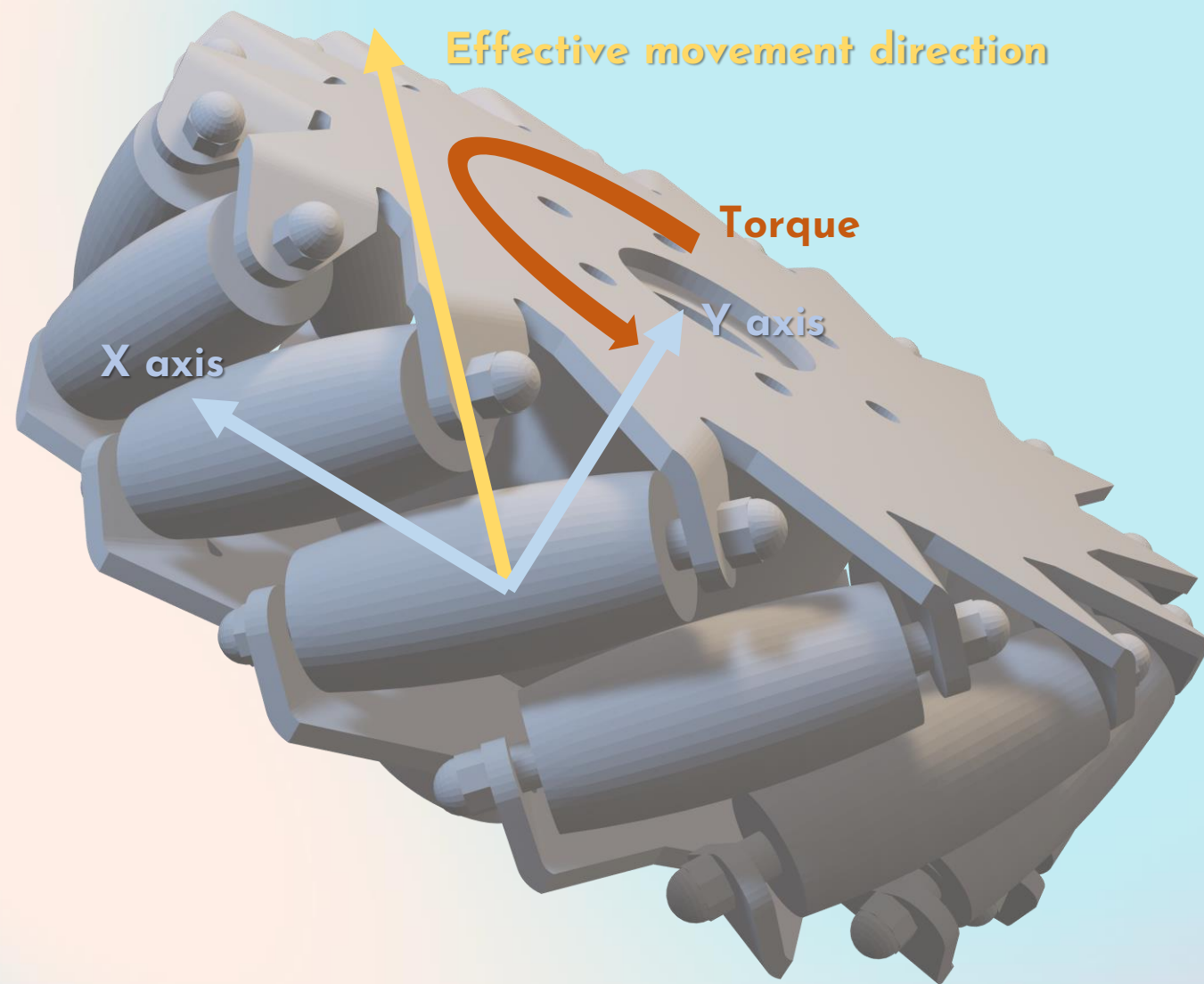


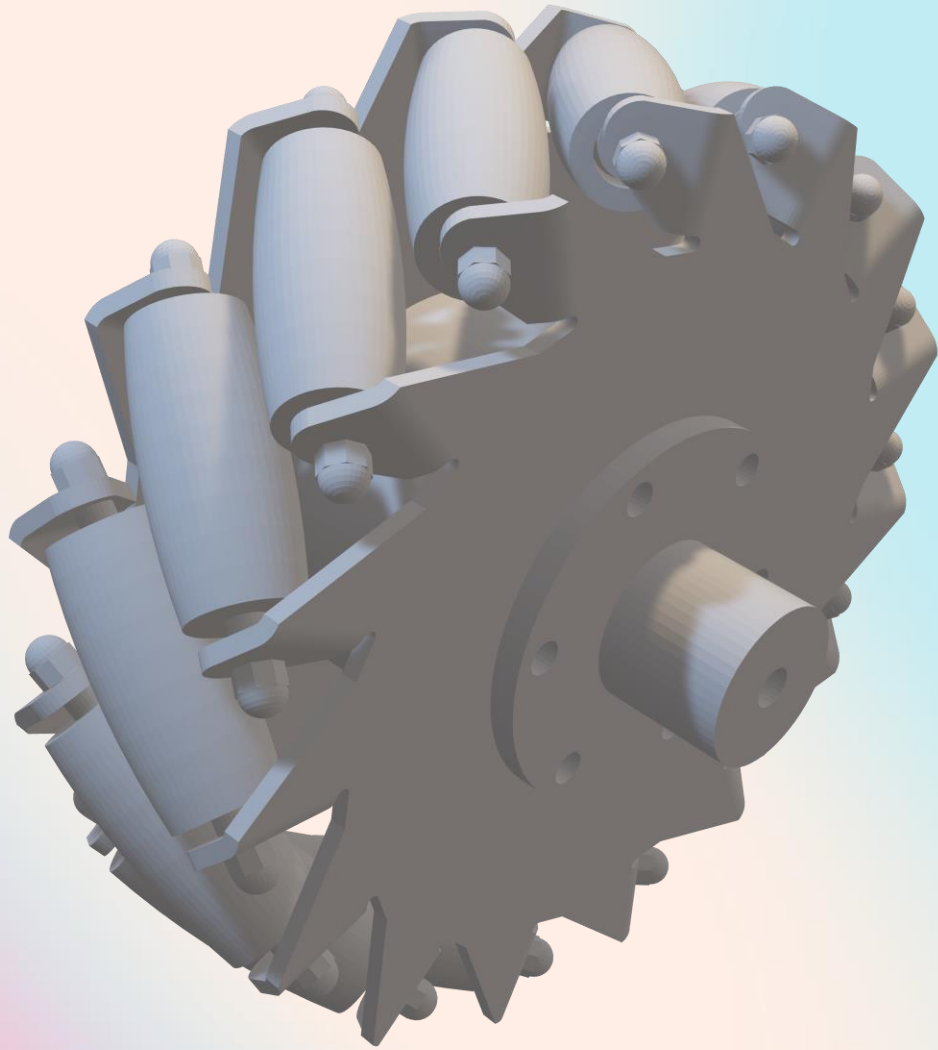
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