Step 8 Selecting Manual mode and running the robot manually

① Press [M-MOD].

The [Operation Mode] window is displayed.
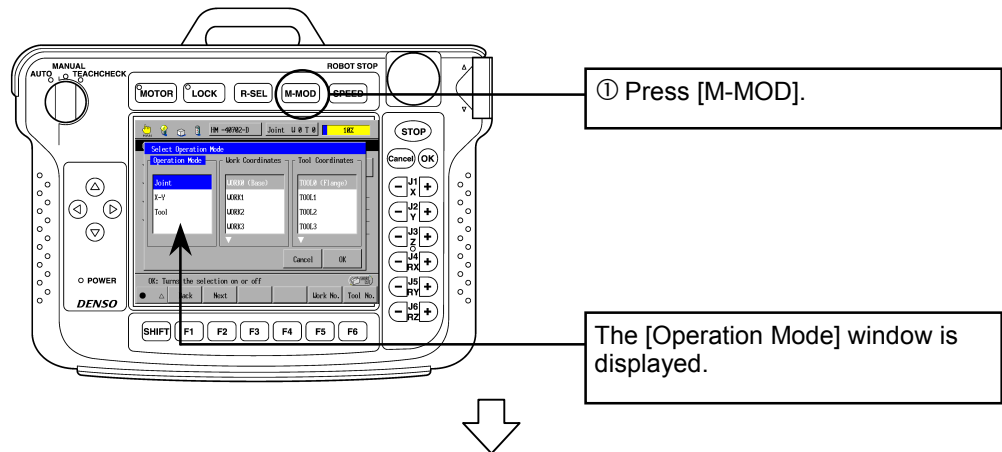
★**Point**★ In Manual mode you may select any of these three modes: Joint mode, X-Y mode and Tool mode.

	<Joint mode >	<X-Y mode>	<Tool mode>
Action	Drives each of the joints independently.	Drives the robot flange linearly in base coordinates.	Drives the robot flange linearly along the work coordinates of the 4th axis.
4-axis robot		The 4th axis will keep the orientation that was held immediately before the robot was driven. 	The 4th axis will hold its orientation.
6-axis robot			