3. $\lambda^k$ 为 $A^k$ 的特征值  Method2 充要条件:  1. 矩阵 $A$ 可相似对角化的充要条件是 $A$ 有 $n$ 个线性无关的特征向量.  2. 矩阵 $A$ 的不同特征值构成的特征子空间正交,即不同特征值对应的特征向	3量正交.
Method3  def Rayleigh(A,x): """ 瑞利商定义  Args: A (Matrix): 要求对称的系数矩阵 x (vector): 特征向量	
Returns:     float:瑞利商的值 """  b = np.dot(A,x)  return np.dot(x,b)/np.dot(x,x)  A = np.array([ [2,5,0],	
<pre>[5,3,7], [0,7,6] ]) lam,x = np.linalg.eig(A) print(Rayleigh(A,x[2])) -3.7754908865633916  def PowerMethod(A,v0 = None,isRayleigh = False,tol = 1e-6,mage)</pre>	max_iter = 150,output_key = False):
*************************************	ults to False.
<pre>A = A.copy()  if v0 is None:     v0 = np.random.rand(A.shape[0])  else:     v0 = v0.copy()  u0 = v0  oldmu = max(v0)</pre>	
<pre>oldmu = max(v0) i = 0 while i &lt; max_iter:     v0 = A @ u0     mu = max(v0)     u0 = v0 / mu</pre>	
<pre>if (abs (mu - oldmu) &lt; tol):     break  oldmu = mu  i += 1  if i &lt; max_iter and output_key:</pre>	
<pre>if isRayleigh:     mu = Rayleigh(A,u0)  print(f"迭代{i+1}次收敛,特征值为:{mu},特征向量为:{u0}")  elif i == max_iter and output_key:     print(f"迭代{i+1}次未收敛,特征值为:{mu},特征向量为:{u0}")  return mu,u0</pre>	
A = np.array([	
p = 0.75  B = A - p*np.eye(A.shape[0])  lam1,vec1 = PowerMethod(B,output_key=True)  ## 瑞利商加速  lam2,vec2 = PowerMethod(A,isRayleigh=True,output_key=True)  迭代19次收敛,特征值为:2.536527100235017,特征向量为:[0.7482221 0]	0.64966214 1.
迭代17次收敛,特征值为:1.7865262714363126,特征向量为: $[0.74822143$ 迭代26次收敛,特征值为:2.5365258604166776,特征向量为: $[0.74822209]$ 下面我们来介绍Householder变换,以及Householder变换的矩阵特征值计算 为初等反射矩阵,称为Householder变换,如果设 $\omega=(\omega_1,\cdots,\omega_n)^T$ ,则:	0.64966136 $1.$
<pre>def householder(omega):     """Householder transformations  Args:     omega (vector): 向量</pre>	$H = egin{bmatrix} -2\omega_2\omega_1 & 1-2\omega_2^2 & \cdots & -2\omega_2\omega_n \ dots & dots & \ddots & dots \ -2\omega_n\omega_1 & -2\omega_n\omega_2 & \cdots & 1-2\omega_n^2 \end{bmatrix}$
<pre>n = omega.shape[0] x = omega.copy() sigma = np.sign(x[0]) * np.linalg.norm(x) e = np.zeros((n,1)) e[0] = 1</pre>	
u = x + sigma * e  beta = np.linalg.norm(u) ** 2 / 2 ##要求系数矩阵非奇异  I = np.eye(n)  H = I - u@u.T / beta  return H	
<pre>def householder_tran(x):     x = x.copy()  x = x / np.linalg.norm(x)  n = x.shape[0]  i = np.eye(n)</pre>	
<pre>H = i - 2 * x @ x.T  return H  x = np.array([     [1],     [0] ])  y = np.array([</pre>	
<pre>[0.6], [0.8] ])  H = householder_tran(x)  y_t = H @ y  x,y,y_t = x.reshape(-1),y.reshape(-1),y_t.reshape(-1)</pre>	
	$\mathbf{P}_{\mathbf{v}}^{\perp}\mathbf{x}$
Householder变换存在的目的即为将一个向量按照另一向量的垂直方向做镜修	$\left\{egin{aligned} H = I - eta^{-1} u u^T \ \sigma = sgn(x_i) \ x\ _2 \end{aligned} ight.$
def QR_householder_decomposition(A,output_key=False): """采用Householder变换进行QR分解  Args: A (matrix): 系数矩阵 output_key (bool, optional): 输出控制. Defaults to Fa	$\left\{egin{array}{l} u=x+\sigma e_i \ eta=rac{\ u\ _2^2}{2} \end{array} ight.$
output_key (bool, optional): 输出控制. Defaults to Fa """  A = A.copy()  n = A.shape[0]  Q = np.eye(n)  i = 0	
<pre>for x in A.T:  y = x[i:].reshape(-1,1)  H_i = householder(y)  A[i:,i:] = H_i @ A[i:,i:]  I_i = np.eye(i)</pre>	
<pre>H = np.block([</pre>	
<pre>R = np.around(A, decimals=8)  if output_key:</pre>	\n{Q}\nR=\n{R},\nQR乘积为:\n{np.around(Q@R,decimals=4)}")
A = np.array([[12, -51, 4],	
[-0.42857143 -0.90285714 0.03428571] [ 0.28571429 -0.17142857 -0.94285714]] R= [[ -1421. 14.] [ 0175. 70.] [ -00. 35.]], QR  QR  QR  (1251. 4.] [ 6. 16768.] [ -4. 2441.]]	