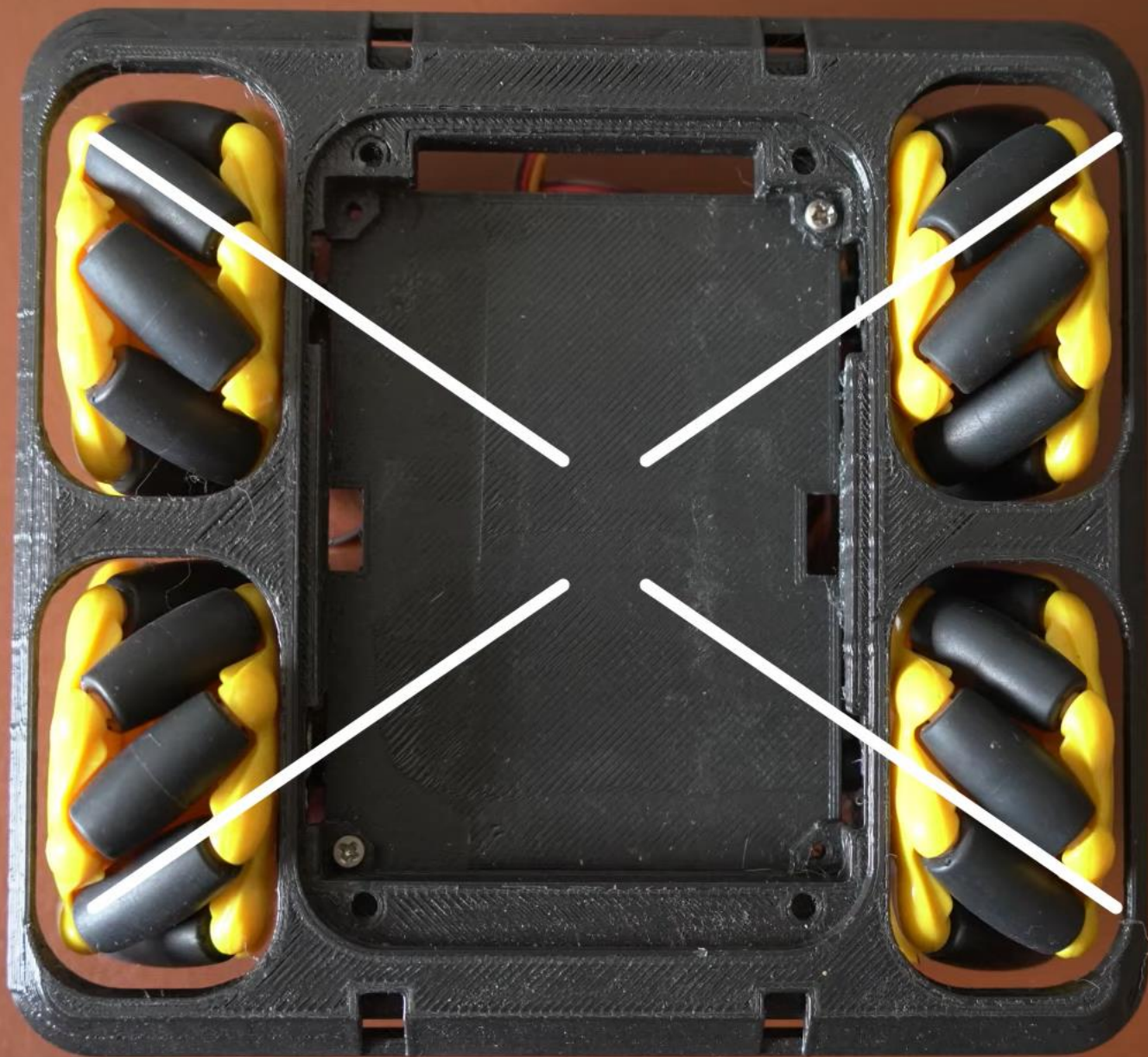
Principles

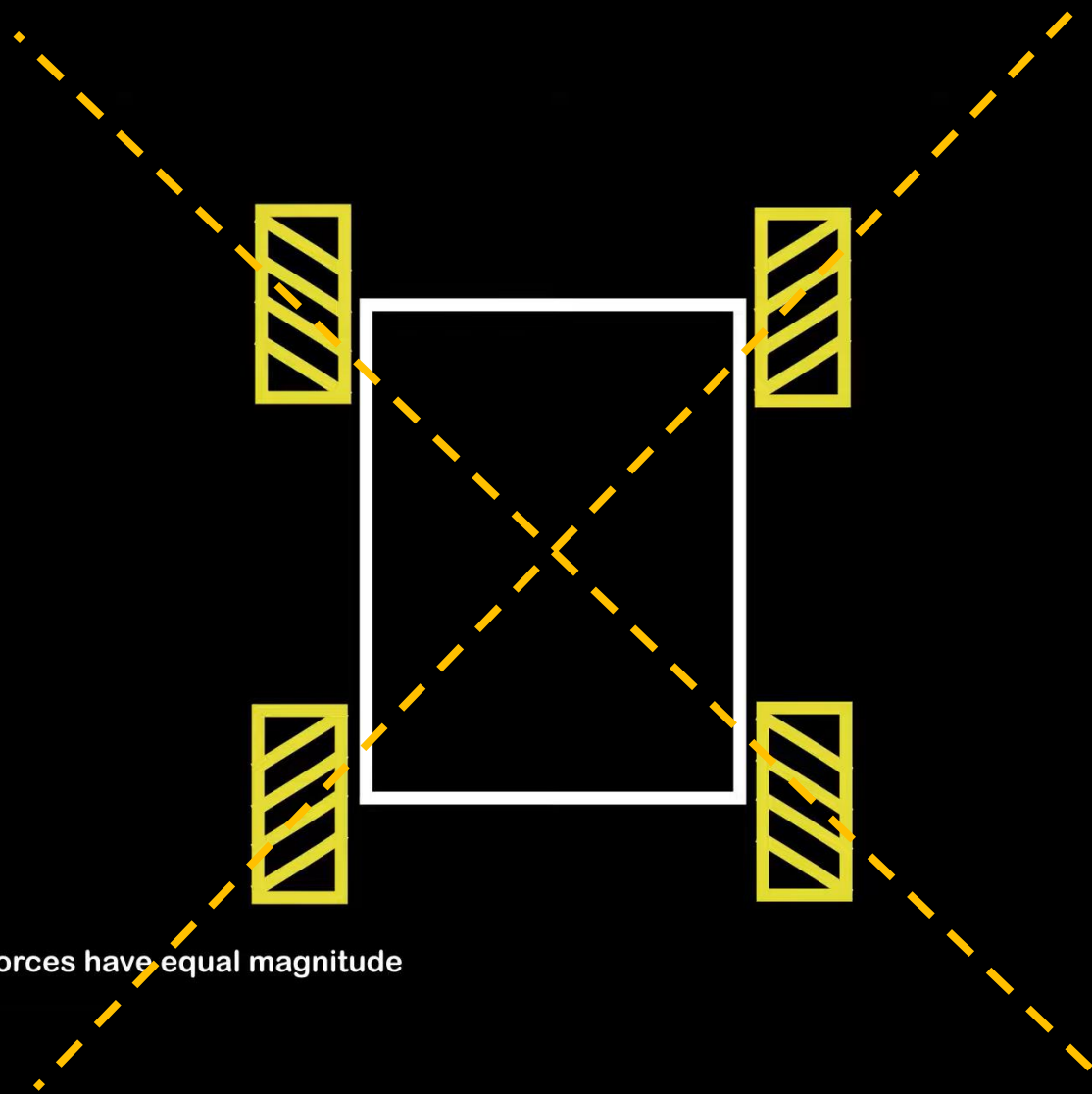




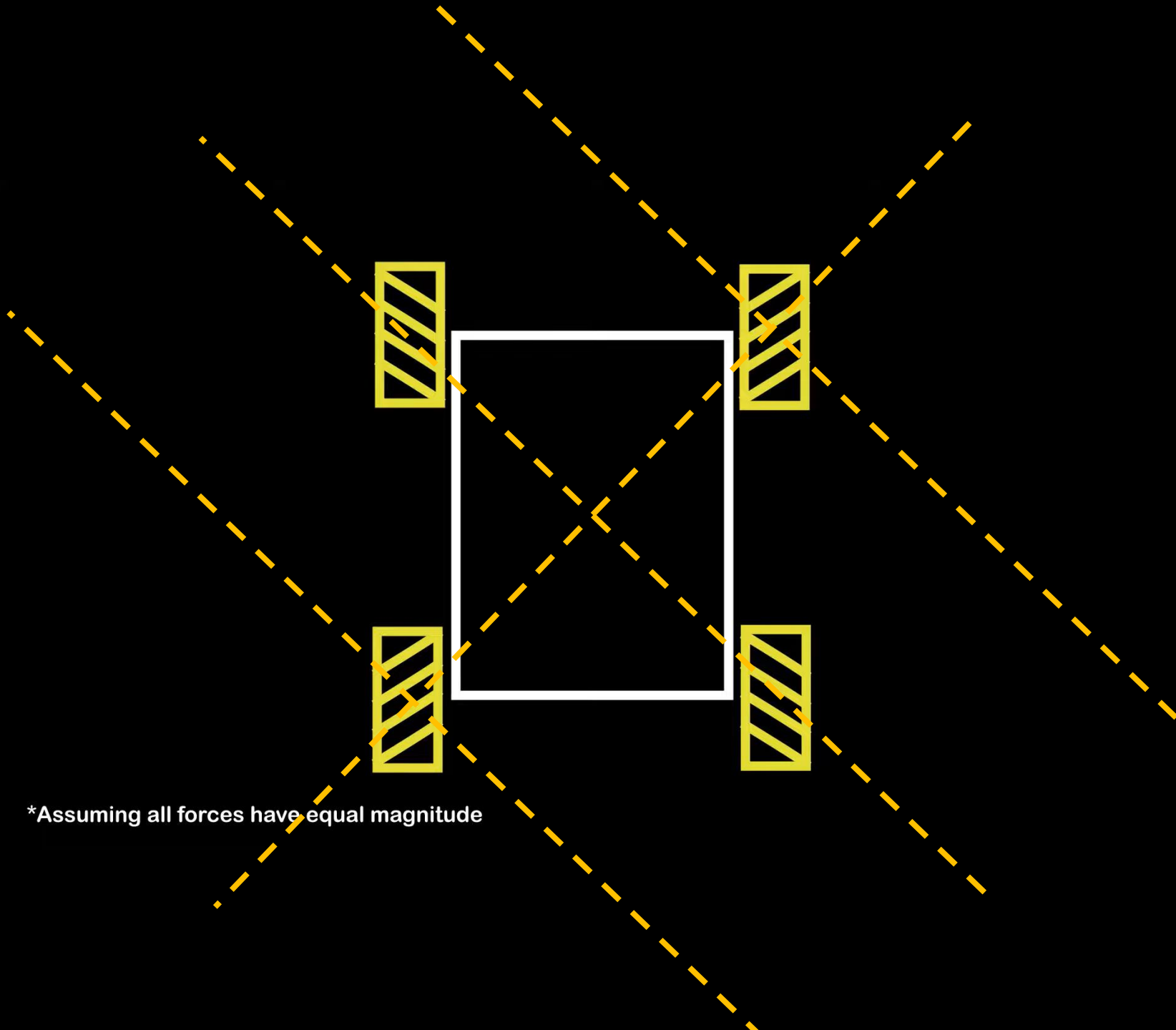


**Locating
wheels**

