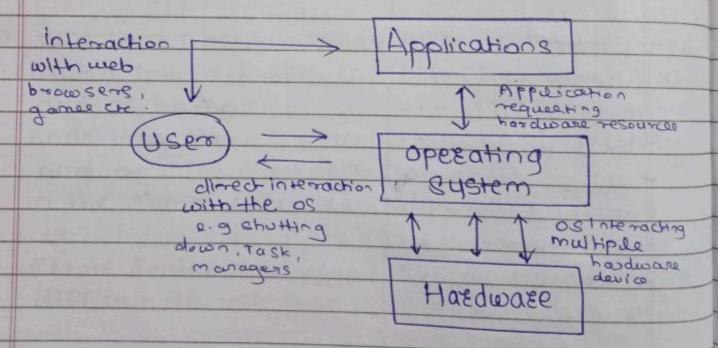
Overview of operating System

Defination:

An operating System (OS) is a slw program that acts as an interface between a computer's howdware and its users.

It is a fundamental component of any computer system and manages the overall operations of a computer or a network of a computers.

The main purpose of an operating system is to provide a convenient and efficient way for users to interact with the computer System.



Different types of operating system exist, including general-purpose operating system like windows, macos, & Linux as wer as specialized operating system Fox specific devices or application (e.g. real time

operating system for smartphones).

-: Dual Mode Operation :-

Dual mode operation, also known as dual privilege mode or privileged mode, is a feature of modern operating systems that enables a clear distinction between privileged and non-privileged operations.

In dual mode operation, the processor os CPU (central processing Unit) operates in two distinct modes.

