



CAN_Marathon_L.vi

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CAN_Marathon_L.vi

Last modified on 17.07.2025 at 13:47

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CAN_Marathon_L.vi

Файл настроек
C:\Program Files (x86)\CAN_Marathon\Test\data\Config.ini

Управление Индикация

Can-Карта
0

Can-канал
№ 1 0

Can-Baud
1M

Can-Flags
CAN 11&29 bit-ID

ACode-Фильтр
0032

AMask-Фильтр
00000000

Tx-Can
0

Rx-Can
0

Настройки
Применить

Настройки
сохранить

Ms_Can
0

Очередь Rx
49

id
046
data[0] 7F
data[1] E5
data[2] 10
data[3] 00
data[4] 00
data[5] 00
data[6] 0C
data[7] 86
len 8
flags 0000
ts 00000000

id
07A
data[0] 7F
data[1] E0
data[2] 04
data[3] 00
data[4] 80
data[5] 00
data[6] 3D
data[7] 00
len 8
flags FE00
ts 1F9141F3

flags: 0x00xx 0 - RTR, 1-SFF, 4-EFF

Зажиг.(Кл.15)
Вкл.

Упр. удал.
Вкл.

M min, [Нм]
-50

Град. M max, [Нм/с]
4000

M max, [Нм]
50

Порог управл. демпф. M, [Нм]
0,1

i - редуктора
9,78

Статус ключей инв.

1 - своб. вращение

Режим работы
1 - энергосбереж.

n, [об/мин]
-1

M, [Нм]
-1,0

Мдейст., [Нм]
12,5

Udc, [В]
0,0

Idc, [А]
-0,5

Is, [А]
0,0

Isd, [А]
0,0

Isq, [А]
0,0

Демпф. U
Демпф. внутр. и внеш.

Тормоза

TCS выкл.

Коробка скоростей
P - парковка

Режим управления
Выключить привод

Упр. токком
Вкл.

Isd, [А]
0,0

Isq, [А]
0,0

Демпф. вкл.

Т макс. IGBT, [°C]
0

IGBT темп. коэф. U
0

IGBT темп. коэф. V
0

IGBT темп. коэф. W
0

IGBT макс. темп. коэф.
0

Т охл. жид., [°C]
0

Т статора NTC1, [°C]
0

Т статора NTC2, [°C]
0

Т статора, [°C]
18

Темп. коэф. статора
0

Темп. мотора
0 - нормальная

Т макс. статора, [°C]
85

n max, [1/мин]
1000

CAN Errs Out

ewl
0

boff
0

hwovr
0

swovr
0

wtout
0

AMПЕРМАГНИТ

LabVIEW Ver. 1.2.0.0

NATIONAL INSTRUMENTS™
LabVIEW™ Evaluation Software

116 n, [об/мин][ns]**116** M, [Нм][Ms]**TF** CAN Stop[Stop]**U8** Can-Карта[Can-Board]
unsigned char



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	Can-Baud
	AMask-Фильтр[AMask]
	ACode-Фильтр[ACode]
	Can-Flags
	Tab Control
	angle_vs_speed[angle_vs_speed]
	spvm/sin_cos[spvm/sin_cos]
	speed/torque_mode[speed/torque_mode]
	mode_angle_pll[mode_angle_pll]
	mode_linear_angle[mode_linear_angle]
	mode_enable_Id[mode_enable_Id]
	mode_i/torque[mode_i/torque]
	mode_debug/car[mode_debug/car]
	fix/dif_pi_k_fapch[fix_dif_pi_k_fapch]
	use_piout/abs_udq[use_piout_abs_udq]
	ena_oscil[ena_oscil]
	ena_dt[ena_dt]
	mode_fix_angle[mode_fix_angle]
	mode_different_fase[mode_different_fase]
	mode_ignore_Uin[mode_ignore_Uin]
	diz_fil_f_w[diz_fil_f_w]
	Режим управления[MotorCtrl]
	bit38 ena_canlog[ena_canlog]
	ena_d_offset_i[ena_d_offset_i]
	fix/dif_pi_k_fapch[ena_fil_table_linear]
	one/two_time_pwm[one_two_time_pwm]
	ena_low_lim_Id[ena_low_lim_Id]
	ena_change_k_Id_lq[ena_change_k_Id_lq]
	ena_Id_peak_mode[ena_Id_peak_mode]
	fix/dif_pi_k_fw[fix_dif_pi_k_fw]
	ena_use_cpu2[ena_use_cpu2]
	ena_hard_reset[ena_hard_reset]
	ena_mtpa[ena_mtpa]
	torq_f_id_massive_mode[torq_f_id_massive_mode]
	auto/bike[auto_bike]
	1rev/2revs[1rev_2revs]





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 ena_nlpd[ena_nlpd]


 ena_pid_tuning_on_speed[ena_pid_tuning_on_speed]


 ena_canlog1[ena_canlog1]


 xx[xx]


 xx[xx 2]


 dis_res_ampl[dis_res_ampl]


 ena_high_speed_oscil[ena_high_speed_oscil]


 ena_4-channel_oscil[ena_4_channel_oscil]


 Зажиг.(Кл.15)[KI_15]


 Демпф. U[Dampf_U]


 Тормоз[Brake active]


 Коробка скоростей[GearCtrl]


 Clr_Reset[TCS active]


 M max, [Нм][M_max]


 M min, [Нм][M_min]


 Град. M max, [Нм/с][M_grad_max]


 Порог управл. демпф. M, [Нм][dM_damp_Ctrl]


 Tx-Can[Tx-Can]


 CAN


 id


 data[0]


 data[1]


 data[2]


 data[3]


 data[4]


 data[5]


 data[6]


 data[7]


 len


 flags


 ts

 Can-канал[Can-Ch]

 Статус ключей инв.[MCU_stGateDrv]

 i - редуктора[i_R]

 n max, [1/мин][n_max]

 Файл настроек [Cfg_file]







































