Numerical Optimization with Python (2024B) Programming Assignment 02

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Abstract

This report details my implementation of interior point method. This is homework for optimization course.

1 Linear Programming (LP)

1.1 Problem Definition

The linear programming problem is defined as follows:

```
\begin{array}{ll} \text{maximize} & x+y \\ \text{subject to} & y \geq -x+1 \\ & y \leq 1 \\ & x \leq 2 \\ & y \geq 0 \end{array}
```

1.2 Results

```
Final solution: [1.99999995 0.99997752]

Objective value at the final solution: -3.000

Constraint 1 value at the final solution: -2.000

Constraint 2 value at the final solution: -0.000

Constraint 3 value at the final solution: -0.000

Constraint 4 value at the final solution: -1.000
```

Figure 1: results for LP

1.3 Plots

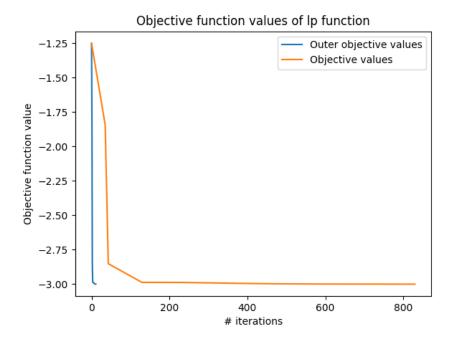


Figure 2: objective value vs. outer iteration number for linear programming case.

Feasible region and path 2D

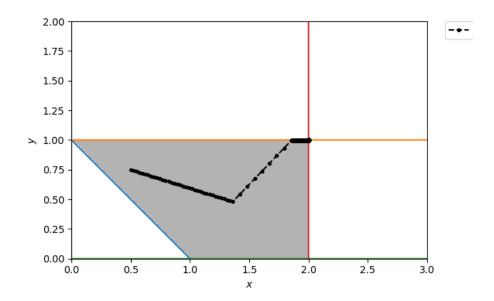


Figure 3: Feasible region and the path taken by the algorithm (LP).

2 Quadratic Programming (QP)

2.1 Problem Definition

The quadratic programming problem is defined as follows:

$$\begin{array}{ll} \text{minimize} & x^2+y^2+(z+1)^2 \\ \text{subject to} & x+y+z=1 \\ & x\geq 0 \\ & y\geq 0 \\ & z\geq 0 \end{array}$$

2.2 Results

```
Final solution: [0.32097619 0.67356423 0.00545958]
Objective value at the final solution: 1.568
Constraint 1 value at the final solution: -0.321
Constraint 2 value at the final solution: -0.674
Constraint 3 value at the final solution: -0.005
Equality constraint 4 value at the final solution: 1.000
```

Figure 4: Results qp

2.3 Plots

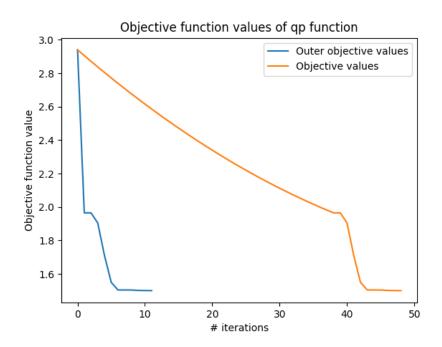


Figure 5: Objective value vs. outer iteration number (QP)

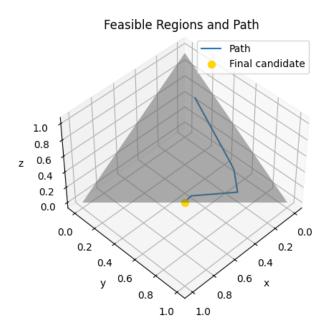


Figure 6: Feasible region and the path taken by the algorithm (QP) $\,$