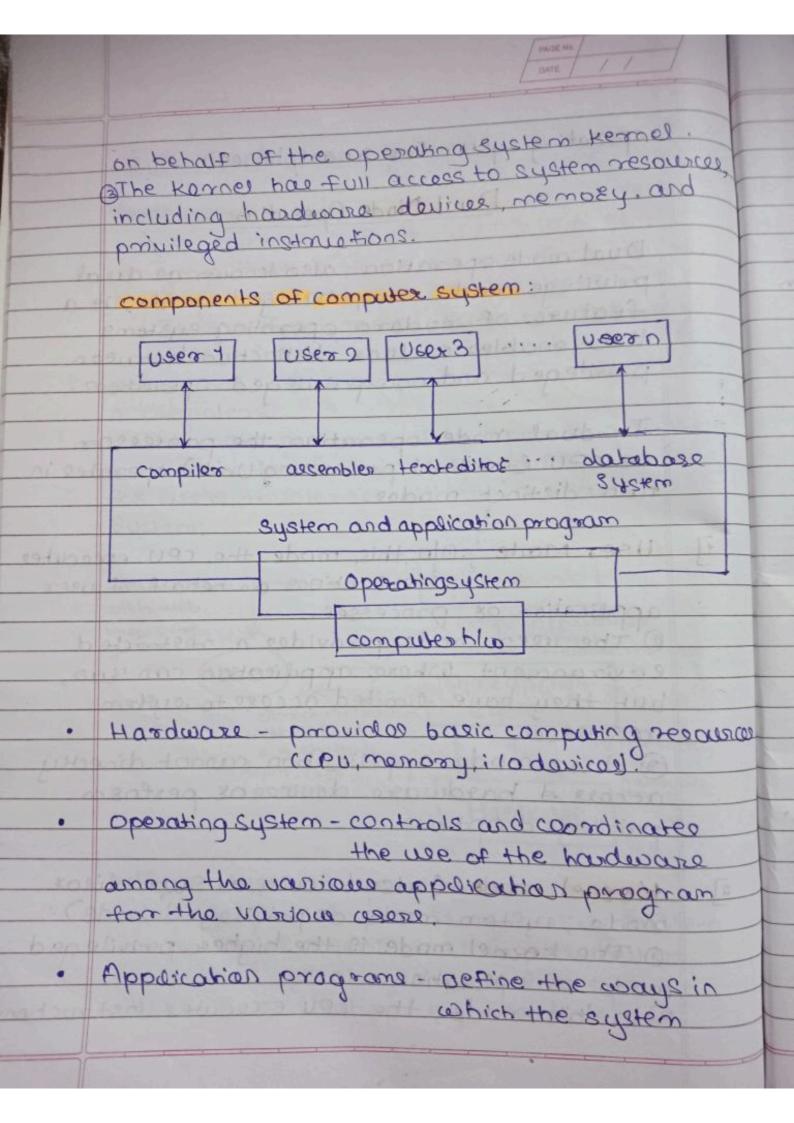
instructions on behalf of user

application or processes.

- D'the user mode provides a restricted environment where application can sur, but they have simited access to system resources.
- 3 User mode appolication cannot directly access & hardware devices or perform privileged options.
- Mode, system mode or privileged mode).

 D'The kornel mode is the higher privileged mode of operation.

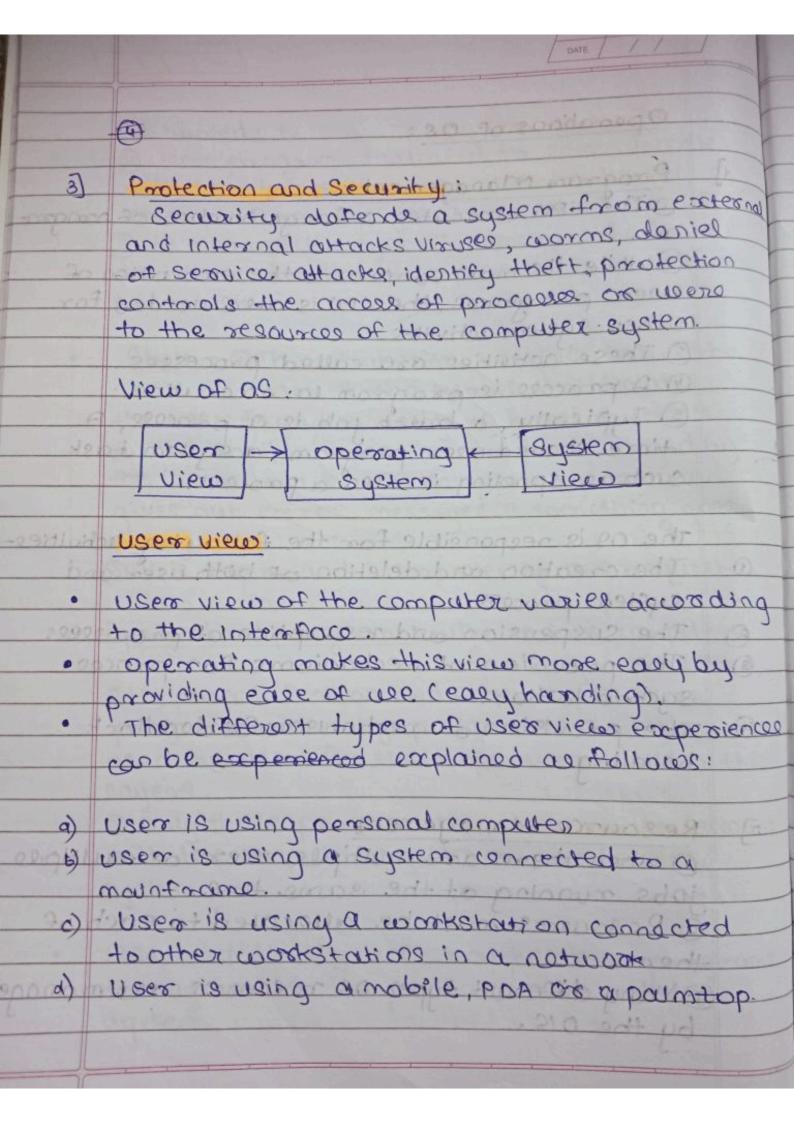
 Plo this mode, the cpu executer instructions