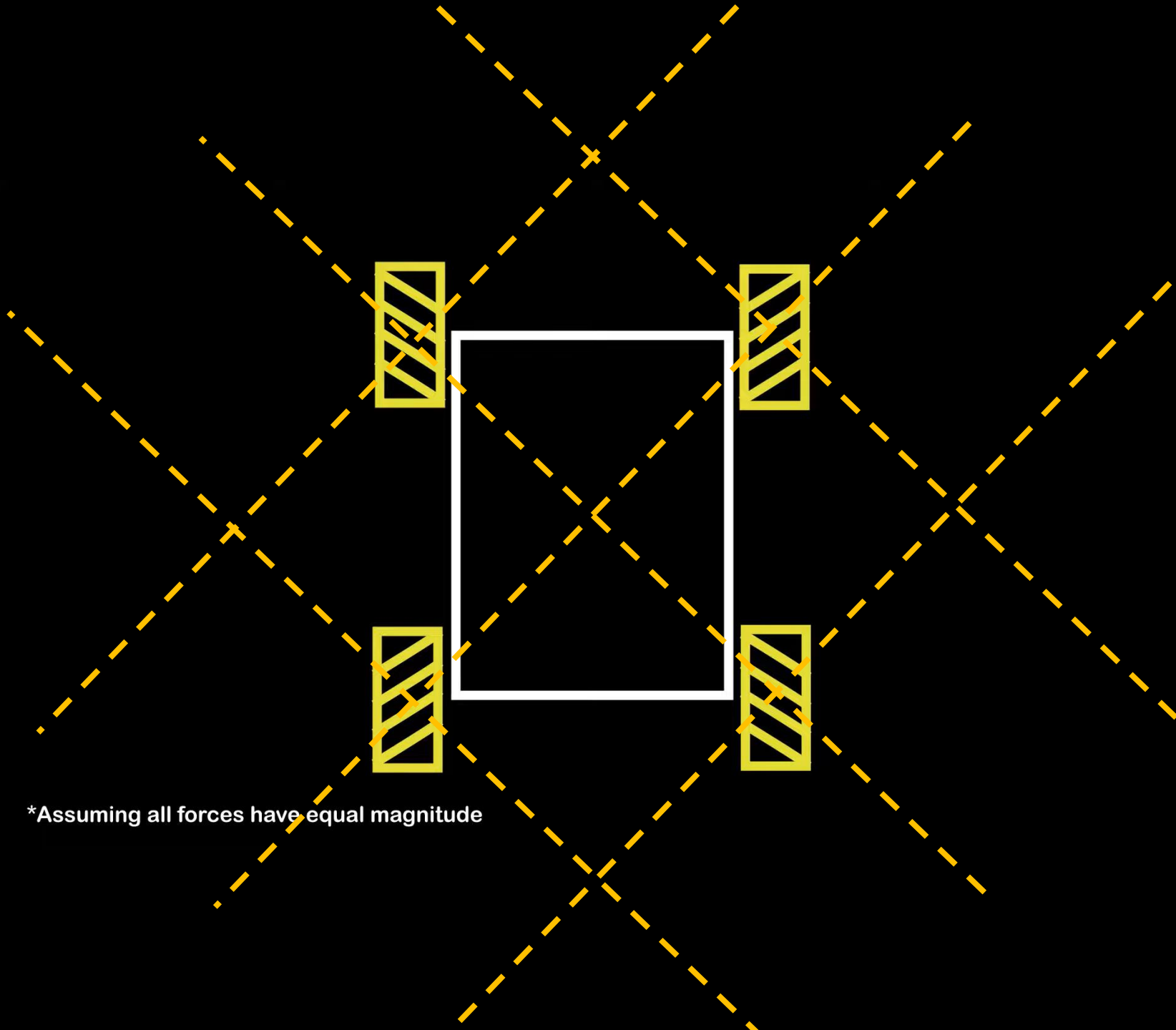




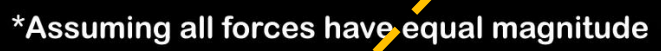
*Assuming all forces have equal magnitude

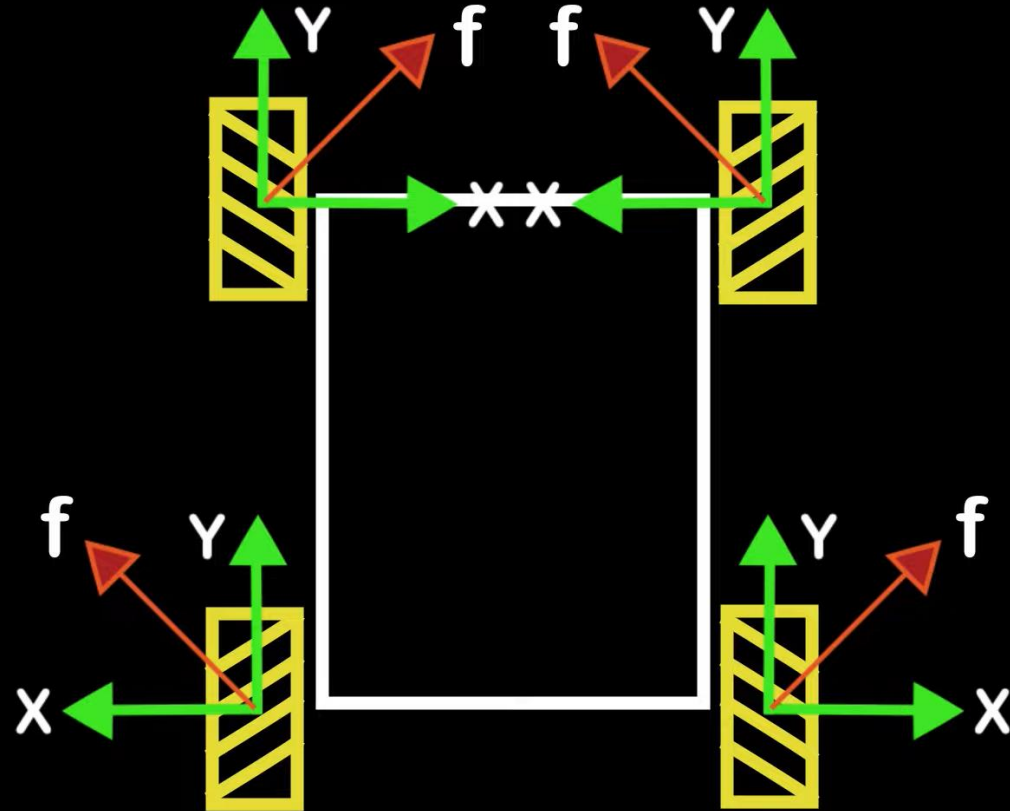