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-  Настройки[Save_Cfg]
-  Настройки[Init]
-  Т макс. статора, [°C][T_Str_max]
-  Упр. удал.[En_rem]
-  n удал., [1/мин][ns_rem]
-  М удал., [Нм][Ms_rem]
-  Isd, [A][Is_sd]
-  Isq, [A][Is_sq]
-  Упр. током[En_Is]
-  USB-CAN интерфейс[CanBoard_Info]
-  Т IGBT-U, [°C][MCU_IGBTTempU]
-  Т IGBT-V, [°C][MCU_IGBTTempV]
-  Т IGBT-W, [°C][MCU_IGBTTempW]
-  Т макс. IGBT, [°C][MCU_IGBTTempMax]
-  IGBT темп. коэф. V[MCU_IGBTTempRiseV]
-  IGBT темп. коэф. W[MCU_IGBTTempRiseW]
-  IGBT макс. темп. коэф.[MCU_IGBTTempRiseMax]
-  IGBT темп. коэф. U[MCU_IGBTTempRiseU]
-  Темп. коэф. статора[MCU_TempRiseCurrStr]
-  Т статора, [°C][MCU_TempCurrStr]
-  Т статора NTC2, [°C][MCU_TempCurrStr2]
-  Т статора NTC1, [°C][MCU_TempCurrStr1]
-  Т охл. жид., [°C][MCU_TempCurrCool]
-  Мдейст., [Нм][M_act]
-  Isq, [A][Isq]
-  Isd, [A][Isd]
-  Idc, [A][Idc]
-  Темп. мотора[Темпер. мотора(статус)]
-  Режим работы[MCU-Status]
-  Разр. конденсаторов
-  Udc15, V
-  Udc мин.
-  Idc мин.
-  М мин.
-  Т статора макс.
-  Udc макс.



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	Idc макс.
	T-Motor over fault
	T-Motor over warn.
	Udc under alarm
	Udc over alarm
	Udc under fault
	I-phase over fault
	Состояние ошибок
	М макс.
	Udc valid
	T IGBT макс.
	T охл. жид. макс.
	n макс.
	М макс. зн. short int
	М мин. зн. short int
	T-Inverter over warn.
	Idc over fault
	Udc over fault
	n-Motor over fault
	MCU disconnected
	MCU serial port fault
	T-Inverter over fault
	n-Motor over warn.
	Idc over warn.
	U-CPLD over fault
	Gate-driver fault
	Ext. low voltage fault
	Int. power-chip fault
	CPLD serious failure
	Main chip - CPLD fault
	Loop interlock fault
	Udc-MCU fault
	T-Motor sensor fault
	I-Phase sensor fault
	MCU self-test fails



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**CAN bus off****Версия ПО ПЛК TC275 [MCU SW-ver]****Версия ПО калибр. ПЛК TC275 [MCU calib_SW-ver]****Версия ПО Hv MCU [MCU Hv SW-ver]****Версия ПО CPLD [MCU CPLD SW-ver]****Версия ПЛК [MCU HW-ver]****M, [Hм][M]****Udc, [B][Udc]****Is, [A][Is]****n, [об/мин][n]****M-статус[M_Status]****n-статус[n-Status]****Демпф. вкл.****Rx-Can[Rx-Can]****CAN****id****data[0]****data[1]****data[2]****data[3]****data[4]****data[5]****data[6]****data[7]****len****flags****ts****Tab Control 2[Tab_M_n]****App_Name****strVersion****Rx-error out[Rx-err out]**

error in can accept error information wired from VIs previously called. Use this information to decide if any functionality should be bypassed in the event of errors from other VIs.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.



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**status**

status is TRUE (X) if an error occurred or FALSE (checkmark) to indicate a warning or that no error occurred.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.

**code**

code is the error or warning code.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.

**source**

source describes the origin of the error or warning.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.

**CAN Errs Out****ewl****boff****hwovr****swovr****wtout****Pe dc, [Bτ][Pe dc]****Ms_Can****Очередь Rx**

short int

**Tx-error out[Tx-err out]**

error in can accept error information wired from VIs previously called. Use this information to decide if any functionality should be bypassed in the event of errors from other VIs.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.

**status**

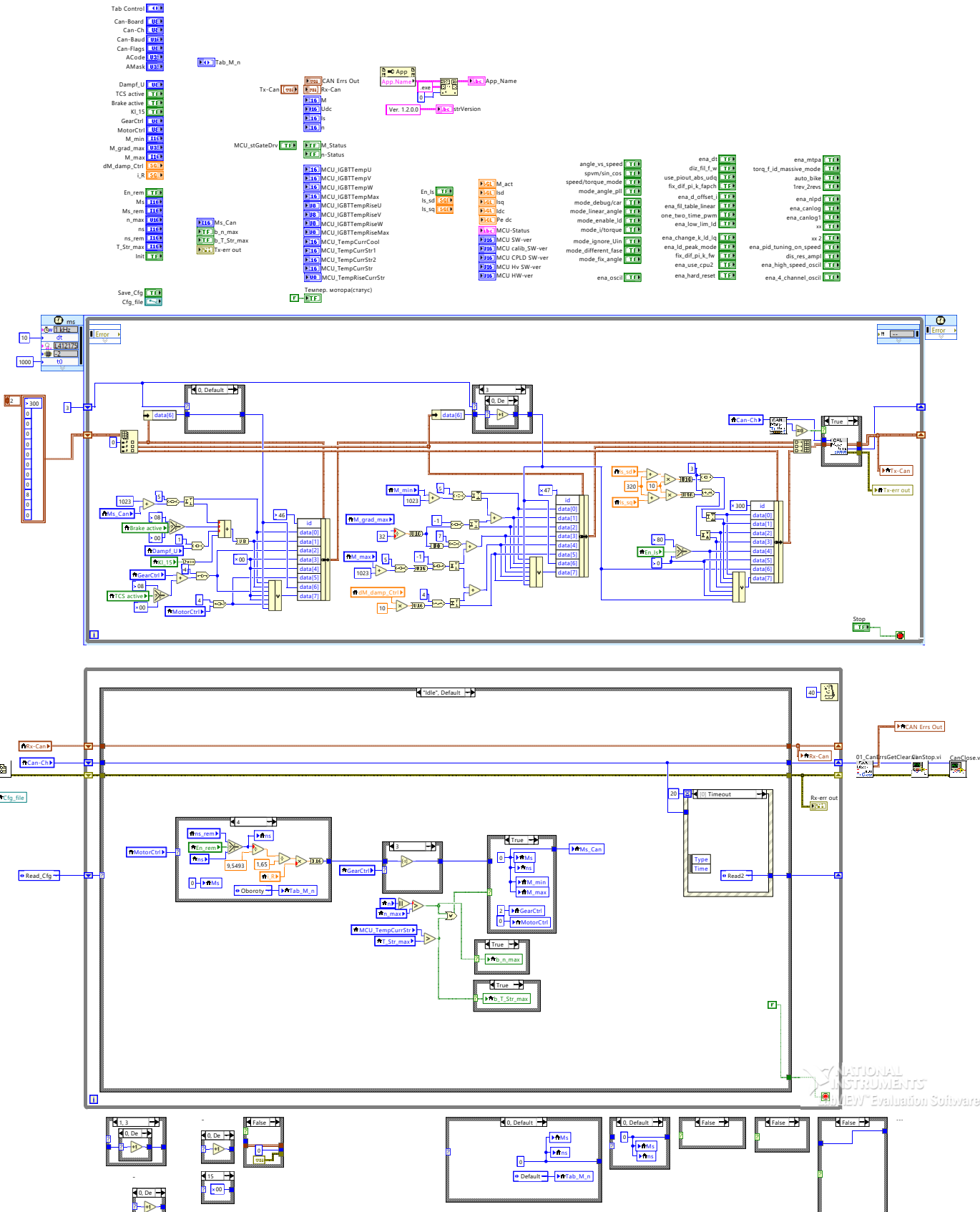
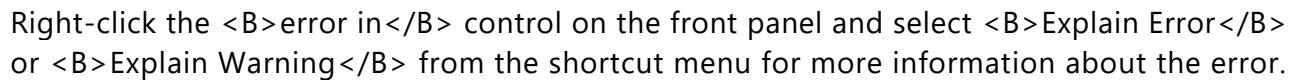
status is TRUE (X) if an error occurred or FALSE (checkmark) to indicate a warning or that no error occurred.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.