resources are used to solve the computing problems of the users. Ccompilers, database systems, vidoo games, business programs). · Users : (people, machines, other computers) Structure of 08: Application Kernel -> Terminals (Hardwaret) Printers DISKS Utilities · Hardware : OThe HIW is centre of Structure that provides the os with basi The how consists of au pt peripherals like memory (RAM, HOD, FDD etc) processor, mouse 57 (09 and other ip devices, terminals printers of . The Kennel : OThe Kernel is the heart of the system - a collection of programs mostly weither in 'c' which commun cate with the how directly. @ Kamel in an interface better blus and of the System and shell. (3) It is loaded into the memory when the system

DATE / / is booted. @ User programs that need to communicate with the blower the services of the kernel, which performs the job on the works behalf (3) It manages the system's mamory, schedules processes, decides their priorities and perform Other task. Shell - OThe Shell is as interface bottos the uses & the kernel that Isolates the user from knowledge of kesnel functions @ The shell accepts the commands keyed by the users and checks for their syntax and gives out error messages it something good 3) It is a command interpreter of was request Application programe - Othe various compilers for larquages like c C++, parcal, fortean and other application programs written by programmers which was used by users for their operations faus in this Dayers @ only those person who maintain as "account' with the computer system as use the UNIX system. User can directly access explaination programs through which they can interest with the Bystem.

Operations of Os: Program Management: OThe CPU executes a large number of programms. (2) While its main concorn is the execution of user programs, the CPU is also needed for Other system activities. 3 These activities are called processes 1 A process is program in execution. (5) Typically, a batch job is a process, A time shared user program, a system task such as spooling is also a process. The creation and deletion of both user and system process 1 The suspension and resumption of processes The provision of mechanisms for process sychaonization. The provision of mechanisms for deadlock hardling. Resource Management: 1) when there are multiple users or multiple jobs running at the same time. @ Resources must be allocated to each of them some on all some testions realto (3) Many different types of resources are manage by the OIS.



System View : from the computer's point of you, the as is involved with the hardware It is know as resource allocators. OS controls many 110 devices. It is a control program that marages that the execution of user program to prevent errors & improper use of computer. Evolution of operating system. Generations of 09. First Generation (1945-1955) Second Generation (1955-1965) Third Generation (1965-1980) Fouth Generation (1980-Pregent) The First Generation (1945-1955): Vaceuum Tubes and Plugboards The earliest electronic digital computers had no operating systems. Machines of the time were so primitive that programs were often entered one bit at time on rows of mechanical awitches (plug boards) Programing languages were unknown (not ever assembly languages.

The Second Generation (1955-1965):
Transistors and Boutch system

Osecond generation 1955-1965-transistors, batch systems.

@ By the early 1950's, the routine had improved somewhat with the introduction of purch cards.

(3) The General Motors Research Laboratories implemented the first os in the early 1950's for their IBM 701.

The system of the so's generally ran

Dese were called single-stream batch proceeding system because programs and data were submitted in group or beatches.

The Third Generation (1965-1980): Integrated Circuits & Multiprogramming.

TG 1965-1980-ICS & multiprogram ming.

(2) The systems of the 1960's were also batch processing systems, but they were able to take botter advantage of the computer's resources by munning several jobs at once.

Es so operating s: designers developed the concept of multiprogramming in which several jobs are in main memory at once; a processor is switched from

job to job as readed to keep several job advancing while keeping the peripheral devices in use.

The Fourth Generation (1980-present):

The Fourth Generation (1980-present):
Personal Computers.

4th Gen 1980: present personal computers with the doublopment of LSI (large Scale Integration) circuits, chips, operating 8. entered in the system entered in the pc and the workstation age.

