Random Walk and its extensions

Object Oriented Programming 2024 First Semester Shin-chi Tadaki (Saga University)

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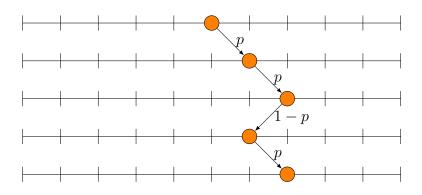
Introduction: What is Random Walk (酔歩)

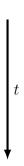
- Random walk is a mathematical object that describes a path that consists of a succession of random steps.
- It is a simple but fundamental example of a stochastic process.
- It also gives us a good insight into the behavior of more complex systems.

One-dimensional Random Walk

- A one-dimensional random walk is a sequence of random steps on a line.
 - The walker starts at the origin and moves by one unit at each step.
 - \bullet At each step, the walker moves left with probability p and right with 1-p.
- The positions of the walker are not important, but the probability distribution of the position is.
- For estimating the probability distribution by simulations, we need to simulate motions of a large number of walkers.

Image of Random walk





Theoretical Analysis

- At t-th step, the position is x if the particle moves right m=(t+x)/2 times and left n=t-m=(t-x)/2 times.
- ullet The probability arriving to the position x is given by the binomial distribution

$$P(x) = {t \choose \frac{t+x}{2}} p^{(t+x)/2} (1-p)^{(t-x)/2}$$
 (2.1)

ullet The probability moving m steps to the right is given by

$$Q(m) = {t \choose m} p^m (1-p)^{t-m}$$
(2.2)

Generating Function (確率母関数) for Q(m)

• For obtaining averages, deviations and other moments, the generating function is a convenient tool.

$$G(z) = \sum_{m=0}^{t} Q(m)z^{m}$$
 (2.3)

General formulae with generating functions

$$G(1) = \sum_{m=0}^{l} Q(m) = 1 \tag{2.4}$$

$$G'(z) = \sum_{m=1}^{t} mQ(m)z^{m-1} = \sum_{m=0}^{t} mQ(m)z^{m-1}$$
(2.5)

$$G'(1) = \sum_{m=0}^{t} mQ(m) = \langle m \rangle \tag{2.6}$$

$$G''(z) = \sum_{m=2}^{t} m(m-1)Q(m)z^{m-2} = \sum_{m=0}^{t} m(m-1)Q(m)z^{m-2}$$

$$G''(1) = \sum_{t=0}^{t} m(m-1)Q(m) = \langle m(m-1) \rangle$$
 (2.8)

For binominal distribution

- For the binomial distribution, the generating function is given by a compact form.
- Those compact forms enable us to calculate the moments easily.

$$G(z) = \sum_{m=0}^{t} {t \choose m} p^m (1-p)^{t-m} z^m = (zp+1-p)^t$$

$$G(1) = 1$$
(2.9)

$$G'(z) = tp (zp + 1 - p)^{t-1}$$
(2.10)

$$G'(z) = tp(zp + 1 - p)$$
(2.11)
$$G'(1) = tp$$
(2.12)

$$\langle m \rangle = tp \tag{2.12}$$

$$\langle x \rangle = \langle 2m - 1 \rangle = 2tp - 1 = t(2p - 1)$$
 (2.14)

$$G''(z) = t(t-1)p^{2} (zp+1-p)^{t-2}$$

$$G''(1) = t(t-1)p^{2} = \langle m^{2} \rangle - \langle m \rangle$$

$$\sigma^{2} = \langle x^{2} \rangle - \langle x \rangle = 4tp(1-p)$$
(2.15)
$$(2.16)$$

Approximated distribution at the visinity of the mean

$$P(x) \propto \exp\left[-\frac{(x - \langle x \rangle)^2}{2\sigma^2}\right]$$
 (2.18)
$$\langle x \rangle = t(2p - 1)$$
 (2.19)

$$\langle x \rangle = t(2p-1) \tag{2.19}$$

$$\sigma^2 = 4tp(1-p) \tag{2.20}$$

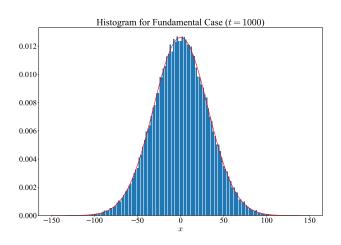
Normal (Gauss) distribution

Class Planning in model package

- Walker class: A class for a single walker
- Simulation class: A class for simulating a large number of walkers
- PositionHistogram class: A class for creating the histogram of the positions

walk() method in Walker class

p=1/2 case



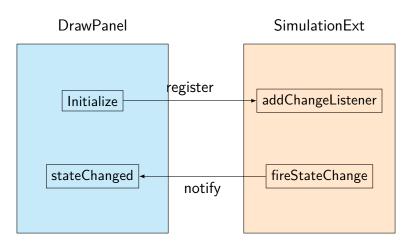
Observer Design Pattern

- You may want to monitor the progress of the simulation.
- However, you need not to monitor the every changes in the simulation.
- Moreover, you may not want to change the Simulation class.
- Observer design pattern is a solution for this case.

Random Walk Simulation with GUI

- GuiMain class: A class for the main frame extended from JFrame.
- DrawPanel class: A class for drawing the histogram extended from JPanel.
- SimulationExt class: A runnable extension of the Simulation class.
 - It observes the changes in the simulation every 10 steps.
 - State changes are notified to the DrawPanel class.

