# Modern approaches to the assessment of demand sensitivity based on uplift models and neural networks

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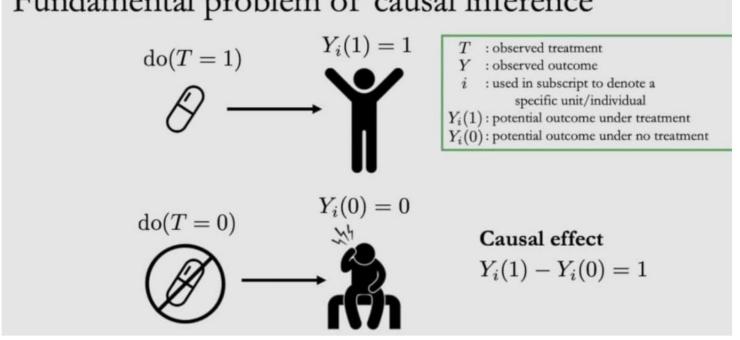
# Problem statement:

- **Uplift modeling**: predicts the incremental effect of a treatment on an individual's behaviour.
- Example: a company wants to send a customer an SMS with a discount offer.
- **Goal**: to detect the persuadable group of people and offer them the discount.

Response if Treated	N	Do-Not-Disturb c	Lost Cause d
	Υ	Sure Thing b	Persuadable <i>a</i>
		Υ	N
		Response if <u>not</u> treated	

# Problem statement:

#### Fundamental problem of causal inference



 Can't take and don't take the pill simultaneously ⇒ it is not possible to observe and count the uplift (or casual effect) directly.

#### Solution:

#### In classical approach:

Casual effect:

$$\tau_i = Y_i^1 - Y_i^0.$$

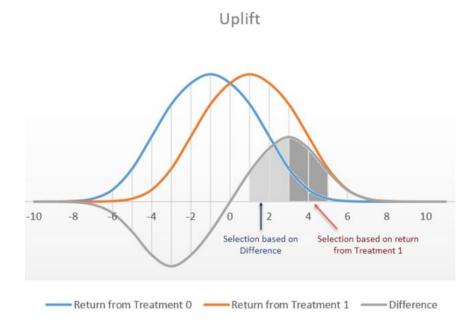
CATE (Conditional Average Treatment Effect):

$$CATE = \mathsf{E}\left[Y_i^1 \mid X_i\right] - \mathsf{E}\left[Y_i^0 \mid X_i\right].$$

#### In uplift modelling:

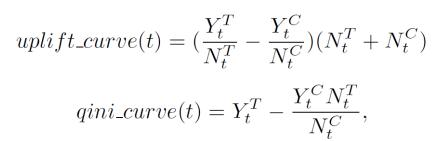
$$uplift = \widehat{CATE} = \mathsf{E}\left[Y_i \mid X_i = x, W_i = 1\right] -$$
 
$$-\mathsf{E}\left[Y_i \mid X_i = x, W_i = 0\right],$$

where  $Y_i = W_i Y_i^1 + (1 - W_i) Y_i^0$  is customer's observed response.

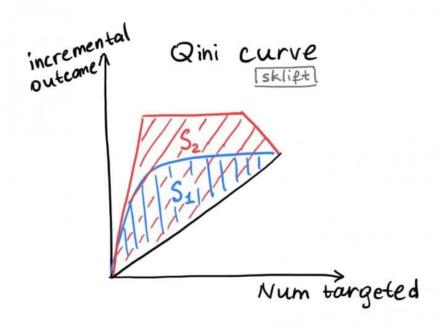


# Uplift metrics

- uplift@k the value of uplift at top k% of data
- area under uplift curve:
- area under qini curve



where  $Y_t^T$  and  $Y_t^C$  are targets in treatment and control groups, respectively.  $N_t^T$  and  $N_t^T$  are sizes of groups and t is the number of targeted objects.



