

# Math 221 Lec 9 (2.3: Inverse Matrices)

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## 1 Inverse matrices

**Remark.** If a matrix  $A$  is invertible, we can find  $A^{-1}$  by performing Gaussian elimination on the augmented matrix  $[A|I]$ . This augmented matrix represents multiple sets of simultaneous equations, wherein we solve for multiple  $\mathbf{x}$  vectors, s.t.  $A\mathbf{x}_1 = i_1$  (the first column of  $I$ ),  $A\mathbf{x}_2 = i_2 \dots$

**Example.** Find the inverse of  $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ .

Fill out...

**Proposition 1.** Nonsingular matrices are invertible.

Why do singular matrices not have inverses?

*Proof.* Assume  $A$  is a singular matrix. Then  $A\mathbf{x} = \mathbf{0}$  has a nontrivial (non-zero) solution. But if  $A^{-1}$  existed,  $A^{-1}A\mathbf{x} = A^{-1}\mathbf{0}$ , which means  $\mathbf{x} = \mathbf{0}$ . This is a contradiction!  $\square$

*Proof.* Alternatively, given singular matrix  $A$ , try solving the multiple systems of equations represented by  $AB = I$ , where  $B$  is the hypothetical  $A^{-1}$ .  $A$  will row reduce to a matrix with a row of zeros in the bottom, which cannot possibly equal the bottom row of  $I$ .  $\square$

## 2 Determinants

**Definition 2** (determinant). The **determinant** of a linear transformation tells us how much a unit of area changes after the transformation is applied.

### 2.1 Geometric interpretation of the determinant

**Example** (geometric interp of determinant in 2 dimensions). If we apply the linear transformation represented by  $A = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$ ,  $\hat{i}$  is stretched by 3 and  $\hat{j}$  is stretched by 2. The area covered by  $[\hat{i} \ \hat{j}]$  thus increases from  $1 * 1 = 1$  to  $2 * 3 = 6$ , so the determinant of the transformation is 6.

**Remark.** In two-dimensional space, a matrix with  $\det(A) = 0$  represents a linear transformation that reduces the **area** of a unit square to 0, collapsing space onto a line (or point).

**Remark.** In three-dimensional space, a matrix with  $\det(A) = 0$  represents a linear transformation that reduces the **volume** of a unit cube to 0, collapsing space onto a plane, line, or point.

**Remark.** The **sign of a determinant** tells us whether the orientation of space has changed. For example, in two-dimensional space, if  $\det(A) = -1$ ,  $\hat{i}$  might go from being to the right of  $\hat{j}$  to being to the left. We can use the right-hand rule to figure out whether the orientation of 3-space has changed.