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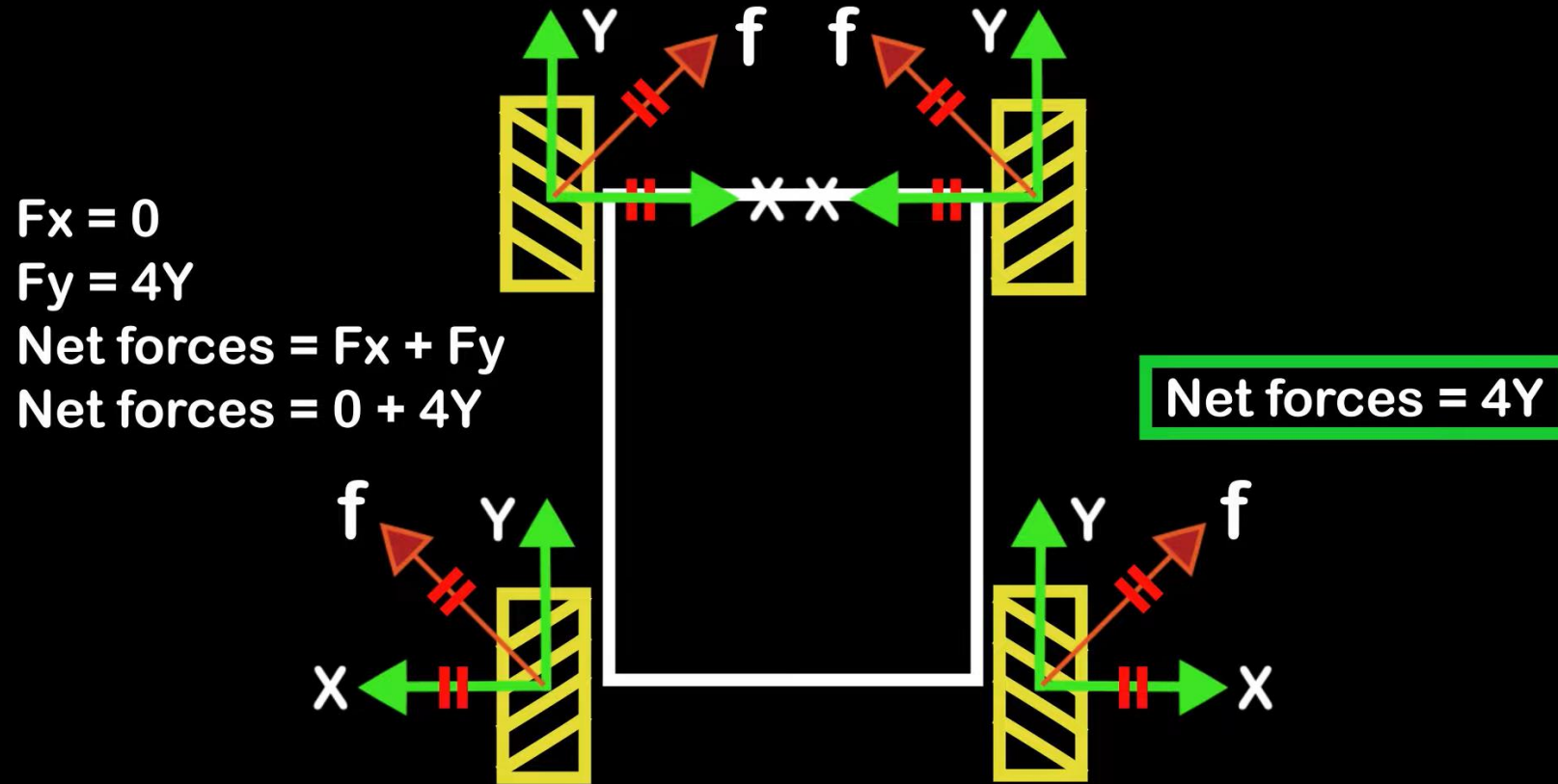


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