Thesis Publications

[1] M. Ristic, B. Noack, and U. D. Hanebeck, "Distributed Range-Only Localisation That Preserves Sensor and Navigator Privacies," *IEEE Transactions on Automatic Control (TAC)*, pp. 1–12, 2023.

[2] M. Ristic and B. Noack, "Privileged Estimate Fusion With Correlated Gaussian Keystreams," in *61st IEEE Conference on Decision and Control (CDC)*, 2022, pp. 7732–7739.

[3] M. Ristic and B. Noack, "Encrypted Fast Covariance Intersection Without Leaking Fusion Weights," in *IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI)*, 2022, pp. 1–6.

[4] M. Ristic, "Data Confidentiality for Distributed Sensor Fusion," 2022, presented at OVGU Doktorandentag.

[5] M. Ristic, B. Noack, and U. D. Hanebeck, "Cryptographically Privileged State Estimation With Gaussian Keystreams," *IEEE Control Systems Letters (L-CSS)*, vol. 6, pp. 602–607, 2022.

[6] M. Ristic, "Cryptographically Privileged State Estimation With Gaussian Keystreams," 2021, presented at Conference on Decision and Control (CDC).

[7] M. Ristic, B. Noack, and U. D. Hanebeck, "Secure Fast Covariance Intersection Using Partially Homomorphic and Order Revealing Encryption Schemes," *IEEE Control Systems Letters (L-CSS)*, vol. 5, no. 1, pp. 217–222, 2021.

[8] M. Ristic, "Secure Fast Covariance Intersection," 2020, presented at Conference on Decision and Control (CDC).