Qini 
$$=\frac{S_1}{S_2}$$

#### Meta-learners: S-learner

S-learner calculates the treatment effect using a single machine learning model

fitting

$$fit\begin{pmatrix} x_{11} & \cdots & x_{1k} & w_1 & y_1 \\ \vdots & \ddots & \vdots & \cdots, & \cdots \\ x_{n1} & \cdots & x_{nk} & w_n & y_n \end{pmatrix}$$

$$X_{train} \qquad W_{train} \qquad Y_{train}$$

inference

#### Meta-learners: T-learner

T-learner is a Two-Model approach

fitting

$$model^{T} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & y_{1} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{p1} & \cdots & x_{pk} & y_{p} \end{pmatrix}, \ model^{C} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & y_{1} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{q1} & \cdots & x_{qk} & y_{q} \end{pmatrix}$$

$$X_{train\_treat} \quad Y_{train\_treat} \quad X_{train\_control} \quad Y_{train\_control}$$

inference

#### Meta-learners: X-learner

$$model^{T} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & y_{1} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{p1} & \cdots & x_{pk} & y_{p} \end{pmatrix}, \ model^{C} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & y_{1} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{q1} & \cdots & x_{qk} & y_{q} \end{pmatrix}$$

$$model^{T}_{new} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & \tilde{d}_{1}^{T} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{p1} & \cdots & x_{pk} & \tilde{d}_{p}^{T} \end{pmatrix}, \ model^{C}_{new} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & \tilde{d}_{1}^{C} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_{q1} & \cdots & x_{qk} & \tilde{d}_{q}^{C} \end{pmatrix}$$

$$X_{train\_treat} \quad Y_{train\_treat} \quad X_{train\_control} \quad X_{train\_control} \quad \tilde{D}^{C}$$

$$model_{new}^{T} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & \tilde{d}_{1}^{T} \\ \vdots & \ddots & \vdots & \cdots \\ x_{p1} & \cdots & x_{pk} \end{pmatrix}, \quad model_{new}^{C} = fit \begin{pmatrix} x_{11} & \cdots & x_{1k} & \tilde{d}_{1}^{C} \\ \vdots & \ddots & \vdots & \cdots \\ x_{q1} & \cdots & x_{qk} & \tilde{d}_{q}^{C} \end{pmatrix}$$

$$X_{train\_treat} \qquad \widetilde{D}^{T} \qquad X_{train\_control} \qquad \widetilde{D}^{C}$$

$$\hat{Y}^{C} = \frac{model^{c}}{predict} \begin{pmatrix} x_{11} & \cdots & x_{1k} \\ \vdots & \ddots & \vdots \\ x_{p1} & \cdots & x_{pk} \end{pmatrix} ; \quad \hat{Y}^{T} = \frac{model^{T}}{predict} \begin{pmatrix} x_{11} & \cdots & x_{1k} \\ \vdots & \ddots & \vdots \\ x_{q1} & \cdots & x_{qk} \end{pmatrix}$$

$$X_{train\_treat} \qquad X_{train\_control}$$

$$\tilde{D}^{T} = Y_{train\_treat} - \hat{Y}^{C}; \quad \tilde{D}^{C} = \hat{Y}^{T} - Y_{train\_control}$$

$$X_{test}$$

$$g \cdot \underset{predict}{model_{new}^{C}} \begin{pmatrix} x_{11} & \cdots & x_{1k} \\ \vdots & \ddots & \vdots \\ x_{m1} & \cdots & x_{mk} \end{pmatrix} + (1-g) \cdot \underset{predict}{model_{new}^{T}} \begin{pmatrix} x_{11} & \cdots & x_{1k} \\ \vdots & \ddots & \vdots \\ x_{m1} & \cdots & x_{mk} \end{pmatrix} = \begin{pmatrix} u_{1} \\ \vdots \\ u_{m} \end{pmatrix}$$

$$X_{test} \qquad X_{test} \qquad uplift$$

#### Meta-learners: R-learner

R-learner is a two-step algorithm

- Fitting two base models using cross-validation and predict on holdout fold i:
  - the outcomes m(-i)(Xi)
  - the propensity scores e(-i)(Xi)