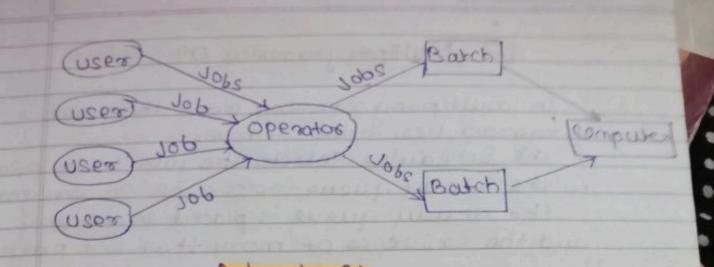
Microprocessor technology evolved to the point that it became possible to build dosk top computers as powerful as the mainframes of the 1970s.

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1	4	Types of operating System.
		Types or openioning system
4]		Batch 08.
[o		Multiprogramming
3		multi-lacking/Time sharing system
u]		multiprocessor System
9	-	Distributed System
6]	11/2	Roal Time Bystem
mann	0	International Comments for the second contract to
-	1	En Batch operating system
alens)		This type of as does not interact with the
	0	omputer directly
10100	-	The user has fo submit a job (written on
-	10	ande or tape) to a computer operator.
312.00	11 200	more is an openator which takes cinilar
	17	obs having the same requirements and around
23	1	THE TOTAL DOCTOR
		It is the responsibility of the operator
	10	soot the lobs with similar hoods
	-	The computer operator places of habit of
	-	Jobs we batched a together but
	ما	anguages and requirements. Of type of
		The monitor is almans in the
	ma	mory and available for execution
	Part.	o caedinos.
	5 14 1	Southern College of the College of t
	stin	Charles Ton Line State Control of the Control of th
	7.5	local interest to have the second



. The idle time for the batch system is less

. It is easy to manage large work repeatedly in botch systems.

· Easier to handle large jobs.

Good for repetitive tack.

Disadvantages

· The computer operators should be well known with batch oystem.

Batch aystems are hand to debug:

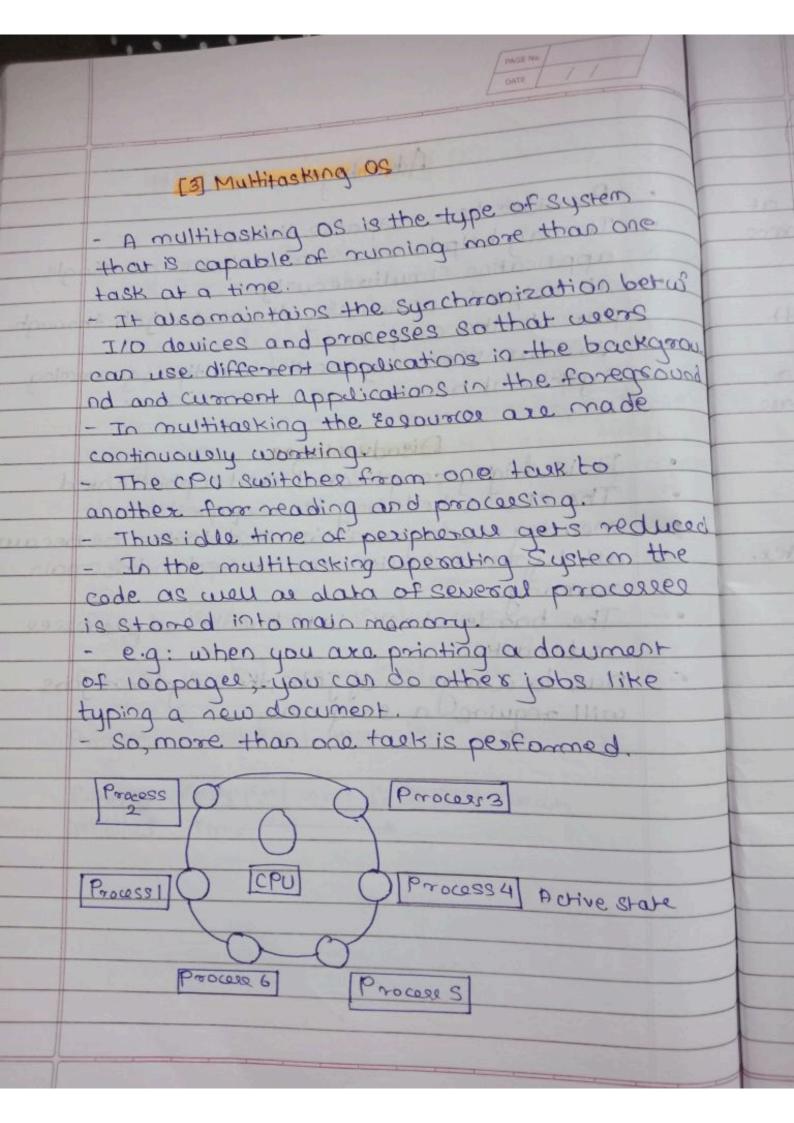
It is sometimes costly.