<pre>def givens_trans(n,i,j,theta):     """生成Givens变换矩阵  Args:     n (_type_): _description_     i (_type_): _description_     j (_type_): _description_     theta (_type_, optional): _description</pre>	专矩阵的另一种形式,它只对矩阵的列进行旋转,而不对行进行旋转,同时保持矩阵的行列式不变且仍具有正交性.
<pre>theta (_type_, optional): _description  """  G = np.eye(n)  G[i,i] = np.cos(theta)  G[i,j] = np.sin(theta)  G[j,i] = -np.sin(theta)  G[j,j] = np.cos(theta)  return G</pre>	
<pre>def givens(x):     """givens约化  Args:</pre>	
<pre>P = np.eye(n) i = 0  for j in range(1,n):     theta = np.arctan(x[j] / x[i])      P_i = givens_trans(n,i,j,theta)     x = P_i @ x</pre>	
<pre>x = P_i @ x  P = P_i @ P  return P  x = np.array([     [0.6] ]).astype(np.float32)  x = np.reshape(x, (-1,1))</pre>	
<pre>x = np.reshape(x,(-1,1))  P = givens(x)  def QR_givens_decomposition(A,output_key = False):     """采用吉文斯变换的 QR 分解  Args:     A (_type_): _description_     ouput_key (_type_): _description_ """</pre>	
<pre>A = A.copy() n = A.shape[0] Q = np.eye(n) i = 0  for j in range(n):     x = A.T[j]</pre>	
<pre>y = np.reshape(x[i:], (-1,1))  P_i = givens(y)  I_i = np.eye(i)  P = np.block([         [I_i,np.zeros((i,n-i))],         [np.zeros((n-i,i)),P_i]] ])</pre>	
<pre>A = P @ A  Q = P @ Q  i += 1  R = np.around(A, decimals=5) Q = np.around(Q.T, decimals=5)  if output_key:</pre>	
print(f"矩阵经{i+1}次Givens列变换后,得到的分解为:\nQ: return Q,R  A = np.array([[12, -51, 4],	{Q}\nR:\n{R}\nQR乘积为:\n{np.around(Q@R,decimals = 0)}")
Q: [[ 0.85714 -0.39429  0.33143]   [ 0.42857  0.90286 -0.03429]   [-0.28571  0.17143  0.94286]] R: [[ 14.  2114.]   [ -0. 17570.]   [ -0.  035.]] QR乘积为: [[ 1251.  4.]   [ 6. 16768.]	
[ -4. 2441.]] 上述分析可知,通过Givens变换或者householder变换可以将一个矩阵变换为I Householder QR:  1. 通过householder变换将矩阵变换为上Hessenberg矩阵. 2. 通过不同的QR方法计算特征值与特征向量.	正交矩阵乘子形式,下面我们来介绍在计算特征值上更为实用的QR方法。
<pre>def householder_trans_hessenberg(A,output_key = False):     """_summary_  Args:     A (_type_): _description_     output_key (bool, optional): _description Defaults """  A = A.copy()  n = A.shape[0]</pre>	is to False.
<pre>i = 1 U = np.eye(n) for x in A.T:     c = x[i:].reshape(-1,1)     sigma = np.sign(c[0]) * np.linalg.norm(c)</pre>	
<pre>e = np.zeros((n-i,1)) e[0] = 1  u = c + sigma * e  beta = sigma*(sigma + c[0])  I_i = np.eye(i)  R_i = np.eye(n-i) - 1/beta * u@u.T</pre>	
<pre>U_i = np.block([</pre>	
<pre>if i == n-1:     break  A = np.around(A, decimals = 6) U = np.around(U, decimals = 6)  if output_key:     print(f"经过{i+1}次迭代,由householder变换生成的矩阵为:\n</pre>	n{A}")
<pre>return A,U  A = np.array([     [-4,-3,-7],     [2,3,2],</pre>	
[2,3,2], [4,2,7] ]).astype(np.float64)  H,U = householder_trans_hessenberg(A, True)  经过3次迭代,由householder变换生成的矩阵为: [[-4. 7.602631 -0.447214] [-4.472136 7.8 -0.4 ] [00.4 2.2 ]]  当我们将矩阵约化为上Hessenberg矩阵后,其特征值我们将有一套很好的算法	法即QR方法来处理这一类问题.