• Minimising of R-loss:

$$\tau^*() = argmin_{\tau} \left\{ \frac{1}{n} \sum_{i=1}^n [(Y_i - \hat{m}^{(-i)}(X_i)) - (W_i - \hat{e}^{(-i)}(X_i))\tau(X_i)]^2 + \Lambda(\tau()) \right\},$$

## Tree-based approaches: Uplift Tree

The tree is constructed to maximize the difference between distribution divergence for the treatment and control groups before and after the split. The best split in each node is chosen based on the gain:

$$D_{qain} = D_{aftersplit}(P^T, P^C) - D_{beforesplit}(P^T, P^C).$$

Three approaches to calculate the divergence:

• the Kullback-Leibler (KL) divergence:

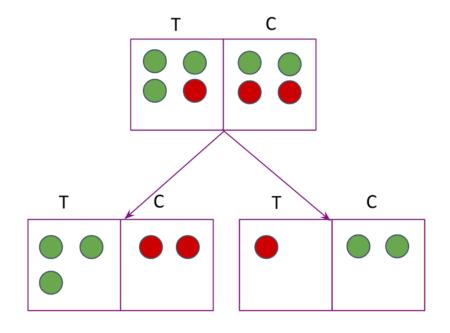
$$KL(P:Q) = \sum_{i} p_i \log \frac{p_i}{q_i};$$

• the Euclidean distance:

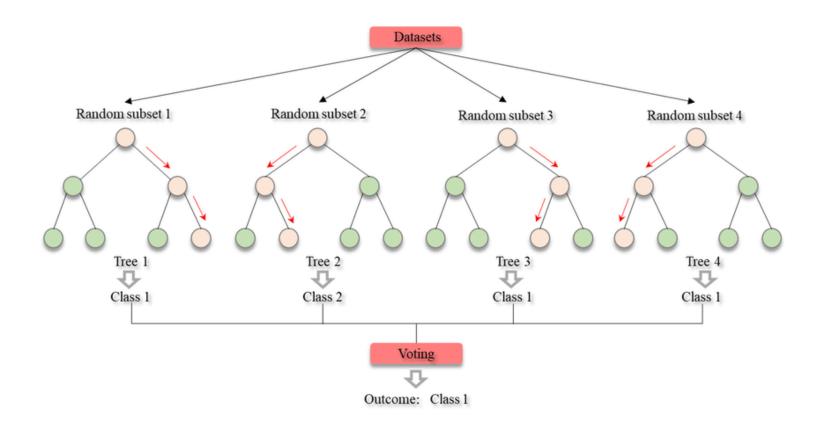
$$ED(P:Q) = \sum_{i} (p_i - q_i)^2;$$

• the Chi-squared divergence:

$$\xi^{2}(P:Q) = \sum_{i} \frac{(p_{i} - q_{i})^{2}}{q_{i}}.$$



# Tree-based approaches: Random Forest



## Boosting

In the project we considered Uplift AdaBoost algorithm:

- 1. Initialize weights  $w_{1,i}^T, w_{1,i}^C$
- 2. For  $m \leftarrow 1, \dots, M$

(a) 
$$w_{m,i}^T \leftarrow \frac{w_{m,i}^T}{\sum_j w_{m,j}^T + \sum_j w_{m,j}^C}; w_{m,i}^C \leftarrow \frac{w_{m,i}^C}{\sum_j w_{m,j}^T + \sum_j w_{m,j}^C}$$

- (b) Build a base model  $h_m$  on  $\mathcal{D}$  with  $w_{m,i}^T, w_{m,i}^C$
- (c) Compute the treatment and control errors  $\epsilon_m^T$ ,  $\epsilon_m^C$
- (d) Compute  $\beta_m^T(\epsilon_m^T, \epsilon_m^C), \beta_m^C(\epsilon_m^T, \epsilon_m^C)$
- (e) If  $\beta_m^T = \beta_m^C = 1$  or  $\epsilon_m^T \notin (0, \frac{1}{2})$  or  $\epsilon_m^C \notin (0, \frac{1}{2})$ :
  - i. choose random weights  $w_{m,i}^T$ ,  $w_{m,i}^C$
  - ii. continue with next boosting iteration

