1. Below a transformation $T: \mathbb{R}^3 \to \mathbb{R}^2$ is defined. Show that T is a linear map. Then create its standard matrix.

$$T\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a+c \\ 2b \end{pmatrix}$$

Solution. To be a linear map, T must be closed under addition and scalar multiplication.

$$T\left(\begin{pmatrix} a \\ b \\ c \end{pmatrix} + \begin{pmatrix} d \\ e \\ f \end{pmatrix}\right) =$$

 \therefore the map is closed under addition.

$$r \cdot T \begin{pmatrix} a \\ b \\ c \end{pmatrix} =$$

: the map is closed under scalar multiplication.

We find the standard matrix for T by applying it to the standard basis vectors

2. Find the standard matrix for the linear map $T: \mathbb{R}^4 \to \mathbb{R}^3$ where

$$T \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} a+2b-c+d \\ a+c+d \\ 2a-4b+6c+2d \end{pmatrix}.$$

Then find a basis for the kernel and image of the linear map T.

Solution. The standard matrix is given by

$$\left(\begin{array}{c|c} T \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \middle| T \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \middle| T \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \middle| T \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 1 & 2 & -1 & 1 \\ 1 & 0 & 1 & 1 \\ 2 & -4 & 6 & 2 \end{pmatrix}.$$

The kernel of T is the null space of this matrix, and the image of T is its column space. Both are found by row reduction.

$$\begin{pmatrix} 1 & 2 & -1 & 1 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 2 & -4 & 6 & 2 & 0 \end{pmatrix} \xrightarrow{R_2 - R_1} \begin{pmatrix} 1 & 2 & -1 & 1 & 0 \\ 0 & -2 & 2 & 0 & 0 \\ 0 & -8 & 8 & 0 & 0 \end{pmatrix} \xrightarrow{-\frac{1}{2}R_2} \begin{pmatrix} 1 & 2 & -1 & 1 & 0 \\ 0 & -2 & 2 & 0 & 0 \\ 0 & -8 & 8 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow[R_1-2R_2]{R_3+8R_2} \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Leading 1's appear in columns 1 and 2, therefore a basis for the column space (and hence the image of T) is

$$\left\{ \begin{pmatrix} 1\\1\\2 \end{pmatrix}, \begin{pmatrix} 2\\0\\4 \end{pmatrix} \right\}.$$

The null space (and hence the kernel of T) is

$$\left\{ s \begin{pmatrix} -1\\1\\1\\0 \end{pmatrix} + t \begin{pmatrix} -1\\0\\0\\1 \end{pmatrix} \middle| s, t \in \mathbb{R} \right\}$$

which has basis

$$\left\{ \begin{pmatrix} -1\\1\\1\\0 \end{pmatrix}, \begin{pmatrix} -1\\0\\0\\1 \end{pmatrix} \right\}.$$

3. Are T_A and T_B one-to-one and onto?

$$T_A \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} -a & 0 \\ a & 0 \\ a & 0 \end{pmatrix} \qquad T_B \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} b \\ -a \\ a+c \end{pmatrix}$$

Solution.

The standard matrix $A = \begin{pmatrix} -1 & 0 \\ 1 & 0 \\ 1 & 0 \end{pmatrix}$ can be reduced to $\begin{pmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$, implying that the second variable

is a free variable. This makes the kernel $s\left\{\begin{pmatrix}0\\1\end{pmatrix}\middle|s\in\mathbb{R}\right\}$ with basis $\left\{\begin{pmatrix}0\\1\end{pmatrix}\right\}$ which is nontrivial (it contains more than just the zero vector). T_A is not one-to-one by default.

contains more than just the zero vector). T_A is not one-to-one by default. A transformation is onto only when everything in the codomain can be created from its image. T_A has the image $\begin{cases} s \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \middle| s \in \mathbb{R} \end{cases}$ which does not span all 3×2 matrices, so the transformation is not onto.

