



ROBOTİKTE MAKİNE GÖRMESİ

ROE510

Homework 6

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Step1: Data Gathering

Data required for this application is collected from a kaggle dataset. Dataset named Dogs vs. Cats is supplied by kaggle for Playground prediction competition and can be found at <https://www.kaggle.com/c/dogs-vs-cats/data> .

Step2: Preparing Development

Training will be performed on Colab, to quickly transfer the training data I have shared on my github with credits to the original data source and use “wget” command to quickly load to my workspace.

Github link to ipynb :

<https://github.com/onuralpArsln/MIAiTutorialProjects/blob/main/5-ImageClass/CatDog/modelTrain.ipynb>

Command to quickly load data:

```
!wget  
https://github.com/onuralpArsln/MIAiTutorialProjects/raw/main/5-ImageClass/CatDog/data.zip -O  
data.zip
```

After using “!unzip -q data.zip” data is unzipped.

Step3 : Data Preprocessing

Images are scaled and then divided into train and validation sets. This allows uniform inputs to network and ability to test success of training.

Step 4: Model Building

A simple model with requested layers is built.

```
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Conv2D, MaxPooling2D, Flatten, Dense, Dropout

model = Sequential([
    Conv2D(32, (3, 3), activation='relu', input_shape=(128, 128, 3)),
    MaxPooling2D((2, 2)),
    Conv2D(64, (3, 3), activation='relu'),
    MaxPooling2D((2, 2)),
    Flatten(),
    Dense(128, activation='relu'),
    Dropout(0.5),
    Dense(1, activation='sigmoid')
])

model.compile(
    optimizer='adam',
    loss='binary_crossentropy',
    metrics=['accuracy']
)
```

Step 5: Training

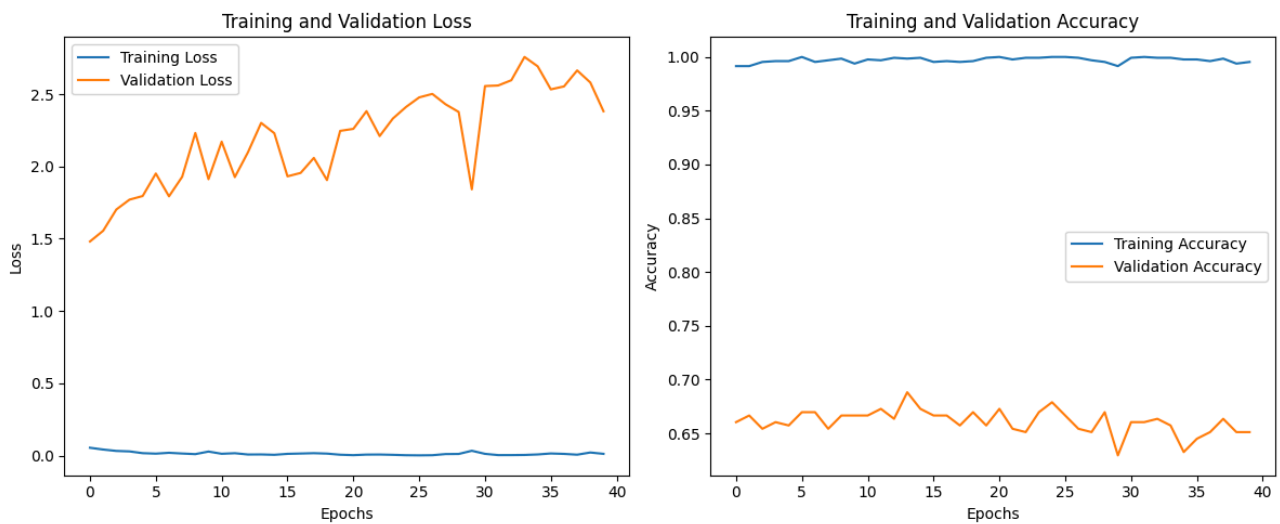
Using `model.fit` training is performed. I have started with batch size 16 and epoch size 10 which was inadequate for the given task. I have increased the batch size and epochs. This given state of hyperparameters of 40 epoch and 32 batch size are the fastest trained values that are still able to perform at acceptable success.

```
history = model.fit(
    X_train, y_train,
    validation_data=(X_val, y_val),
    epochs=40,
    batch_size=32
)
```

Step 6: Evaluation



Randomly selected five visuals to test results with only one is miss classed.