(f) 
$$w_{m+1,i}^T \leftarrow w_{m,i}^T \cdot (\beta_m^T)^{1[h_m(x_i^T) = y_i^T]}$$

(g) 
$$w_{m+1,i}^C \leftarrow w_{m,i}^C \cdot (\beta_m^C)^{1[h_m(x_i^C)=1-y_i^C]}$$

(h) 
$$\beta_m \leftarrow \min\{\beta_m^T, \beta_m^C\}$$

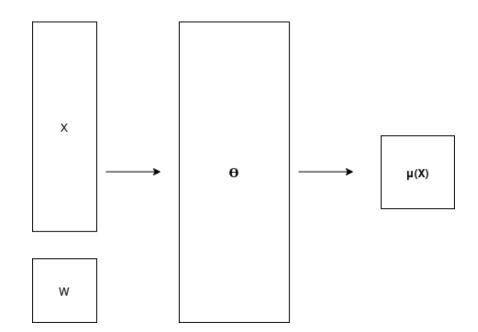
(i) Add  $h_m$  with coefficient  $\beta_m$  to the ensemble

Output: The final hypothesis

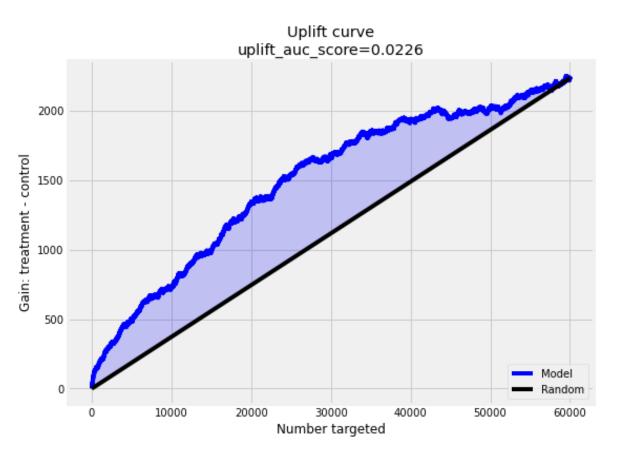
$$h_f(x) = \begin{cases} 1 & if \sum_{m=1}^{M} \left(\log \frac{1}{\beta_m}\right) h_m(x) \ge \frac{1}{2} \sum_{m=1}^{M} \log \frac{1}{\beta_m}, \\ 0 & otherwise. \end{cases}$$
 (2)

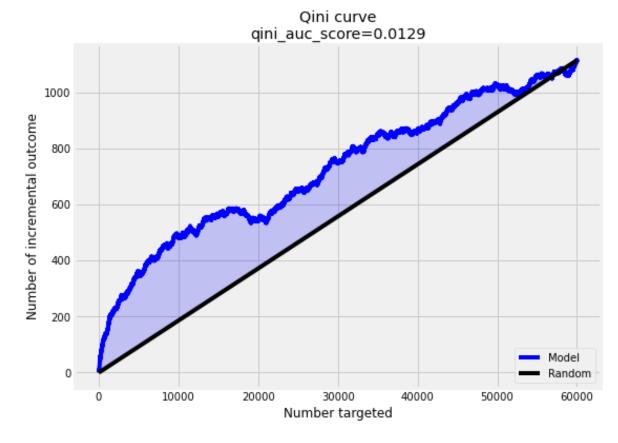
# Neural Network for uplift modeling

- Transformed outcome is used as target
- MLP architecture
- Transformed output depending on treatment  $\hat{y}_i = \begin{cases} \mu(x_i), & \text{if } w_i = 1 \\ -\mu(x_i), & \text{if } w_i = 0 \end{cases}$
- Training and validation on X5 dataset



