GANs in action

ProGAN

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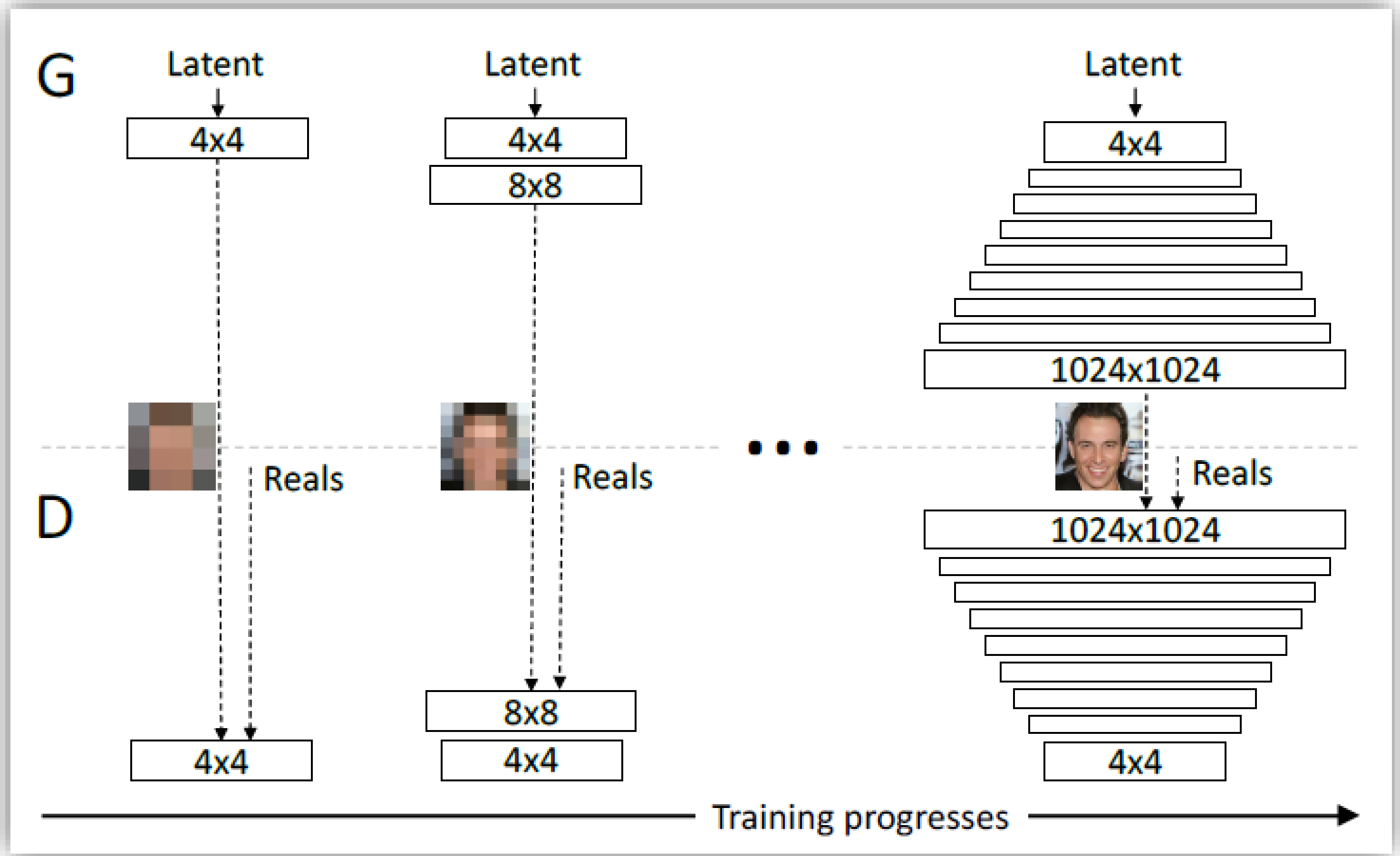
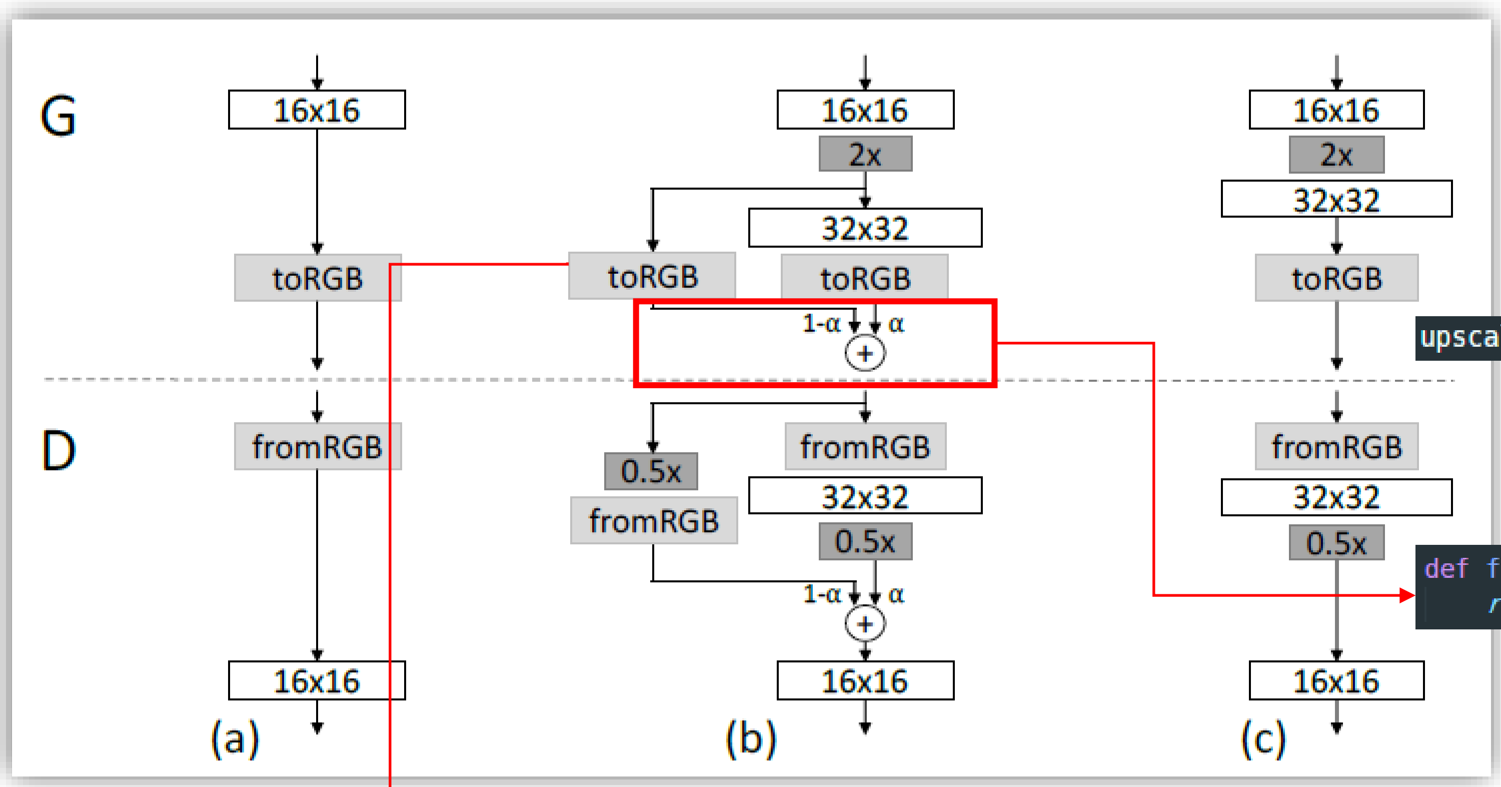
Contents

