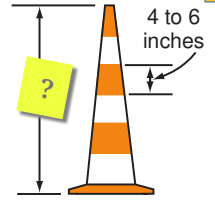
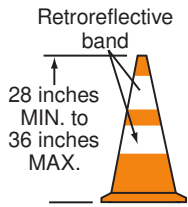
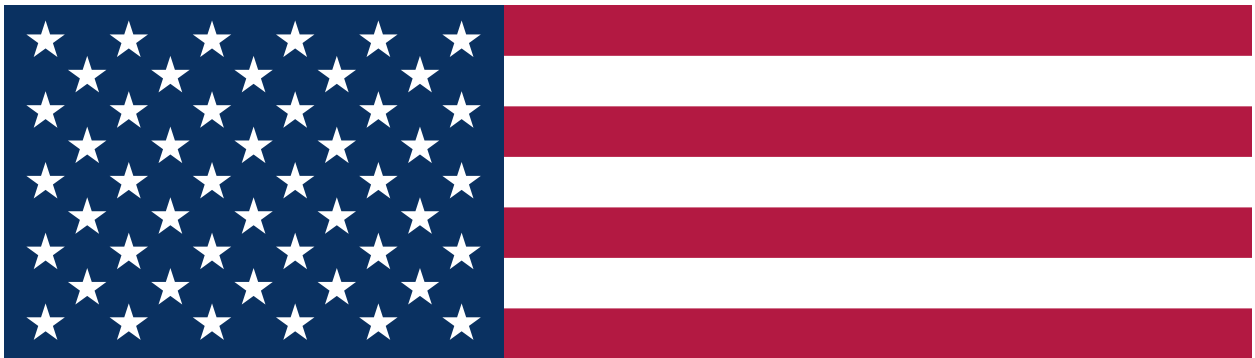


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the result of post-composing $\varphi\Theta$
with the “poly-action”

Chapter 1 - A Tutorial Introduction

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This approach and its drawbacks. Most notable is that the complete story on any particular feature is not found here, and the tutorial, by being brief, may also be misleading. And because the examples do not use the full power of C, they are not as concise and elegant as they might be. We have tried to minimize these effects, but be warned. Another drawback is that later chapters will necessarily repeat some of this chapter. We hope that the repetition will help you more than it annoys.

In any case, experienced programmers should be able to extrapolate from the material in this chapter to their own programming needs. Beginners should supplement it by writing small, similar programs of their own. Both groups can use it as a framework on which to hang the more detailed descriptions that begin in [Chapter 2](#).

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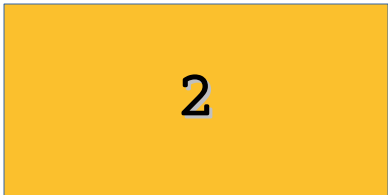
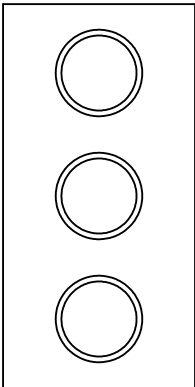
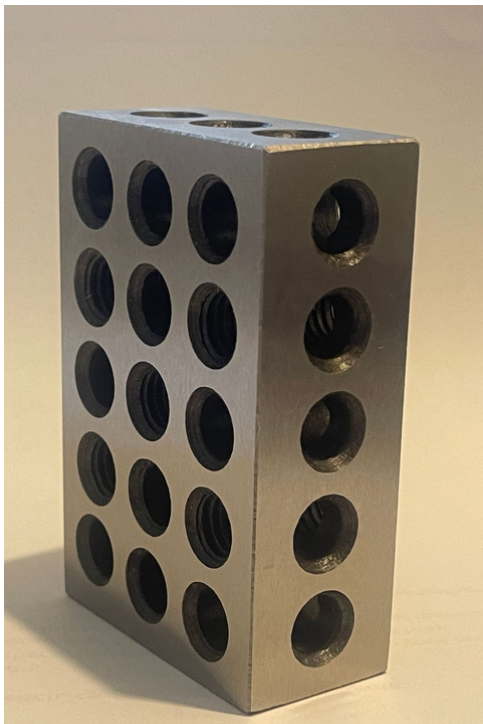
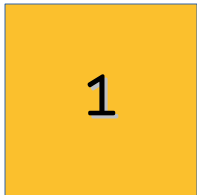
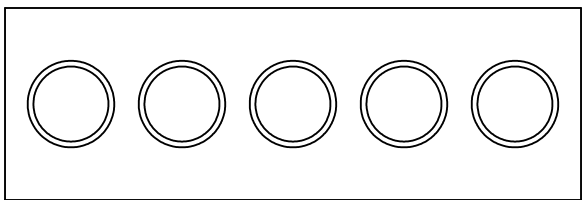
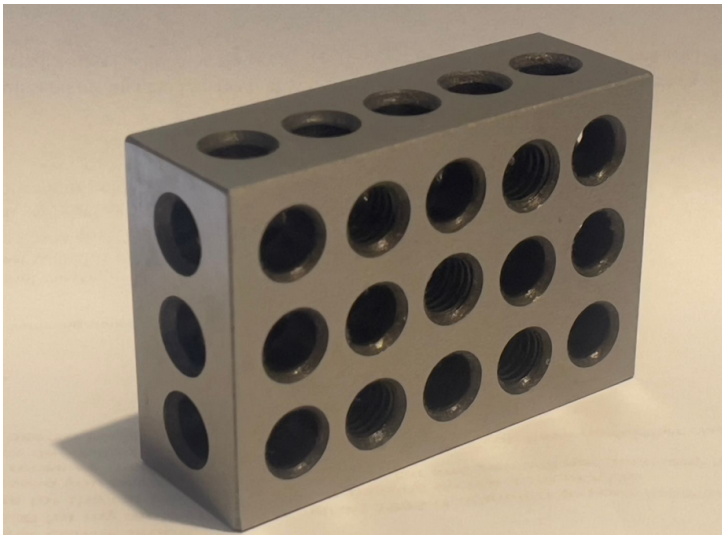
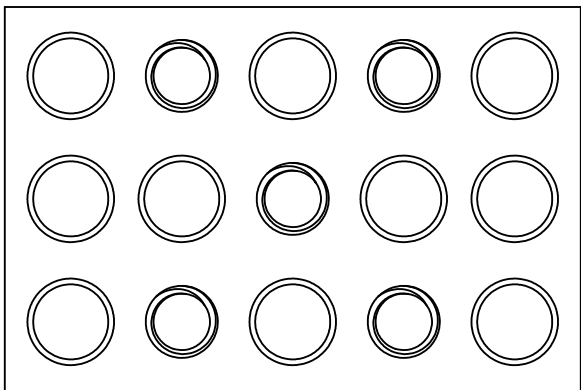


Figure 6H-6. Shoulder Work with Minor Encroachment (TA-6)