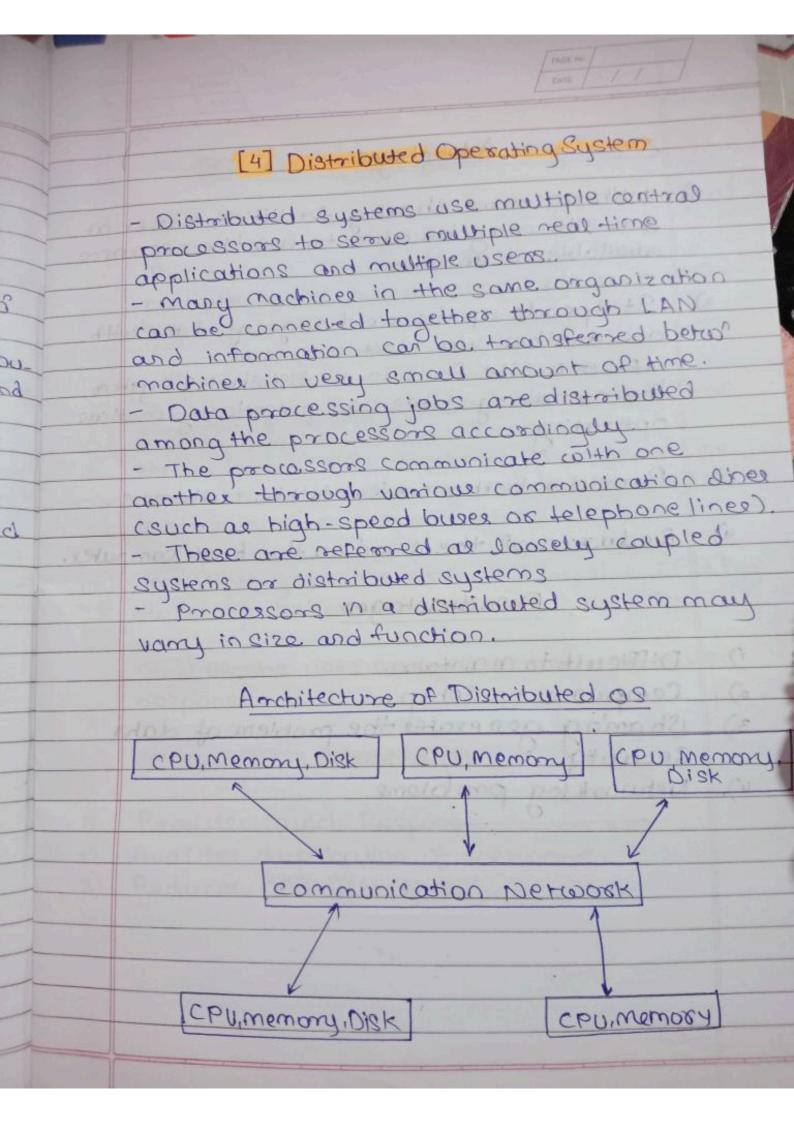
. The other jobs will have to write for an unknown time if any job fails.

