### Math 221 Lec 11

#### 2.4: Elementary matrices, 2.5: Transpose

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#### 1 Transpose

**Remark.** The transpose of a matrix A is the matrix  $A^{\mathsf{T}}$  where  $(A^{\mathsf{T}})_{ij} = A_{ji}$ . Entries are reflected over the diagonal **Remark.** If  $x, y \in \mathbb{R}^n$ , we can think of their dot dot product  $\mathbf{x} \cdot \mathbf{y}$  as

$$\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^\intercal \mathbf{y}$$

**Remark.** Note then that  $\mathbf{a}^{\intercal}\mathbf{a} = \mathbf{a} \cdot \mathbf{a} = \|\mathbf{a}\|^2$ 

**Remark.**  $\mathbf{x} \cdot \mathbf{y}$  produces a scalar, so  $\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^{\mathsf{T}} \mathbf{y}$  or  $\mathbf{y}^{\mathsf{T}} \mathbf{x}$  (both of which are  $1 \times 1$  matrices), but  $\mathbf{x} \cdot \mathbf{y} \neq \mathbf{y} \mathbf{x}^{\mathsf{T}}$  or  $\mathbf{x} \mathbf{y}^{\mathsf{T}}$ , both of which would be  $n \times n$  matrices.

**Remark.** The linear transformation represented by the  $n \times n$  matrix  $\mathbf{a}\mathbf{a}^{\intercal}$  is  $\operatorname{proj}_{\mathbf{a}}\mathbf{x}$ . By expressing the projection formula in terms of  $\mathbf{a}$  and  $\mathbf{a}^{\intercal}$ , we can clearly show that it is a function in terms of  $\mathbf{a}$ .

Proof.

$$\begin{aligned} \operatorname{proj}_{\mathbf{a}}\mathbf{x} &= \frac{\mathbf{x} \cdot \mathbf{a}}{\|\mathbf{a}\|^2} \mathbf{a} \\ &= \frac{\mathbf{a}^T \mathbf{x}}{\|\mathbf{a}\|^2} \mathbf{a} \\ &= \mathbf{a} \frac{\mathbf{a}^T \mathbf{x}}{\|\mathbf{a}\|^2} \end{aligned} \qquad \text{(express dot product as matrix mult, per second remark above)} \\ &= \mathbf{a} \frac{\mathbf{a}^T \mathbf{x}}{\|\mathbf{a}\|^2} \qquad \text{(can move since one of the terms above is a scalar)} \\ &= \frac{\mathbf{a} \mathbf{a}^T \mathbf{x}}{\mathbf{a} \cdot \mathbf{a}} \\ &= \left(\frac{\mathbf{a} \mathbf{a}^T}{\mathbf{a}^T \mathbf{a}}\right) \mathbf{x} \qquad \text{(again, express dot product as matrix mult)} \end{aligned}$$

**Example** (projection expressed with transposes).

$$\operatorname{proj}_{\begin{bmatrix}1\\1\\1\end{bmatrix}} = \frac{\begin{bmatrix}1\\1\\1\end{bmatrix}\begin{bmatrix}1&1&1\end{bmatrix}}{\begin{bmatrix}1\\1\\1\end{bmatrix}\begin{bmatrix}1\\1\\1\end{bmatrix}} = \frac{1}{\begin{bmatrix}1\\1\\1\end{bmatrix}\begin{bmatrix}1\\1\\1\end{bmatrix}}$$
 denom is  $1 \times n$  times  $n \times 1$ , aka dot prod 
$$= \frac{1}{3}\begin{bmatrix}1&1&1\\1&1&1\\1&1&1\end{bmatrix}$$

**Definition 1** (orthogonal matrix). An  $n \times n$  matrix A is orthogonal if  $A^{\mathsf{T}}A = I_n$ , which is true iff  $\mathbf{a}_i \cdot \mathbf{a}_j = 0$  for  $i \neq j$  and 1 for i = j.

# 2 Left multiplication (row vector \* matrix)

**Remark.** Let A be an  $n \times m$  matrix. Let  $\mathbf{x}$  be a vector of length n. The operation in which a row vector is multiplied by a matrix can be expressed as  $\mathbf{x}^{\mathsf{T}} \mathbf{A}$ .

**Proposition 2.**  $A\mathbf{x} \cdot \mathbf{y} = \mathbf{x} \cdot \mathbf{A}^{\mathsf{T}} \cdot \mathbf{y}$  (To move the matrix across a dot product operator, we must transpose it)

Proof.

$$(A\mathbf{x}) \cdot \mathbf{y} = (A\mathbf{x})^{\mathsf{T}} \mathbf{y}$$
$$= \mathbf{x}^{\mathsf{T}} A^{\mathsf{T}} \mathbf{y}$$
$$= \mathbf{x}^{\mathsf{T}} (A^{\mathsf{T}} \mathbf{y})$$
$$= \mathbf{x} \cdot A^{\mathsf{T}} \mathbf{y}$$

dot product as matrix mult

## 3 Elementary matrices

**Proposition 3.** Every invertible matrix can be expressed as a product of elementary matrices.

Proof. Since A is invertible, we can row reduce it to the identity matrix. We do this by multiplying A on the left by a series of elementary matrices  $E = (E_k)(\ldots)(E_2)(E_1)$  such that EA = I. Elementary matrices are invertible, so we can multiply both sides of that equation by  $E^{-1}$ . Then  $A = E^{-1} = (E_1^{-1})(E_2^{-1})(\ldots)(E_k^{-1})$ .

**Remark.** When we apply elementary operations to the rows of a matrix A, we multiply A on the left by an elementary matrix E, such that we get a transformed version of the rows of A.

$$EA = \begin{bmatrix} -E_1A & -\\ -E_2A & -\\ \vdots \\ -E_mA & - \end{bmatrix}$$

**Remark.** We construct a row swap elementary matrix E by taking  $I_m$  and interchanging rows i and j to swap  $A_i$  and  $A_j$ . A row of E,  $E_k$ , looks like

$$\begin{cases} e_k^{\mathsf{T}}, & \text{if } k \neq i \text{ or } j \\ e_j^{\mathsf{T}}, & \text{if } k = i \\ e_i^{\mathsf{T}}, & \text{if } k = j \end{cases}$$

where  $e_i$  is the *i*-th basis vector and  $e_i^{\mathsf{T}}$  is the *i*-th basis row vector. Thus,

$$E_k A = \begin{cases} A_k, & \text{if } k \neq i \text{ or } j \\ A_j, & \text{if } k = i \\ A_i, & \text{if } k = j \end{cases}$$