The standard matrix for $B=\begin{pmatrix}0&1&0\\-1&0&0\\1&0&1\end{pmatrix}$ representing T_B can be reduced to $I^3=\begin{pmatrix}1&0&0\\0&1&0\\0&0&1\end{pmatrix}$ whose kernel only contains the zero vector. Therefor T_B is one-to-one. The transformation is also onto as the basis for the image spans the whole codomain, \mathbb{R}^3 .

4. Using the characteristic equation $\det(A - \lambda I) = 0$, find the eigenvalues for matrices C and D.

$$C = \begin{pmatrix} 5 & 3 \\ 0 & -3 \end{pmatrix} \qquad D = \begin{pmatrix} 2 & 1 & 0 \\ 4 & 3 & 4 \\ -1 & 0 & 2 \end{pmatrix}$$

Solution. To find eigenvalues for a matrix M we solve the characteristic equation $\det(M-\lambda I)=0$.

$$0 = \begin{vmatrix} 5 - \lambda & 3 \\ 0 & -3 - \lambda \end{vmatrix} = (5 - \lambda)(-3 - \lambda) - 0 \quad \Rightarrow \quad \lambda = 5 \text{ or } \lambda = -3.$$

$$0 = \begin{vmatrix} 2 - \lambda & 1 & 0 \\ 4 & 3 - \lambda & 4 \\ -1 & 0 & 2 - \lambda \end{vmatrix} = (2 - \lambda) \begin{vmatrix} 3 - \lambda & 4 \\ 0 & 2 - \lambda \end{vmatrix} - 1 \begin{vmatrix} 4 & 4 \\ -1 & 2 - \lambda \end{vmatrix} = (2 - \lambda)((3 - \lambda)(2 - \lambda) - 0) - (4(2 - \lambda) - 1(4))$$

$$= (3 - \lambda)(2 - \lambda)^2 - 4(2 - \lambda + 1) = (3 - \lambda)((2 - \lambda)^2 - 4) \quad \Rightarrow \quad \lambda = 0, 3, 4$$

5. Find the eigenspaces for matrix D (defined above) such that $(D - \lambda I)\mathbf{x} = \mathbf{0}$.

Solution.

Eigenvalues $\lambda = 0, 3, 4$ were obtained in Question 4. For each of these, we must find an eigenspace. For $\lambda = 0$:

For $\lambda = 3$:

$$\begin{pmatrix} -1 & 1 & 0 & 0 \\ 4 & 0 & 4 & 0 \\ -1 & 0 & -1 & 0 \end{pmatrix} \xrightarrow{\begin{array}{c} -R_1 \\ \frac{1}{4}R_2 \end{array}} \begin{pmatrix} 1 & -1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ -1 & 0 & -1 & 0 \end{pmatrix} \xrightarrow{\begin{array}{c} R_2 - R_1 \\ R_3 + R_1 \end{array}} \begin{pmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & -1 & -1 & 0 \end{pmatrix} \xrightarrow{\begin{array}{c} R_1 + R_2 \\ R_3 + R_2 \end{array}} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow E_3 = \left\{ t \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \middle| t \in \mathbb{R} \right\} = \operatorname{span} \left\{ \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

For $\lambda = 4$:

$$\begin{pmatrix} -2 & 1 & 0 & 0 \\ 4 & -1 & 4 & 0 \\ -1 & 0 & -2 & 0 \end{pmatrix} \xrightarrow{R_1 - 2R_3} \begin{pmatrix} 0 & 1 & 4 & 0 \\ 0 & -1 & -4 & 0 \\ -1 & 0 & -2 & 0 \end{pmatrix} \xrightarrow{R_1 + R_2} \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & -4 & 0 \\ 1 & 0 & 2 & 0 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow E_4 = \left\{ t \begin{pmatrix} -2 \\ -4 \\ 1 \end{pmatrix} \middle| t \in \mathbb{R} \right\} = \operatorname{span} \left\{ \begin{pmatrix} -2 \\ -4 \\ 1 \end{pmatrix} \right\}$$