Notify State Changes



Notify State Changes

```
public void run() {
 1
          while (running) {
2
               this.oneStep();
3
               //Every 10 steps, notify the listeners
if (t % 10 == 0) {
4
 5
                   fireStateChanged();
6
               try {
 8
                   Thread.sleep(100):
               } catch (InterruptedException ex) {
10
11
12
      }
13
14
      private void fireStateChanged() {
15
          listeners.forEach(
16
                   li -> li.stateChanged(new ChangeEvent(this)));
17
      }
18
```

Continuous Random Walk

- In the continuous random walk, the displacement of a walker is given by a random variable with a probability distribution.
- The distribution of the positions of the walkers is given by a continuous function.

Class Planning

- AbstractRandom class: An abstract class for the random number generator
- Walker class: A class for a single walker, whose position is continuous.
- Simulation class: A class for simulating a large number of walkers
- Histogram class: A class for creating the histogram of the continuous positions

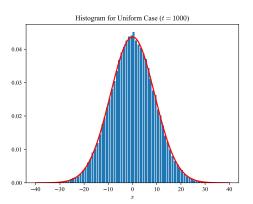
Walker class

```
public double walk() {
    double r = random.getNext();
    x += r;
    return x;
}
```

- random is an instance of AbstractRandom class.
- The distribution of the random variables is defined in the subclass of AbstractRandom.

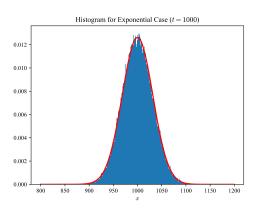
Uniform distribution

$$f(x) = \begin{cases} 1 & (-1/2 \le x \le 1/2) \\ 0 & (\text{otherwise}) \end{cases}$$
 (5.1)



Exponential distribution

$$f(x) = e^{-x}$$
 $x \in [0, \infty)$ (5.2)



Central Limiting Theorem: 中心極限定理

• $\{X_k\}$: random variables obeying an identical distribution with the mean μ and deviation σ^2

$$S_n = \sum_{k=1}^n X_k \tag{5.3}$$

$$S_n^* = \frac{S_n - n\mu}{\sqrt{n}\sigma} \tag{5.4}$$

$$\lim_{n \to \infty} P(S_n^* \le a^*) = \frac{1}{\sqrt{2}} \int_{-\infty}^{a^*} \exp\left[-\frac{x^2}{2}\right] dx$$
 (5.5)

• In the limit $n \to \infty$, S_n^* obeys the standard normal distribution $N\left(0,1\right)$

Appendix: Generating nonuniform random numbers

- For generating nonuniform random numbers, we need to transform the uniform random numbers.
- Two types of methods
 - Transform method
 - Rejection method

Transform method

• For a probability density f(x) $(x \in [a,b))$, the probability distribution F is given by

$$F(x) = \int_{a}^{x} f(t)dt \tag{6.1}$$

- ullet The transform method is available if the inverse function F^{-1} is obtained.
- procedure
 - Generate a uniform random number $r \in [0, 1)$.
 - $x = F^{-1}(r)$
 - $\{x\}$ is a random number obeying the probability density f(x).

Generating random numbers obeying exponential distribution

• In continuousModel/Main1.java, the random numbers obeying the exponential distribution $f(x)=e^{-x}$ $(x\in[0,\infty])$ are generated.

$$F(x) = \int_0^x e^{-t} dt = 1 - e^{-x}$$
 (6.2)

$$F^{-1}(x) = -\ln(1-x) \tag{6.3}$$

```
AbstractRandom random = new Transform(x->-Math.log(1-x), seed);
Simulation sys = new Simulation(n, random);
```

Appendix: Characteristic functions: 特性関数

- The characteristic function of a continuous random variable is a counterpart of the generating function of a discrete random variable.
- ullet For the probability density function f(x), the characteristic function is defined by

$$\varphi(z) = \int_{-\infty}^{\infty} f(x)e^{izx} dx$$
 (7.1)

General formulae with characteristic functions

$$\varphi(0) = \int_{-\infty}^{\infty} f(x) dx = 1 \tag{7.2}$$

$$\varphi'(z) = i \int_{-\infty}^{\infty} x f(x) e^{izx} dx$$
 (7.3)

$$\varphi'(0) = i \int_{-\infty}^{\infty} x f(x) dx = i \langle x \rangle$$
 (7.4)

$$\varphi''(z) = -\int_{-\infty}^{\infty} x^2 f(x) e^{izx} dx$$
 (7.5)

$$\varphi''(0) = -\int_{-\infty}^{\infty} x^2 f(x) dx = -\left\langle x^2 \right\rangle \tag{7.6}$$

Characteristic function for uniform distribution

$$f(x) = \begin{cases} 1 & (-1/2 \le x \le 1/2) \\ 0 & (\text{otherwise}) \end{cases}$$
 (7.7)

$$\varphi(z) = \int_{-1/2}^{1/2} e^{izx} dx = \frac{2}{z} \sin(\frac{z}{2})$$
 (7.8)

$$=1-\frac{z^2}{24}+\frac{z^4}{1920}+O(z^6) \tag{7.9}$$

$$\langle x \rangle = 0 \tag{7.10}$$

$$\left\langle x^2 \right\rangle = \frac{1}{12} \tag{7.11}$$

 $f(x) = e^{-x} \qquad x \in [0, \infty)$

Characteristic function for exponentioal distribution

$$\varphi(z) = \int_0^\infty e^{izx} e^{-x} dx = \frac{1}{1 - iz} \qquad \varphi(0) = 1 \qquad (7.13)$$

$$\varphi'(z) = \frac{i}{(1 - iz)^2} \qquad \varphi'(0) = i \qquad (7.14)$$

$$\varphi''(z) = \frac{2}{(1 - iz)^3} \qquad \varphi''(0) = 2 \qquad (7.15)$$

$$\langle x \rangle = 1 \qquad \langle x^2 \rangle = 2 \qquad (7.16)$$

$$\sigma^2 = 1 \qquad (7.17)$$

(7.12)