**code**

code is the error or warning code.

Right-click the error in control on the front panel and select Explain Error or Explain Warning from the shortcut menu for more information about the error.



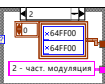
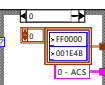
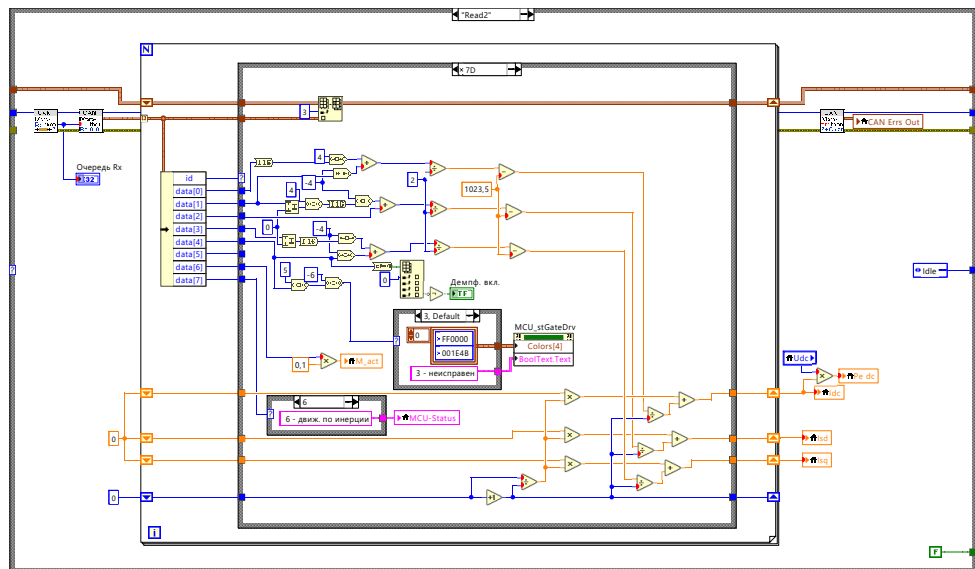
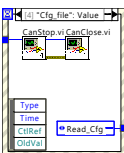
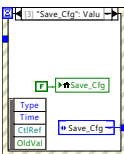
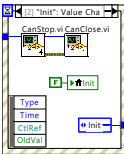
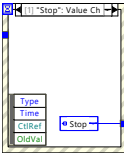
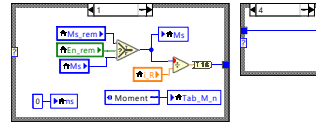


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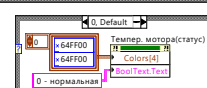
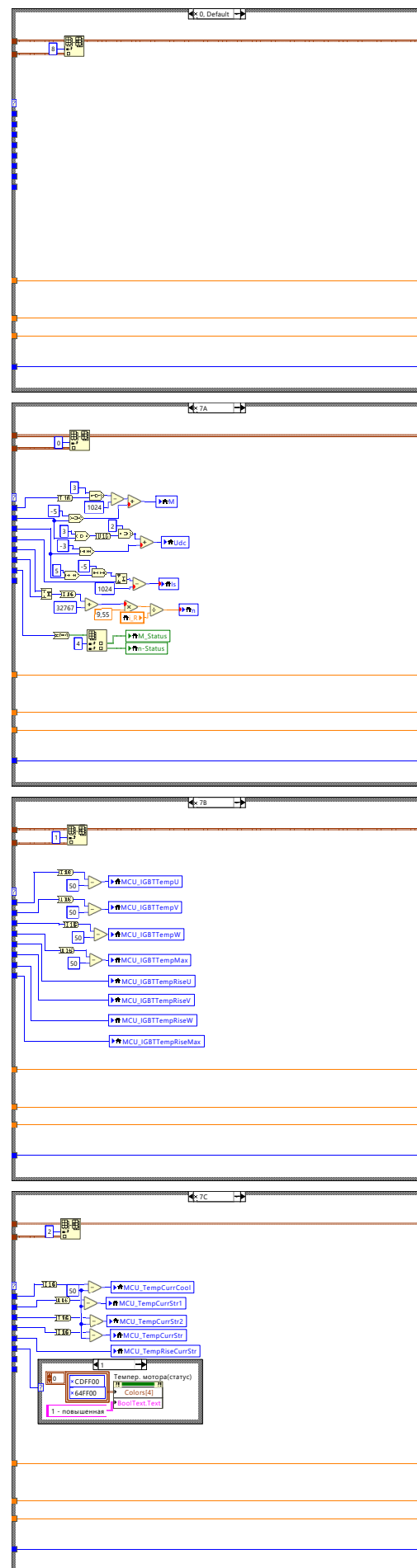