[2] Multiprogramming 09 - In multiprogramming more than one program lies in the memorey. The Schedules selects the jobs to be play in the ready queue from a no. of program - The ready queue is placed in memory and the existence of more than one program in mais memory is known as multiprogrammin - Since there is only one processor, multiple programs cannot be executed at a time. - Instead the 03 exacutes past of one program then the part of another and so on. e.q user can open word, excel, access & other apparations in a oystem Prog A Run wast Run wait Proop B wait Run wout Run wait Prog. c wait Run wait Run wait Proq. D Run Run Run w cuit Run Run Run wait

Advantages Provides less response time. It may help to run various jobs in a single application simultaneously. · It helps to optimizing the total job throughput of the computer: · various were may use the multiprogramming system at once. Disadvantages It is highly complicated and sophisticated The CPU scheduling is required.

Memory management is need in the as because all types of tacks are stored in the main momory. The hander task is to handle auprocesses and tasks. · Due to dange no of jobs, the long-term jobs will require a long wait.





Advantages 1) with resource sharing facilities, a user at one site may be able to use the resources available at another. a) It speads up the oxchange of data with one another via electronic mail. If one site fails in a distributed system, the remaining sites can potentially continue operating. Provides botter services to the customers 4) Reduction of the load on the bost computer. Disadvantages Difficult to maintain Compdoor to Setup. Shaning generates the problem of data Security, Networking problems 4).

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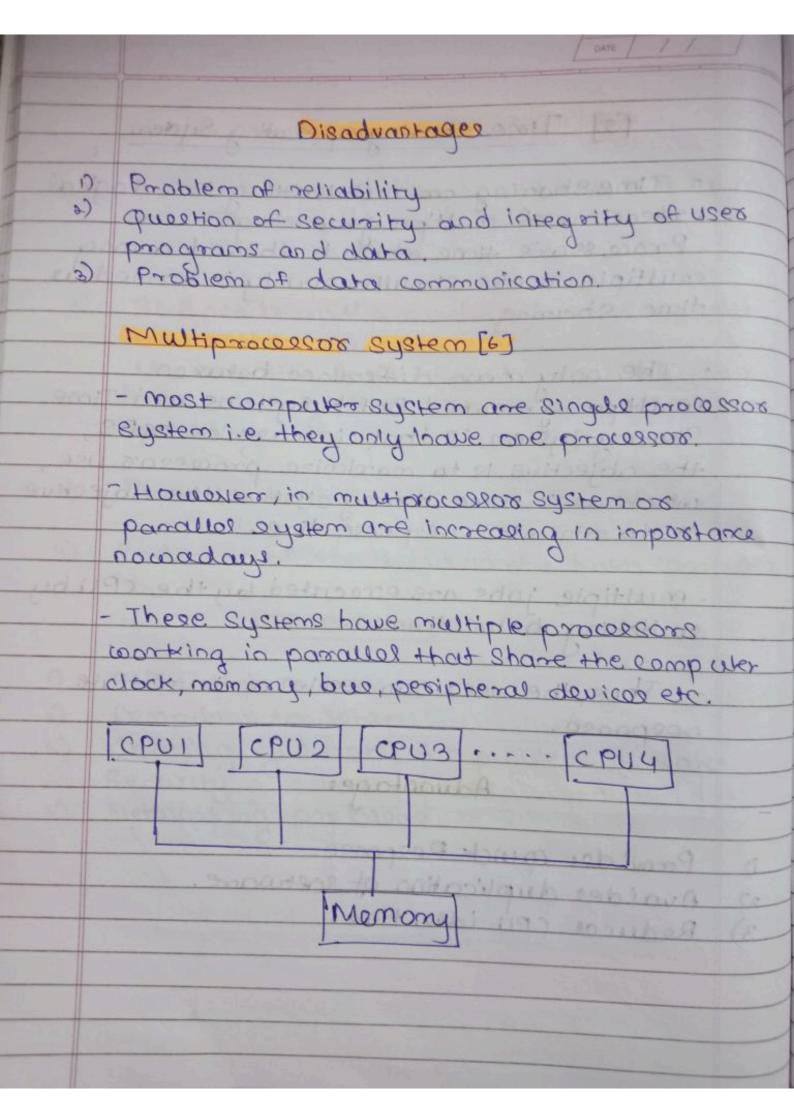
[5] Time sharing operating System.

