```
1
     % rewrited by wang.david.wei 2020.3.5
     % 2020.3.6 compress with start position
3
     function mtspf ga(varargin)
4
                         100*rand(61,2); % 60 sensor nodes position and start/end position
5
                     =
                         [0 0];
                                         %start/end position(0,0)
         xy(1,:)
6
         dmat
                                         %distance matrix for all sensors
                     =
                         [];
 7
         nSalesmen
                     =
                                         %mutiple salesmen
                         4 ;
8
                     =
         minTour
                         2;
                                         %min tour constraint
         popSize
                         80;
                                         %particle size or population
9
                     =
10
         numIter
                     =
                         5e3;
                                         %the number of iterate
11
         showProg
                         true;
                                         %show the figure
12
13
                                         %distance matrix calculation
         if isempty(dmat)
14
             nPoints = size(xy,1);
                                         %distance matrix size
15
             a = meshgrid(1:nPoints);
                                         %meshgrid
16
             dmat = reshape(sqrt(sum((xy(a,:)-xy(a',:)).^2,2)), nPoints, nPoints);
17
         end
18
19
         N=nPoints; %senors and start/end position sum
20
         n =N-1;
                     %sensor number
21
                    = max(1,min(n,round(real(nSalesmen(1)))));
         nSalesmen
22
                    = max(1,min(floor(n/nSalesmen),round(real(minTour(1)))));
         minTour
                   = max(8,8*ceil(popSize(1)/8));
23
         popSize
                     = max(1,round(real(numIter(1))));
24
        numIter
25
         showProg
                  = logical(showProg(1));
26
         % Initializations for Route Break Point Selection
27
         nBreaks = nSalesmen-1;
28
         dof = n - minTour*nSalesmen;
                                                % degrees of freedom
29
         addto = ones(1,dof+1);
30
         for k = 2:nBreaks
31
             addto = cumsum(addto);
32
         end
33
         cumProb = cumsum(addto)/sum(addto);
34
         % Initialize the Populations
35
                                               % population of routes
         popRoute = zeros(popSize,n);
36
         popBreak = zeros(popSize,nBreaks); % population of breaks
37
         popRoute(1,:) = (1:n) + 1;
38
         popBreak(1,:) = rand breaks();
39
         for k = 2:popSize
40
             popRoute(k,:) = randperm(n) + 1;
41
             popBreak(k,:) = rand breaks();
42
         end
         pclr = ~get(0,'DefaultAxesColor'); % Select the Colors for the Plotted Routes
43
44
         clr = [1 \ 0 \ 0; \ 0 \ 0 \ 1; \ 0.67 \ 0 \ 1; \ 0 \ 1 \ 0; \ 1 \ 0.5 \ 0];
45
         globalMin = Inf; % Run the GA
46
         totalDist = zeros(1,popSize);
47
         distHistory = zeros(1, numIter);
48
         tmpPopRoute = zeros(8,n);
49
         tmpPopBreak = zeros(8,nBreaks);
50
         newPopRoute = zeros(popSize,n);
51
         newPopBreak = zeros(popSize,nBreaks);
52
         if showProq
53
             figure('Name','MTSP for WRSN| Current Best Solution','Numbertitle','off');
54
             hAx = gca;
55
         end
56
         for iter = 1:numIter
57
             for p = 1:popSize
                                   % Evaluate Members of the Population
58
                 d = 0;
59
                 pRoute = popRoute(p,:);
60
                 pBreak = popBreak(p,:);
61
                 rng = [[1 pBreak+1];[pBreak n]]';
62
                 for s = 1:nSalesmen
63
                     d = d + dmat(1,pRoute(rng(s,1))); % Add Start Distance
64
                     for k = rng(s,1):rng(s,2)-1
65