CAN_Marathon_L.vi

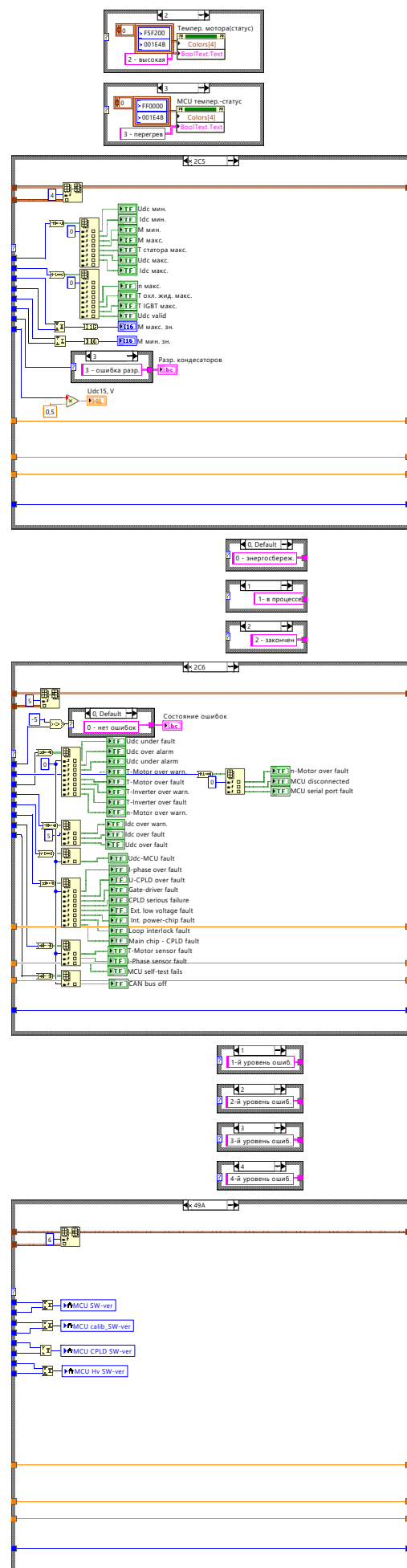
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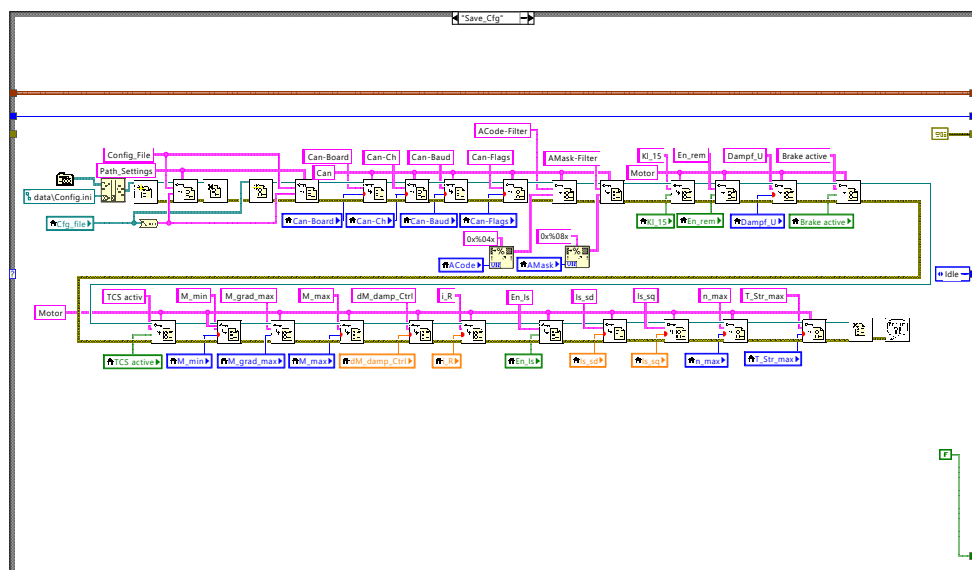
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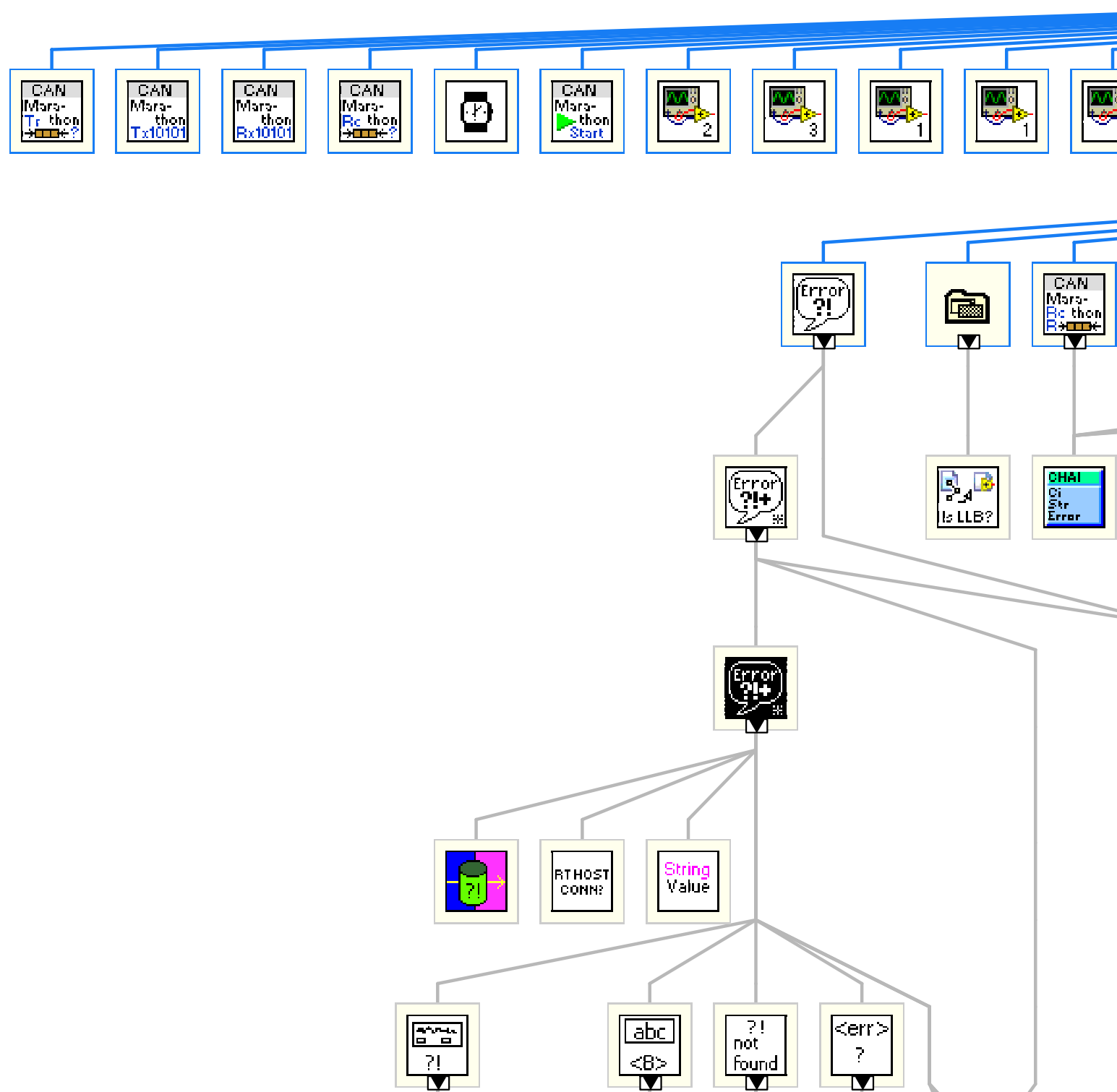