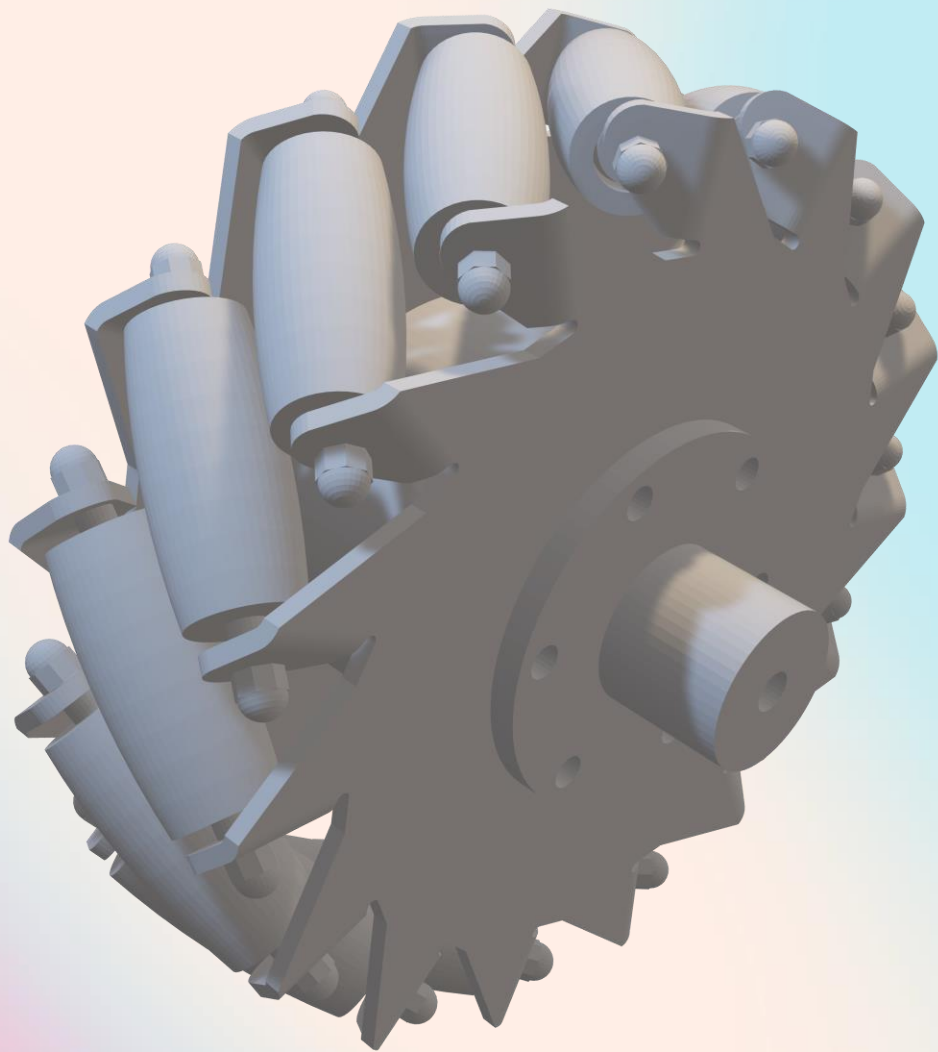




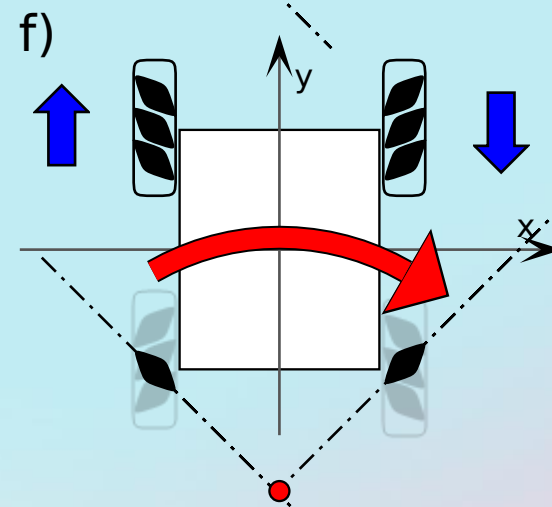
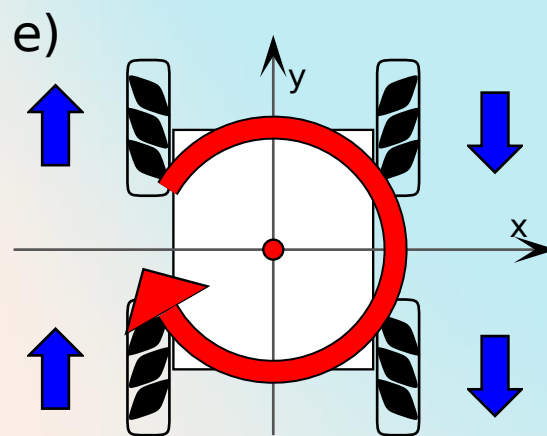
