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import numpy as np
import matplotlib.pyplot as plt

import sympy as sp
import nbconvert
import pandas

from IPython.display import display, Math, Latex

In [ ]: A = np.array(
[
[1,2],
[-3,4]
])

norm1 = np.linalg.norm(A,ord = 1)
norm2 = np.linalg.norm(A,ord = 2)
norm_inf = np.linalg.norm(A,ord = np.inf)
print(norm1,norm2,norm_inf)
6.0 5.464985704219043 7.0

In [ ]: def tril(A,index = 0):
'''
得到A矩阵第index行以下的矩阵
Args:
A (_Matrix_): 输入矩阵
'''
n=len(A)
L = np.zeros_like(A)
for i in range(index,n):
for j in range(0,i+1-index):
L[i,j] = A[i,j]
return L

def diag(A):
D = np.zeros_like(A)
for i in range(len(A)):
D[i,i] = A[i,i]
return D

def triu(A,index = 0):
'''
得到A矩阵第index行以上的矩阵
Args:
A (_Matrix_): 输入矩阵
'''
n=len(A)
U = np.zeros_like(A)
for j in range(index,n):
for i in range(0,i+1-index):
U[i,j] = A[i,j]
return U

def Jacobi_iteration(A,b,x0,tol = 1e-6,max_iter = 50):
'''
采用Jacobi迭代法求解线性方程组Ax=b
Args:
A (_type_): _description_
b (_type_): _description_
x0 (_type_): _description_
tol (_type_): _description_
max_iter (_type_): _description_
'''
dA = diag(A)
r0 = np.linalg.norm(b - np.dot(A,x0))
L = tril(A,1)
U = triu(A,1)
B = L + U

for k in range(max_iter):
x1 = np.dot(np.linalg.inv(dA),b - np.dot(B,x0))
r1 = np.linalg.norm(b - np.dot(A,x1))
if r1/r0 <= tol:
print(f"迭代次数:{k+1},结果为:{x1}")
break
else:
x0 = x1

if k == max_iter-1:
print("迭代次数已达到最大值")
return x1

In [ ]: def Gauss_Seidel_iteration(A,b,x0,tol = 1e-6,max_iter = 50):
'''采用Gauss_Seidel法求解线性方程组Ax=b
Args:
A (_type_): _description_
b (_type_): _description_
x0 (_type_): _description_
tol (_type_): _description_
max_iter (_type_): _description_
'''
dA = diag(A)
r0 = np.linalg.norm(b - np.dot(A,x0))
L = tril(A,1)
U = triu(A,1)
B = L + U

for k in range(max_iter):
x1 = np.dot(np.linalg.inv(dA - L),b + np.dot(U,x0))
r1 = np.linalg.norm(b - np.dot(A,x1))
if r1/r0 <= tol:
print(f"迭代次数:{k+1},结果为:{x1}")
break
else:
x0 = x1

if k == max_iter-1:
print("迭代次数已达到最大值")
return x1

In [ ]: def Successive over relaxation(A,b,x0,w = 0.15,tol = 1e-6,max_iter = 50):
'''采用松弛迭代方法求解线性方程组
Args:
A (_type_): _description_
b (_type_): _description_
w (_type_): _description_
tol (_type_): _description_
max_iter (_type_): _description_
Returns:
'''
dA = diag(A)
r0 = np.linalg.norm(b - np.dot(A,x0))
L = tril(A,1)
U = A - L

for k in range(max_iter):
C = np.linalg.inv(dA - w*L)
x1 = np.dot(np.dot(np.linalg.inv(dA - w * L),((1-w) * dA + w * U)),x0) + w * np.dot(np.linalg.inv(dA - w*L),b)
r1 = np.linalg.norm(b - np.dot(A,x1))
if r1/r0 <= tol:
print(f"迭代次数:{k+1},结果为:{x1}")
break
else:
x0 = x1 + w*(x1 - x0)

if k == max_iter-1:
print("迭代次数已达到最大值")
return x1

In [ ]: def grad_descent(A,b,x0,tol = 1e-6,max_iter = 150):
'''
采用梯度下降法计算Ax = b的解
Args:
A (_Matrix_): 系数矩阵
b (_Vector_): 向量
x0 (_Vector_): 初始向量
'''
A = A.copy()
b = b.copy()
x0 = x0.copy()

r0 = b - np.dot(A,x0) ## 初始残差
i = 0 ## 迭代次数

while np.linalg.norm(r0) > tol and i <= max_iter:
P = r0
A_P = np.dot(A,P)

alpha = np.dot(P,r0)/np.dot(P,A_P)

x0 = x0 + alpha * P
r0 -= alpha * A_P
i += 1

if i <= max_iter:
x = x0
print(f"Iterator:{i+1}时收敛到目标精度,求解出的解为:{x}")

else:
residual = np.linalg.norm(r0)
x = x0
print(f"Iterator:{i+1},但未达到目标精度,残差为{residual}")

return x

In [ ]: A = np.array(
[
[10,0],
[0,1]
])
).astype(np.float64)
b = np.array([8,5]).astype(np.float64)
x0 = np.array([1,1]).astype(np.float64)
x = grad_descent(A,b,x0)
print(x)