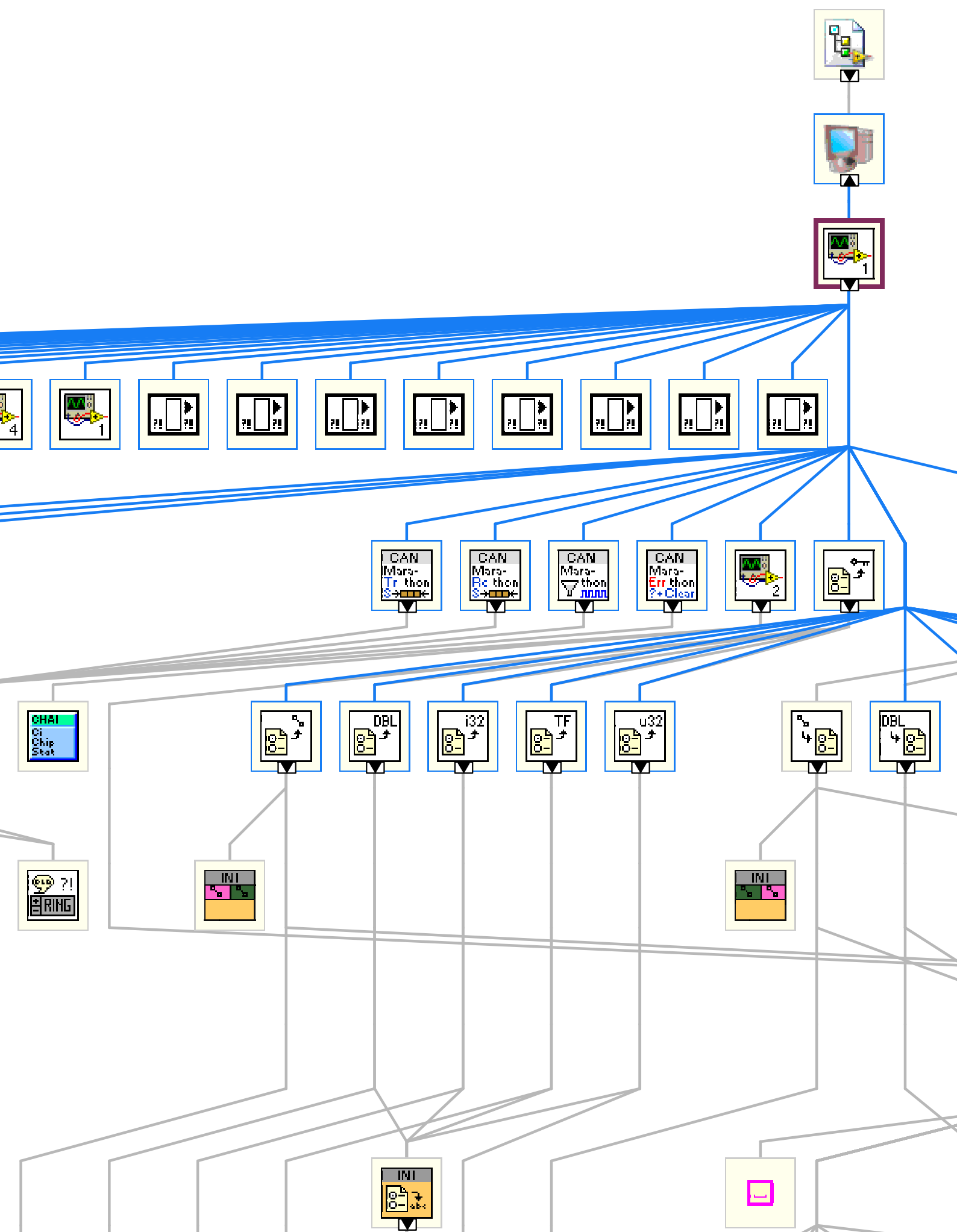
CAN_Marathon_L.vi

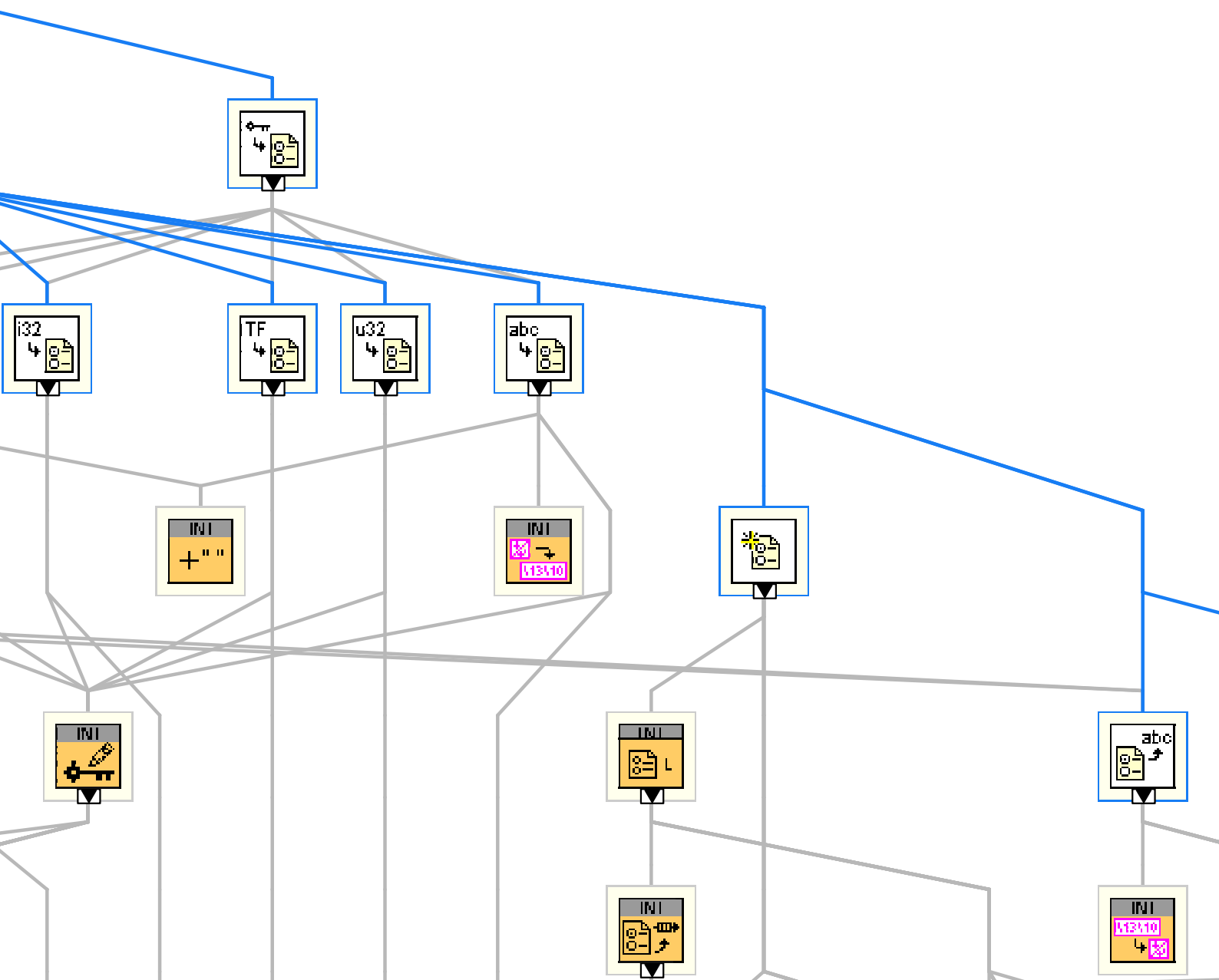
C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CAN_Marathon_L.vi