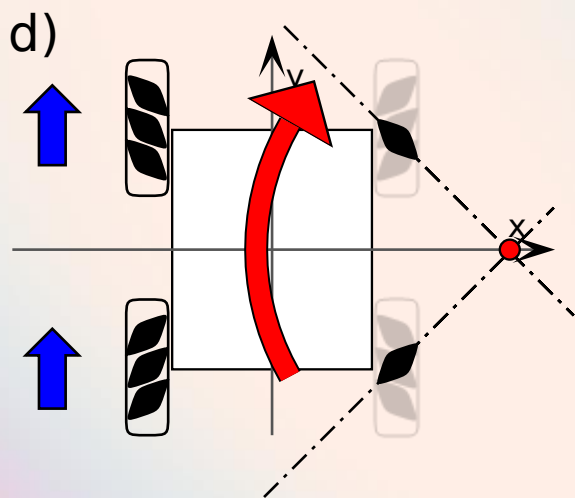
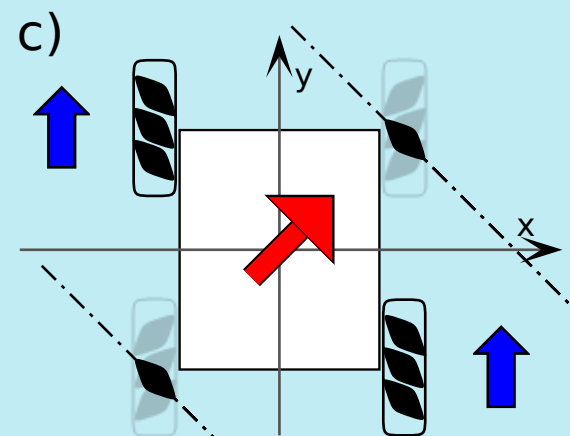
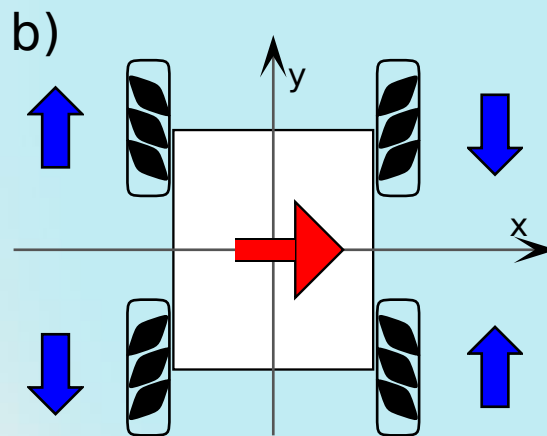
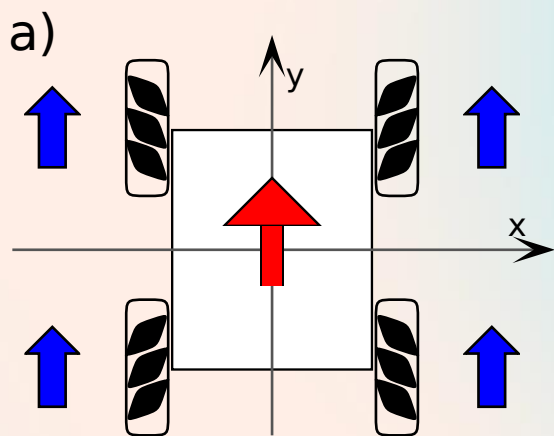
