# EE583 -Take Home Final

Q-1)

- a) There are L-1 independent parameters over X.
- bill H we assign every nodes with as possible as much parents we could reach the maximum number of independent parameters. So, there

(L-1)+L(L-1)+L2(L-1)+...+(2-2(L-1)+Ln-1(L-1)

= (L-1) $\frac{2}{L}$  $\frac{1}{L}$ = (L-1) $\frac{(1-L^n)}{(1-L)}$ =  $L^n-1$  independent parameters at most.

Here we set kan-1.

c.) This question has some solution with above part.

$$(L-1)+L(L-1)+L^{2}(L-1)+....+L^{m}(L-1)$$
  
=  $(L-1)\sum_{i=1}^{n}L^{i-1}=(L-1)(1-L^{n})=L^{n}-1$  independent parameters.

Q2-)

Def. 1 - Undirected graphical model 6 is called Markov Random Field if two nodes are conditionally independent whenever they are seperated by evidence nodes. So, for any node Xi, following conditional property hold:

P(Xi/XNi) = P(Xi/XNi)

X61 = all nodes except Xi XN: = neighborhood of Xi Def. 2 - A probability distribution P(X) on an undirected graphical model 6 is called o Gibbs distribution if it can be factorized into positive functions defined on cliques that cover all nodes and edges of 6. That is;

 $P(X) = \frac{1}{2} TT Pe(Xc)$  C: set of all cliques Z. normalization constant. . The Hammersley Clifford Theorem claims that above 2-definitions are equivalent. . So we can represent any positive distribution in log-domoin,

P(X) = 1 TT De(Xe)

=> logP(X)= I log De(Xc)-log Z

=> bgP(x) = I wefc(xe) - log ?

=> P(x) = 1 exp( I we fe(xe))

In this question I start the factors order 0 for each. In question Grades factor include g1,g2,g3 however I take them g0,g1,g2 as others for write the code efficiently.

• The joint probability of the non-loopy networks for given parameters are;

```
0.6000 0.3000 0.0036 0.0600 0.000036
```

The joint probabilities are ordered such that the first is for joint probability of node 1, second for node 2 and so on.

• The joint probability of the loopy networks for given parameters are;

```
0.6000 0.3000 0.0036 0.0600 0.00000216
```

My joint probability algorithm and the running codes are in Appendix Q3.

#### Q4)

a)

In this question I find the marginal probability of the vector for n=2,3,....,10. I put the marginal probabilities here in order from 2 to 10.

```
for n=2
0.6120
        for n=3
0.6010
0.6150 for n=4
0.6020
        for n=5
0.6010 for n=6
        for n=7
0.6060
0.6220
        for n=8
        for n=9
0.6040
0.6000
       for n=10
```

I also put here graph for n=10. This graph is contain number of iteration versus the average value marginal probability of X. Since I take probabilities random the starting point of graph change every run but final convergences are almost same.

My direct (top-down) sampling algorithm in Appendix Q4a.

### b)

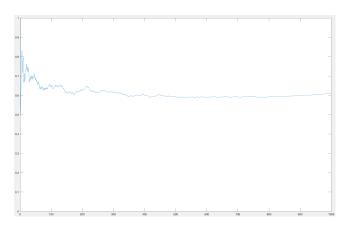
In this question I find the marginal probability of the vector for n=2,3,....,10. I put the marginal probabilities here in order from 2 to 10.

```
0.6160 for n=2
0.6054 for n=3
0.6044 for n=4
0.6044 for n=5
0.6044 for n=6
0.6044 for n=7
0.6044 for n=8
0.6044 for n=9
0.6044 for n=10
```

I don't put any graph because there is no convergences. From messages we could find the marginal probabilities directly.

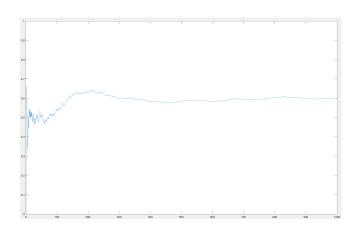
My belief propagation (sum-product) algorithm in Appendix Q4b.

e) In here I implement the Gibbs Algorithm. For n = 5 I put the Probabilities and the plot of number of iterations versus average marginal probability of X.



Here the results and graphs for the n=10.

0.6060 for n=2 0.5870 for n=3 0.5910 for n=4 0.5990 for n=5 0.6220 for n=6 0.5850 for n=7 0.6100 for n=8 0.5920 for n=9 0.6000 for n=10



Graphs shape are changes because of I take the inputs randomly. Both graphs converges to same value with same as Q4a.

My Gibbs Sampling algorithm in Appendix Q4e.

