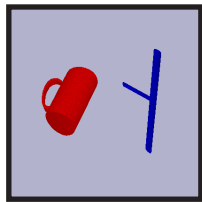
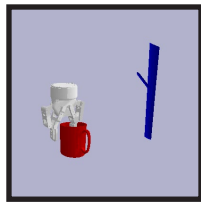


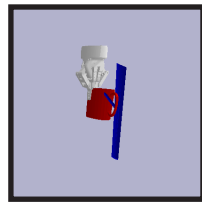
warping model



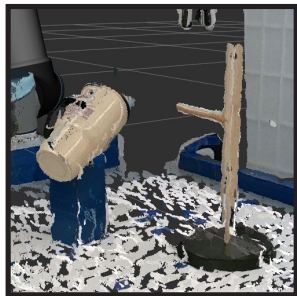
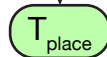
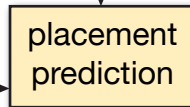
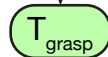
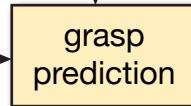
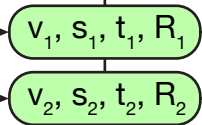
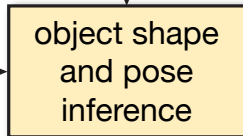
inferred scene



grasp demo



placement demo



observed point cloud