Progressive structure



Progressive structure

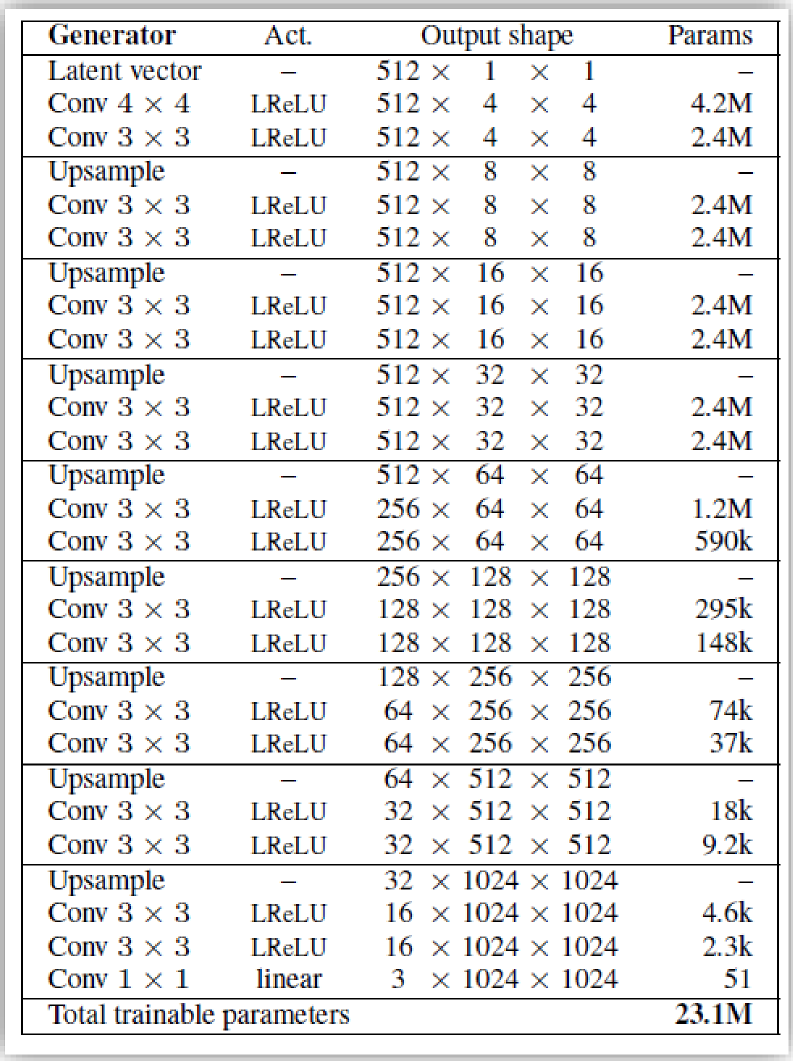


```
upscaled = nn.Upsample(scale_factor=2, mode='nearest')(out)
```

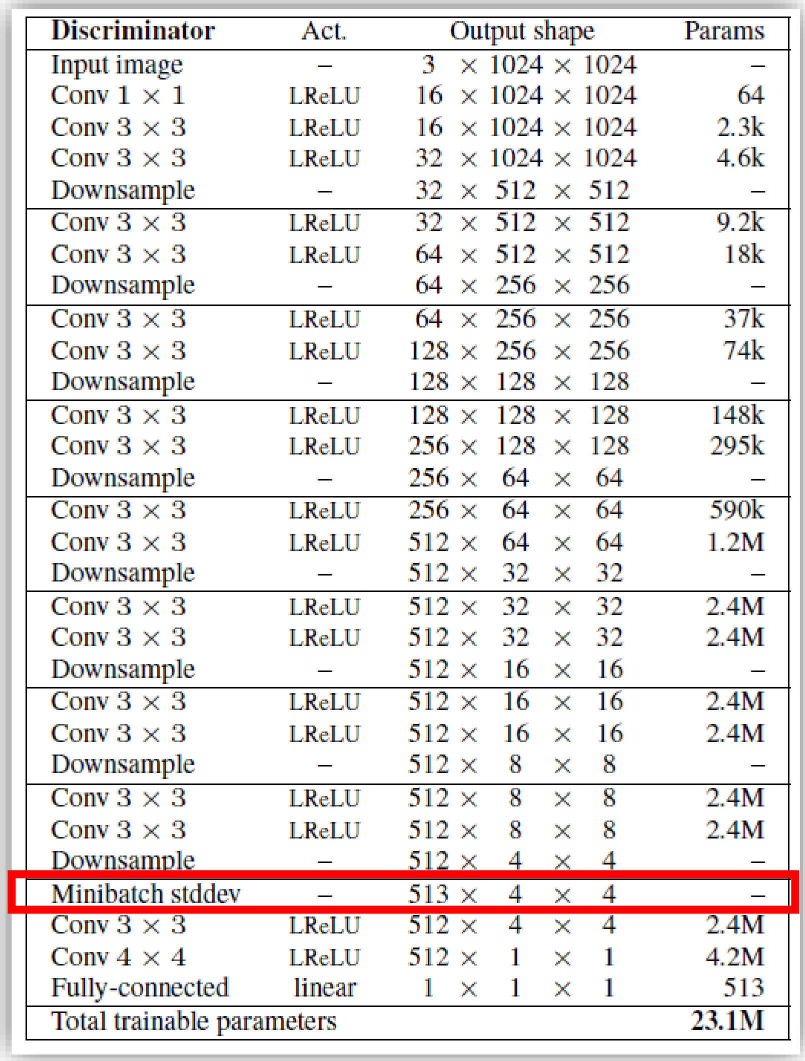
```
def fade_in(self, alpha, upscaled, generated):
    return torch.tanh(alpha*generated + (1 - alpha)*upscaled)
```

```
self.to_rgb = WeightScaledConv2d(in_channels, img_channels, kernel_size=1, stride=1, padding=0)
```