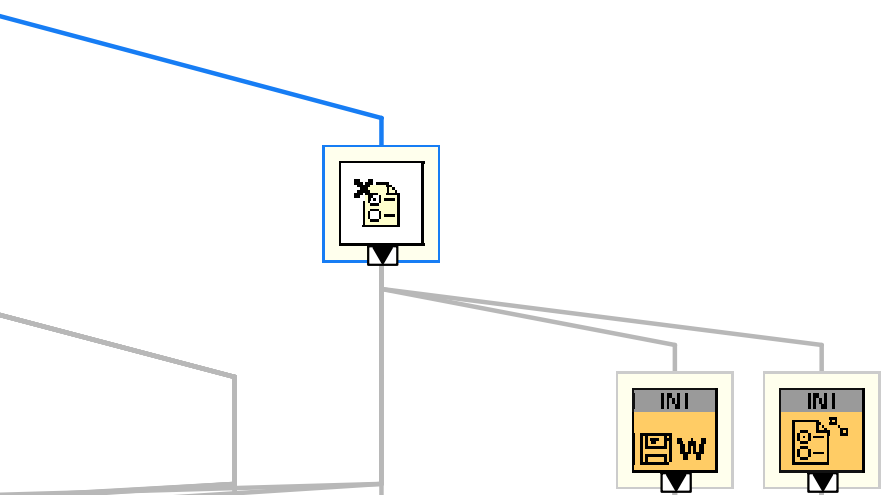
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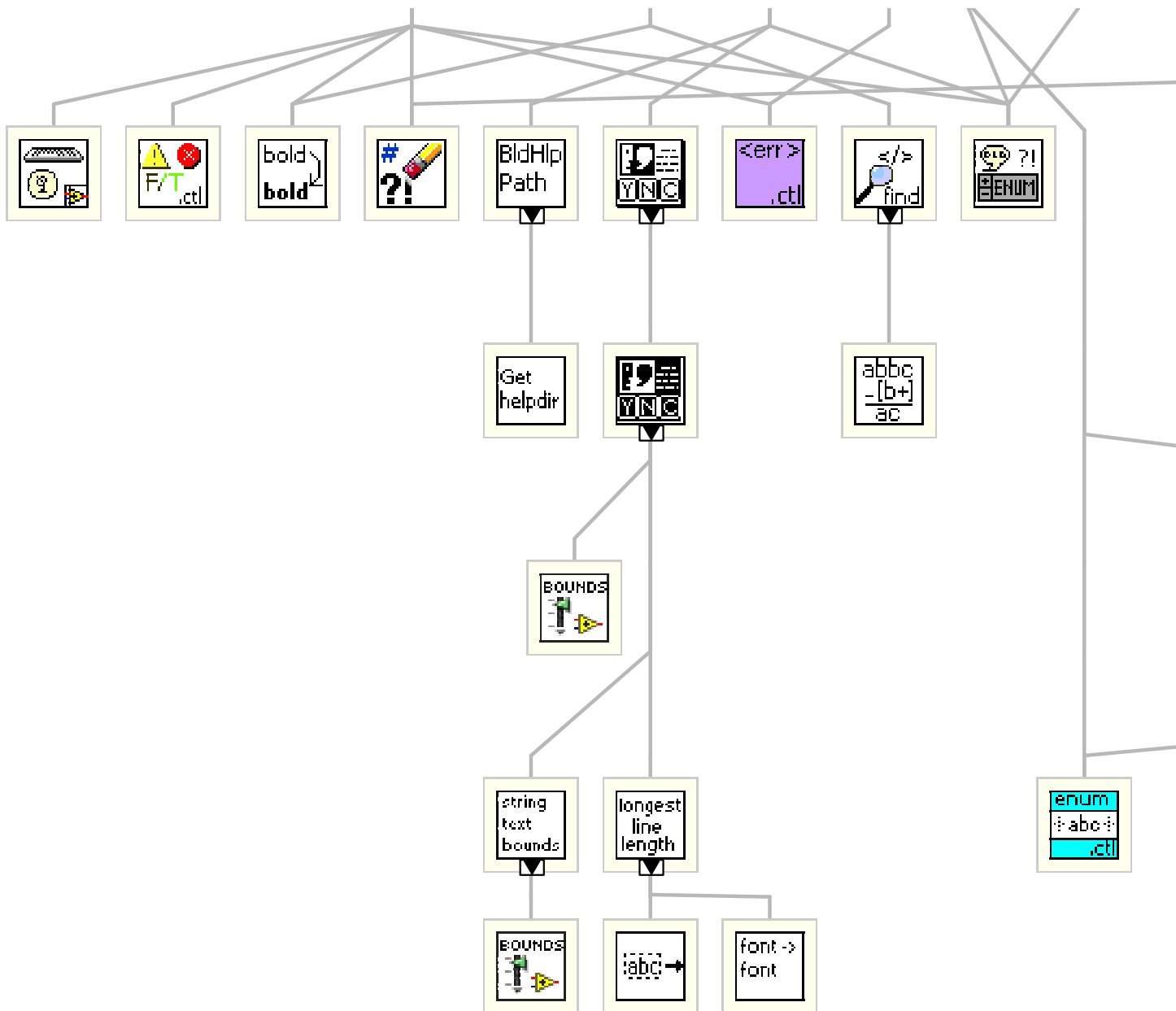