                         d = d + dmat(pRoute(k), pRoute(k+1));
66
67
                     d = d + dmat(pRoute(rng(s,2)),1); % Add End Distance
68
                 end
69
                 totalDist(p) = d;
70
71
             [minDist,index] = min(totalDist); % Find the Best Route in the Population
             distHistory(iter) = minDist;
73
             if minDist < globalMin</pre>
```

```
74
                   globalMin = minDist;
 75
                   optRoute = popRoute(index,:);
 76
                   optBreak = popBreak(index,:);
 77
                   rng = [[1 optBreak+1];[optBreak n]]';
 78
                   if showProg % Plot the Best Route
 79
                       for s = 1:nSalesmen
 80
                           rte = [1 \text{ optRoute}(rng(s,1):rng(s,2)) 1];
 81
                           plot(hAx,xy(rte,1),xy(rte,2),'.-','Color',clr(s,:));
 82
                           hold(hAx, 'on');
 83
                       end
 84
                       plot(hAx,xy(1,1),xy(1,2),'o','Color',pclr);
 85
                       title (hAx, sprintf ('Total Distance = %1.4f, Iteration =
                       %d',minDist,iter));
 86
                       hold(hAx, 'off');
                       drawnow;
 87
 88
                   end
 89
              end
 90
              randomOrder = randperm(popSize); % Genetic Algorithm Operators
 91
              for p = 8:8:popSize
 92
                   rtes = popRoute(randomOrder(p-7:p),:);
 93
                   brks = popBreak(randomOrder(p-7:p),:);
 94
                   dists = totalDist(randomOrder(p-7:p));
 95
                   [ignore,idx] = min(dists); %#ok
                   bestOf8Route = rtes(idx,:);
 96
 97
                   bestOf8Break = brks(idx,:);
 98
                   routeInsertionPoints = sort(ceil(n*rand(1,2)));
 99
                   I = routeInsertionPoints(1);
100
                   J = routeInsertionPoints(2);
101
                   for k = 1:8 % Generate New Solutions
102
                       tmpPopRoute(k,:) = bestOf8Route;
103
                       tmpPopBreak(k,:) = bestOf8Break;
104
                       switch k
105
                           case 2 % Flip
106
                               tmpPopRoute(k,I:J) = tmpPopRoute(k,J:-1:I);
107
                           case 3 % Swap
108
                               tmpPopRoute(k,[I J]) = tmpPopRoute(k,[J I]);
109
                           case 4 % Slide
110
                               tmpPopRoute(k, I:J) = tmpPopRoute(k, [I+1:J I]);
111
                           case 5 % Modify Breaks
112
                               tmpPopBreak(k,:) = rand breaks();
113
                           case 6 % Flip, Modify Breaks
114
                               tmpPopRoute(k,I:J) = tmpPopRoute(k,J:-1:I);
115
                               tmpPopBreak(k,:) = rand breaks();
116
                           case 7 % Swap, Modify Breaks
                               tmpPopRoute(k,[I J]) = tmpPopRoute(k,[J I]);
117
118
                               tmpPopBreak(k,:) = rand breaks();
119
                           case 8 % Slide, Modify Breaks
120
                               tmpPopRoute(k,I:J) = tmpPopRoute(k,[I+1:J I]);
121
                               tmpPopBreak(k,:) = rand breaks();
122
                           otherwise % Do Nothing
123
                       end
124
                   end
125
                   newPopRoute(p-7:p,:) = tmpPopRoute;
                   newPopBreak(p-7:p,:) = tmpPopBreak;
126
127
              end
128
              popRoute = newPopRoute;
129
              popBreak = newPopBreak;
130
131
          function breaks = rand breaks() % Force Breaks to be at Least the Minimum Tour
132
              nAdjust = find(rand < cumProb,1)-1;</pre>
133
              spaces = ceil(nBreaks*rand(1,nAdjust));
134
              adjust = zeros(1,nBreaks);
135
              for kk = 1:nBreaks
136
                   adjust(kk) = sum(spaces == kk);
137
138
              breaks = minTour*(1:nBreaks) + cumsum(adjust);
139
          end
140
      end
```