Progressive structure

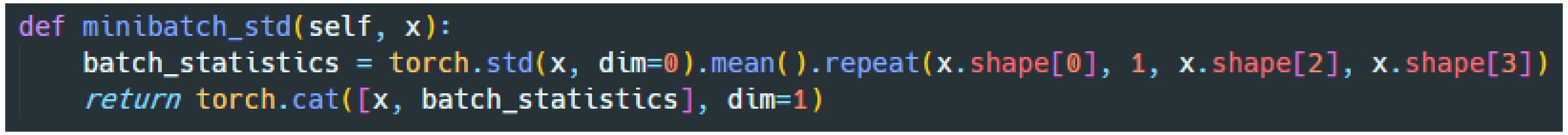


Generator	Act.	Output shape	Params
Latent vector	–	512 × 1 × 1	–
Conv 4 × 4	LReLU	512 × 4 × 4	4.2M
Conv 3 × 3	LReLU	512 × 4 × 4	2.4M
Upsample	–	512 × 8 × 8	–
Conv 3 × 3	LReLU	512 × 8 × 8	2.4M
Conv 3 × 3	LReLU	512 × 8 × 8	2.4M
Upsample	–	512 × 16 × 16	–
Conv 3 × 3	LReLU	512 × 16 × 16	2.4M
Conv 3 × 3	LReLU	512 × 16 × 16	2.4M
Upsample	–	512 × 32 × 32	–
Conv 3 × 3	LReLU	512 × 32 × 32	2.4M
Conv 3 × 3	LReLU	512 × 32 × 32	2.4M
Upsample	–	512 × 64 × 64	–
Conv 3 × 3	LReLU	256 × 64 × 64	1.2M
Conv 3 × 3	LReLU	256 × 64 × 64	590k
Upsample	–	256 × 128 × 128	–
Conv 3 × 3	LReLU	128 × 128 × 128	295k
Conv 3 × 3	LReLU	128 × 128 × 128	148k
Upsample	–	128 × 256 × 256	–
Conv 3 × 3	LReLU	64 × 256 × 256	74k
Conv 3 × 3	LReLU	64 × 256 × 256	37k
Upsample	–	64 × 512 × 512	–
Conv 3 × 3	LReLU	32 × 512 × 512	18k
Conv 3 × 3	LReLU	32 × 512 × 512	9.2k
Upsample	–	32 × 1024 × 1024	–
Conv 3 × 3	LReLU	16 × 1024 × 1024	4.6k
Conv 3 × 3	LReLU	16 × 1024 × 1024	2.3k
Conv 1 × 1	linear	3 × 1024 × 1024	51
Total trainable parameters			23.1M