Iterator:15时收敛到目标精度,求解出的解为:[0.80000004 4.99999921]
0.80000004 4.99999921

我们很容易能够发现梯度下降法每次前进后,下一次的方向与上一次的方向必定正交即:
```

$$P_{k+1} \perp P_k$$

这就意味着,我们在每次前进后必须沿着垂直的方向前进,尽管我们在当前步骤内取得了局部的小值,但这并不意味着在全局内我们是最优策略.转化为Code方面的来看,也就是grad_descent采用的是 greedy (贪心)策略,但是实际上,我们面临的问题并不都是贪心的 \ 在这种意义上,我们或许需要寻找一个相对来说收敛更快的算法,这也就引出了我们下面定义的共轭梯度法

```
In [ ]: def AspaceDot(A,u,v):
'''
A-内积定义
Args:
A (_Matrix_): A矩阵 (要求对称正定)
u (_Vector_): 内积向量
v (_Vector_): 内积向量
Returns:
'''
- float/integer : 返回u,v在A矩阵意义下的内积

return np.dot(u,ABv)

def conjugate_gradient(A,b,x0,tol=1e-6,max_iter=150):
'''采用共轭梯度法来求解Ax=b的解
Args:
A (_type_): _description_
b (_type_): _description_
x0 (_type_): _description_
tol (_type_, optional): _description_. Defaults to 1e-6.
maxiter (int, optional): _description_. Defaults to 150.
'''
A = A.copy()
b = b.copy()
x0 = x0.copy()

r = b - ABx0
P = list()
P.append(r)
i = 0

while i <= max_iter and np.linalg.norm(r)>tol:

alpha = np.dot(P[-1],r) / np.dot(P[-1],ABP[-1])

x0 = x0 + alpha*P[-1]
r = b - ABx0
t = r
length = len(P)

for j in range(length):
t = t - AspaceDot(A,P[j],r) / AspaceDot(A,P[j],P[j]) * P[j]
P.append(t)
i += 1

if i == max_iter:
x = x0
residual = np.linalg.norm(r)

print(f"Iterator:{max_iter},算法未收敛,残差为:{residual},x为:{x0}")

else:
x = x0

print(f"Iterator:{i},算法收敛,x为:{x}")

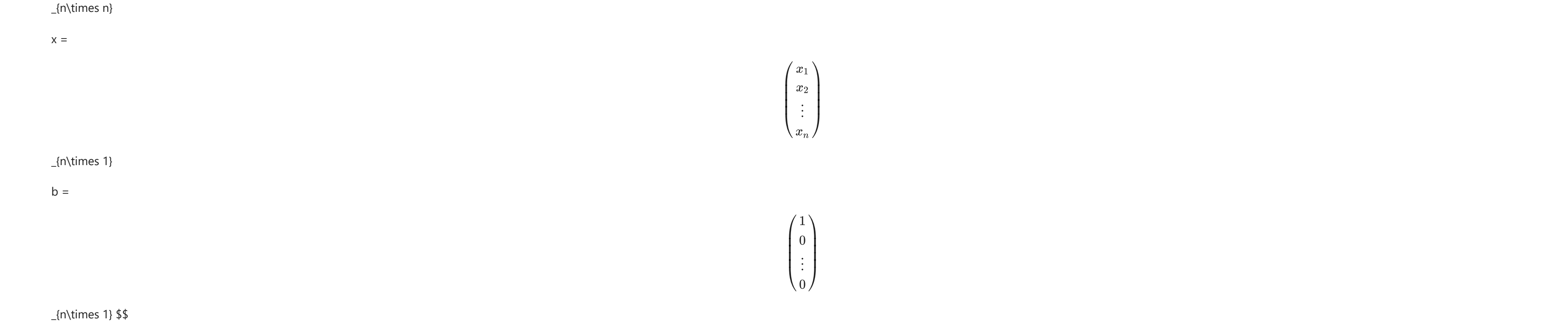
return x

In [ ]: A = np.array(
[
[10,0],
[0,1]
])
).astype(np.float64)
b = np.array([8,5]).astype(np.float64)
x0 = np.array([1,1]).astype(np.float64)
x = conjugate_gradient(A,b,x0)
print(x)

Iterator:2,算法收敛,x为:[0.8 5.]
[0.8 5.]