- Time Shaving on multitasking is a dogical extension of multiprogramming.

 Proce ssor's time which is shared among multiple users simultaneously is termed be time Shaving.
- The only main difference baturean multiprogrammed Batch systems and Time Sharing system is that in case of MBS, the objective is to maximize processor use, where as in time sharing system, the objective is to minimize response time.
- mutiple jobs are executed by the CPU by switching betwo them.
- Thus, the user can receive an immediate response.

Advantages

- 1) Provider quick Response
- 2) Avoides duplication of software.
- 3) Reduces (PU idea time!



Types of multiprocessors systems.

- symmetric multiprocessor

1. Symmetric Multiprocosson:

- O in these types of systems, each processor contains a similar copy of the os and they all communicate with each other.
- @ All the processors are in a pear to pear relationship is no master-slave relationship exists batween them.
- 3 An example: Encore version of unix for the multimax computer.

Asymmetric Multiprocessos:

O in asymmetric systems, each processor is given a predefined task.

of there is a master processor that gives instruction to all the other processors.

a master slave relationship.

D'Asymmetric multiprocessor was the only type of multiprocessor available before Symmetric multiprocessors were created

DATE / / / Advantages Improved performance: multiprocessor system can execute tasks faster than singule-processor sistems, as the workload can be distributed across multiple processor. Cetter Scalability: It can be Scaled more easily than singleprocessor systems. Increaced revability: It can continue to operate even if one processor fails, as the remaining processors can continue to execute tasks Disadvantage Increased computarity: multiprocesses computer system are more computer than single-computer systems, and they require additional hardware, software & management relource. Higher power consumpation: Multicomputed require more pourox to operate than

Single-computer systems, which can increase the cost of operating and maintaining the system.

3. Difficult programming: Developing Blue that

can effectively

utilize multiple computers can be challenging,

and it requires specialized programming

[7] Real Time 05

- Real time Operating System has well defined fixed time constraints.
- Processing should be done within the defined contraints-Hard & soft real time system.
- A primary objective of real time systems is to provide quick event response time and thus meet the scheduling deadlines

Types:

1) Hand real-time: When an event occurs,
it should be serviced
within the predictable time au times in a
given hard real time system

Softweal-time: It means that only the precodence & 2) sequence for the task operations are defined, interrupt latencies are small. There can be few deviations between expected laterices of the tasks & observed time commints and a few deadline misses are accepted maxim utilization of devices and systems. 1) Thus more of from au the resources Focus or running applications & loss importance to appairations that are in the Error free. I have to be memory Allocation. Diaducintages Limited Tasks: Use Heavy system Resources: sometimes the system resources are not 20 youd & are expensive as well. compde se Algorithms: Applications: Flight control Eyetem Simulatione.

/ WOR HILL		

	*	Difference botween R	eal Time System 8
1		Difference botween R Time Sharing System.	
1	-		Time sharing 08
-	-	Real Time OS	In TSOS fixed time 13
-		be completed within	given to each process
1		fixed aleadline.	and all processes are
1	27	+xoo seedonine.	arranged in aqueus
		4	3
	(2)	A RTS has well.	It requires more
		defined, fixed time	complicated CPU
		Constraints.	scheduling algorithms
		and commonts to	9001
	(3)	Response time 19	Response time is not
		important.	important.
		not eldipunosi al Al	1193 shipping si II (B)
1		Process deals with	Process deals with
-	17.00	singula application	more than one application
1		at 8 time.	Simultaneously
+		OTBACK STATE	LAS ARMS CASE J
4	6	computer resources	computer resources
-	2 post	are not shared	are shared botween
1		betwo the user	the user.
1		the technology of	a series and the series of the
-	<u>G</u>	No modification is	The pagazana and ba
-	01	possible.	modified and weitten
-		nottnessian	
-			by the users.
1	(3)	Switching in air	
1		Switching is not present	Takes place, among
		present.	the processes.