Discriminator	Act.	Output shape	Params
Input image	–	3 × 1024 × 1024	–
Conv 1 × 1	LReLU	16 × 1024 × 1024	64
Conv 3 × 3	LReLU	16 × 1024 × 1024	2.3k
Conv 3 × 3	LReLU	32 × 1024 × 1024	4.6k
Downsample	–	32 × 512 × 512	–
Conv 3 × 3	LReLU	32 × 512 × 512	9.2k
Conv 3 × 3	LReLU	64 × 512 × 512	18k
Downsample	–	64 × 256 × 256	–
Conv 3 × 3	LReLU	64 × 256 × 256	37k
Conv 3 × 3	LReLU	128 × 256 × 256	74k
Downsample	–	128 × 128 × 128	–
Conv 3 × 3	LReLU	128 × 128 × 128	148k
Conv 3 × 3	LReLU	256 × 128 × 128	295k
Downsample	–	256 × 64 × 64	–
Conv 3 × 3	LReLU	256 × 64 × 64	590k
Conv 3 × 3	LReLU	512 × 64 × 64	1.2M
Downsample	–	512 × 32 × 32	–
Conv 3 × 3	LReLU	512 × 32 × 32	2.4M
Conv 3 × 3	LReLU	512 × 32 × 32	2.4M
Downsample	–	512 × 16 × 16	–
Conv 3 × 3	LReLU	512 × 16 × 16	2.4M
Conv 3 × 3	LReLU	512 × 16 × 16	2.4M
Downsample	–	512 × 8 × 8	–
Conv 3 × 3	LReLU	512 × 8 × 8	2.4M
Conv 3 × 3	LReLU	512 × 8 × 8	2.4M
Downsample	–	512 × 4 × 4	–
Minibatch stddev	–	513 × 4 × 4	–
Conv 3 × 3	LReLU	512 × 4 × 4	2.4M
Conv 4 × 4	LReLU	512 × 1 × 1	4.2M
Fully-connected	linear	1 × 1 × 1	513
Total trainable parameters			23.1M

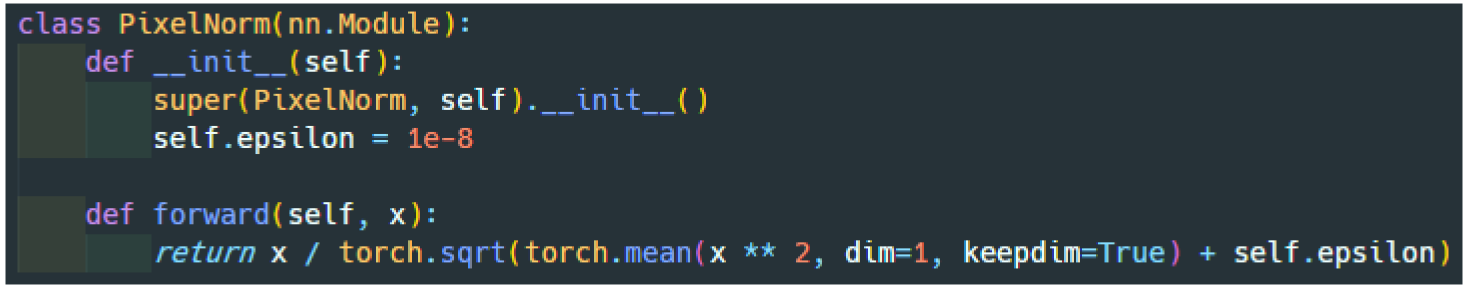
Minibatch Stddev



```python
def minibatch_std(self, x):
    batch_statistics = torch.std(x, dim=0).mean().repeat(x.shape[0], 1, x.shape[2], x.shape[3])
    return torch.cat([x, batch_statistics], dim=1)
```

Pixel Normalization

$$b_{x,y} = a_{x,y} / \sqrt{\frac{1}{N}\sum_{j=0}^{N-1}(a_{x,y}^{j})^2 + \epsilon}, \text{where } \epsilon = 10^{-8}$$



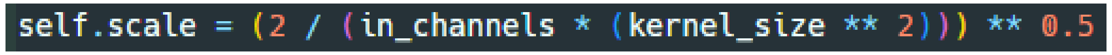
```python
class PixelNorm(nn.Module):
    def __init__(self):
        super(PixelNorm, self).__init__()
        self.epsilon = 1e-8

    def forward(self, x):
        return x / torch.sqrt(torch.mean(x ** 2, dim=1, keepdim=True) + self.epsilon)
```

Equalized Learning Rate

$$W \sim N(0, Var(W))$$

$$Var(W) = \sqrt{\frac{2}{n_{in}}} \longrightarrow \sqrt{\frac{2}{k \, * \, k \, * \, n_{in}}}$$



```python
self.scale = (2 / (in_channels * (kernel_size ** 2))) ** 0.5
```

ProGAN