上机练习1\ 分别利用 Jacobi,Gauss-Seidel,SOR迭代法 计算 Ax = b, n = 15 并画出向量 x 的图像 $$ A =
```

$$\begin{pmatrix} \frac{5}{2} & -1 & 0 & \cdots & 0 & -1 \\ -1 & \frac{3}{2} & -1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots & \vdots \\ -1 & 0 & \cdots & 0 & -1 & \frac{5}{2} \end{pmatrix}$$

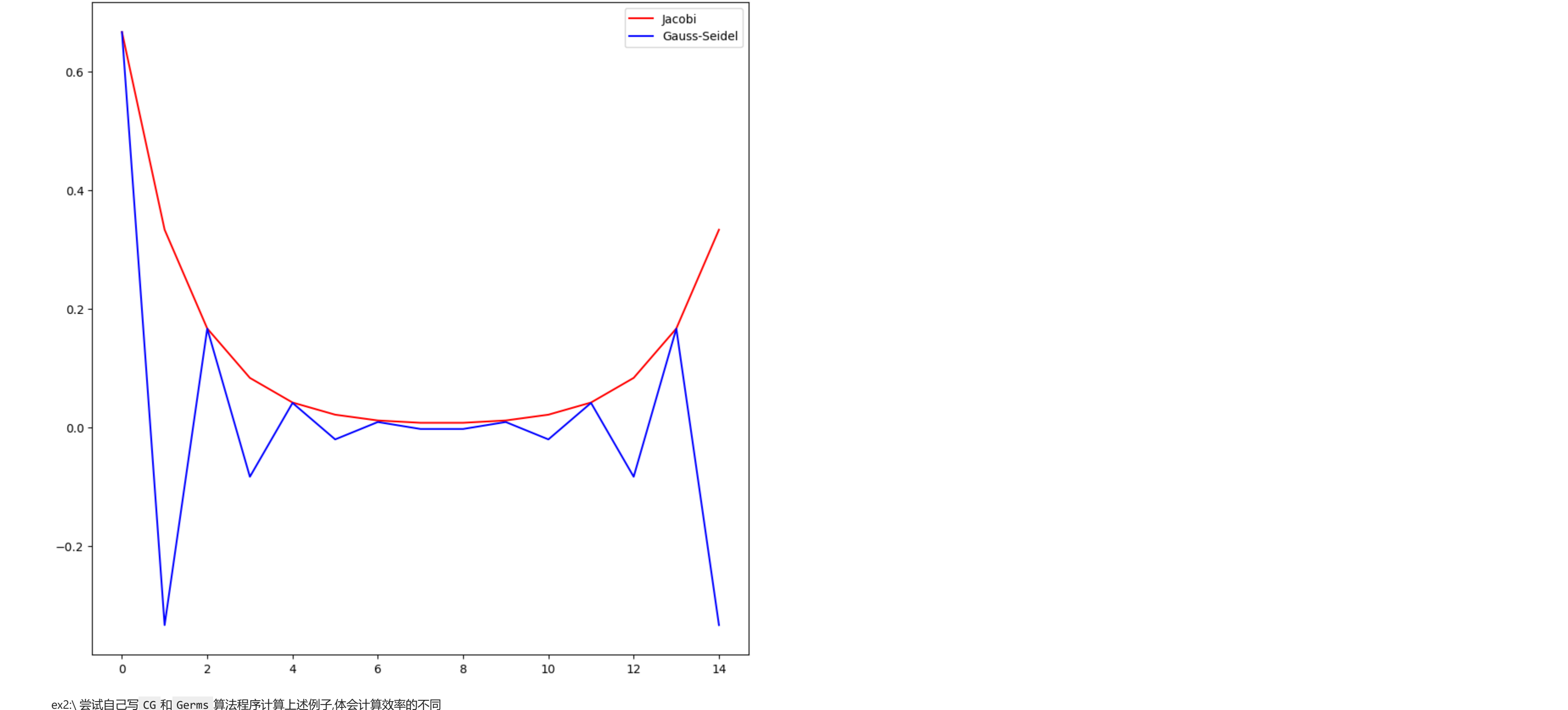


```
In [ ]: A = np.zeros((15,15)).astype(np.float64)

for i in range(15):
A[i,i] = 5/2
if i != 0:
A[i,i-1] = -1
if i != 14:
A[i,i+1] = -1
A[0,14],A[14,0] = -1,-1
b = np.zeros(15).astype(np.float64)
b[0] = 1
x0 = np.random.rand(15).astype(np.float64)
x_jaco = Jacobi_iteration(A,b,x0)
x_gauss = Gauss_Seidel_iteration(A,b,x0)
#x_sor = SuccessiveSOR_iteration(A,b,x0)

n = 15
plt.figure(figsize=(10,10))
plt.plot(range(n),x_jaco,'r-',label='Jacobi')
plt.plot(range(n),x_gauss,'b-',label='Gauss-Seidel')
plt.plot(range(n),x_sor,'g-',label='SOR')
plt.legend()
plt.show()

迭代次数已达到最大值
迭代次数已达到最大值
```



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ex2\ 尝试自己写 CG 和 Geres 算法程序计算上列例子,体会计算效率的不同

In [ ]: x = conjugate_gradient(A, b, x0, tol=1e-6, max_iter=150)

plt.plot(range(len(x)), x)

Iterator:2,算法收敛,x为:[0.66670736 0.3333842 0.16675324 0.08349864 0.04199347 0.02148503
0.01171911 0.00781274 0.00781274 0.01171911 0.02148503 0.04199347
0.08349864 0.16675324 0.3333842 ]
[<matplotlib.lines.Line2D at 0x7f8ebcd00>]

Out [ ]:
```