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**CanClose.vi**

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**CanStop.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanStop.vi

**NI_LVConfig.lvlib:Write Key (String).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key (String).vi

**05_CanStatus.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\0_CAN_Marathon\05_CanStatus.vi

**NI_LVConfig.lvlib:Close Config Data.vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Close Config Data.vi

**NI_LVConfig.lvlib:Write Key (I32).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key (I32).vi

**NI_LVConfig.lvlib:Write Key.vi**

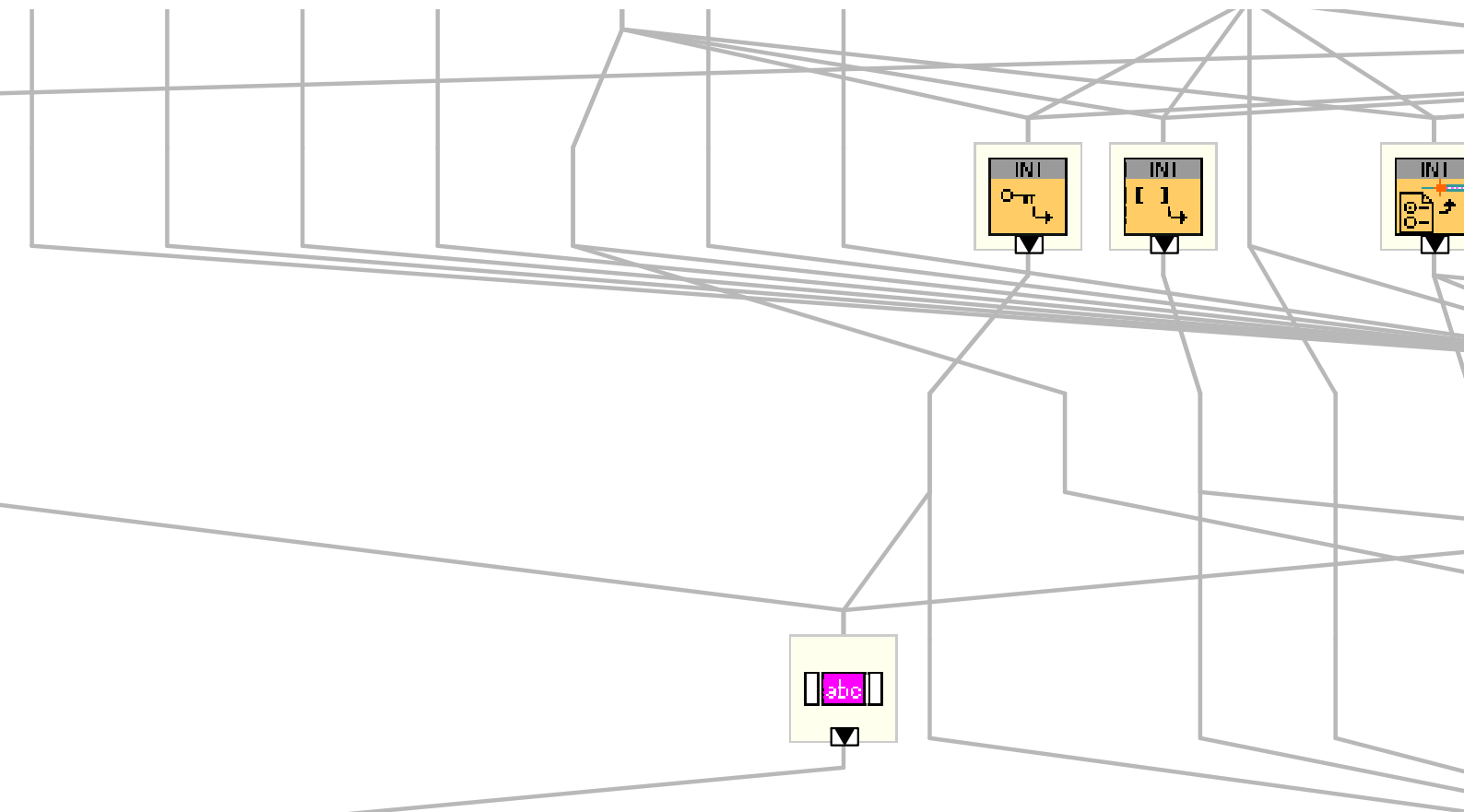
C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key.vi