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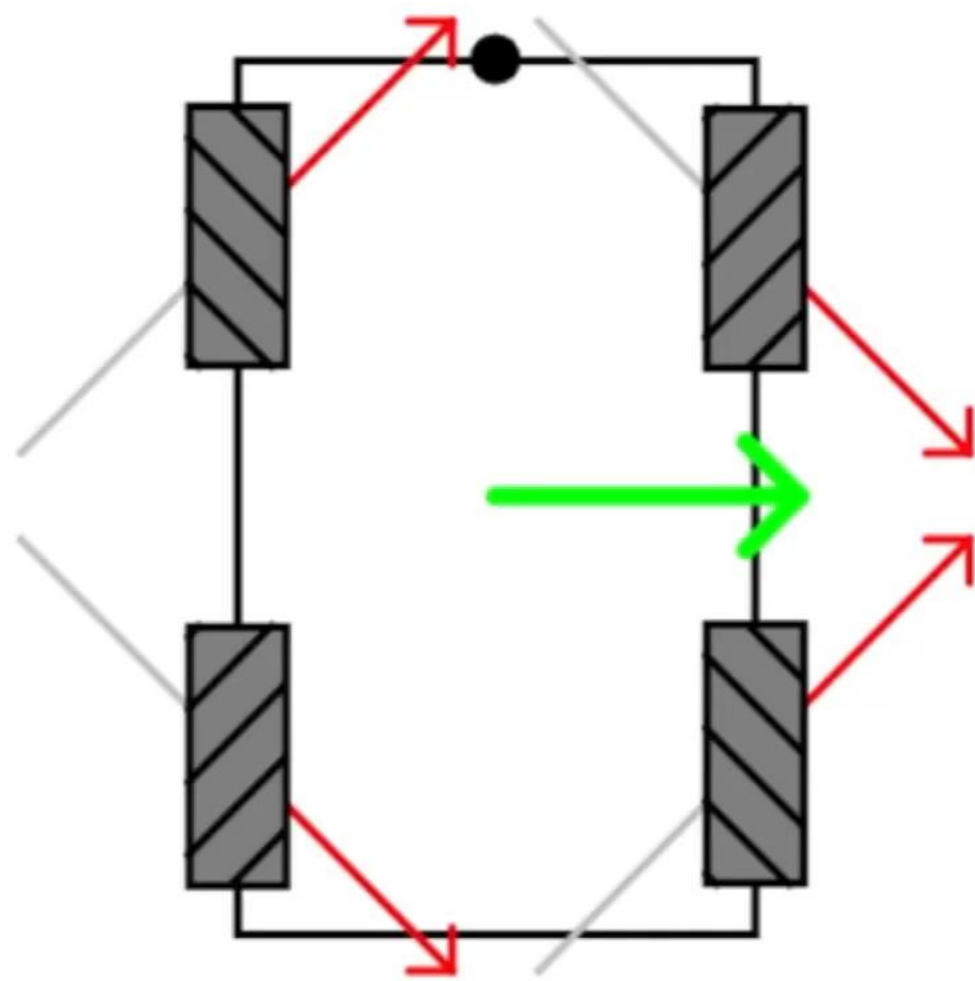


*Assuming all forces have equal magnitude



MOTIONS





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Development of a Mobile Low Cost 3D Human Motion Tracking System

INSPECTOR: ERKİN GEZGİN