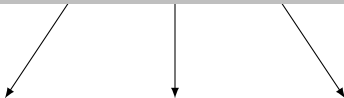


# 1. Prediction



$$\langle \mathcal{E}_{pk_0}(\omega) : \omega \in \{x_k^3, y_k^3, x_k^2 y_k, x_k y_k^2, x_k^2, y_k^2, x_k y_k, x_k, y_k\} \rangle$$



Sensor 1



Sensor  $n$