*	Différence between mi	utitasking and multiprog.
30	Multitasking, task shares the common resource i.e. CPU.	A computer running A computer running more than one program at a time is caused as multiprogramming
(a)	multitasking is the ability of a computer to bandle a number of task or jobs simultaneously.	multiprogramming is the capacity to man as handle several programs at the same time.
	It is possible cpu to moning more than one task (jab) at the dame, time.	14 is impossible for a cpu to muning more than one program at the same time.
	e.g. let us say us are printing a dac. of 100 pages.	e.g. lot as say there are two programs weiting in the pools to be executed.
0	Objective is to minimize the reeponse time.	Improvement in CPU Utilization.
	Simple compdanity	ti compagnity is

Mobile OS

OA mobile OS is an operating system that is appearably designed to run on mobile devices such as mobile phones, smartphones, PDAs, such as mobile phones, smartphones, PDAs, table computers and other handheld dovices. The mobile OS is the slw platform of top of which other programs, cauda application programs, can run on mobile devices.

3) An operating system of for smartphones tablets and other mobile devices is called mobile 08.

Some of the most popular Os for mobile devices includes.

Android OS:

O An android os is an open source operating system primarily used in mobile devices.

O written primarily in Java and based on the Linux os, it was initially developed by Android Inc. and was eventually purchased by Google in 2005

TOS: Dios is the operating system croated by Apple Inc. for mobile devices. @ The los is used in many of the mobile devices for apple such as diphone, iPod, @ los is used a lot and only lags behind iPad etc. Android in terms of popularity. Command based as DISK OPERATING SYSTEM (DOS) Olt is MS DOS Microsoft disk operating Byston 3 It is a single user, non-graphical line omented command or menu-odriver of 3 11 has a simple interface but the interface ie less user friendly @ e.q dir, mkdir etc DNIX 08: o Developed in 1970 by Kon Thompson at Bell Laboratory. @ UNIX mus on a wider range of system than any other 08. 3 H allows people to work together & shall information in controlled way @ UNIX provides pouros & flexibility.

GUI Based 08:

- MINDOWS
- o windows is doublaged by microsoft
- (2) It is a forerunner to the Apple macross
- 3 Microsoft provided ms-003 a graphical user interface called windows.
- I windows system components.
- Hardware Abstraction layer (HAL) HAL provides postability across platforms,
- KERNEL It is responsible for handling all second & emergand to brish
- EXECUTIVE It is weitten in c and includes 10 (3) components
- LINUX: OI+ 18 afree and open source of 2 @ 1+ Supports GUI
 - 3 It supports multiple languages
 - @ It supports multiple users, multithreading multitasking & networking as usals.
 - (3) It is postable and can be installed on any machine.

components of LINUX: programs and processes. @ System Libraries - Provided interaction with the bennel to 3 System utilities - These are the programs that carry out individual specialized management task TICK STORY OF THE PARTY OF THE PARTY OF THE SHEET STREET STREET han no of n Bi +THO: XSUMES

23	1000	[care / / / /
1		questions asked.
1	1	Define real time os. List any four applications of
	2	Enlist types of Os. Explain multiprogramming
	3.	List components of as. Explain process management in detail.
	O.	Diff: multiprogrammed and multitasking as any (2 points)
	8.	Explain Time sharing 03.
	6.	Describe any 2 components of O.S.
_	7.	etate & describe any two advantages of multipros
		Ssor system.
	8.	Describe working of Time shaving System with near diagram.
	9.	State ary two features of linear.
-	10.	Difference bokuson Time Sharing & Road Times system.
	tt.	Explain real time os. Explain with any two
1	10	applications of it.
1	100.	Describe multiprocessor os. writes ite
	13.	advantages.
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