In the given graphic we can see training loss is approaching zero while validation loss is increasing, this might indicate an overfitting situation.

Step 7: New Model and Evaluation

New model is built with fewer epochs and obtained a better result at early steps.

```

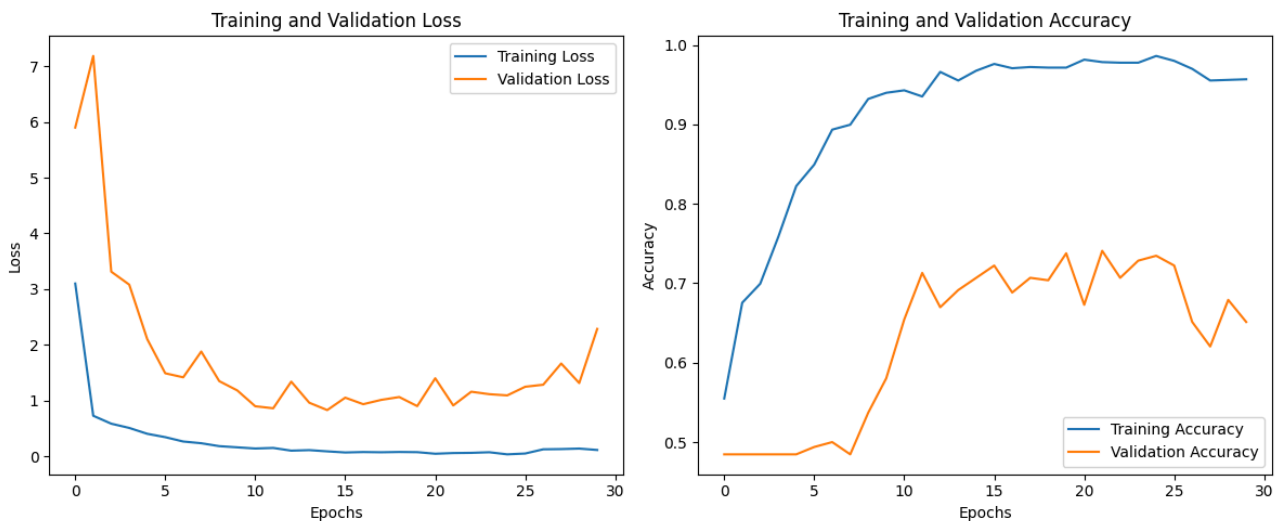
model = Sequential([
    # 1. Convolution + MaxPooling
    Conv2D(32, (3, 3), activation='relu', input_shape=(128, 128, 3)),
    BatchNormalization(),
    MaxPooling2D((2, 2)),

    # 2. Convolution + MaxPooling
    Conv2D(64, (3, 3), activation='relu'),
    BatchNormalization(),
    MaxPooling2D((2, 2)),

    # Convolution + MaxPooling
    Conv2D(128, (3, 3), activation='relu'),
    BatchNormalization(),
    MaxPooling2D((2, 2)),

    # Fully Connected Layers
    Flatten(),
    Dense(256, activation='relu'), # Daha büyük bir dense layer ekledik
    Dropout(0.5),                 # Regularization için dropout ekledik
    Dense(1, activation='sigmoid') # Binary classification için
])

```



In these results we can see that validation loss decreases with training loss at early epoch showing that overfitting is reduced initially. Yet there is still room for improvement. More data and better model structure can solve this problem.