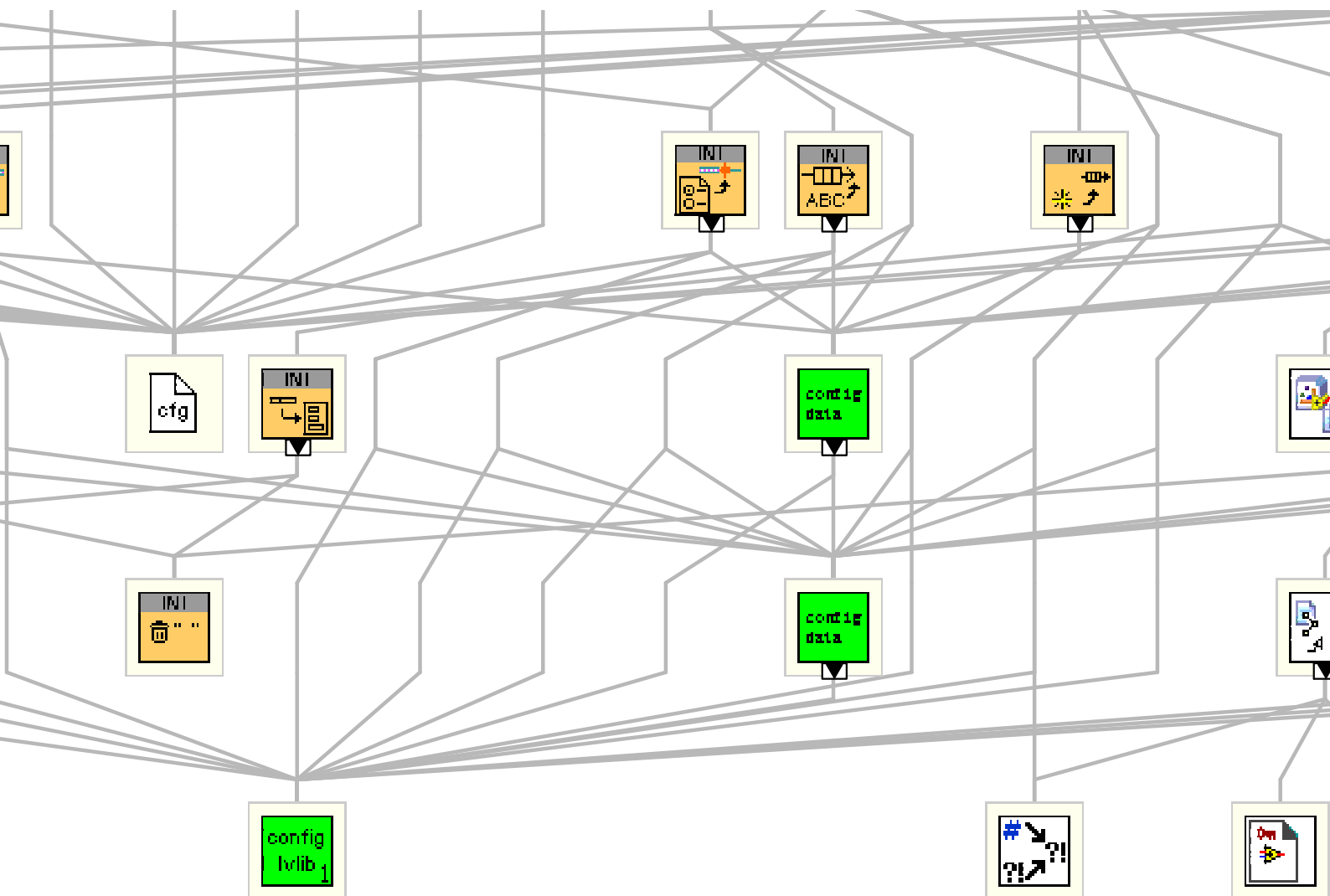
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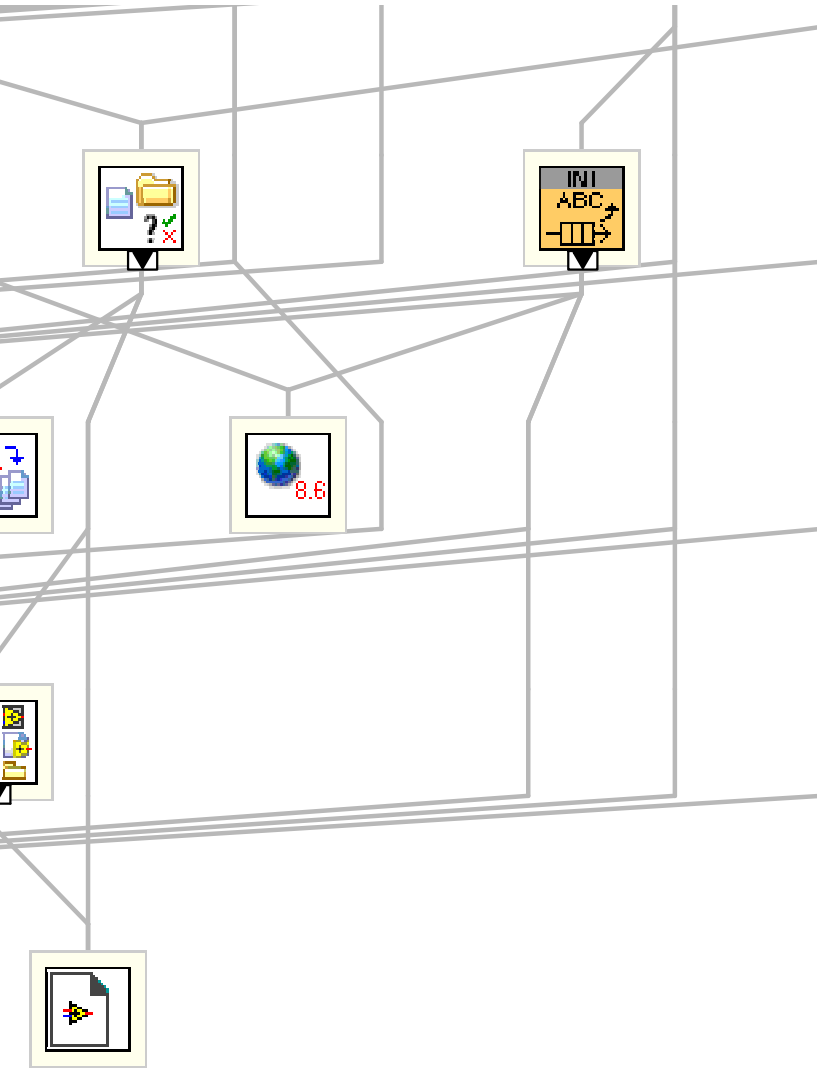


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**CanInit.vi**

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**CanBoard_Info.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanBoard_Info.vi

**CanSetFilter.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanSetFilter.vi

**NI_LVConfig.lvlib:Read Key (I32).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (I32).vi

**NI_LVConfig.lvlib:Read Key (U32).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (U32).vi

**NI_LVConfig.lvlib:Read Key.vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key.vi

**NI_LVConfig.lvlib:Read Key (Boolean).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (Boolean).vi

**NI_LVConfig.lvlib:Open Config Data.vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Open Config Data.vi

**Simple Error Handler.vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\error.llb\Simple Error Handler.vi

**Application Directory.vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\file.llb\Application Directory.vi

**01_CanErrsGetClear.vi**C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\0_CAN_Marathon\
01_CanErrsGetClear.vi**CanSetBaud.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanSetBaud.vi

**CanStart.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanStart.vi

**CanOpen.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanOpen.vi

**NI_LVConfig.lvlib:Write Key (U32).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key (U32).vi

**NI_LVConfig.lvlib:Write Key (Boolean).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key (Boolean).vi

**NI_LVConfig.lvlib:Write Key (Double).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Write Key (Double).vi

**07_CanTrStat.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\0_CAN_Marathon\07_CanTrStat.vi

**NI_LVConfig.lvlib:Read Key (String).vi**

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (String).vi

**CanTrQueThreshold.vi**

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanTrQueThreshold.vi



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04_CanRead_Cnt.vi

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\0_CAN_Marathon\04_CanRead_Cnt.vi



CanRcQueThreshold.vi

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanRcQueThreshold.vi



CanRcQueGetCnt.vi

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\CanRcQueGetCnt.vi



NI_LVConfig.lvlib:Read Key (Path).vi

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (Path).vi



03_CanRcQueResize.vi

C:\Users\s.makov\Downloads\CAN_Marathon\CAN_Marathon\0_CAN_Marathon\
03_CanRcQueResize.vi



06_CanTransmit_Cnt.vi

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06_CanTransmit_Cnt.vi



NI_LVConfig.lvlib:Read Key (Double).vi

C:\Program Files\National Instruments\LabVIEW 2020\vi.lib\Utility\config.llb\Read Key (Double).vi



Wait.vi

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"CAN_Marathon_L.vi History"

Current Revision: 1268