<pre>def QR_method(A,isSymmetric = False,output_key = False,tol :     """     QR方法求解矩阵特征值  Args:     A (_type_): _description_     output_key (bool, optional): _description Defaults     tol (_type_, optional): _description Defaults to :     """</pre>	= 1e-5, max_iter = 50):  ts to False.
<pre>A = A.copy()  if np.allclose(A, A.T):     isSymmetric = True  n = A.shape[0]  if isSymmetric:     U = np.eye(n)</pre>	
<pre>A,_ = householder_trans_hessenberg(A)  ##print(A)  def sumOfUpper(A):     res = 0      for i in range(A.shape[0]):         for j in range(0,i):</pre>	
<pre>for j in range(0,i):     res += A[i][j] ** 2  return res ** 0.5  def diag(A):     res = []  for i in range(A.shape[0]):     res.append(A[i][i])  return res</pre>	
<pre>i = 0 while i &lt; max_iter:     s_i = A[-1][-1]     I_i = np.eye(n)     Q,R = QR_householder_decomposition(A)</pre>	
<pre>if isSymmetric:     U = U @ Q  A = R @ Q  i += 1  if sumOfUpper(A) &lt; tol:     break</pre>	
<pre>if i == max_iter:     print("迭代次数过多, 无法收敛")     return None else:  if output_key:     print(f"矩阵经分解后特征值为\n{A}\n,特征向量为:\n{U})  if isSymmetric:     eigvector = np.around(U,decimals = 5)     eigvalue = np.around(A,decimals = 5)</pre>	}")
<pre>eigvector = np.around(U,decimals = 5) eigvalue = np.around(A,decimals = 5)  return eigvalue, eigvector  else:  eigvector = [] eigvalue = np.around(A,decimals = 5)  return eigvalue, eigvector</pre>	
A = np.array([	
<pre>矩阵经分解后特征值为 [[ 4.73205086e+00 -8.68901403e-06 1.00000000e-07]   [-8.60999986e-06 2.99999995e+00 -8.00000000e-08]   [ 0.00000000e+00 0.00000000e+00 1.26794920e+00]] ,特征向量为: [[-0.21132777 -0.57734921 -0.78867512]   [ 0.57735317 0.57734736 -0.57735027]   [-0.78867225 0.5773542 -0.2113249 ]] 上机练习1:\ 利用householder变换约化矩阵:</pre>	
为上Hessenberg矩阵 $H$ ,求出反射矩阵 $P$ 使得 $H=PAP$ $A = \underset{\{1,3,4\}, \{3,1,5\}, \{4,2,1\}}{\text{Particle}}$	$A = \begin{pmatrix} 1 & 3 & 4 \\ 3 & 1 & 5 \\ 4 & 2 & 1 \end{pmatrix}$
[4,2,1] ]).astype(np.float64)  H,P = householder_trans_hessenberg(A)  print(f"经householder约化后矩阵\n{A}\n变换为:\n{H},\n其反射矩阵\ 经householder约化后矩阵 [[1. 3. 4.] [3. 1. 5.] [4. 2. 1.]] 变换为:	\n{P}\n")
[4. 2. 1.]] 变换为:  [[150.] [-5. 4.36 -0.52] [-0. 2.48 -2.36]],  其反射矩阵  [[1. 0. 0.] [00.6 -0.8] [00.8 0.6]]  上机练习2:用幂法、反幂法计算矩阵最大最小特征值对,以及QR算法计算	
的所有特征值和特征向量 A = np.array([ [1, 1, 1/2],	$A = \left(egin{array}{ccc} 1 & 1 & 1/2 \ 1 & 1 & 1/4 \ 1/2 & 1/4 & 2 \end{array} ight)$
[1, 1, 1/2], [1, 1, 1/4], [1/2, 1/4, 2] ]).astype(np.float64)  lambdal = PowerMethod(A)  print(f"由幂法得到的特征值:\n{lambdal}\n")  eigvalue,eigvector = QR_method(A)  print(f"由QR方法得到的特征值:\n{eigvalue}\n,特征向量\n{eigvector}	$0$ r $\}$ $\backslash$ n" $)$
	)))
由幂法得到的特征值: (2.5365245826319622, array([0.74822017, 0.64966012, 1. 由QR方法得到的特征值: [[ 2.53653e+00 -1.00000e-05 0.00000e+00]     [-1.00000e-05 1.48012e+00 0.00000e+00]     [ 0.00000e+00 0.00000e+00 -1.66500e-02]] ,特征向量 [[ 0.53149 0.44428 0.72121]     [-0.73042 -0.19078 0.65581]	