## **Appendix**

#### Q3.) Algorithm

JointProb = JointProbability(Edges,Factors,x)

```
function JointProb = JointProbability(Edges,Factors,x)
len = length(Edges(:,1));
num_of_nodes = max(Edges(:));
for i=1:num of nodes
  if any(Edges(:,2)==i) == 0
     JointProb(i) = Factors\{i\}(x(i)+1);
  else
     Parents = [];
     length_parents_factor = [];
     for j=1:len
        if i == Edges(i,2);
          Parents = [Parents Edges(j,1)];
          length_parents_factor = [length_parents_factor length(Factors{Edges(j,1)}(1,:))];
        end
     end
     num_of_parents = length(Parents);
     for j=1:num_of_parents
        order = length(Factors{i}(:,1))/length_parents_factor(num_of_parents+1-j);
        Factors{i} = Factors{i}(order*x(Parents(num of parents+1-j))+1:order*(x(Parents(num of parents+1-
j))+1),:);
     JointProb(i) = Factors{i}(x(i)+1);
     for k=1:num of parents
        JointProb(i) = JointProb(i)*JointProb(Parents(k));
     end
  end
end
Running code for non-loopy networks;
clear;
clc;
Edges = [1,3;2,3;2,4;3,5];
Factors\{1\} = [0.6, 0.4];
Factors\{2\} = [0.7, 0.3];
Factors\{3\} = [0.3 \ 0.4 \ 0.3; \ 0.05 \ 0.25 \ 0.7; \ 0.9 \ 0.08 \ 0.02; \ 0.5 \ 0.3 \ 0.2];
Factors\{4\} = [0.95, 0.05; 0.2, 0.8];
Factors\{5\} = [0.1,0.9;0.4,0.6;0.99,0.01];
x = [0,1,2,0,1];
JointProb = JointProbability(Edges,Factors,x)
Running code for loopy networks;
clear;
clc;
Edges = [1,3;2,3;2,4;3,5;4,5];
Factors\{1\} = [0.6, 0.4];
Factors\{2\} = [0.7,0.3];
Factors\{3\} = [0.3 \ 0.4 \ 0.3; \ 0.05 \ 0.25 \ 0.7; \ 0.9 \ 0.08 \ 0.02; \ 0.5 \ 0.3 \ 0.2];
Factors\{4\} = [0.95,0.05;0.2,0.8];
Factors\{5\} = [0.4,0.6;0.6,0.4;0.99,0.01;0.01,0.99;0.4,0.6;0.8,0.2];
x = [0,1,2,0,1];
```

```
Q4.)
a.)
clear;
clc;
a = 0.7;
b = 0.5;
c = 0.3;
n = 10;
G = zeros(n,n);
sample = 1000;
sum = zeros(n-1,1);
for index=1:sample
  for i=1:n
     for j=1:(n+1-i)
        G(i,j) = rand;
        if i == 1 \&\& G(i,j) > 1-c
          G(i,j) = 1;
        elseif i == 1
          G(i,j) = 0;
        elseif G(i-1,j) == G(i-1,j+1) \&\& G(i,j) > 1-a
          G(i,j) = 1;
        elseif G(i-1,j) \sim= G(i-1,j+1) \&\& G(i,j) > 1-b
          G(i,j) = 1;
        else
          G(i,j) = 0;
        end
     end
  end
  den = G(2:n,1);
  sum = sum + G(2:n,1);
  X(index) = sum(n-1) / index;
end
Probabilities = sum/sample
Range=[0 sample 0 1];
num_of_iter=1:sample;
figure(1)
plot(num_of_iter,X(num_of_iter));
axis(Range);
b.)
clear;
clc;
n = 10;
Message = [0.7 \ 0.3];
Factors = [0.3 \ 0.7; 0.5 \ 0.5; 0.5 \ 0.5; 0.3 \ 0.7];
Coefficient = zeros(4,2);
for i=1:(n-1)
  row = 1;
  for j=1:2
     for k=1:2
        Coefficient(row,:) = Message(j)*Message(k);
        row = row + 1;
     end
  end
  Message = sum(Coefficient.*Factors);
  JointProbability(i) = Message(2);
end
JointProbability
```

```
e.)
clear;
clc;
a = 0.7;
b = 0.5;
c = 0.3;
n = 10;
G = zeros(n,n);
sample = 1000;
Cs = 1-a;
alfa = log(b*(1-a)/(a*(1-b)));
beta = \log((1-b)/(1-a));
gama = log(a/(1-a));
sigma = log(c/(1-c));
sum = zeros(n-1,1);
X = zeros(sample, 1);
for num_of_iter=1:sample
  for i=1:n
     for j=1:(n-i+1)
       G(i,j) = rand;
       if i==1
          Ps = [Cs Cs*exp(sigma*1)];
       else
          y = G(i-1,j);
          z = G(i-1,j+1);
          x = 1;
          Ps = [Cs^*exp(beta^*(y-z)^2) \ Cs^*exp(alfa^*x^*(y-z)^2 + beta^*(y-z)^2 + gama^*x)];
       PsX = Ps(2)/(Ps(1)+Ps(2));
       if G(i,j) < PsX
          G(i,j) = 1;
       else
          G(i,j) = 0;
       end
     end
  end
  sum = sum + G(2:n,1);
  X(num_of_iter) = sum(n-1)/num_of_iter;
end
Probabilities = sum/sample
Range=[0 sample 0 1];
num_of_iter=1:sample;
figure(1)
plot(num_of_iter,X(num_of_iter));
axis(Range);
```