#### Results: meta-learners

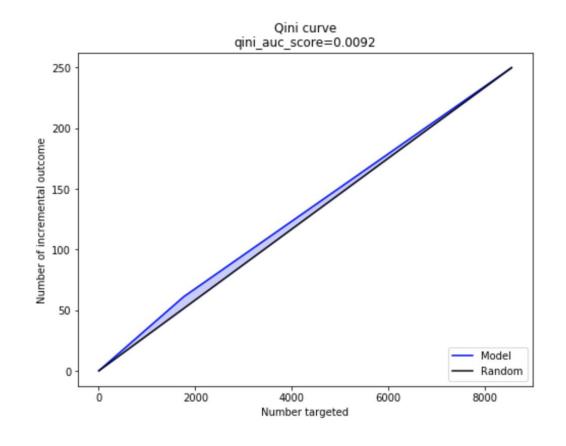


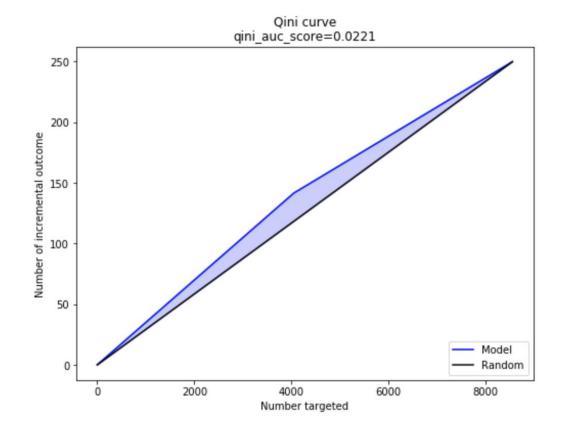


Uplift curve for S learner on X5 dataset

Qini curve for T learner on X5 dataset

## Results: random forest and boosting

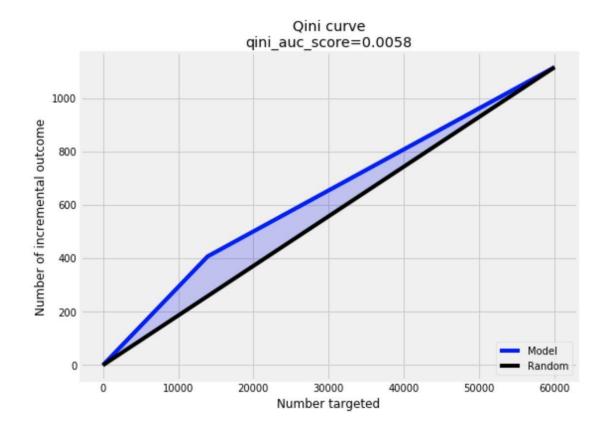


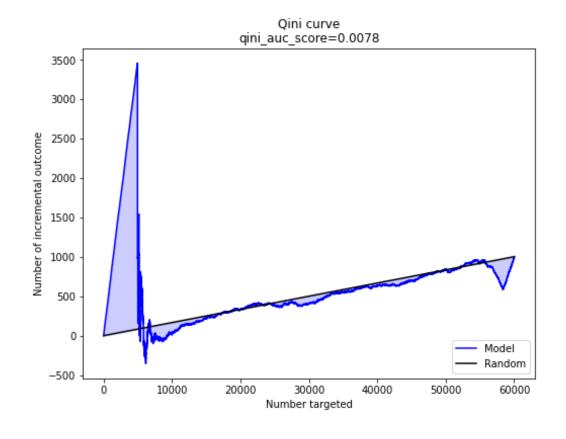


Qini curve for random forest On MineThatData

Qini curve for boosting On MineThatData

#### Results: trees and neural network





Qini curve for tree with depth 8, X5 dataset

Qini curve for Neural Network, X5 dataset

#### Conclusion

- Meta-learners (S-, T-, X- and R-learners)
- Tree-based approaches (Uplift Tree, Random Forest)
- Boosting (AdaBoost)
- Neural networks
- Comparison on 3 datasets

# Thank you for your attention!