view frames Result Recorded at time: 19.198 map Broadcaster: /amcl Average rate: 34.453 Hz Most recent transform: 19.673 (-0.475 sec old) Buffer length: 3.425 sec odom Broadcaster: /qazebo Average rate: 40.292 Hz Most recent transform: 19.197 (0.001 sec old) Buffer length: 3.425 sec base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate: 50.296 Hz Average rate: 50.296 Hz Most recent transform: 0.000 (19.198 sec old) \Most recent transform: 0.000 (19.198 sec old) \Most recent transform: 0.000 (19.198 sec old) Most recent transform: 19.175 (0.023 sec old) Most recent transform: 19.175 (0.023 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.380 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.380 sec tm\_cntrl\_box merged\_laser\_frame front\_laser\_frame left\_wheel right\_wheel back\_laser\_frame tm\_base base\_footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 19.198 sec old) Buffer length: 0.000 sec tm\_base\_link Broadcaster: /robot state publisher Average rate: 50.296 Hz
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Most recent transform: 19.175 ( 0.023 sec old) Buffer length: 3.380 sec tm\_wrist\_2\_link Broadcaster: /robot state publisher Average rate: 50.296 Hz Most recent transform: 19.175 (0.023 sec old) Buffer length: 3.380 sec tm\_wrist\_3\_link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (19.198 sec old) Most recent transform: 0.000 (19.198 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tm\_flange\_link realsense mount Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz \Most recent transform: 0.000 (19.198 sec old) Most recent transform: 0.000 (19.198 sec old) Most recent transform: 0.000 (19.198 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec robotiq 85 base link camera1\_realsense\_lens  $tm_{tool0}$ Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 50.296 Hz Average rate: 50.296 Hz Average rate: 50.296 Hz Average rate: 50.296 Hz Most recent transform: 0.000 (19.198 sec old) Most recent transform: 19.175 (0.023 sec old) Most recent transform: 19.175 (0.023 sec old) Most recent transform: 19.175 (0.023 sec old) \Most recent transform: 19.175 (0.023 sec old) Buffer length: 0.000 sec Buffer length: 3.380 sec Buffer length: 3.380 sec Buffer length: 3.380 sec Buffer length: 3.380 sec camera1\_realsense robotiq\_85\_right\_knuckle\_link robotiq\_85\_left\_inner\_knuckle\_link robotiq\_85\_left\_knuckle\_link robotiq\_85\_right\_inner\_knuckle\_link Broadcaster: /robot\_state\_publisher Average rate: 50.296 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.296 Hz Most recent transform: 0.000 (19.198 sec old) Most recent transform: 19.175 (0.023 sec old) Most recent transform: 0.000 (19.198 sec old) Most recent transform: 0.000 (19.198 sec old) Most recent transform: 19.175 (0.023 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.380 sec Buffer length: 3.380 sec robotiq\_85\_left\_finger\_link robotiq\_85\_right\_finger\_link robotiq\_85\_left\_finger\_tip\_link robotiq\_85\_right\_finger\_tip\_link camera1\_realsense\_gazebo